

Towards Faithful Dialogs via Focus Learning

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Abstract

Maintaining faithfulness between responses and knowledge is an important research topic for building reliable knowledge-grounded dialogue systems. Existing models heavily rely on the elaborate data engineering and increasing the model’s parameters ignoring to track the tokens that significantly influence losses, which is decisive for the optimization direction of the model in each iteration. To address this issue, we propose Focus Learning (FocusL), a novel learning approach that adjusts the contribution of each token to the optimization direction by directly scaling the corresponding objective loss. Specifically, we first introduce a positioning method by utilizing relevance distributions between knowledge and each response token to locate knowledge-aware tokens. Then, we further design a relevance-to-weight transformation to provide dynamic token-level weights for adjusting the cross-entropy loss. Finally, we use the weighted loss to encourage the model to pay special attention to the knowledge utilization. Experimental results demonstrate that our method achieves the new state-of-the-art results and generates more reliable responses while maintaining training stability.

1 Introduction

Although open-domain conversation systems can generate smooth and fluent responses with the help of large-scale pre-trained models (Raffel et al., 2020; Lewis et al., 2020), vacuous responses (Li et al., 2016) continue to be prevalent. To enrich the content of responses, an effective way is to introduce external knowledge (Dinan et al., 2019; Zhou et al., 2018). The knowledge-grounded model, however, frequently generates responses that appear knowledgeable but are not derived from the given knowledge. This means that the correctness of the knowledge used in responses cannot be guaranteed. As shown in Figure 1, the "Oklahoma"

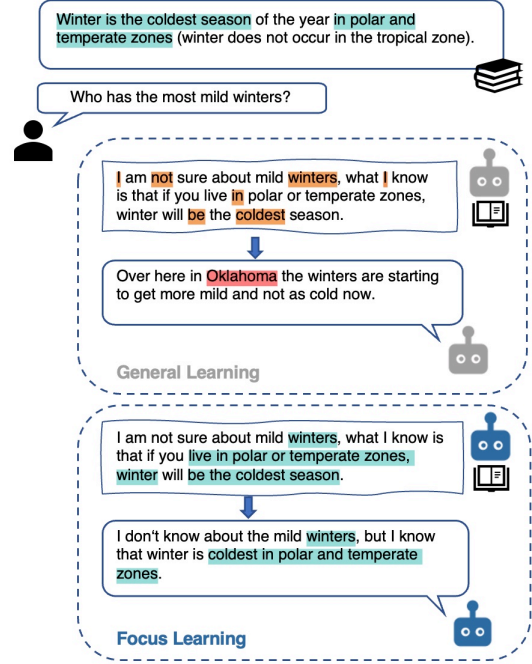


Figure 1: The different learning focus (i.e., the tokens that corresponding losses significantly influence the total objective loss) between general learning and focus learning. Original learning focus without guidance in general learning are fragmented with no rules to follow. Our methods make the model focus on the knowledge-aware tokens (i.e., tokens that have high semantic relevance to knowledge) to alleviate the hallucinations.

in the response is not present in the given knowledge and relevant knowledge is unverifiable. This phenomenon is known as the *hallucination* (Dziri et al., 2022a) problem. Due to the inability to verify knowledge, hallucinations can mislead users and reduce the model’s credibility.

Numerous methods have been developed to tackle the hallucination problem by knowledge graph (Kang et al., 2022; Dziri et al., 2021), contrastive learning (Sun et al., 2022) or control code (Rashkin et al., 2021). These models enhance the model’s attention to knowledge by increasing parameters and elaborate data engineering. An im-

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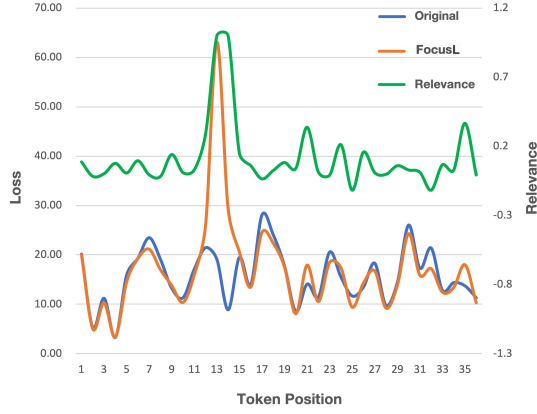


