

HOMework 3

Denise Landini - 1938388

For extra-credit I choose to do:

1. Ray-Patch Intersection (4 points):

To implement this extra-credit:

a. In *yocto_pathtrace.h*:

- I add **quads** in the struct pathtrace_shape;
- I add **set_quads** in the part in which I write the shape properties.

b. I change the following functions in *yocto_pathtrace.cpp* by adding what it is necessary. The functions are:

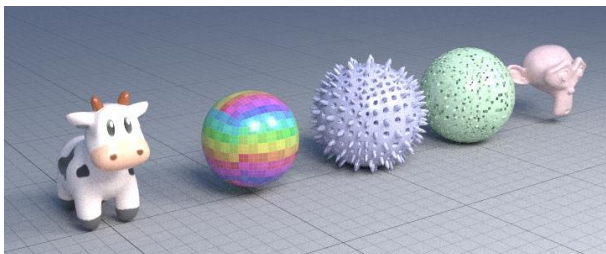
- Eval_position;
- Eval_element_normal;
- Eval_textcoord;
- Eval_element_tangent;
- Eval_normalmap;
- Eval_shading_normal;
- Init_bvh,
- Intersect_shape_bvh;
- Sample_lights;
- Tesselate_shape.

c. In *yocto_pathtrace.cpp*, I create a new function **ray_patch_intersect**.

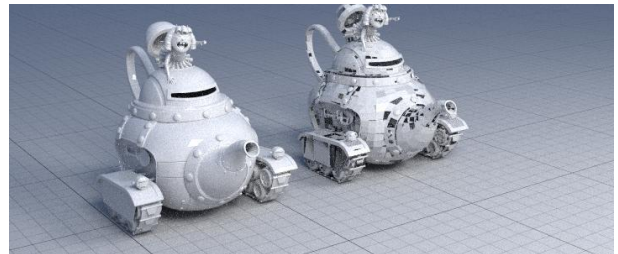
d. In *ypathtrace.cpp* I change:

- Init_scene.

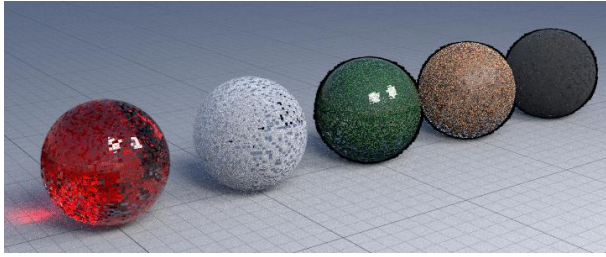
These are the pictures that I realize with my code, and I see that there is a problem, but I don't know how to resolve it.



