

EE 417 Introduction to Computer Vision

Images, Windows and Histograms

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Sabancı
Üniversitesi

An Array of 50×50 Numbers

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46 58 70 76 76 69 60 67 71 54 80 103 100 87 77 55 30 22 23 22 23 26 22 22 20 20 221
44 61 71 72 72 69 32 49 34 46 39 64 65 57 40 21 17 18 11 16 16 21 20 19 19 204
48 61 70 71 64 59 49 41 43 48 24 34 30 26 17 13 17 20 16 9 9 15 16 16 17 181
43 58 62 61 63 60 44 39 41 43 26 16 15 14 13 16 17 16 11 11 14 17 16 11 8 14 171
38 48 58 56 52 58 47 41 43 39 17 14 19 16 14 12 14 19 30 39 42 41 34 27 19 111
36 37 47 46 48 60 44 43 46 45 25 19 20 38 16 13 14 26 43 59 71 78 80 76 79 50 251
37 38 35 32 66 87 47 47 58 51 21 19 20 38 14 13 20 36 52 61 68 71 70 79 82 78 861
39 36 35 27 67 108 67 52 67 52 22 17 20 38 15 15 23 34 40 40 43 46 45 56 58 72 911
35 37 39 32 50 87 87 55 56 53 29 19 22 14 13 19 26 40 46 49 55 57 59 64 61 63 731
37 34 33 38 46 61 69 44 52 45 27 24 24 13 9 24 44 50 56 63 67 72 77 71 76 891
37 38 43 37 48 53 42 38 45 35 24 27 27 16 9 31 39 63 87 74 79 79 84 88 87 79 831
35 46 47 38 58 53 38 43 41 30 22 25 24 19 10 33 67 76 74 74 80 82 89 93 75 49 391
39 49 52 45 51 48 44 19 38 25 19 20 17 17 10 30 69 63 82 77 85 92 89 64 45 45 491
46 53 60 60 50 42 43 36 33 21 15 16 13 14 11 27 66 74 63 59 81 99 94 60 57 50 431
62 75 70 81 72 45 43 41 30 18 13 15 13 13 13 21 37 45 38 42 72 96 102 80 51 26 211
61 81 75 72 63 42 39 28 12 14 34 13 15 15 38 50 55 58 47 89 96 72 24 23 451
43 58 65 55 42 41 40 33 23 13 13 13 14 12 11 28 57 48 28 32 35 54 76 53 41 52 621
47 50 51 47 40 32 29 30 12 11 12 13 12 12 24 32 12 13 23 28 35 53 58 59 69 721
41 50 51 46 44 40 33 30 22 12 9 11 11 10 10 16 15 28 48 57 55 46 62 67 61 68 801

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This is actually a digital image when ...