Figure 2: Distributions of the loss and the relevance between knowledge and response tokens. We select a response as an example and visualize the loss, semantic relevance to knowledge, and the adjusted loss (FocusL) at the beginning of training. In the original loss, the model is less sensitive to optimization of knowledge-aware tokens. In contrast, the loss of knowledge-aware tokens in FocusL are larger than the others, and the knowledge-irrelevant tokens’ loss are scaled down.

portant assumption for them is that the model has the ability to give more attention to knowledge during training, yet this is not always held true. We consider this to be a common problem with general training methods which neglect to track the tokens that significantly influence the objective loss (i.e., learning focus). Different from the traditional concept of attention mechanisms which primarily focus on identifying important information in the input, the focus emphasizes important information in the target response. As the example shown in Figure 1, in general learning scenario, the learning focus is often out of control, and the model tends to focus on simple words (e.g., *be*, *the*), which lead to neglect of the tokens that have high relevance to knowledge referred as knowledge-aware tokens (e.g., *polar or temperate zones*). Intuitively, knowledge-aware tokens are even more critical for improving consistency, and focusing the model’s attention on them can make the optimization goal fitter for the task. Therefore, it is necessary to revise the original learning focus. However, there are two main challenges: (1) How to locate the desired learning focus? Due to the fact that the learning focus is on different words in each sentence and the token-level manual annotation of responses is extremely time-consuming and labor-intensive, the existing datasets do not have a fine-grained annotation of key semantic words in the responses. (2) Given the desired learning focus, how to correct

the original learning focus? Existing training methods with cross-entropy loss lack direct guidance on learning focus.

To address above issues, we propose a novel learning approach, **Focus Learning** (FocusL). Instead of impacting knowledge utilization implicitly, we directly scale the corresponding objective loss to adjust the contribution of each token to the optimization direction. Specifically, for the first challenge, we first define the desired learning focus in knowledge-grounded dialogue task as knowledge-aware tokens. Then we devise a positioning method to get the relevance score distribution between knowledge and each response token. For the second challenge, we explore a relevance-to-weight transformation method to provide dynamic token-level weights for the cross-entropy loss. Finally, we use the corrected learning focus to guide the model training. As we can see in Figure 2, the losses of knowledge-aware tokens do not gain a high proportion of the original loss distribution. In contrast, our approach can expand the gap between knowledge-aware tokens and the others, which increases the impact of the change of knowledge-aware tokens’ loss on the final loss, thus affecting the optimization direction and guiding the model to pay more attention to knowledge utilization.

Our main contributions are summarized as below:

- We rethink existing models and learning methods, and propose a novel learning approach to address the hallucination problem by adjusting the learning focus.
- We propose a positioning method and a relevance-to-weight transformation method to adaptively scale the loss of each token in the response.
- Experimental results demonstrate that our approach significantly outperforms the current state-of-the-art baselines, and effectively reduces hallucinations while maintaining high quality of responses.

2 Related Work

Knowledge-grounded Dialogue Generation

Knowledge-grounded dialogue systems aim to alleviate vacuous responses by injecting external knowledge into the dialogue model. Recently,

various forms of external knowledge have been used in dialogue systems, such as tables (Moghe et al., 2018), graphs (Bollacker et al., 2008; Moon et al., 2019; Zhou et al., 2020; Peng et al., 2022), documents (Ghazvininejad et al., 2017; Zhou et al., 2018; Zhao et al., 2019). In spite of research on the forms of knowledge, most existing systems focus on knowledge selection (Lian et al., 2019; Kim et al., 2020; Zheng et al., 2020; Meng et al., 2020; Li et al., 2022) and response generation with given knowledge (Xu et al., 2020; Ma et al., 2020; Cai et al., 2020; Zhao et al., 2020). In this work, we mainly focus on avoiding models using unverifiable knowledge in response generation with given knowledge.

