33-765 Homework 9

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33. Statistical Physics of the N-dimensional Quadratic Hamiltonian

Consider a phase space with N degrees of freedom $\{x_i\}_{i=1,\dots,N}$ and on it a quadratic Hamiltonian

$$H = \frac{1}{2} \mathbf{x}^{\top} \mathbf{K} \mathbf{x}$$

or in components,

$$H = \frac{1}{2}x_i K_{ij} x_j$$

where the "kernel" **K** is symmetric and positive definite. To de-clutter the problem, we will ignore the beauty factor $\frac{1}{N!h^N}$.

1. Show that the canonical partition function is given by $Z := \text{Tr}(e^{-\beta H}) = \int d^N x \, e^{-\frac{1}{2}\beta x_i K_{ij} x_j} = \left(\det \frac{\beta \mathbf{K}}{2\pi}\right)^{-1/2}$.

If we change bases to one in which K_{ij} is diagonal $(y_i = T_{ij}x_j, \det(T) = 1 \text{ since } \mathbf{T} \text{ must be orthogonal}),$

$$Z = \int d^{N}x e^{-\frac{1}{2}\beta x_{i}K_{ij}x_{j}}$$

$$= \int d^{N}y \det(T)e^{-\frac{1}{2}\beta y_{i}T_{ij}^{-1}K_{ij}T_{ij}y_{j}}$$

$$= \int d^{N}y e^{-\frac{1}{2}\beta y_{i}K_{ii}y_{i}}$$

$$= \int d^{N}y e^{\sum_{i=1}^{N} -\frac{1}{2}\beta K_{ii}y_{i}^{2}}$$

$$= \int d^{N}y \prod_{i=1}^{N} e^{-\frac{1}{2}\beta K_{ii}y_{i}^{2}}$$

$$= \prod_{i=1}^{N} \int dy_{i} e^{-\frac{1}{2}\beta K_{ii}y_{i}^{2}}$$

$$= \prod_{i=1}^{N} \left(\sqrt{\frac{2\pi}{\beta K_{ii}}}\right)$$

$$= \left(\sqrt{\frac{2^N \pi^N}{\beta^N \prod_{i=1}^N K_{ii}}}\right)$$

where

$$\prod_{i=1}^{N} K_{ii} = \det(\mathbf{K})$$

since the diagonalized K has its eigenvalues on the diagonal and the determinant can be defined as the product of the eigenvalues.

$$Z = \left(\sqrt{\frac{2^N \pi^N}{\beta^N \det(\mathbf{K})}}\right)$$
$$= \left(\sqrt{\det\left(\frac{2\pi}{\beta \mathbf{K}}\right)}\right)$$
$$= \left(\det\frac{\beta \mathbf{K}}{2\pi}\right)^{-1/2}$$

We can bring the other constants in because they are multiplied N-times, and

$$\det(\alpha \mathbf{K}) = \alpha^N \det(\mathbf{K})$$

where N is the dimension of \mathbf{K} .

2. Starting with the result from problem 31.1, show that the equipartition theorem in this case can be written as

$$\langle \mathbf{x} \otimes \mathbf{x} \rangle \equiv \langle \mathbf{x} \mathbf{x}^{\top} \rangle = k_B T \mathbf{K}^{-1}$$

or, in components,

$$\langle x_i x_j \rangle = k_B T K_{ij}^{-1}.$$

From problem 31.1, we know that

$$\left\langle x_i \frac{\partial H}{\partial x_j} \right\rangle = k_B T \delta_{ij}$$

$$\begin{split} \frac{\partial H}{\partial x_k} &= \frac{1}{2} \partial_k \left(x_i K_{ij} x_j \right) = \frac{1}{2} \left(\delta_{ik} K_{ij} x_j + x_i K_{ij} \delta_{jk} \right) \\ &= \frac{1}{2} \left(K_{kj} x_j + K_{ik} x_i \right) \\ &= \frac{1}{2} \left(K_{kj} x_j + K_{ki} x_i \right) \\ &= \frac{1}{2} \left(K_{kj} x_j + K_{kj} x_j \right) \\ &= K_{kj} x_j \\ \frac{\partial H}{\partial x_j} &= K_{jk} x_k \end{split}$$

so

$$\langle x_i K_{jk} x_k \rangle = k_B T \delta_{ij}$$
$$\langle x_i x_k \rangle = k_B T \delta_{ij} K_{jk}$$
$$= k_B T K_{ik}$$
$$\langle x_i x_j \rangle = k_B T K_{ij}$$