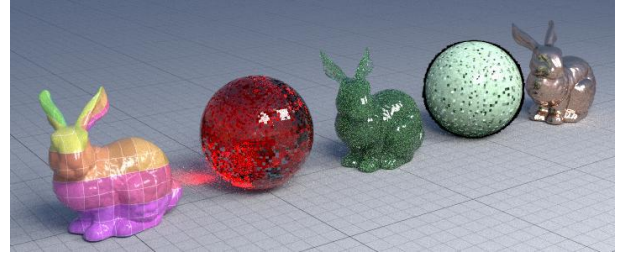
01_surface_720_256



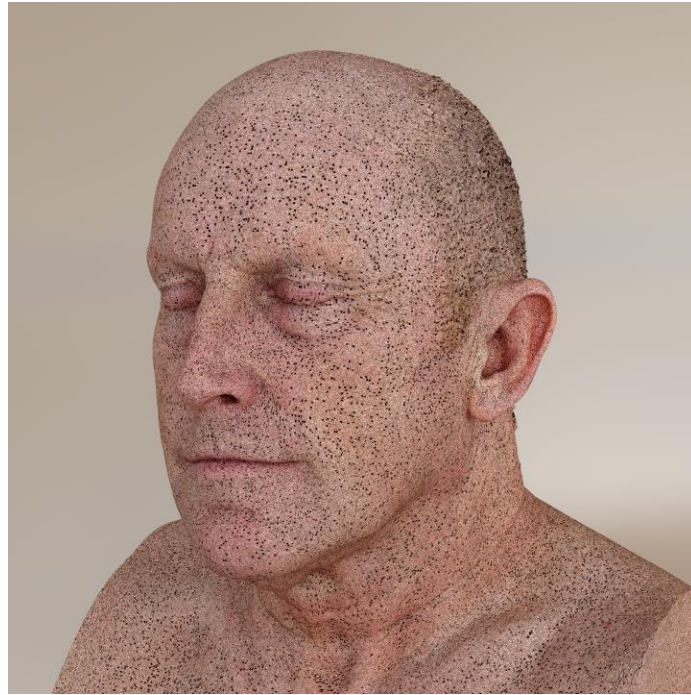
02_rollingteapot_720_256



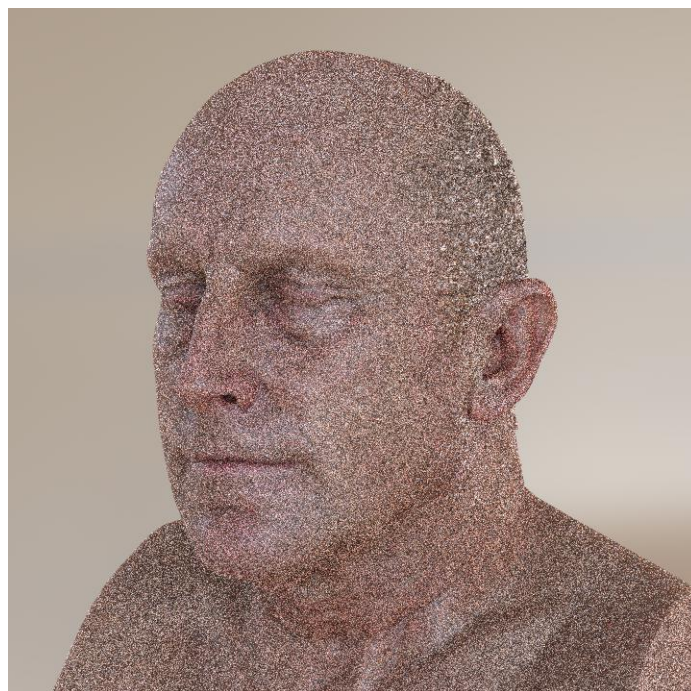
03_volume_720_256



06_extra_720_256



04_head1_720_256



05_head1ss_720_256

```

[=====]    9/    9 00:00.554 load scene
[=====]   19/   19 00:00.027 convert done
[=====]    5/    5 00:00.647 tessellate shape
[=====]    6/    6 00:00.586 build bvh
[=====]    4/    4 00:00.029 build light
[=====]  256/  256 00:45.780 render image
[=====]    1/    1 00:00.016 save image
Premere un tasto per continuare . . .

```

Time without Ray_Patch_intersection

```

[=====]    9/    9 00:00.573 load scene
[=====]   19/   19 00:00.024 convert done
[=====]    5/    5 00:00.757 tessellate shape
[=====]    6/    6 00:00.529 build bvh
[=====]    4/    4 00:00.027 build light
[=====]  256/  256 00:49.052 render image
[=====]    1/    1 00:00.027 save image
Premere un tasto per continuare . . .

```

Time with Ray_Patch_intersection

This is the comparison between the time without using Ray_Patch_intersection and by using it. I can see that the execution with Ray_Patch_intersection is slower than the other, even if of a few seconds.

