

## Discrete Optimization: Homework #3, Ex. #6

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If  $x^*$  is feasible, we will call  $A_{x^*}x \leq b_{x^*}$  the subsystem of  $Ax \leq b$  that is satisfied by  $x^*$  with equality. We can notice that if  $\text{rank}(A_{x^*}) = n$ , then  $x^*$  is an extreme point since the unique solution of  $A_{x^*}x = b_{x^*}$  is  $x^*$  (Theorem 3.1). Suppose now that  $\text{rank}(A_{x^*}) < n$ . Similarly to the proof of Thm 3.2, we claim that if  $x^*$  is feasible, then there exists a  $y^*$  with  $c^T y^* > c^T x^*$  and  $\text{rank}(A_{y^*}) > \text{rank}(A_{x^*})$ . If we prove this claim, it will imply that in at most  $n$  steps we will find an extreme point.

To prove this, let  $d \neq 0 \in \mathbb{R}^n$  be a vector with  $A_{x^*}d = 0$ . If  $c^T d < 0$ , we can switch it to  $-d$ . As  $c^T d > 0$ , we consider the points  $x^* + \lambda d$  with  $\lambda > 0$  and let  $\lambda_{\max} = \max\{\lambda \text{ such that } x^* + \lambda d \text{ is feasible}\}$ .  $\text{Rank}(A_{(x^* + \lambda d)}) > \text{rank}(A_{x^*})$  and  $c^T(x^* + \lambda d) > c^T x^*$  so the claim is verified.

We now prove the claim in the case where  $c^T d = 0$ . If  $c^T d = 0$ , then  $Ad \neq 0$  because  $\text{rank}(A) = n$ . Let  $\lambda_{\max}$  be  $\max\{\lambda \geq 0 : A(x^* \pm \lambda d) \leq b\}$ . Then one can choose  $y^* = x^* + \lambda_{\max}d$  or  $y^* = x^* - \lambda_{\max}d$ , one of which has to satisfy the condition of the claim.

This means that we can use this process at most  $n$  times to find an  $x$  such that  $Ax = b$  which would be an extreme point. Finding  $d$  is solving a system of  $n$  equations, which can be done in polynomial time as seen during the lecture. We only consider all non-zero components of  $d$  because if  $d_i = 0$  :  $\left| \frac{(b - A_{x^*}x^*)_i}{d_i} \right| \longrightarrow \infty$ . Finding  $\lambda_{\max} = \min\left\{\frac{(b - A_{x^*}x^*)_i}{d_i}\right\}$  can be done in polynomial time. In the case where  $c^T d = 0$ , then  $\lambda_{\max} = \min\left\{\frac{(b - Ax^*)_i}{d_i}\right\}$  which can be easily calculated in polynomial time.