

Adaptation Algorithm (Static Error)

Static error model

$$\varepsilon = \omega^T \tilde{\theta}$$

Lyapunov function

$$V = \frac{1}{2\gamma} \tilde{\theta}^T \tilde{\theta} = \frac{1}{2\gamma} \|\tilde{\theta}\|^2$$

Adaptation algorithm

$$\dot{\tilde{\theta}} = \gamma \omega \varepsilon$$

Parametric error model

$$\begin{aligned} \dot{\tilde{\theta}} &= -\gamma \omega \omega^T \tilde{\theta} \\ \det(\omega \omega^T) &\equiv 0 \end{aligned}$$

Adaptation algorithm with improved parametric convergence (Kreisselmeier's scheme)

Modified model of parametric errors

$$\dot{\tilde{\theta}} = -\gamma L(s) [\omega \omega^T] \tilde{\theta}$$

where $L(s)$ is the operator with "memory" with which we use a stable minimum-phase positive transfer function.



$L(s) [\omega \omega^T] \geq \alpha_0 I > 0$, if the regressor satisfies the persistent excitation condition

Lyapunov function derivative

$$\dot{V} = \frac{1}{\gamma} \tilde{\theta}^T \dot{\tilde{\theta}} = -\tilde{\theta}^T L(s) [\omega \omega^T] \tilde{\theta} \leq -\alpha_0 \|\tilde{\theta}\|^2 = -2\gamma\alpha_0 V$$

Modified adaptation algorithm

$$\dot{\hat{\theta}} = \gamma \left(L(s) [\omega \varepsilon + \omega \omega^T \hat{\theta}] - L(s) [\omega \omega^T] \hat{\theta} \right)$$

Adaptation algorithm with improved parametric convergence (Lion`s scheme)

Modified model of parametric errors

$$\dot{\tilde{\theta}} = -\gamma \Xi^T \Xi \tilde{\theta}$$

where $\Xi = \text{col} \left(H_1(s) \begin{bmatrix} \omega^T \end{bmatrix}, H_2(s) \begin{bmatrix} \omega^T \end{bmatrix}, \dots, H_q(s) \begin{bmatrix} \omega^T \end{bmatrix} \right) \in \mathbb{R}^{q \times m}$, $q \geq m$, $H_i(s)$, $i = \overline{1, q}$ are linear independent stable minimum-phase positive transfer functions.



$\Xi^T \Xi \geq \lambda_0 I > 0$, if the regressor satisfies the persistent excitation condition

Lyapunov function derivative

$$\dot{V} = \frac{1}{\gamma} \tilde{\theta}^T \dot{\tilde{\theta}} = -\tilde{\theta}^T \Xi^T \Xi \tilde{\theta} \leq -\lambda_0 \|\tilde{\theta}\|^2 = -2\gamma\lambda_0 V$$

Modified adaptation algorithm

$$\dot{\hat{\theta}} = \gamma \Xi^T (\bar{\Xi} - \Xi \hat{\theta})$$

where $\bar{\Xi} = \text{col} \left(H_1(s) \begin{bmatrix} \varepsilon + \omega^T \hat{\theta} \end{bmatrix}, H_2(s) \begin{bmatrix} \varepsilon + \omega^T \hat{\theta} \end{bmatrix}, \dots, H_q(s) \begin{bmatrix} \varepsilon + \omega^T \hat{\theta} \end{bmatrix} \right)$.