Interpreting Numbers by Intensities

0 is "Black", 255 is "White", numbers in between are levels of gray



Each number is shown as a shaded small square, called a *pixel*

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41 22 11 20 19 28 62 93 78 29 53 66 59 64 57 57 52 48
48 27 14 20 21 28 49 60 105 130 109 106 82 89 81 58 49 49
50 37 19 22 24 30 24 86 244 254 171 118 97 89 69 63 55 54
58 49 28 21 21 9 56 255 255 232 155 124 102 80 76 91 90 88
74 60 37 21 19 13 54 203 193 147 139 141 121 116 111 123 111 98
82 74 36 15 22 31 28 71 99 100 141 156 142 132 121 136 114 83
91 79 38 6 22 37 40 49 74 108 121 112 103 102 104 95 73 58
93 81 31 6 35 29 41 68 84 92 98 93 86 86 87 90 91 112
91 79 25 13 26 35 64 85 97 91 94 101 99 89 92 119 127 94
92 71 16 10 21 45 87 87 95 95 94 100 97 101 94 87 75 31
83 47 40 70 49 46 88 93 98 95 102 110 97 95 93 81 71 59
81 34 30 69 47 39 85 95 93 98 106 113 105 98 103 100 88 69
68 46 15 26 20 30 78 88 94 103 102 101 102 95 100 99 73 56
71 54 19 28 26 21 54 79 95 99 97 96 96 91 90 71 48 42
79 57 21 17 20 21 44 76 90 98 101 102 98 88 76 45 33 38
82 56 21 16 20 27 50 86 89 99 102 103 98 85 65 35 38 64
78 52 23 24 27 40 72 95 98 101 99 101 93 82 62 33 39 51
74 47 25 24 28 47 87 93 87 111 100 100 93 77 53 30 36 49
79 50 34 32 36 58 86 77 84 104 111 97 91 76 60 61 60 59
80 50 36 39 52 78 98 87 85 103 108 100 92 73 68 74 65 48
75 51 37 34 31 34 59 79 91 107 105 101 95 71 39 45 42 33
77 60 36 27 26 24 34 42 61 81 83 83 90 87 56 32 39 43
77 69 44 25 28 42 53 46 47 68 66 57 72 77 70 43 3 0
78 73 54 35 29 39 47 46 46 65 71 49 63 60 45 67 131 138
78 76 61 37 30 40 39 34 34 60 78 61 61 67 50 65 214 255
71 71 68 44 25 37 53 39 43 67 80 69 61 73 72 56 93 209
63 58 53 45 28 40 66 59 50 66 79 76 69 77 79 77 61 138

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These are regions in the shown image with intensities ≥ 180 ; the pixels showing the teeth are still below threshold 180

Arrays of Numbers

... allow us to do numerical calculations, for example with the intention to improve the contrast in the digital image



Image Carrier

An image I is a rectangular array of *pixels* (x, y, u)

A pixel combines location $p = (x, y) \in \mathbb{Z}^2$ and sample u at p

\mathbb{Z} is the set of all integers; points $(x, y) \in \mathbb{Z}^2$ form a *regular grid*

An image I is defined on a *carrier*

$$\Omega = \{(x, y) : 1 \leq x \leq N_{cols} \wedge 1 \leq y \leq N_{rows}\} \subset \mathbb{Z}^2$$

of N_{cols} times N_{rows} pixel locations (grid points)

$$Z^2 = Z \times Z$$

↑
Cartesian product

$$\{a, b\} \times \{a, b\}$$

$$= \{(a, a), (a, b), (b, a), (b, b)\}$$

$\begin{matrix} & \rightarrow x \\ y \downarrow \end{matrix}$

$$|\Omega| = \# \text{ elements in } \Omega$$

↑
cardinality of set
 Ω


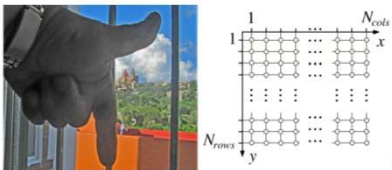


Image Coordinate System



Assuming a left-hand coordinate system, the thumb defines the x-axis and the pointer the y-axis while looking into the palm of the hand





Image Rows and Columns

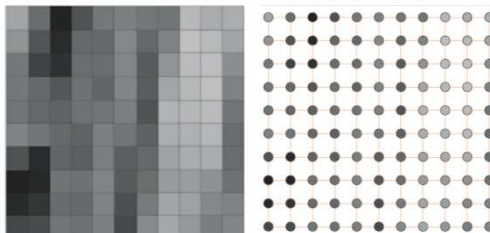
We assume a left-hand coordinate system in Ω

Row y
contains grid points $\{(1, y), (2, y), \dots, (N_{cols}, y)\}$, for $1 \leq y \leq N_{rows}$


Column x
contains grid points $\{(x, 1), (x, 2), \dots, (x, N_{rows})\}$, for $1 \leq x \leq N_{cols}$