3. We now amend the Hamiltonian by a "source term", $H = \frac{1}{2}\mathbf{x}^{\top}\mathbf{K}\mathbf{x} - \mathbf{J} \cdot \mathbf{x}$. This Hamiltonian is still quadratic, but it takes its minimum not at $\mathbf{x} = \mathbf{0}$ but at some displaced value \mathbf{x}^* . Find it!

To minimize the Hamiltonian, we set its derivative to zero and solve:

$$\frac{\partial H}{\partial \mathbf{x}} = \frac{1}{2} \left(\mathbf{x}^{\top} \cdot \mathbf{K} + \mathbf{K}^{\top} \cdot \mathbf{x} \right) - \mathbf{J}$$
$$0 = \mathbf{K}^{\top} \mathbf{x}^{*} - \mathbf{J}$$
$$\mathbf{x}^{*} = \mathbf{K}^{-1} \cdot \mathbf{J}$$

4. Use your result from the previous part to complete the square of this shifted quadratic matrix expression. In other words, write it in the form $H = \frac{1}{2}(\mathbf{x} - \mathbf{x}^*)^{\top} \mathbf{K}(\mathbf{x} - \mathbf{x}^*) + \text{stuff.}$

$$\frac{1}{2} (\mathbf{x} - \mathbf{x}^*)^{\top} \mathbf{K} (\mathbf{x} - \mathbf{x}^*) = \frac{1}{2} (\mathbf{x}^{\top} \mathbf{K} \mathbf{x} + (\mathbf{x}^*)^{\top} \mathbf{K} \mathbf{x}^* - (\mathbf{x}^*)^{\top} \mathbf{K} \mathbf{x} - \mathbf{x}^{\top} \mathbf{K} \mathbf{x}^*)$$

$$= \frac{1}{2} (\mathbf{x}^{\top} \mathbf{K} \mathbf{x} + (\mathbf{K}^{-1} \cdot \mathbf{J})^{\top} \mathbf{K} \mathbf{K}^{-1} \cdot \mathbf{J} - (\mathbf{K}^{-1} \cdot \mathbf{J})^{\top} \mathbf{K} \mathbf{x} - \mathbf{x}^{\top} \mathbf{K} \mathbf{K}^{-1} \cdot \mathbf{J})$$

$$= \frac{1}{2} (\mathbf{x}^{\top} \mathbf{K} \mathbf{x} + \mathbf{J}^{\top} \cdot (\mathbf{K}^{-1})^{\top} \mathbf{K} \mathbf{K}^{-1} \cdot \mathbf{J} - \mathbf{J}^{\top} \cdot (\mathbf{K}^{-1})^{\top} \mathbf{K} \mathbf{x} - \mathbf{x}^{\top} \mathbf{K} \mathbf{K}^{-1} \cdot \mathbf{J})$$

$$= \frac{1}{2} (\mathbf{x}^{\top} \mathbf{K} \mathbf{x} + \mathbf{J}^{\top} \mathbf{K}^{-1} \mathbf{J} - \mathbf{J}^{\top} \mathbf{x} - \mathbf{x}^{\top} \mathbf{J})$$

$$= \frac{1}{2} \mathbf{x}^{\top} \mathbf{K} \mathbf{x} + \frac{1}{2} \mathbf{J}^{\top} \mathbf{K}^{-1} \mathbf{J} - \mathbf{J} \cdot \mathbf{x}$$

$$= H + \frac{1}{2} \mathbf{J}^{\top} \mathbf{K}^{-1} \mathbf{J}$$
so
$$H = \frac{1}{2} (\mathbf{x} - \mathbf{x}^*)^{\top} \mathbf{K} (\mathbf{x} - \mathbf{x}^*) - \frac{1}{2} \mathbf{J}^{\top} \mathbf{K}^{-1} \mathbf{J}$$