Hallucinations in Text Generation Generating responses that are unfaithful to the provided knowledge, known as the hallucination, is a tricky problem in knowledge-grounded dialogue systems. Recently, the hallucination problem has attracted increasing attention because the generated text appears smooth and fluent but usually contains false knowledge, which significantly threatens the model’s credibility. Some studies reduce hallucinations by introducing knowledge graph (Kang et al., 2022; Dziri et al., 2021), controllable generation (Rashkin et al., 2021), and contrastive learning (Sun et al., 2022). In a recent study, Dziri et al. (2022b) analyze the source of hallucination in detail and find that the most knowledge-grounded conversation datasets (Dinan et al., 2019; Zhou et al., 2018) inherently contain hallucinations, and models trained on such dataset further amplify hallucinations, which demonstrate that the pattern of hallucination responses is more likely to be learned by the model. To address this problem, Dziri et al. (2022a) further propose FaithDial, a new dataset that removes hallucinations in the Wizard of Wikipedia (Dinan et al., 2019). Different from these studies about models and datasets, we find that the training method with unexpected learning focus also plays a vital role in the hallucination problem and then present a method to adjust the original focus.

3 Methods

3.1 Our Approach

The overview of FocusL is presented in Figure 3. Given the conversation context $C = (c_1, \dots, c_n)$ consisting of a sequence of n dialogue turns and

the corresponding knowledge $K = (k_1, \dots, k_m)$ for the current turn, where m is the number of tokens in K , the goal of our task is to generate responses $Y = (y_1, \dots, y_T)$ where T is the number of tokens in Y . We first form the input I with joint knowledge K and conversation context C as follows:

$$I = [K; C] \quad (1)$$

where the utterances of C are delimited by the speaker identifier (either `<user>` or `<bot>`). Then we use T5 (Raffel et al., 2020) as the base model, which is a pre-trained encoder-decoder model that uses the transformer architecture (Vaswani et al., 2017). Taking I as input, the base model outputs a logit distribution $h = (h_1, \dots, h_T)$, where h_t is the corresponding logit distribution of the t -th token in Y . The positioning module locate knowledge-aware tokens in the response Y and calculate the corresponding adjust weight. The focus shifting module adjusts the original logit distribution h to obtain the final logit distribution h_w . Finally, we train the model to produce the next conversation utterance $y_1 \dots y_T$ by minimizing the cross-entropy loss.

In the following, we introduce three steps of the FocusL training process: (1) locate knowledge-aware tokens which used as the new learning focus (§3.2); (2) calculate adjust weights based on the relevance of knowledge with each token in the response (§3.3); (3) switch original learning focus to the knowledge-aware tokens (§3.4).

3.2 Learning Focus Positioning

To adjust the learning focus of the model, we first define knowledge-aware tokens as the new learning focus which is more in line with the knowledge-grounded dialogue task. And then we use the distance between the response token and knowledge in semantic space to measure its relevance:

$$relevance(y_t^r, \mathcal{K}) = \frac{y_t^r \cdot \mathcal{K}}{\|y_t^r\| \cdot \|\mathcal{K}\|} \quad (2)$$

To get the semantic representation of the token y_t and the knowledge K , we use the embedding layer $Emb(\cdot)$ of the base model to obtain a dense representation:

