Today

Task oriented chat-bots

Constituency parsing

Natural language understanding

Two tasks (intent detection and slot filling): identify speaker's intent and extract semantic constituents from the natural language query

Sentence	first	class	fares	from	boston	to	denver
Slots	B-class_type	I-class_type	0	0	B-fromloc	0	B-toloc
Intent	airfare						

Figure: ATIS corpus sample with intent and slot annotation

- Intent detection is a classification task
- Slot filling is a sequence labelling task

NLU datasets: ATIS [1], Snips [2]

Joint intent detection and slot filling [3]

- The encoder models is a biLSTM
- The decoder is a unidirectional LSTM
- At each step the decoder state s_i is: $s_i = f(s_{i-1}, y_{i-1}, h_i, c_i)$, where $c_i = \sum_{j=1}^{T} \alpha_{i,j} h_j$, $\alpha_{i,j} = \frac{\exp(e_{i,j})}{\sum_{k}^{T} \exp(e_{i,k})}$, $e_{i,k} = g(s_{i-1}, h_k)$

The inputs are explicitly aligned. Costs from both decoders are back-propagated to the encoder.

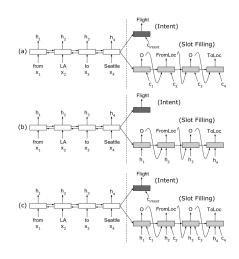


Figure: Encoder-decoder models

Joint intent detection and slot filling [3]

- BiLSTM reads the source sequence
- forward RNN models slot label dependencies
- the hidden state h_i at each step is a concatenation of the forward state fh_i and backward state bh_i
- the hidden state is h_i combined with the context vector c_i
- c_i is calculated as a weighted average of $h = (h_1, ..., h_T)$

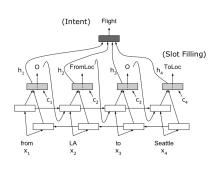


Figure: RNN-based model

0	0	B-fromloc. city_name	0	B-toloc. city_name	0	0	B-depart_time. time_relative	B-depart_time. period_of_day
flight	from	cleveland	to	dallas	that	leves	before	noon

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Grammar as a Foreign Language [4]

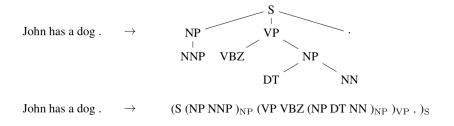


Figure: Example parsing task and its linearization

Grammar as a Foreign Language [4]

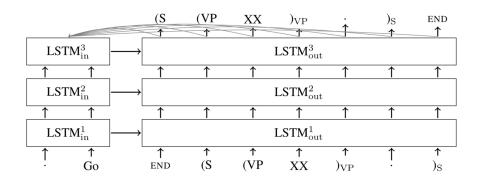


Figure: LSTM+attention encoder-decoder model for parsing

Grammar as a Foreign Language [4]

An important extension of the sequence-to-sequence model is by adding an attention mechanism. We adapted the attention model from [2] which, to produce each output symbol B_t , uses an attention mechanism over the encoder LSTM states. Similar to our sequence-to-sequence model described in the previous section, we use two separate LSTMs (one to encode the sequence of input words A_i , and another one to produce or decode the output symbols B_i). Recall that the encoder hidden states are denoted (h_1,\ldots,h_{T_A}) and we denote the hidden states of the decoder by $(d_1,\ldots,d_{T_B}):=(h_{T_A+1},\ldots,h_{T_A+T_B})$.

To compute the attention vector at each output time t over the input words $(1, \ldots, T_A)$ we define:

$$u_i^t = v^T \tanh(W_1' h_i + W_2' d_t)$$

$$a_i^t = \operatorname{softmax}(u_i^t)$$

$$d_t' = \sum_{i=1}^{T_A} a_i^t h_i$$

The vector v and matrices W_1', W_2' are learnable parameters of the model. The vector u^t has length T_A and its i-th item contains a score of how much attention should be put on the i-th hidden encoder state h_i . These scores are normalized by softmax to create the attention mask a^t over encoder hidden states. In all our experiments, we use the same hidden dimensionality (256) at the encoder and the decoder, so v is a vector and W_1' and W_2' are square matrices. Lastly, we concatenate d_t' with d_t , which becomes the new hidden state from which we make predictions, and which is fed to the next time step in our recurrent model.

Reference I



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Reference II



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