Lecture 8: More on Y_{lm} Functions

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NB

I will be using L for \mathbb{L} from here onward.

If we don't have the full range of the spherical angles, we actually have to solve the original ∇^2 differential equations and can't use L and L^2 or the Y_{lm} functions.

$$Y_{lm}(\theta,\phi) = \sqrt{\frac{2l+1}{4\pi} \frac{(l-m)!}{(l+m)!}} P_l^m(\cos\theta) e^{\imath m\phi}$$
 (1)

where

$$P_l^m(x) = \frac{(-1)^m}{2^l l!} (1 - x^2)^{m/2} \frac{d^{l+m}}{dx^{l+m}} (x^2 - 1)^l.$$
 (2)

Orthogonality tells us:

$$\int Y_{lm}^*(\theta,\phi)Y_{l'm'}(\theta,\phi)d\Omega = \delta_{ll'}\delta_{mm'}$$
(3)

The spectral decomposition tells us:

$$\sum_{lm} Y_{lm}(\theta, \phi) Y_{lm}^*(\theta', \phi') = \delta(\phi - \phi') \delta(\cos \theta - \cos \theta')$$
(4)

since $\delta(f(x)) = \frac{1}{f'(x_0)}\delta(x - x_0)$.

MR

In EM, we write Y_{lm} such that $Y_{lm}(\theta, \phi) = (-1)^m Y_{l,-m}^*(\theta, \phi)$.

For general spherical solutions,

$$\Phi = \sum g_{lm}(r)Y_{lm}(\theta,\phi)$$
 or

$$\frac{1}{r^2}\partial_r r^2 \partial_r g - \frac{l(l+1)}{r^2} = 0 \tag{5}$$

so $r^2 \partial_r^2 g + 2r \partial_r g - l(l+1)g = 0.$

Suppose $g = r^{\lambda}$:

$$[\lambda(\lambda - 1) + 2\lambda - l(l+1)]r^{\lambda} = 0 \tag{6}$$

so $\lambda = l$ or -(l+1)

Therefore, the general solution in spherical systems (which use the periodicity in both ϕ and θ) is:

$$\Phi = \sum_{l=0}^{\infty} \sum_{m=-l}^{l} [A_l r^l + B_l r^{-(l+1)}] Y_{lm}(\theta, \phi).$$
 (7)

0.0.1 Systems with ϕ -independence

If we have an axis of symmetry, set the z-axis as the axis of symmetry. Therefore solutions should be independent of the angle around the z-axis (ϕ) .

This means $Y_{lm} \to Y_{l0}$ so $P_l^m \to P_l(x) = \frac{1}{2^l l!} \frac{d^l}{dx^l} (x^2 - 1)^l$, which are not normalized for "historical reasons". The differential equation then becomes:

$$\frac{d}{dx}(1-x^2)\frac{d}{dx}P_l + l(l+1)P_l = 0, \ x \in [-1,1].$$
(8)

Remark. There are other solutions $Q_l(x) = \frac{1}{2}P_l(x)\ln\left[\frac{1-x}{1+x}\right] + R_l(x)$ where R_l is a polynomial of degree l-1.

Additionally $\int_{-1}^{1} P_l(x) P_{l'}(x) dx = \frac{2l+1}{2} d_{ll'}$

Jackson notes some "easy" relations from Rodriguez's formula:

1.
$$\frac{d}{dx}P_{l+1} - \frac{d}{dx}P_{l-1} - (2l+1)P_l = 0$$

2.
$$(l+1)P_{l+1} - (2l+1)xP_l + lP_{l-1} = 0$$

3.
$$P_{2k}(0) = \frac{(2k-1)!!}{2^k k!} (-1)^k$$

It can be shown that:

$$\frac{1}{|\vec{x} - \vec{x}'|} = \begin{cases} \sum \frac{1}{r^{l+1}} A_l P_l(\cos \gamma) & r > r' \\ \sum r^l B_l P_l(\cos \gamma) & r < r' \end{cases}$$
(9)

where γ is the angle between the vectors.

Equivalently,

$$\frac{1}{|\vec{x} - \vec{x}'|} = \sum_{l=0}^{\infty} \frac{r_{<}^{l}}{r_{>}^{l+1}} P_{l}(\cos \gamma)$$
 (10)

where $r_{<}$ and $r_{>}$ correspond to the smaller and larger vector.