$$y_t^r = Emb(y_t) \quad (3)$$

$$\mathcal{K} = \frac{1}{m} \sum_{i=1}^m Emb(k_i) \quad (4)$$

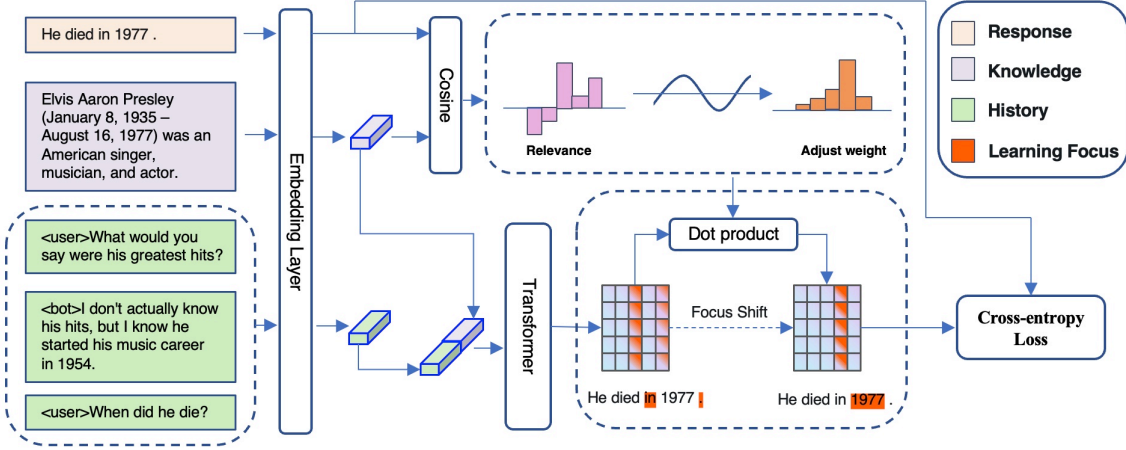


Figure 3: Training process of FocusL. We first calculate original model output based on the given knowledge and the context. Then we calculate the relevance score between each token in the response and knowledge, and further convert it to the adjust weight distribution. Finally, we use the adjust weight to scale the original loss.

Note that we do not use the model’s encoder to obtain the representation vector of knowledge and responses, we think that the output of the embedding layer is sufficient to provide the desired semantic information, and also has less impact on the training speed. Instead of outputting knowledge-aware tokens directly, the positioning method uses relevance matrix to provide more information for §3.3.

3.3 Adjust Weight

To adaptively assign a weight for each token to adjust the corresponding logit value, we can simply define adjust weight scalar w_t^a as follows:

$$w_t^a = \begin{cases} 2, & \text{if } \text{relevance}(y_t^r, \mathcal{K}) \geq \theta \\ 1, & \text{otherwise} \end{cases} \quad (5)$$

where θ is a threshold value. We rigidly define knowledge-aware tokens by setting a specific θ . The token with relevance greater than the threshold is regarded as knowledge-aware token and obtain a high adjust weight to increase corresponding loss. We keep the original logit value unchanged for tokens with relevance scores less than the threshold.

However, the boundaries of knowledge-aware tokens are difficult to define, and the threshold value easily influences the learning effect of the model. To solve this problem, we further propose two different methods for converting relevance scores into adjust weights.

Liner Weight To make full use of the information in the relevance matrix, we propose to assign a different adjust weight to each token. We obtain a

non-negative distribution by the following formula:

$$w_t^a = 1 + \text{relevance}(y_t^r, \mathcal{K}) \quad (6)$$

This method adaptively scales up the loss of knowledge-aware tokens while scaling down the loss of rest tokens. Although this can adjust the weights of all tokens, a linear weight distribution is not a good simulation due to the complexity of focus changes in real-world human learning. Meanwhile, the weights between knowledge-aware and irrelevant tokens are not significantly different, which does not have a large enough impact on the loss.

Non-linear Weight To ensure the stability of training, we aim to increase the loss of knowledge-aware tokens as much as possible while keeping that the adjusted final loss is not too different from the original loss. Therefore the distribution of weights should be smoother at low relevance interval and steeper at high relevance interval. We map the original relevance distribution to a logarithmic distribution with the following formula:

$$w_t^a = -\ln(1 - \text{relevance}(y_t^r, \mathcal{K}) + \lambda) + 1 \quad (7)$$

where $\lambda \in (0, e - 2)$ is a small constant that we call it smoothing factor. A large smoothing factor represents a smoother distribution of the obtained weights.

3.4 Focused Cross-Entropy Loss

After obtaining the adjust weight w_t^a , we scale the original logit and then use the new logit to calculate the probability of each token. At the time step t ,

given original model outputs h_t , the probability of the token y_t is calculated as follows:

$$p_w(y_t|y_{<t}, \mathcal{I}) = \text{softmax}(w_t^a \cdot h_t) \quad (8)$$

We define the final loss for optimization as the **Focused Cross-Entropy (FCE)** loss:

$$\mathcal{L}_{FCE} = -\frac{1}{T} \sum_{t=1}^T \log p_w(y_t|y_{<t}, \mathcal{I}) \quad (9)$$

where T is the length of the response. FCE changes the original loss distribution, which leads the model to shift original learning focus to desired tokens. To reduce this loss function, the gradient descent approach is used to update all parameters.