2. Adaptive Rendering (4 points):

To implement this extra-credit:

a. In *yocto_pathtrace.h* I modified:

- `pathtrace_params;`
 - `pathtrace_state;`
- by adding some parameters and state that are useful.

b. I add the following four structs:

- `trace_info;`
- `pixel;`
- `sample_spread;`
- `statistic.`

c. I add the following functions:

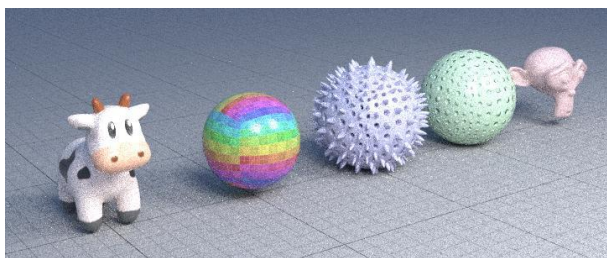
- `progress_callback_adaptive;`
- `checkEnd;`
- `trace_sample;`
- `trace_until_quality;`
- `trace_by_budget;`
- `create_sample_spread;`
- `all_image_ij;`
- `parallel_pixels_in_list;`
- `trace_image;`
- `get_max_progress;`
- `get_actual_progress;`
- `collect_statistics.`

d. I create a new app called *ypathtrace_adpative.cpp*

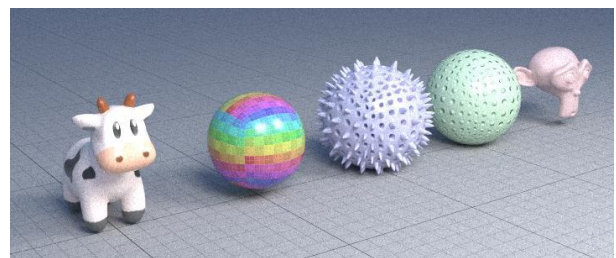
These are the pictures that I realize with my code.

At left there is the pictures that I realize with quality 1 and at right there are the pictures that I realize with quality 3.

I can see that there is the difference that I was expecting: the better is quality 3.



