
LECTURE 24: FORCE ACTING ON A LOCALIZED CURRENT DISTRIBUTION

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From the previous lecture, we found that

$$\vec{m} = \frac{1}{2} \int \vec{x} \times \vec{J}(x) d^3x$$

We assume that

$$\vec{F} = q\vec{v} \times \vec{B}$$

or

$$\vec{F} = \int \vec{J} \times \vec{B} d^3x$$

We will Taylor expand this in components (to deal with the cross product):

$$\begin{aligned} F_i &= \int \epsilon_{ijk} J_j \left[B_k(0) + x_l \partial_l \Big|_0 B_k + \frac{1}{2} (x_l \partial_l)^2 \Big|_0 B_k + \dots \right] dx \\ &= \epsilon_{ijk} B_k(0) \int \cancel{J_j} d^3x + \int d^3x \epsilon_{ijk} J_j x_l \partial_l \Big|_0 B_k + \dots \end{aligned}$$

Recall the way we split up index notation in last lecture:

$$\int x_l J_j d^3x = \int x_{[l} J_{j]} + \cancel{x_{(l} J_{j)}} d^3x = \frac{1}{2} \int \underbrace{x_l J_j - x_j J_l}_{\epsilon_{ljm} (\vec{x} \times \vec{J})_m} d^3x$$

so

$$\begin{aligned} F_i &= \epsilon_{ijk} \epsilon_{ljm} \frac{1}{2} \int (\vec{x} \times \vec{J})_m d^3x \partial_l \Big|_0 B_k \\ &= (\delta_{il} \delta_{km} - \delta_{im} \delta_{kl}) m_m \partial_l \Big|_0 B_k = m_k \partial_i \Big|_0 B_k - \underbrace{m_i \partial_k \Big|_0 B_k}_{\nabla \cdot \vec{B} = 0} \end{aligned}$$

We can then say that

$$\vec{F} \approx \nabla \Big|_0 (\vec{m} \cdot \vec{B})$$

Recall that since $\nabla \times \vec{B} = 0$ (we suppose this magnetic field is external), $\partial_i B_k - \partial_k B_i = 0$, so

$$m_k \partial_i B_k = m_k \partial_k B_i$$

so

$$\vec{F} \approx (\vec{m} \cdot \nabla) \Big|_0 \vec{B}$$

What is the torque on this system?

Notation

Jackson uses “ n ”, but we will use \mathcal{T}

$$\mathcal{T} = \int \vec{x} \times (\vec{J} \times \vec{B}) d^3x$$

Again, let's look at the elements:

$$\begin{aligned} \mathcal{T}_i &= \int (J_i(x_k B_k) - B_i(x_k J_k)) d^3x \\ &= \int J_i(x_k B_k) d^3x - \int B_i x_k J_k d^3x \end{aligned}$$

because we can expand B_i as

$$B_i(0) + \vec{x} \cdot \nabla \Big|_0 \vec{B} + \dots$$

and

$$B_i(0) \int x_k J_k d^3x = 0$$

because these are symmetrized indices.

We can expand the other side as

$$\begin{aligned} \mathcal{T}_i &= \int J_i x_k [B_k(0) + (\vec{x} \cdot \nabla) \Big|_0 \vec{B} + \dots] d^3x \\ &= \int \frac{1}{2} (x_k J_i - x_i J_k) B_k(0) d^3x + \dots \\ &= \epsilon_{kil} m_l B_k(0) \\ &= \epsilon_{ilk} m_l B_k(0) \\ &= \vec{m} \times \vec{B}(0) \end{aligned}$$

Remark

$$\begin{aligned} \nabla \times \vec{B} &= \mu_0 \vec{J} \\ \nabla \times \nabla \times \vec{B} &= \mu_0 \nabla \times \vec{J} \\ \nabla \nabla \cdot \vec{B} - \nabla^2 \vec{B} &= \mu_0 \nabla \times \vec{J} \end{aligned}$$

so

$$\nabla^2 \vec{B} = -\mu_0 \nabla \times \vec{J}$$

From quantum mechanics, (circularly polarized light, for example), we know that these fields must carry some information about angular momentum. This can't be derived from our current expansions of \vec{B} and \vec{E} . There is a more “transparent” expansion, but of course, it requires a “roundabout” way of doing the expansion. In the special case of

$\vec{J} = 0$, we find that $\nabla \times \vec{B} = 0$ so $\vec{B} = -\nabla \Phi_m$, where Φ_m is some scalar potential for the magnetic field. There is a problem with this. If we were to look at some path of current and integrate over a path overlapping it (passing through x_0),

$$\oint_{\Gamma} \vec{B} \cdot d\vec{l} = \mu_0 I$$

this would imply that

$$\int \nabla \Phi_m \cdot d\vec{l} = \Phi_m(\vec{x}_0) - \Phi_m(\vec{x}_0) = 0$$

unless we allow the potential to be multivalued (which we shouldn't).

