# Summary of Short-term Research Objectives

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# 1 Model Specification

Let L be a K-dimensional Bernoulli random variable denoting the true state. Consider the general log linear model:

$$f(l; \Theta) = \exp\{\Theta_1^T l + \Theta_2^T u_2 + \dots + \Theta_K^T u_K - A^*(\Theta)\}\$$

where  $U_k$  is a  $\binom{K}{k} \times 1$  vector of k-way cross-products, k = 1, ..., K, and  $\Theta = (\Theta_1, ..., \Theta_K)$  contains the the natural parameters, which is a  $(2^K - 1) \times 1$  vector.

Model restrictions, let  $\tilde{l} = (l, u_2, \dots, u_K)^T$ , and  $S = \sum_{j=1}^K L_j = s$  has some fixed pmf

$$\pi(s) := P(S = s) = \frac{1}{A(\Theta)} \sum_{\tilde{l}: S = s} \exp\{\Theta^T \tilde{l}\}, \ s = 0, 1, \dots, K$$
 (1)

$$A(\Theta) = \sum_{\tilde{l}: l \in \{0,1\}^K} \exp\{\Theta^T \tilde{l}\}$$
 (2)

## 2 Posterior Distribution

$$\begin{split} P(\mu, \theta^{(2)} | L) \propto & P(L, \mu, \theta^{(2)}) \\ \propto & P(L, \mu, \theta^{(1)}, \theta^{(2)}, \pi) \\ \propto & P(L | \mu, \theta^{(1)}, \theta^{(2)}, \pi) P(\mu, \theta^{(1)}, \theta^{(2)}, \pi) \\ \propto & P(L | \theta^{(1)}, \theta^{(2)}) P(\theta^{(1)}, \theta^{(2)} | \mu, \pi) P(\mu) P(\pi) \\ \propto & QE(L; \theta^{(1)}, \theta^{(2)}) UFR(\theta^{(1)}, \theta^{(2)} | \mu, \pi) N(logit(\mu), \Sigma) tPois(\pi) \end{split}$$

where QE is the second-order log linear model.

UFR is a Multivariate distribution of  $[\theta^{(1)}, \theta^{(2)}|\mu, \pi]$  subject to non-linear constrains:  $M(\theta^{(1)}, \theta^{(2)}) = \mu$  and  $\Pi(\theta^{(1)}, \theta^{(2)}) = \pi$ , which can be sampled by a two-step procedure. tPois is a truncated conjugate Poisson distribution defined as:

$$\pi \sim \text{Dirichilet(hist(\vec{s}))}$$

$$s \sim \frac{\lambda^s}{s!} e^{-\lambda} / [1 - \sum_{s>K} \frac{\lambda^s}{s!} e^{-\lambda}]$$

# 2.1 On sampling $[\Theta|\mu,\pi]$

#### 2.1.1 General model

For General model,  $\tilde{L}$  is a square matrix with dimension  $J_1 = 2^K - 1$ . Recall that

$$A(\Theta) = \frac{1}{\pi(0)}$$

$$\pi(s) = \frac{1}{A(\Theta)} \sum_{\tilde{l}:S=s} \exp\{\Theta^T \tilde{l}\}, s = 1, \dots, K$$

$$\mu_k = \frac{1}{A(\Theta)} \sum_{\tilde{l}:l_k=1} \exp\{\Theta^T \tilde{l}\}, k = 1, \dots, K$$

$$(3)$$

Define intermediate parameter  $\phi_j = \exp(\theta^T \tilde{l}_j) > 0$ ,  $\Theta = (\theta^{(1)}, \theta^{(2)}, \dots, \theta^{(K)}), j = 1, \dots, J_1$  and two  $K \times J_1$  sub-design matrices B, C, where  $B[k, j] = 1(\tilde{l}_j^T 1 = k), C[k, j] = 1(\tilde{L}[j, k] = 1)$ . Thus (6) and (7) become

$$\vec{\phi} > 0$$

$$B\vec{\phi} = \vec{\pi}/\pi(0)$$

$$C\vec{\phi} = \vec{\mu}/\pi(0)$$

Note that B and C are not independent constraints and should be compatible so that  $\binom{B}{C}$  has rank 2K-1.

Based on [1][2], we can sample  $\vec{\phi}$  from Uniform distribution subject to the above linear constraints efficiently and robustly. Then  $\Theta$  are the solutions to the linear system ( $J_1$  equations with  $J_1$  unknowns):

$$\tilde{L}\Theta = \log \vec{\phi}$$

Since  $\vec{\phi}$  fully specifies all cell probabilities, the posterior distribution becomes

$$P(\mu, \vec{\phi}|L) \propto \text{LL}(L; \vec{\phi}) \text{UFR}(\vec{\phi}|\mu, \pi) \text{N}(\text{logit}(\mu), \Sigma) \text{tPois}(\pi)$$