Pixels





Left: Image values as shades in *grid squares* (grid cells)
Right: Image values as labels at *grid points* (centers of grid squares)



Grid Cells, Grid Points, and Adjacency

Grid cell model
A pixel is a homogeneously shaded square cell

Grid point model
A pixel is a labelled grid point

Pixel adjacency
Not defined by the pixels themselves; needs to be defined by us

Two Examples

Two pixel locations p and q in grid cell model are adjacent iff $p \neq q$ and

- (1) their tiny shaded squares share an edge (\equiv 4-adjacency)
- (2) their tiny shaded squares share an edge or corner (\equiv 8-adjacency)

Two Examples

Adjacency defines *connectedness* and *connected sets* of pixels

Left and middle: Connectedness of gray pixels due to 4-adjacency, either in grid cell or in grid point model; the two white pixels are not 4-adjacent

Right: Connectedness of gray pixels due to 8-adjacency in grid cell model forms a loop; the 8-adjacency of the two white pixels is "crossing" this loop (Edges or corners of grid cells are shown as elongated rectangles or squares)

An Image Window

Image processing is often local (just addressing data in a window)

73 × 77 window in image SanMiguel; marked pixel location $p = (453, 134)$

The *reference point* of a window is usually at the window's centre

Image Windows

Unique identifier for an image window:

A window $W_p^{m,n}(I)$

is a subimage of image I of size $m \times n$

positioned with respect to a *reference point* p

Default: odd number $m = n$ and p at the center of the window

Example (on page before): $W_{(453,134)}^{73,77}(\text{SanMiguel})$

Usually: Simplify notation to W_p

(because image and size of window are known by given context)

Integer Values and G_{\max}

Scalar image: Values are integers $u \in \{0, 1, \dots, 2^a - 1\}$

Common: $a = 8$ (i.e. one byte) or $a = 16$

Let $G_{\max} = 2^a - 1$ be the general maximum image value

Example

A *gray-level image* is a scalar image where scalar values represent gray levels, with $0 = \text{black}$ and $2^a - 1 = \text{white}$; all other gray-levels are linearly interpolated between black and white

Binary and Vector-Valued Images

A *binary image* (e.g. produced by *thresholding*) has two values, traditionally $0 = \text{white}$ and $1 = \text{black}$ (black objects on white background)

A *vector-valued image* has more than one *channel* or *band*

Image values $[u_1, \dots, u_{N_{\text{channels}}}]^T$ are vectors

Example: Color images in the *RGB color model* have channels for the red, green, and blue component; values u_i in each channel are in the set $\{0, 1, \dots, G_{\max}\}$ (like a gray-value image)

Example of an RGB Color Image

RGB colour image Fountain and its three channels for Red (upper right), Green (lower left), and Blue (lower right)

Basic Statistics

Mean

Given: $N_{cols} \times N_{rows}$ scalar image I

Mean (i.e., the "average gray level") of image I

$$\begin{aligned}\mu_I &= \frac{1}{N_{cols} \cdot N_{rows}} \sum_{x=1}^{N_{cols}} \sum_{y=1}^{N_{rows}} I(x, y) \\ &= \frac{1}{|\Omega|} \sum_{(x,y) \in \Omega} I(x, y) \\ &= \frac{1}{|\Omega|} \sum_{p \in \Omega} I(p)\end{aligned}$$

$|\Omega| = N_{cols} \cdot N_{rows}$ is the cardinality of the carrier Ω

Variance and Standard Deviation

Variance of image I

$$\sigma_I^2 = \frac{1}{|\Omega|} \sum_{(x,y) \in \Omega} [I(x, y) - \mu_I]^2$$

Root σ_I is the *standard deviation* of image I

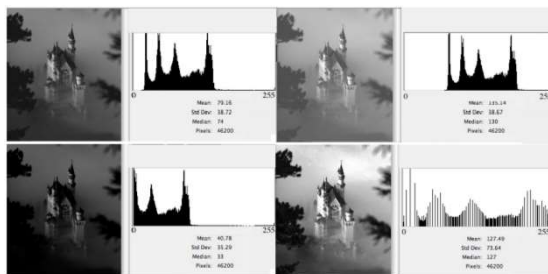
Well-known formula in statistics:

$$\sigma_I^2 = \left[\frac{1}{|\Omega|} \sum_{(x,y) \in \Omega} I(x, y)^2 \right] - \mu_I^2$$

