

-SystemC Flow-

1. basic adder
2. SR latch is in the delta_delay
3. **SR latch with THREAD** is in thread_example
 - a. toplevel is for testbench > connecting modules
 - i. https://github.com/TUK-SCVP/SCVP.artifacts/tree/master/delta_delay
 - b. giving names to the ports
 - i. https://github.com/TUK-SCVP/SCVP.artifacts/tree/master/feedback_loop
 - c. thread example
 - i. https://github.com/TUK-SCVP/SCVP.artifacts/tree/master/thread_example

BU yukarıdaki 3lü a,b,c birbirlerinin aynısı gibi. Sadece 2. olan, yani feedback loop durmuyor, infinite loop.

4. switching values of variables
 - a. https://github.com/TUK-SCVP/SCVP.artifacts/tree/master/swapping_example
5. event queue
 - a. https://github.com/TUK-SCVP/SCVP.artifacts/tree/master/sc_event_and_queue
6. clock generator > not important
 - a. https://github.com/TUK-SCVP/SCVP.artifacts/tree/master/clock_generator
7. Waveform Tracing - sc_clock - Connecting Modules (Binding) = önemli
 - a. file:///C:/Users/User/Desktop/SystemC/SystemC.pdf > page 101
8. connecting modules in hierarchical (not1 > not2 > not3)
 - a. https://github.com/TUK-SCVP/SCVP.artifacts/tree/master/not_chain

9. data types

- a. <https://github.com/TUK-SCVP/SCVP.artifacts/tree/master/datatypes>

10. polymorphism

- a. page 120

11. custom channel = FIFO > can be only implemented by using SC_THREADS

- a. https://github.com/TUK-SCVP/SCVP.artifacts/tree/master/custom_fifo

12. Khan Process Network (KPN) > not detailed

- a. https://github.com/TUK-SCVP/SCVP.artifacts/tree/master/kpn_example

13. Mutex > not detailed

- a. https://github.com/TUK-SCVP/SCVP.artifacts/tree/master/mutex_example

14. custom signal

- a. https://github.com/TUK-SCVP/SCVP.artifacts/tree/master/custom_signal

15. port arrays > 1 module with multiple ports > static

- a. https://github.com/TUK-SCVP/SCVP.artifacts/tree/master/port_arrays

16. multiple ports > dynamic

- a. <https://github.com/TUK-SCVP/SCVP.artifacts/tree/master/multiports>

17. multiple binding

- a. page 147

18. dynamic processes

- a. https://github.com/TUK-SCVP/SCVP.artifacts/tree/master/dynamic_processes

19. printing out report > not important

- a. <https://github.com/TUK-SCVP/SCVP.artifacts/tree/master/reporting>

20. callbacks

- a. <https://github.com/TUK-SCVP/SCVP.artifacts/tree/master/callbacks>

21. TLM design > has written on the course from scratch

- a. https://github.com/TUK-SCVP/SCVP.artifacts/tree/master/custom_tlm

22. TLM Initiator (CPU) > Target (Memory) & Blocking Transport

- a. https://github.com/TUK-SCVP/SCVP.artifacts/tree/master/tlm_initiator_target

- b. page 188

23. TLM interconnect components dynamically

- a. Initiator (CPU) > Interconnect (Bus) > Targets (Memory1 & Memory2)
- b. https://github.com/TUK-SCVP/SCVP.artifacts/tree/master/tlm_initiator_interconnect_target
- c. port arrays are used

24. Quantum keeper > for timing synchronization

- a. https://github.com/TUK-SCVP/SCVP.artifacts/tree/master/tlm_quantum_keeper

25. DMI (Direct Memory Interface) = bypass the interconnect (ie Bus)

- a. https://github.com/TUK-SCVP/SCVP.artifacts/tree/master/tlm_init_dmi

26. Blocking transport but without time

- a. https://github.com/TUK-SCVP/SCVP.artifacts/tree/master/tlm_init_debug_transport