5. Show that for a general
$$\mathbf{J} \neq \mathbf{0}$$
, the partition function is given by $Z = \operatorname{Tr} e^{-\beta H} = \left(\det \frac{\beta \mathbf{K}}{2\pi}\right)^{-1/2} e^{\frac{1}{2}\beta \mathbf{J}^{\top} \mathbf{K}^{-1} \mathbf{J}}$

This follows easily from the first part of this problem along with the fact that the part we just added by completing the square doesn't depend on \mathbf{x} , so we can factor it out:

$$Z = \int d^N x \, e^{-\frac{1}{2}\beta x_i K_{ij} x_j} e^{\frac{1}{2}\beta \mathbf{J}^{\mathsf{T}} \mathbf{K}^{-1} \mathbf{J}} = e^{\frac{1}{2}\beta \mathbf{J}^{\mathsf{T}} \mathbf{K}^{-1} \mathbf{J}} \int d^N x \, e^{-\frac{1}{2}\beta x_i K_{ij} x_j}$$
$$= \left(\det \frac{\beta \mathbf{K}}{2\pi} \right)^{-1/2} e^{\frac{1}{2}\beta \mathbf{J}^{\mathsf{T}} \mathbf{K}^{-1} \mathbf{J}}$$

6. Prove that $\langle x_i x_j \rangle = \langle x_i x_j \rangle_{\mathbf{J} = \mathbf{0}} + \langle x_i \rangle \langle x_j \rangle$. Hence, unsurprisingly, the covariance $\operatorname{Cov}(x_i, x_j)$ does not depend on \mathbf{J} .

$$\left\langle x_i \frac{\partial H}{\partial x_j} \right\rangle = \left\langle x_i (x_k K_{kj} - J_j) \right\rangle$$

$$= \left\langle x_i x_k K_{kj} - x_i J_j \right\rangle$$

$$= K_{kj} \left\langle x_i x_k - x_i J_i K_{kj}^{-1} \right\rangle$$

$$k_B T \delta_{ij} = K_{kj} \left\langle x_i x_k - x_i x_k^* \right\rangle$$

$$k_B T K_{kj}^{-1} \delta_{ij} = \left\langle x_i x_k \right\rangle - \left\langle x_i \right\rangle x_j^*$$

$$k_B T K_{kj}^{-1} = \left\langle x_i x_j \right\rangle - \left\langle x_i \right\rangle \left\langle x_j \right\rangle$$

$$\left\langle x_i x_j \right\rangle_{\mathbf{I} = \mathbf{0}} = \left\langle x_i x_j \right\rangle - \left\langle x_i \right\rangle \left\langle x_j \right\rangle$$

7. Verifying that $k_B T \frac{\partial}{\partial J_k} e^{-\beta H} = x_k e^{-\beta H}$, re-derive the equipartition theorem by continuing the following calculation:

$$\operatorname{Cov}(x_i, x_j) = \langle x_i x_j \rangle_{\mathbf{J} = \mathbf{0}} = \left. \frac{\operatorname{Tr}(x_i x_j e^{-\beta H})}{\operatorname{Tr}(e^{-\beta H})} \right|_{\mathbf{J} = \mathbf{0}} = \left. \frac{\operatorname{Tr}\left(\left(k_B T \frac{\partial}{\partial J_i}\right) \left(k_B T \frac{\partial}{\partial J_j}\right) e^{-\beta H}\right)}{\operatorname{Tr}(e^{-\beta H})} \right|_{\mathbf{J} = \mathbf{0}} = \cdots$$