4 Experiments

To evaluate the effectiveness of our method, we conduct experiments following the settings in (Dziri et al., 2022a). We use pre-trained T5 (Raffel et al., 2020)¹ from the HuggingFace library (Wolf et al., 2020) as our base language model and train 10 epochs via accumulating gradients for 4 steps. We utilize a learning rate of 6.25E-5, and AdamW (Loshchilov and Hutter, 2019) for optimization. We set the warmup ratio to 4% followed by a linear decay. The max length of the input and output is 256 and 128 respectively. We set the batch size to 8. For adjust weights, we set the smoothing factor λ to 0.01 and the threshold value θ to 0.5. As for decoding, we use nucleus sampling with $p = 0.6$. We train our model on a single NVIDIA Tesla V100 GPU with 32GB memory. Each epoch takes about 130 minutes for WoW and 35 minutes for FaithDial. Our code is available at <https://github.com/Mute-ZEN/AgileLightning>.

4.1 Datasets

We conduct experiments on two knowledge-grounded dialogue datasets: (1) Wizard of Wikipedia (**WoW**) published in (Dinan et al., 2019); (2) FaithDial published in (Dziri et al., 2022a)

WoW is a widely used dataset for knowledge-grounded dialogue based on Wikipedia. WoW is collected by two crowdsourcing workers, one of which is a knowledgeable wizard and the other is an inquisitive apprentice. The wizard can access the knowledge of Wikipedia, while the apprentice

cannot. The dataset includes 22,311 conversations with 201,999 turns, and the test set has two subsets: Test Seen and Test Unseen. Test Seen comprises 533 topics that overlap with the training set and contain new dialogues. Test Unseen contains 58 topics that have never been encountered in training or validation.

FaithDial Since the current knowledge conversation dataset (Dinan et al., 2019) contains a large number of hallucination responses (Dziri et al., 2022b), Dziri et al. (2022a) proposes FaithDial, which corrects the responses in WoW to be more faithful to knowledge. The percentage of corrections to the original wizard’s responses exceeded 80%. The dataset contains a total of 5,649 conversations with 50,761 turns.

4.2 Baselines

We compare our model with the following baselines:

GPT2 (Radford et al., 2019) is an autoregressive model based on the transformer decoder architecture (Vaswani et al., 2017).

DIALOGPT (Zhang et al., 2020) is pre-trained on a large scale dialogue datasets based on GPT2 to be more applicable to conversation generation.

DOHA (Prabhumoye et al., 2021) equips the BART (Lewis et al., 2020) model with a knowledge-aware attention module, enabling specific attention to the information in the knowledge.

CTRL (Rashkin et al., 2021) utilizes control codes to guide the model to generate responses that are more faithful to knowledge. Following (Dziri et al., 2022a), we use T5 as the base model of CTRL.

4.3 Evaluation Metrics

We aim to verify the effectiveness of our method in two aspects: **fluency** and **faithfulness**. We use both automatic metrics and human evaluations to compare all models.

Automatic Metrics We use **BLEU** (Papineni et al., 2002), **ROUGE** (Lin, 2004) to evaluate the fluency of the generated responses, which reflect the similarity of the generated responses to the reference responses and both are widely used in text generation evaluation (Dziri et al., 2022a; Zhou et al., 2022). To evaluate the faithfulness

¹<https://huggingface.co/t5-base>

of the generated responses to knowledge, we use **BERTScore** (Zhang et al., 2019), **F1** and **Q²** (Honovich et al., 2021). BERTScore can measure the semantic similarity of responses to knowledge with sentence embeddings from BERT (Devlin et al., 2019), while F1 measures the lexical overlap between responses and knowledge, and Q² uses an automated question-and-answer technique to evaluate the consistency of responses and knowledge.

Human Evaluation To mitigate the unreliability of automatic evaluation, we use more diverse evaluation methods to show the model performance as objectively as possible, and further conduct a human evaluation to verify the effectiveness of our method. We randomly select 100 dialogues from the test set of FaithDial and ask three human evaluators to evaluate. We ask the human evaluators to rate the fluency (**Fluency**), informativeness (**Inform.**) and faithfulness (**Faithful.**) of the generated responses on a 5-point scale, where 1, 3, and 5 indicate unacceptable, moderate, and perfect performance, respectively. Among the metrics, **Fluency** evaluate the response generation quality, **Inform.** evaluate the whether the response is safe or vacuous, and **Faithful.** focus on whether the knowledge used in response is come from the given knowledge, which is stricter than **Inform.**. We then calculate the average score of the three human evaluators as the final score.