If we look at $\vec{x} \cdot \vec{B}$ instead, we see that

$$\vec{x} \cdot \nabla^2 \vec{B} = \nabla^2(\vec{x} \cdot \vec{B}) - 2 \cancel{\nabla \cdot \vec{B}}^0$$

so

$$\nabla^2 \vec{B} = -\mu_0 \nabla \times \vec{J} \implies \vec{x} \cdot \nabla^2 \vec{B} = -\mu_0 \vec{x} \cdot \nabla \times \vec{J} = \nabla^2(\vec{x} \cdot \vec{B})$$

We can now start playing with this expression:

$$\begin{aligned} \nabla^2(\vec{x} \cdot \vec{B}) &= -\mu_0 \vec{x} \cdot \nabla \times \vec{J} \\ &\rightarrow x_i \epsilon_{ijl} \partial_j J_l \\ &= \epsilon_{ijl} x_i \partial_j J_l \\ &= (\vec{x} \times \nabla) \cdot \vec{J} \end{aligned}$$

so

$$\begin{aligned} \nabla^2(\vec{x} \cdot \vec{B}) &= -\mu_0 (\vec{x} \times \nabla) \cdot \vec{J} \\ &= -\mu_0 \underbrace{(-\vec{x} \times \nabla)}_{\vec{\mathbb{L}}} \cdot \vec{J} \\ &= -\mu_0 \vec{\mathbb{L}} \cdot \vec{J} \end{aligned}$$

so

$$\vec{x} \cdot \vec{B} = \frac{\mu_0}{4\pi} \int \frac{\vec{\mathbb{L}} \cdot \vec{J}(x')}{|\vec{x} - \vec{x}'|} d^3x'$$

We now expand the denominator in terms of our spherical harmonics:

$$\begin{aligned} \vec{x} \cdot \vec{B} &= \frac{\mu_0}{4\pi} \int (\vec{\mathbb{L}} \cdot \vec{J})(x') \sum_{l=0}^{\infty} \sum_{m=-l}^l \frac{4\pi}{2l+1} Y_{lm}^*(\theta', \varphi') Y_{lm}(\theta, \varphi) \frac{r_{>}^l}{r_{>}^{l+1}} d^3x' \\ &= \frac{\mu_0}{4\pi} \int \sum_{l,m} Y_{lm}^*(\Omega') \vec{\mathbb{L}} \cdot \vec{J}(\Omega', r') d\Omega' dr' \frac{4\pi}{2l+1} \frac{r_{>}^l}{r_{>}^{l+1}} d^3x' Y_{lm}(\Omega) \end{aligned}$$

It turns out that we can also express

$$\vec{x} \cdot \vec{B} = -r \frac{\partial \Phi_m}{\partial r}$$

so

$$\begin{aligned}
\frac{\partial \Phi_m}{\partial r} &= \frac{-\imath \mu_0}{4\pi} \frac{1}{r} \sum_{l,m} \int \frac{4\pi}{2l+1} Y_{lm}^*(\Omega') (\vec{\mathbb{L}} \cdot \vec{J})(\Omega', r') r'^l d\Omega' dr' \frac{Y_{lm}(\Omega)}{r^{l+1}} \\
&= \left(\frac{-\imath \mu_0}{4\pi} \right) \sum_{l,m} \left(\frac{4\pi}{2l+1} \int Y_{lm}^*(\Omega) \vec{\mathbb{L}} \cdot \vec{J} d\Omega' r'^l dr' \right) \frac{Y_{lm}}{r^{l+1}} \\
&= \Phi_M = \frac{\imath \mu_0}{\sqrt{l+1}} \sqrt{l} \sum_{l,m} \left(\frac{4\pi}{2l+1} \right) \left\{ \int \frac{\vec{\mathbb{L}} Y_{lm}^*}{\sqrt{l(l+1)}} \cdot \vec{J} d\Omega' r'^l dr' \right\} \frac{Y_{lm}}{r^{l+1}}
\end{aligned}$$

where $\vec{\mathbb{L}} Y_{lm}^*$ are the vector spherical harmonics