Looking at the numerator, we can pull the derivatives out of the trace because the trace is an integral over x and J does not depend on x. Ignoring the factors of K_BT (for now), the numerator reads:

$$\partial_{J_i}\partial_{J_j}\operatorname{Tr} e^{-\beta H} = \partial_{J_i}\partial_{J_j}\left(\det\frac{\beta \mathbf{K}}{2\pi}\right)^{-1/2}e^{\frac{1}{2}\beta \mathbf{J}^{\mathsf{T}}\mathbf{K}^{-1}\mathbf{J}}$$

For brevity, I will define $A \equiv \left(\det \frac{\beta \mathbf{K}}{2\pi}\right)^{-1/2}$.

$$\begin{split} \partial_{J_{i}}\partial_{J_{j}}Ae^{\frac{1}{2}\beta J_{k}K_{kl}^{-1}J_{l}} &= \partial_{J_{i}}A\left(e^{\frac{1}{2}\beta J_{k}K_{kl}^{-1}J_{l}}\right)\frac{\beta}{2}\left(\delta_{jk}K_{kl}^{-1}J_{l} + J_{k}K_{kl}^{-1}\delta_{jl}\right) \\ &= \partial_{J_{i}}A\left(e^{\frac{1}{2}\beta J_{k}K_{kl}^{-1}J_{l}}\right)\frac{\beta}{2}\left(K_{jl}^{-1}J_{l} + J_{k}K_{kj}^{-1}\right) \\ &= \partial_{J_{i}}A\left(e^{\frac{1}{2}\beta J_{k}K_{kl}^{-1}J_{l}}\right)\beta(K_{jl}^{-1}J_{l}) \\ &= A\left(e^{\frac{1}{2}\beta J_{k}K_{kl}^{-1}J_{l}}\right)\partial_{J_{i}}\beta(K_{jl}^{-1}J_{l}) + A\partial_{J_{i}}\left(e^{\frac{1}{2}\beta J_{k}K_{kl}^{-1}J_{l}}\right)\beta(K_{jl}^{-1}J_{l}) \\ &= A\left(e^{\frac{1}{2}\beta J_{k}K_{kl}^{-1}J_{l}}\right)\left[\beta K_{jl}^{-1}\delta_{li} + K_{jl}^{-1}J_{l}\frac{\beta^{2}}{2}(\delta_{ik}K_{kl}^{-1}J_{l} + J_{k}K_{kl}^{-1}\delta_{il})\right] \\ &= A\left(e^{\frac{1}{2}\beta J_{k}K_{kl}^{-1}J_{l}}\right)\left[\beta K_{jl}^{-1}\delta_{li} + K_{jl}^{-1}J_{l}\frac{\beta^{2}}{2}(K_{il}^{-1}J_{l} + J_{k}K_{ki}^{-1})\right] \\ &= A\left(e^{\frac{1}{2}\beta J_{k}K_{kl}^{-1}J_{l}}\right)\left[\beta K_{jl}^{-1}\delta_{li} + K_{jl}^{-1}J_{l}\beta^{2}K_{il}^{-1}J_{l}\right] \\ &= \operatorname{Tr} e^{-\beta H}\left[\beta K_{jl}^{-1}\delta_{li} + K_{jl}^{-1}J_{l}\beta^{2}K_{il}^{-1}J_{l}\right] \end{split}$$

However, this whole thing is being evaluated at $\mathbf{J} = \mathbf{0}$. If we reinsert this expression into the equation, the traces in the numerator and denominator cancel. I will write the factors of $k_B T k_B T \equiv \frac{1}{\beta^2}$:

$$\langle x_i x_j \rangle = \frac{1}{\beta^2} \left[\beta K_{jl}^{-1} \delta_{li} + K_{jl}^{-1} J_i \beta^2 K_{il}^{-1} J_l \right]^0$$
$$= \frac{1}{\beta} K_{ij}^{-1}$$
$$= k_B T K_{ij}^{-1}$$

34. Statistical Physics of the Double Pendulum

Consider a planar double pendulum: two masses m_1 and m_2 , two pendulum lengths l_1 and l_2 , and two degrees of freedom φ_1 and φ_2 .