5 Results

The results on FaithDial and WoW are shown in Table 1, 2 and 3. As can be seen, FocusL outperforms all baselines in both faithfulness and fluency.

5.1 Automatic Evaluation

FCE vs CE To test the effectiveness of FocusL equipped with FCE, we compare our method with baselines on FaithDial dataset, and report the results in Table 1. We use the test results of baselines from (Dziri et al., 2022a) and keep the same metric calculate method to evaluate FocusL. We can see that our method outperforms the state-of-the-art baselines on all automatic metrics. In particular, FocusL achieves a significant improvement in BERTScore, F1, BLEU, ROUGE, and a large improvement in Q² F1 and Q² NLI. We also find that the models based on transformer decoder architecture (GPT2, DIALOGPT) perform worse than the encoder-decoder architecture (T5, CTRL, DOHA). Noticably, despite the fact that CTRL performs

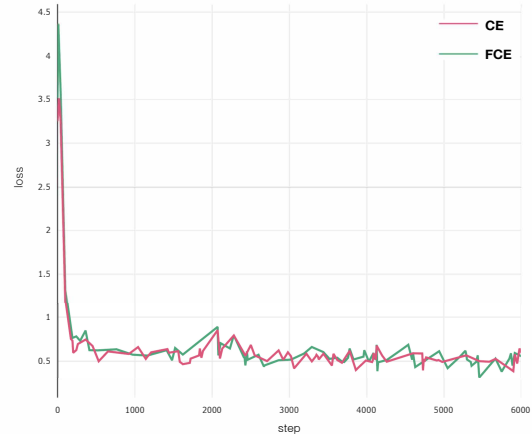


Figure 4: The loss during training. FCE has almost no impact on training stability.

well in terms of faithfulness, it doesn’t improve fluency much. In contrast, FocusL achieves a significant improvement in both faithfulness and fluency. This indicates that FocusL reasonably utilizes knowledge during conversation.

Moreover, to demonstrate the learning focus of our approach, we analyze the trend of loss during training as shown in Figure 4. FocusL achieves higher performance with nearly the same trend as the original CE loss variation and also shows that our FCE loss does not destabilize training. Compared to the original CE loss, FCE has a higher loss at the beginning of training, which the more significant adjustment of our approach to the learning focus at the beginning of training can explain.

Robustness to Out-of-Domain Knowledge To evaluate the ability to apply knowledge of out-of-domain, We further test our method on WoW, and report the results in Table 2. We select the baselines which perform well on FaithDial and use T5 as the backbone for comparison. We train the model on the WoW training set and then test it on the two subsets separately. Results show that FocusL outperforms all baselines on faithfulness metrics, significantly improves model’s reliability with slightly impact on fluency. It is worth noting that our model improves more significantly in the out-of-domain setting, which indicates that our method is more robust to out-of-domain knowledge.

Robustness to Data Size In order to verify the learning efficiency of our approach with adjusted learning focus, we also conduct experiments in a low-resource setting. We randomly select 1/2, 1/4,

Models	Faithfulness				Fluency	
	BERTScore	F1	Q ² F1	Q ² NLI	BLEU	ROUGE
GPT2	0.36	50.41	58.4	69.8	9.50	33.43
DIALOGPT	0.36	52.25	56.5	66.2	9.63	33.13
DOHA	0.39	58.32	69.1	78.3	9.89	31.78
T5	0.41	59.22	70.4	79.5	10.31	33.89
CTRL	0.46	62.21	72.4	81.5	10.41	33.97
FocusL	0.50**	65.07*	73.25	82.58	11.58**	35.41**

Table 1: Automatic results on FaithDial to evaluate the Faithfulness and Fluency of the generated responses. The best performance are **bolded**. One "*" denotes statistical significant with $p < 0.05$, and "***" denotes significant improvement with $p < 0.01$.