## 2.1.2 QE model

For QE model,  $\tilde{L}$  is a  $J_1 \times J_2$ , where  $J_1 = 2^K - 1$ ,  $J_2 = \frac{1}{2}K(K+1)$ . Let  $\theta = (\theta^{(1)}, \theta^{(2)})$ , we have a over-determined linear system after sampling  $\vec{\phi}$ : ( $J_1$  equations with  $J_2$  unknowns)

$$\tilde{L}\theta = \log \vec{\phi}$$

In this case, we can first find  $\Theta$  as in last section and then solve the constrained Least Square problem to get the QE parameter estimates  $\theta$ :

minimize 
$$||\theta - \Theta||_2^2$$
  
subject to  $Be^{\tilde{L}\theta} = \vec{\pi}/\pi(0)$   
and  $Ce^{\tilde{L}\theta} = \vec{\mu}/\pi(0)$ 

### 2.2 Example for K = 3

For K=3 with the General Log-linear model,  $\Theta=(\theta_1,\theta_2,\theta_3,\theta_{12},\theta_{13},\theta_{23},\theta_{123})^T$   $\Phi=(\phi_1=\exp{(\theta_1)},\ldots,\phi_4=\exp{(\theta_1+\theta_2+\theta_{12})},\ldots,\phi_7=\exp{(\theta_1+\theta_2+\theta_3+\theta_{12}+\theta_{13}+\theta_{23}+\theta_{123})})^T$ When we made prior assumption on  $\vec{\mu}=(\mu_1,\mu_2,\mu_3)^T$  and  $\pi_0$ , the sampling constraints are:

$$\sum_{i=1}^{7} \phi_i = \frac{1 - \pi_0}{\pi_0}$$

$$\phi_1 + \phi_4 + \phi_5 + \phi_7 = \frac{\mu_1}{\pi_0}$$

$$\phi_2 + \phi_4 + \phi_6 + \phi_7 = \frac{\mu_2}{\pi_0}$$

$$\phi_3 + \phi_5 + \phi_6 + \phi_7 = \frac{\mu_3}{\pi_0}$$

$$\phi_i \in (0, \frac{1}{\pi_0} - 1)$$

And an implicit assumption is  $\mu_k < 1 - \pi_0 \le \sum_{k=1}^3 \mu_k$ .

By applying row reduction to the augmented matrix of the above 4 equations, we have

$$\begin{pmatrix} 1 & 0 & 0 & 0 & 0 & -1 & -1 & \frac{\mu_2 + \mu_3 + \pi_0 - 1}{\pi_0} \\ 0 & 1 & 0 & 0 & -1 & 0 & -1 & \frac{\mu_1 + \mu_3 + \pi_0 - 1}{\pi_0} \\ 0 & 0 & 1 & 0 & 1 & 1 & 1 & -\frac{\mu_3}{\pi_0} \\ 0 & 0 & 0 & 1 & 1 & 1 & 2 & \frac{1 - \pi_0 - \sum_{k=1}^{3} \mu_k}{\pi_0} \end{pmatrix}$$

Thus let  $\phi_5 = u, \phi_6 = v, \phi_7 = w$ , the feasible region of  $\Phi$  is defined by:

$$\begin{pmatrix} v + w - \frac{\mu_2 + \mu_3 + \pi_0 - 1}{\pi_0} \\ u + w - \frac{\mu_1 + \mu_3 + \pi_0 - 1}{\pi_0} \\ -u - v - w + \frac{\mu_3}{\pi_0} \\ -u - v - 2w - \frac{1 - \pi_0 - \sum_{k=1}^3 \mu_k}{\pi_0} \\ v \\ w \end{pmatrix} = \begin{pmatrix} -\frac{\mu_2 + \mu_3 + \pi_0 - 1}{\pi_0} \\ -\frac{\mu_1 + \mu_3 + \pi_0 - 1}{\pi_0} \\ \frac{\mu_3}{\pi_0} \\ -\frac{1 - \pi_0 - \sum_{k=1}^3 \mu_k}{\pi_0} \\ 0 \\ 0 \end{pmatrix} + u \begin{pmatrix} 0 \\ 1 \\ -1 \\ -1 \\ -1 \\ 1 \\ 0 \\ 0 \end{pmatrix} + v \begin{pmatrix} 1 \\ 0 \\ -1 \\ -1 \\ 0 \\ 1 \\ 0 \end{pmatrix} + w \begin{pmatrix} 1 \\ 1 \\ -1 \\ -2 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

and  $\phi_i \in (0, \frac{1}{\pi_0} - 1)$  for  $i = 1, \dots, 7$ 

To sample (u, v, w) from its feasible space, we can do as follow:

- 1. Sample v from Unif(0,  $\frac{1-\mu_1-\pi_0}{\pi_0}$ ).
- 2. Sample u from Unif $(0, \frac{\mu_3}{\pi_0} v)$ .
- 3. Sample w from Unif(max( $\frac{\mu_2+\mu_3+\pi_0-1}{\pi_0}-v, \frac{\mu_1+\mu_3+\pi_0-1}{\pi_0}-u), \frac{\mu_3}{\pi_0}-v-u$ ).

# Reference

- 1. Smith RL . Efficient Monte-Carlo Procedures for Generating Points Uniformly Distributed over Bounded Regions. Operations Research, 32(6), 12961308 (1984).
- 2. Van den Meersche, Karel, K. E. R. Soetaert, and D. J. Van Oevelen. "xsample (): an R function for sampling linear inverse problems." Journal of Statistical Software 30 (2009).