1. Write down the Lagrangian $L(\varphi_1, \varphi_2, \dot{\varphi}_1, \dot{\varphi}_2)$ of the system.

$$L = KE - PE$$

where

$$KE = \sum_{i} \frac{1}{2} m_i v_i^2 = \sum_{i} \frac{1}{2} m_i (\dot{x}_i^2 + \dot{y}_i^2)$$

and

$$PE = \sum_{i} mgy_i$$

Of course, this is in Cartesian coordinates, not the coordinates given by the problem. In the given coordinates,

$$x_1 = l_1 \sin(\varphi_1)$$

$$y_1 = -l \cos(\varphi_1)$$

$$x_2 = l_1 \sin(\varphi_1) + l_2 \sin(\varphi_2)$$

$$y_2 = -l_1 \cos(\varphi_1) - l_2 \cos(\varphi_2)$$

In these coordinates, we find that

$$KE = \frac{m_1 + m_2}{2} l_1^2 \dot{\varphi}_1^2 + \frac{m_2}{2} l_2^2 \dot{\varphi}_2^2 + m_2 l_1 l_2 \dot{\varphi}_1 \dot{\varphi}_2 \cos(\varphi_1 - \varphi_2)$$

and

$$PE = -(m_1 + m_2)l_1g\cos(\varphi_1) - m_2l_2g\cos(\varphi_2)$$

so

$$L = \frac{m_1 + m_2}{2} l_1^2 \dot{\varphi}_1^2 + \frac{m_2}{2} l_2^2 \dot{\varphi}_2^2 + m_2 l_1 l_2 \dot{\varphi}_1 \dot{\varphi}_2 \cos(\varphi_1 - \varphi_2 a) + (m_1 + m_2) l_1 g \cos(\varphi_1) + m_2 l_2 g \cos(\varphi_2)$$

2. Expand the Lagrangian to quadratic order.

To quadratic order, $\cos(\varphi) \to 1 - \frac{\varphi^2}{2}$ and $\cos(\varphi_1 - \varphi_2) \to 1 + \varphi_1 \varphi_2 - \frac{1}{2} (\varphi_1^2 - \varphi_2^2)$. When we put these substitutions into the Lagrangian and cancel anything else that is now of higher than quadratic order, we find that

$$KE = \frac{m_1 + m_2}{2} l_1^2 \dot{\varphi}_1^2 + \frac{m_2}{2} l_2^2 \dot{\varphi}_2^2 + m_2 l_1 l_2 \dot{\varphi}_1 \dot{\varphi}_2$$
$$= \dot{\varphi}^{\top} \mathbf{A} \dot{\varphi}$$

where

$$\mathbf{A} = \frac{1}{2} \begin{pmatrix} (m_1 + m_2)l_1^2 & m_2l_1l_2 \\ m_2l_1l_2 & m_2l_2^2 \end{pmatrix}$$

The potential energy becomes

$$\begin{aligned} \text{PE} &= -(m_1 + m_2)l_1 g \left(1 - \frac{1}{2}\varphi_1^2 \right) - m_2 l_2 g \left(1 - \frac{1}{2}\varphi_2^2 \right) \\ &= -g l_1 (m_1 + m_2) - g l_2 m_2 + \frac{1}{2} g \left(l_1 (m_1 + m_2)\varphi_1^2 + l_2 m_2 \varphi_2^2 \right) \\ &= \varphi^\top \mathbf{B} \varphi \end{aligned}$$

where

$$\mathbf{B} = \frac{g}{2} \begin{pmatrix} (m_1 + m_2)l_1 & 0\\ 0 & m_2 l_2 \end{pmatrix}$$

and we can eliminate the two constant terms out in front because they will not effect the equations of motion. All together, the Lagrangian now reads as

$$L = \dot{\varphi}^{\top} \mathbf{A} \dot{\varphi} - \varphi^{\top} \mathbf{B} \varphi$$

3. Calculate the canonically conjugate momenta p_1 and p_2 belonging to φ_1 and φ_2 .

The canonical conjugate momenta are defined as

$$\mathbf{p} = \frac{\partial L}{\partial \dot{\varphi}} = \mathbf{A}^{\top} \dot{\varphi} + \dot{\varphi}^{\top} \mathbf{A} = 2 \mathbf{A} \dot{\varphi}$$

so

$$\dot{\varphi} = \frac{1}{2} \mathbf{A}^{-1} \mathbf{p}$$

Note that one of the operations I did above was only possible because A is symmetric, so it is equal to its transpose.