Test Set Split	Models	Faithfulness				Fluency	
		BERTScore	F1	Q ² F1	Q ² NLI	BLEU	ROUGE
seen topic	T5	0.48	61.88	69.08	75.02	12.44	32.79
	CTRL	0.49	62.99	70.56	76.35	12.61	33.20
	FocusL	0.52	65.25	71.41	77.32	12.63	32.95
unseen topic	T5	0.47	60.68	67.13	73.09	12.63	32.81
	CTRL	0.46	59.81	66.70	72.59	12.30	32.73
	FocusL	0.51	63.99	69.09	74.97	12.48	32.84

Table 2: Automatic results on WoW to evaluate the Faithfulness and Fluency of the generated responses. The best performance are **bolded**.

1/8, 1/16, and 1/32 of the training data and report the results in Figure 5. We can see that our method has higher faithfulness even with 1/32 training data. Results also show that FocusL has more significant improvement compared with baselines in the low-resource setting, which demonstrates that our approach can learn how to use knowledge more efficiently. The faithfulness of both T5 and CTRL does not change significantly, however their fluency decrease severely, which might be explained by that models tend to copy knowledge and ignore the fluency of the response. In comparison, FocusL can achieve a better trade-off between fluency and faithfulness with limited data.

Meanwhile the performance of the model should be weakened as the amount of data decreases, however the experimental results do not seem to be what we expected. We can see that all models in the Figure 5 have almost the highest BERTScore at 1/16 data, and our model FocusL even reaches the highest value on the BLEU metric as well. After rigorously repeating the experiment multiple times, the results obtained remain the same. We argue that this may be related to the data distribution

Models	Faithful.	Fluency	Inform.
T5	2.80	3.62	3.23
CTRL	2.98	3.53	3.14
FocusL	3.11*	3.59	3.44*

Table 3: Human evaluation on WoW. **Bolded** numbers indicate the best performance. Numbers marked with * indicate that the improvement is statistically significant (p -value < 0.05).

characteristics of the dataset and deserves further study.

5.2 Human Evaluation

In addition to automatic evaluation, we present human evaluation results in Table 3. We choose T5 and CTRL as baselines for comparison. Results show that FocusL receives higher scores on both **Faithful.** and **Inform.**, and fluency is slightly lower than T5. Overall, our approach can make the model more reliable with almost as much fluency as baselines.

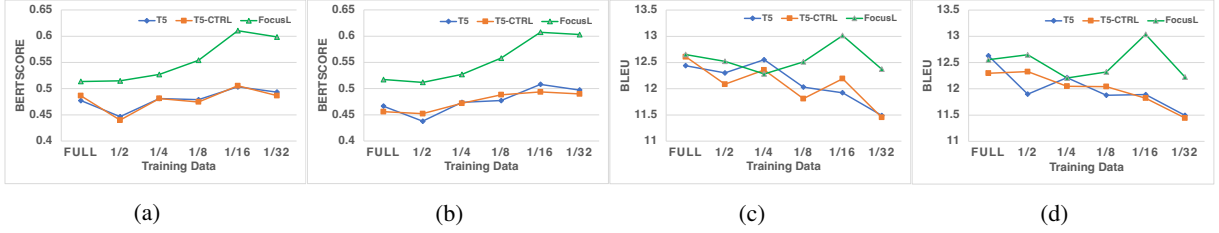


Figure 5: Automatic results on WoW with limited training data. (a) and (b) show the results of BERTScore on seen and unseen test set, respectively. (c) and (d) show the results of BLEU on seen and unseen test set, respectively.

Model	BERTScore	F1	BLEU
FocusL	0.51	66.11	11.65
-TW	0.38	52.63	9.10
-LW	0.42	57.86	11.62
w/o FCE	0.40	57.17	11.89

Table 4: The ablation study of various adjust weight distribution. **Bolded** numbers indicate the best performance.

Model	BERTScore	F1	BLEU
FocusL	0.51	66.11	11.65
$\lambda = 0.05$	0.45	61.51	11.78
$\lambda = 0.1$	0.50	64.55	11.53
$\lambda = 0.2$	0.44	60.88	12.08
$\lambda = 0.4$	0.43	60.19	12.13
$\lambda = 0.7$	0.43	60.81	12.53

Table 5: The ablation study of various λ for non-linear adjust weight distribution. **Bolded** numbers indicate the best performance.