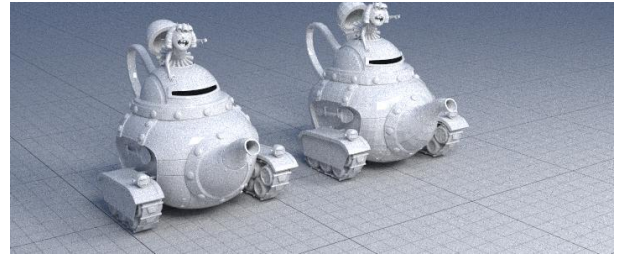
01_surface_720_256 q1



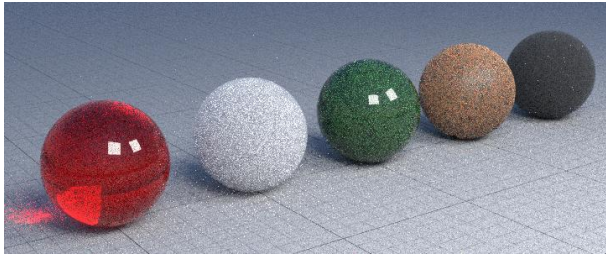
01_surface_720_256 q3



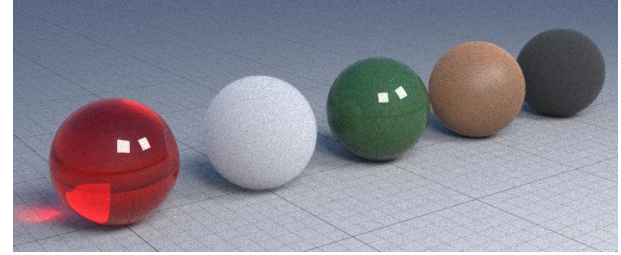
02_rollingteapot_720_256 q1



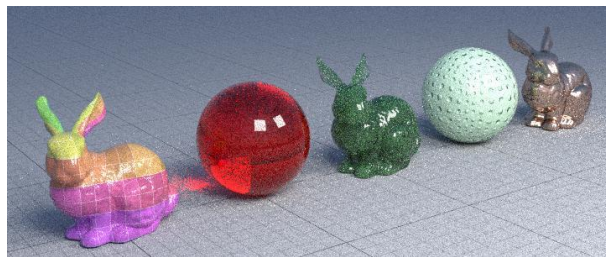
02_rollingteapot_720_256 q3



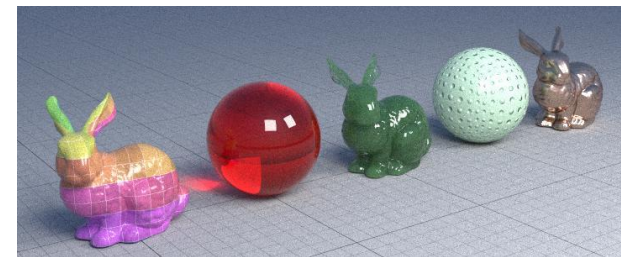
03_volume_720_256 q1



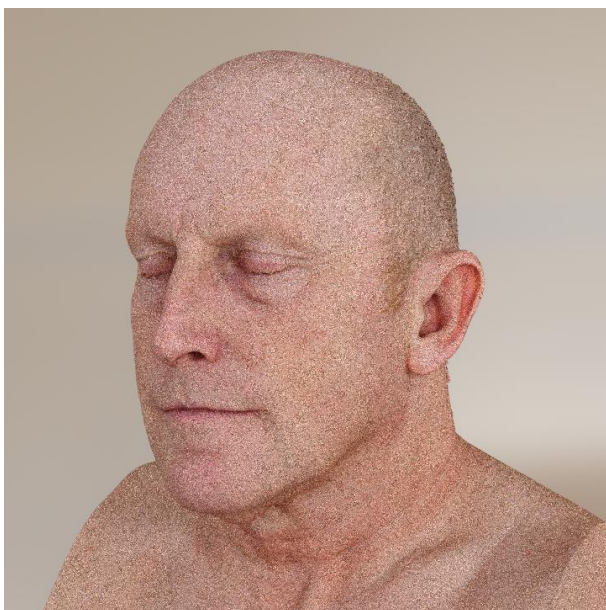
03_volume_720_256 q3



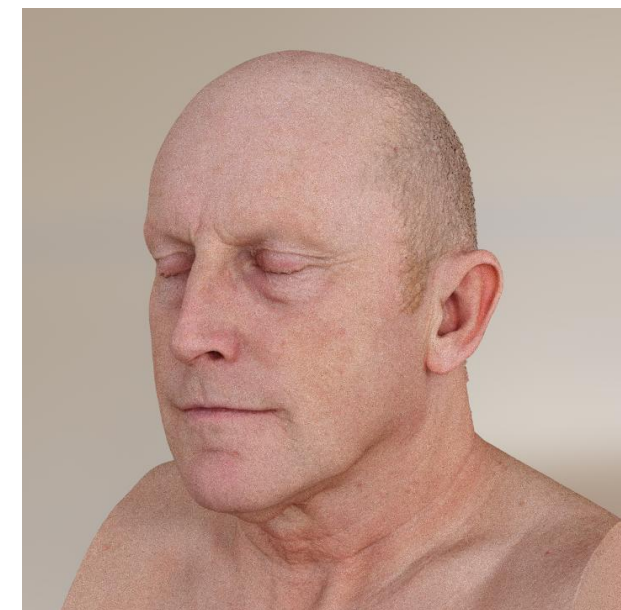
06_extra_720_256 q1



06_extra_720_256 q3



04_head1_720_256 q1



04_head1_720_256 q3



05_head1ss_720_256 q1



05_head1ss_720_256 q3