Thus: Mean and variance calculated by running through image I only once
Why?

$$\text{Standard deviation} = \sqrt{\text{Variance}} \geq 0$$

Four Histograms



Histograms for a 200×231 image Neuschwanstein

Upper left: Original image. Upper right: Brighter version. Lower left: Darker version. Lower right: After histogram equalization (defined later)

Definition of Histograms

A *histogram* represents tabulated frequencies, typically by using bars in a graphical diagram

Given: Scalar image I with pixels (x, y, u) , where $0 \leq u \leq G_{max}$

Absolute frequencies (count of appearances of u in Ω)

$$H_I(u) = |\{(x, y) \in \Omega : I(x, y) = u\}|$$

$|\dots|$ denotes the cardinality of a set

$H_I(0), H_I(1), \dots, H_I(G_{max})$ define the (absolute) *gray-level histogram* of I

Relative frequencies (between 0 and 1) define a *relative histogram*

$$h_I(u) = \frac{H_I(u)}{|\Omega|}$$



More on Histograms

We have:

$$\mu_I = \sum_{u=0}^{G_{\max}} u \cdot h_I(u) \quad \text{or} \quad \sigma_I^2 = \sum_{u=0}^{G_{\max}} [u - \mu_I]^2 \cdot h_I(u)$$

Absolute and relative cumulative frequencies define cumulative histograms

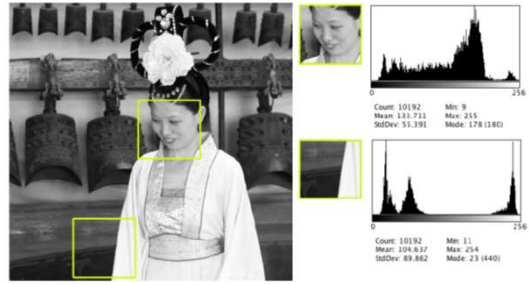
$$C_I(u) = \sum_{v=0}^u H_I(v) \quad \text{and} \quad c_I(u) = \sum_{v=0}^u h_I(v)$$

Observation

Relative frequencies are comparable to the *probability density function* $\Pr[I(p) = u]$ of discrete random numbers $I(p)$, relative cumulative frequencies are comparable to the *probability function* $\Pr[I(p) \leq u]$



Histograms for Two Image Windows

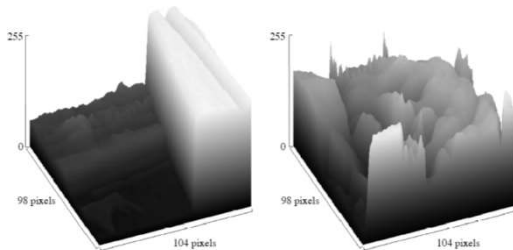


Draw a sketch of the cumulative histograms of both windows!



3D Views of Gray-Level Images

3-dimensional (3D) views illustrate different "degrees of homogeneity" in an image window; here for the two windows from Page 32



Left: Steep slope from lower plateau to higher plateau illustrates an "edge"



Value Statistics in a Window

Given: Window $W = W_p^{n,n}(I)$, with $n = 2k + 1$ and $p = (x, y)$

We have in window coordinates

$$\mu_W = \frac{1}{n^2} \sum_{i=-k}^{+k} \sum_{j=-k}^{+k} I(x+i, y+j)$$

Formulas for variance, histograms, and so forth, can be adapted analogously