





```
[1] import numpy as np
Q = [[0, 0, 1, 0, 0, 0, 0, 0, −5],
          [0, 0, 0, 0, 0, 1, 0, 0, -4],
          [1, 0, 1, 0, 0, 0, -7, 0, -7],
          [0, 0, 0, 1, 0, 1, -4, 0, -4],
          [1, 1, 1, 0, 0, 0, -7, -7, -7],
          [0, 0, 0, 1, 1, 1, -5, -5, -5],
          [0, 1, 1, 0, 0, 0, 0, -6, -6],
          [0, 0, 0, 0, 1, 1, 0, -6, -6]]
[9]
      QT = np.transpose(Q)
      QT
                                           0],
    array([[ 0,
                  0,
                      1,
                          0,
                              1,
                                  0,
                                       0,
                 0,
                      0,
                          0,
                             1,
                                  0,
                                      1,
                                           0],
            [ 0,
                 0,
                          0,
            [ 1,
                     1,
                              1,
                                  0,
                                           0],
            [ 0,
                      0,
                  0,
                         1,
                              0,
                                  1,
                                           0],
            [ 0,
                                  1,
                  0,
                      0,
                          0,
                              0,
                                           1],
                     0,
            [ 0,
                              0,
                 1,
                         1,
                                  1,
                                           1],
                  0, -7, -4, -7, -5,
            [ 0,
                                           0],
                     0,
                          0, -7, -5, -6, -6,
            [-5, -4, -7, -4, -7, -5, -6, -6]]
```

Figure 1: Q and Q transpose matrix

In Figure 2, we multiply the Q and Q transpose and we input the resulting matrix to function np.linalg.eig. The function gives two outputs. It gives a matrix(Figure 3) of eigenvectors(in columns) and gives a 1-D array of corresponding eigenvalues of the eigenvectors. Therefore the smallest eigenvalue of the 1-D array indicates the solution for the 'a' vector.

```
[10] Symmetric matrix = np.matmul(QT,Q)
     Symmetric_matrix
                                   0,
     array([[
                 2,
                             2,
                                         0,
                                               0, -14, -7, -14
                             2,
                                               0, -7, -13, -13,
                       2,
                                   0,
                 1,
                 2,
                       2,
                           4,
                                   0,
                                         0,
                                               0, -14, -13, -25],
                 0,
                       0,
                             0,
                                         1,
                                   2,
                                               [2, -9, -5, -9],
                                 1,
                                       2,
                                               2, -5, -11, -11
              [
                       0,
                       0,
                                   2,
                                         2,
                                               4, -9, -11, -19],
              [-14,
                      -7, -14,
                                  -9,
                                        -5,
                                              -9, 139, 74, 139],
              [-7, -13, -13, -5, -11, -11,
                                                   74, 146, 146],
              [-14, -13, -25, -9, -11, -19, 139, 146, 252]])
[13] eigenvalues, matrix = np.linalg.eigh(Symmetric matrix)
[15] np.set_printoptions(suppress=True)
     print(eigenvalues)
                                                                        1.04621443
      [ -0.
                         0.00879951
                                        0.01307177
                                                        0.62936395
         6.32190546
                       32.58386497
                                       69.45979685 442.936983061
                      Figure 2: np.linalg.eigh function is used
 ##smallest eigenvalue is the 1st element, hence the eigenvector that gives the smallest eigenvalue
 ## of the matrix below is the first column. That will be the solution for vector a.
 print(matrix)
 [ [ \ 0.73029674 \ \ 0.31569415 \ \ 0.26671749 \ -0.31742916 \ \ 0.35241227 \ -0.24670845 ]
   0.04362755 0.07758551 -0.04606554]
   \hbox{ [ 0.31950483 -0.68770976 -0.05304357 -0.30684075 -0.48559227 -0.29023778 ] } 
   0.0542431 -0.0558555 -0.04367046]
  [ 0.22821773  0.27483107 -0.66779499
                                  0.41905063 -0.16107061 -0.46039615
   -0.08676274 0.01785284 -0.07124691]
  0.03537917 0.0436298 -0.03021729]
[ 0.36514837 -0.50952875 -0.14969644 0.47013732 0.48558576 0.34954222
   0.03057906 -0.05839005 -0.0359336 ]
   \hbox{\tt [0.18257419 0.16238127 -0.55651679 -0.48708554 -0.10782779 0.61072023] }
   -0.07455756 -0.01710941 -0.05364835]
  [ 0.09128709  0.04263619  0.06383694  0.0008212  -0.00945497  -0.02245244
   -0.50341454 -0.71957402 0.46256514]
   [ \ 0.04564355 \ -0.10826417 \ \ 0.00093936 \ \ 0.00241872 \ -0.00795203 \ \ 0.01332353 ] 
   -0.53224529 0.68347859 0.48530405]
  0.66570993 0.00254525 0.73234265]]
```

Figure 3: Eigenvectors

```
[35] col1 = [val[0] for val in matrix]
    print(col1)

[0.7302967433412046, 0.319504825209886, 0.22821773229355038, 0.365148371670974, 0.365148371668889, 0.18257418583472038, 0.09128709291769165, 0.0456435464585

[36] ##normalize by a9
    for i in range(9):
        col1[i]=col1[i]/(0.045643546458704956)
        print(col1)
        ##the resulting vector is 'a'.
```

 $[16.00000000004218,\ 6.99999999977024,\ 5.000000000000561,\ 8.0000000000029235,\ 7.9999999999835545,\ 3.9999999999978213,\ 2.0000000000061724,\ 0.99999999999964964,$

Figure 4: The solution vector

The normalized solution vector is:

[16.0000000004218, 6.99999999977024, 5.00000000000561, 8.000000000029235, 7.999999999835545, 3.999999999978213, 2.000000000061724, 0.9999999999964964, 1.0]