5.3 Ablation Study

Finally, we attempt to study the performances of variation of FCE described in §3.3. Results for different adjust weight distribution are shown in Table 4, and Table 5 is for different λ in non-linear weight. In Table 4, we compared the weight distribution with the threshold (TW), linear weight (LW), non-linear weight (FocusL), and without FCE (w/o FCE). Among them, TW performs the worst, which may be influenced by the threshold. In contrast, the effect of LW is more stable than TW and does not suffer from hyperparameter effects. Even though BLEU is slightly lower than CE, FocusL has significantly improved BERTScore and F1.

To further study the effect of λ in non-linear weight, we set λ to 0.05, 0.1, 0.2, 0.4, 0.7, and present the results in Table 5. Note that FocusL

Given Knowledge:

The global presentation of cheerleading was led by the 1997 broadcast of ESPN’s International cheerleading competition, and the worldwide release of the 2000 film "Bring It On".

Context:

<user> She has done a lot of dance and tumbling already. She will try it out and see what works best for her.
 <bot> Got it, are you from the United States? Cheerleading is an activity that originated there, it is also predominantly in America.
 <user> Yes we are, she wants to be a cheerleader since she was a little kid, I am sure she will be fine. I could see her going on to do it in college as well.

Gold Response: Nice, have you watched the film Bring It on ? it is from 2000 .

T5: I see, did you know that the 1998 televised ESPN’s International cheerleading competition led to the global presentation of cheerleading? That’s interesting.

CTRL: Yes, the world presented cheerleading in 1997.

FocusL: I see, did you know that the movie Bring It On was released in 2000 ?

Table 6: An example case from FaithDial.

uses $\lambda = 0.01$ in the experiments. As the λ increases, faithfulness metrics of the model gradually decrease, and fluency metrics gradually increase. This indicates that smaller λ with steeper weight distribution makes the model more sensitive to knowledge-aware tokens’ losses, which increases the accuracy of knowledge utilization. In contrast, larger λ with smoother weight distribution makes the model focus on the quality of the response.

5.4 Case Study

To better illustrate the advantage of our approach, we present an example case in Table 6. We randomly select one dialogue from the test set of FaithDial, and compare the responses generated by T5, CTRL, and FocusL. It can be observed that the response generated by T5 uses a wrong year "1998" while the given knowledge is about "1997", and its causality also cannot be inferred from the

given knowledge. CTRL misunderstands the given knowledge and ignores the impact of "Bring It On" on the global presentation of cheerleading. In contrast, FocusL can generate a response more related to the given knowledge and closest to the gold response, which contains all knowledge entities in the gold response.

6 Conclusion

In this paper, we propose a novel learning approach with more direct guidance on the training process to improve the faithfulness of knowledge-grounded dialogue systems, referred to as FocusL. By leveraging semantic relevance between the response and knowledge, FocusL corrects the model's learning focus, leading to more consistent and fluent response generation. We empirically show that our approach has the best performance with a stable training process and is robust to data size and out-of-domain knowledge. FocusL is simple yet effective and can achieve state-of-the-art results in two knowledge-grounded datasets.

Limitations

As we have shown, there is much room to improve the learning approach, which incur lower costs than increasing model's parameters or elaborate data engineering. This paper is an exercise in guiding learning focus, and we argue that FocusL is not perfect for the positioning method and the relevance-to-weight transformation method. For example, our positioning method may contain noise, and some words that are not important in given knowledge may be used as our learning focus. We will continue to explore better methods to guide the model's learning focus. Meanwhile, our method only experiments on the basic cross-entropy loss, and still needs to be explored for other learning approaches such as contrastive learning.

Ethics Statement

FocusL aims to convey correct knowledge to users rather than misleading hallucinations. We hope to see a reliable and trustworthy dialogue system impact from better guiding the model's learning focus. However, even if the dialogue system does not produce hallucinations, there is still a risk of potential misuse. For example, the dialogue systems may be used to spread misinformation or to mislead users. If possible, we would prefer that the

model itself has the ability to identify undesirable knowledge and block it.

Acknowledgements

This work is supported by the National Natural Science Foundation of China (Grant No.U21B2009). This research is also supported by the Strategic Priority Research Program of Chinese Academy of Science, Grant No.XDC02030400.

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