27. TLM basic memory manager

- a. https://github.com/TUK-SCVP/SCVP.artifacts/tree/master/tlm_memory_manager

28. TLM 4 Phase Handshake

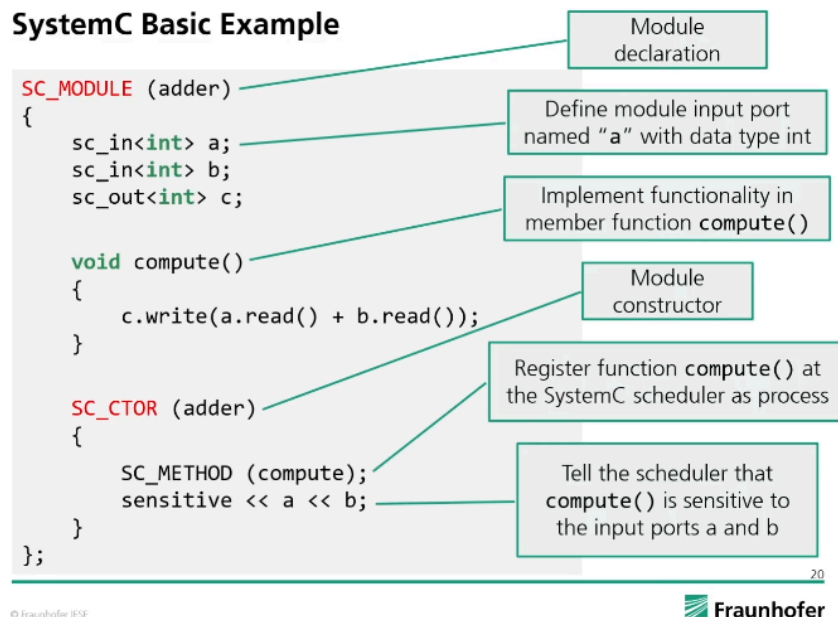
- a. https://github.com/TUK-SCVP/SCVP.artifacts/tree/master/tlm_it_initiator_target
29. TLM Sockets > no binding required
- a. https://github.com/TUK-SCVP/SCVP.artifacts/tree/master/tlm_simple_sockets
30. TLM multi-pass-through sockets
- a. https://github.com/TUK-SCVP/SCVP.artifacts/tree/master/tlm_multipasstrough_sockets
31. TLM backpressure
- a. https://github.com/TUK-SCVP/SCVP.artifacts/tree/master/tlm_at_backpressure
32. TLM payload extension
- a. https://github.com/TUK-SCVP/SCVP.artifacts/tree/master/tlm_payload_extensions

ADDER

- SC_MODULE(adder) {}; == class adder : public sc_module {};
- <> == means **template**
- sc_in<int>, sc_out<int>
- void **compute**() { the function}
- C = A + B ==> c.write(a.read() + b.read()) ==> This means these a b and c are not variables, but signals.
- SC_CTOR(adder) {
 - SC_METHOD(**compute**);
 - Sensitive << a << b;
- For an adder for example, we write SC_MODULE(adder){}; Then inside these {}, we write inputs and outputs.
- THEN, **again inside this module**, we define the **method**, which is the function that this module should do. => do it with **void**

- AGAIN, **inside the SC_MODULE**, we will add the constructor, which is **SC_CTOR(adder)**. The name inside should be the same as the name of the module.
 - Inside this SC_CTOR, add SC_METHOD(name of the void function), telling that computation will be done by this adder when it is called.
 - Then we add the sensitivity list by just writing sensitive and using << for each signal

SystemC Basic Example



●

SC_MODULE and SC_CTOR Macros

■ SC_MODULE(XYZ) is a short macro for: `class XYZ : public sc_module`

■ SC_CTOR(XYZ) is a short macro for:

```

SC_HASPROCESS(XYZ);
XYZ(const sc_module_name &name) : sc_module(name)
  
```

●

- SC_CTOR yerine SC_HASPROCESS de yazılabilirmiş.

SR LATCH

- In SC_CTOR, we define the PORTS.
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