4. Find the Hamiltonian $H(\varphi_1, \varphi_2, p_1, p_2)$ of the system.

The Hamiltonian is defined by

$$H = KE + PE$$

and substituting in the conjugate momenta from the previous problem, we find

$$H = \frac{1}{4} \mathbf{p}^{\mathsf{T}} \mathbf{A}^{-1} \mathbf{p} + \varphi^{\mathsf{T}} \mathbf{B} \varphi$$

5. Show that the kinetic energy has the form $\frac{1}{2}\mathbf{x}^{\mathsf{T}}\mathbf{K}\mathbf{x}$ that we discussed in the previous problem. What is \mathbf{x} and what is \mathbf{K} ?

The kinetic energy sure seems to have the same form with $\mathbf{x} = \mathbf{p}$ and $\mathbf{K} = \frac{1}{2}\mathbf{A}^{-1}$. We must determine if \mathbf{A}^{-1} is positive definite and symmetric. We can write it as

$$\frac{1}{2}\mathbf{A}^{-1} = \frac{1}{4\det(\mathbf{A})} \begin{pmatrix} m_2 l_2^2 & -m_2 l_1 l_2 \\ -m_2 l_1 l_2 & (m_1 + m_2) l_1^2 \end{pmatrix} \equiv \mathbf{K}$$

By observation, it is symmetric. Additionally, it must be positive definite since all of it's eigenvalues

$$\lambda = \frac{1}{2}\operatorname{Tr}(\mathbf{K}) \pm \sqrt{\frac{1}{4}\operatorname{Tr}(\mathbf{K})^2 - \det(\mathbf{K})}$$

are positive, as a result of $det(\mathbf{K}) = \frac{1}{m_1 m_2 l_1^2 l_2^2} > 0$.

6. Calculate \mathbf{K}^{-1} .

$$\mathbf{K}^{-1} = 2\mathbf{A} = \begin{pmatrix} (m_1 + m_2)l_1^2 & m_2l_1l_2 \\ m_2l_1l_2 & m_2l_2^2 \end{pmatrix}$$

7. Finally, let's turn up the heat: If this system is in contact with a heat bath at temperature T, calculate the correlation coefficient between p_1 and p_2 !

The correlation can be written as

$$\rho_{p_i p_j} = \frac{\operatorname{Cov}(p_i, p_j)}{\sigma_{p_i} \sigma_{p_j}} = \frac{\operatorname{Cov}(p_i, p_j)}{\sqrt{\operatorname{Cov}(p_i, p_i)\operatorname{Cov}(p_j, p_j)}}$$
$$= \frac{\langle p_i p_j \rangle}{\sqrt{\langle p_i^2 \rangle \langle p_j^2 \rangle}}$$
$$= \frac{\mathbf{K}_{ij}^{-1}}{\sqrt{\mathbf{K}_{ii}^{-1} \mathbf{K}_{jj}^{-1}}}$$

$$\rho_{p_1 p_2} = \frac{m_2 l_1 l_2}{\sqrt{((m_1 + m_2)l_1^2)(m_2 l_2^2)}}$$
$$= \frac{m_2}{\sqrt{m_1 + m_2^2}}$$

In the limit of $m_2 >> m_1$, we see that $\rho_{p_1p_2} \to 1$, indicating that as the middle mass becomes less consequential, the momenta become directly correlated. When $m_2 << m_1$, $\rho_{p_ip_j} \to 0$, indicating that in this limit, the momenta will have no correlation at all.