

# Summary of Short-term Research Objectives

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## 1 Model Specification

Let  $L$  be a  $K$ -dimensional Bernoulli random variable denoting the true state. Consider the general log linear model:

$$f(l; \Theta) = \exp\{\Theta_1^T l + \Theta_2^T u_2 + \dots + \Theta_K^T u_K - A^*(\Theta)\}$$

where  $U_k$  is a  $\binom{K}{k} \times 1$  vector of  $k$ -way cross-products,  $k = 1, \dots, K$ , and  $\Theta = (\Theta_1, \dots, \Theta_K)$  contains the the natural parameters, which is a  $(2^K - 1) \times 1$  vector.

Model restrictions, let  $\tilde{l} = (l, u_2, \dots, u_K)^T$ , and  $S = \sum_{j=1}^K L_j = s$  has some fixed pmf

$$\begin{aligned} \pi(s) &:= P(S = s) \\ &= \frac{1}{A(\Theta)} \sum_{\tilde{l}: S=s} \exp\{\Theta^T \tilde{l}\}, \quad s = 0, 1, \dots, K \end{aligned} \tag{1}$$

$$A(\Theta) = \sum_{\tilde{l}: l \in \{0,1\}^K} \exp\{\Theta^T \tilde{l}\} \tag{2}$$

## 2 Research Objectives

Suppose  $\{L_i\}$  are i.i.d random variables with density  $P(L_i; \Theta)$  defined above, our goal is to find a re-parameterization from  $\Theta$  to  $(\boldsymbol{\pi}, \boldsymbol{\gamma})$  such that  $P(L_i; \Theta) = P(L_i; \boldsymbol{\pi}, \boldsymbol{\gamma})$ , where  $\boldsymbol{\pi} = (\pi_0, \pi_1, \dots, \pi_s, \dots, \pi_K)^T$ , with  $\sum_{s=0}^K \pi_s = 1$ .

## 3 Results

### 3.1 Definition of New Parameters

Using previous notations, with some properly defined  $\boldsymbol{\gamma}$ , we have:

$$\begin{aligned} P(L_i; \boldsymbol{\pi}, \boldsymbol{\gamma}) &= P(L_i, S_i; \boldsymbol{\pi}, \boldsymbol{\gamma}) \\ &= P(L_i | S_i; \boldsymbol{\pi}, \boldsymbol{\gamma}) P(S_i; \boldsymbol{\pi}, \boldsymbol{\gamma}) \end{aligned}$$

where  $P(L_i | S_i; \boldsymbol{\pi}, \boldsymbol{\gamma}) = P(L_i | S_i; \boldsymbol{\gamma})$  because  $1(S_i = s)$  is the sufficient statistic for  $\pi_s$ , furthermore  $S_i$  is the sufficient statistic for  $\boldsymbol{\pi}$ . Also  $P(S_i; \boldsymbol{\pi}, \boldsymbol{\gamma}) = \pi_{S_i}$  by definition.

Therefore, we have

$$P(L_i; \boldsymbol{\pi}, \boldsymbol{\gamma}) = P(L_i | S_i; \boldsymbol{\gamma}) \pi_{S_i}$$

Then we define the following parameters:

$$\begin{aligned} \gamma_{j_1, \dots, j_s} &= P(L_{ij_1} = \dots = L_{ij_s} = 1 | S_i = s) \\ \boldsymbol{\gamma} &= (\gamma_1, \gamma_2, \dots, \gamma_{12}, \dots, \gamma_{1\dots K})^T, \text{ where } \sum_j \gamma_j = \sum_{j \neq j'} \gamma_{jj'} = \sum_{j \neq j' \neq j''} \gamma_{jj'j''} = \dots = \gamma_{1\dots K} = 1 \end{aligned} \quad (3)$$

Therefore  $(\boldsymbol{\pi}, \boldsymbol{\gamma})^T$  is a vector of length  $2^K + K$  with degrees of freedom  $2^K - 1$ .

Let  $J_i = \{j : L_{ij} = 1\}$ . We have,

$$P(L_i; \boldsymbol{\pi}, \boldsymbol{\gamma}) = \gamma_{J_i} \pi_{S_i} \quad (4)$$

The relation between  $(\boldsymbol{\pi}, \boldsymbol{\gamma})$  and  $\Theta$  is defined by equation (2) together with:

$$\gamma_{J_i} = \frac{\exp(\Theta^T \tilde{l}_i)}{\sum_{l: l^T \mathbf{1} = S_i} \exp(\Theta^T \tilde{l})} \quad (5)$$

with  $2^K - 1 - K$  degrees of freedom.

Therefore (1), (3) and (5) together define  $2^K - 1$  non-linear equations for  $2^K - 1$  unknowns. If there exists a unique root for the above non-linear system, then there is a one-to-one mapping between  $(\boldsymbol{\pi}, \boldsymbol{\gamma})$  and  $\Theta$ , which provides the re-parameterization.

### 3.2 Find the Re-parameterization