

# Final Poster - Vision

Yigit Deniz Celebi, Alper Ari, Bora Arda Zeytinoglu  
abd-vision

Modality 2/2

## Motivation

- To build an AutoML pipeline, which aims to train an image classification model with any given dataset.
- To increase model's accuracy on test dataset while fine tuning its hyperparameters using scientific approaches.
- To find balance between training time and top-1 accuracy score.
- To apply multiprocessing and parallelization techniques to speed up exploration in configure space
- To apply data augmentations to create data variations that helps the model improve accuracy score

## Planning

- Choosing (suitable) datasets/training splits
- Data augmentation
- Finding the best epochs
- Fine tuning hyperparameters
- Splitting the data 80/20 for training and validation purposes
- Choosing best model to balance speed and accuracy
- Feeding the data into the model for final training
- Evaluating the predictions and obtaining the top-1 accuracy score

## Coding Approach

### Literature & Research

- Before everything, we tried to find a promising and easy-to-use AutoML library from the internet and decided on Neps.
- We did research about how CNNs work, types of layers and the difference between popular networks such as ResNet, VGG, ShuffleNet, MobileNet, EfficientNet, etc.
- Depending on the CNN we chose, we also determined the data augmentation techniques before we feed our data into the model.
- Before we started implementing HPO speed up techniques like Bayesian Optimization, Successive Halving, Hyperband and Priorband, we went through their scientific papers to understand how they actually work.
- We also did a research about learning rate schedulers by going through PyTorch's documentation. We ended up using OneCycleLR and ReduceLRonPlateau schedulers and adding them to our configuration space.
- We tried several plotting libraries to visualize and analyze prediction results.

### Implementation

- 1- We started with implementing AutoML class with its member variables and functions.
- 2- Then we built the base of our pipeline code inside AutoML class which is to be callable and generic.
- 3- We came up with several CNNs with their hyperparameters and structured our configuration space.
- 4- After making sure that our automated pipeline works with Tiny VGG i.e. it successfully evaluates configurations and finds the best one, we decided to use pre-trained models like MobileNetV2 for faster training and better accuracy.
- 5- We introduced various data augmentation transforms and extended our configuration space.
- 6- We added multiprocessing feature to our pipeline to explore more configurations in a unit time.
- 7- First we used hyperband to speed up the training, then switched to priorband by giving higher confidence to epochs.
- 8- We introduced learning rate scheduler to our pipeline for the sake of dynamic algorithm configuration.

Week 1

Week 2

Week 3

Week 4

Week 5

Week 6

Week 7

Week 8

Week 9

Week 10

Bonus

Literature

### Resources Used

For development:

- 2 GTX1650 GPU
- 1 RTX4070Ti GPU
- 2 Intel Core CPUs
- 1 AMD CPU
- Total compute estimate: 600 CPU-h

For AutoML:

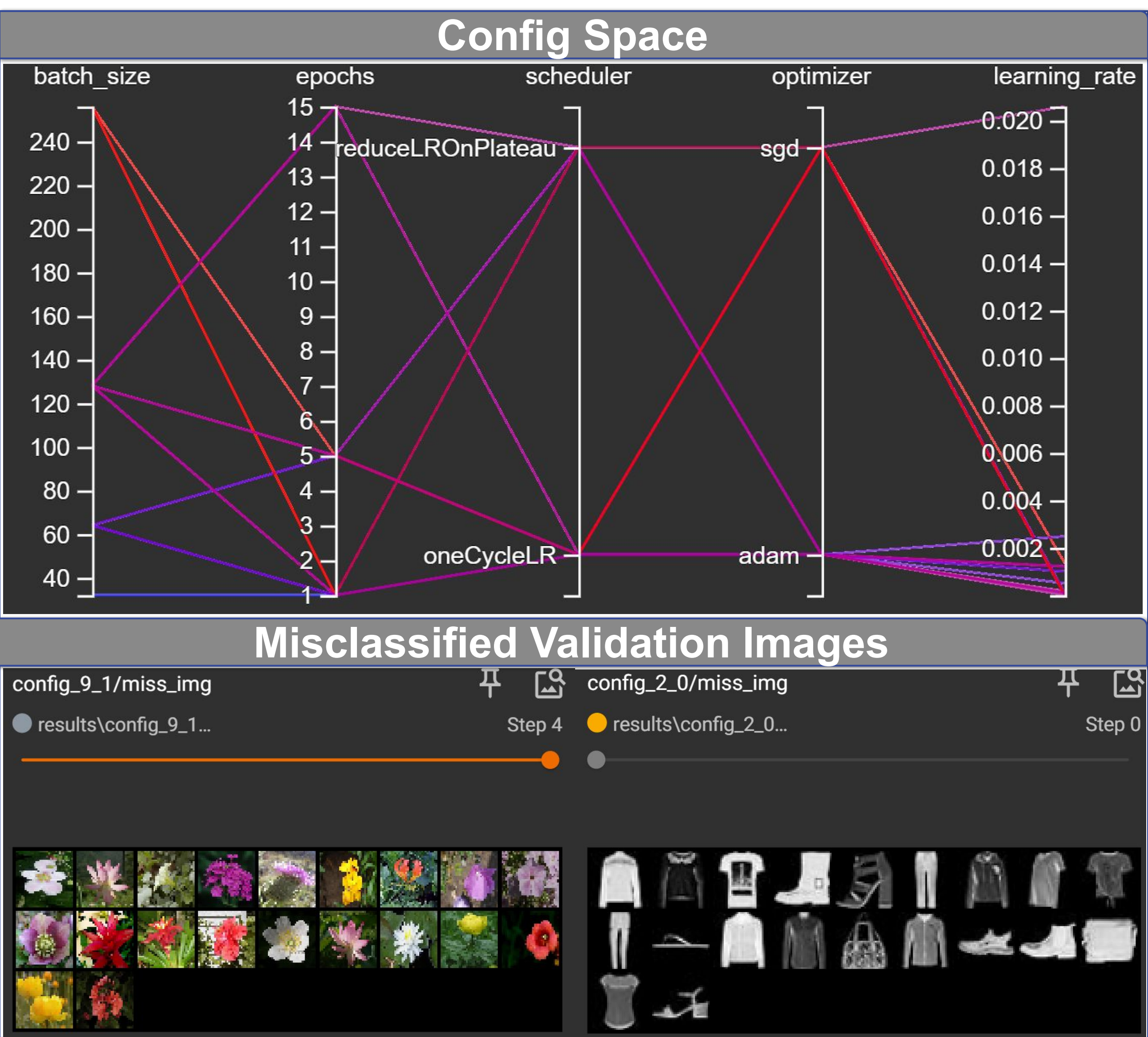
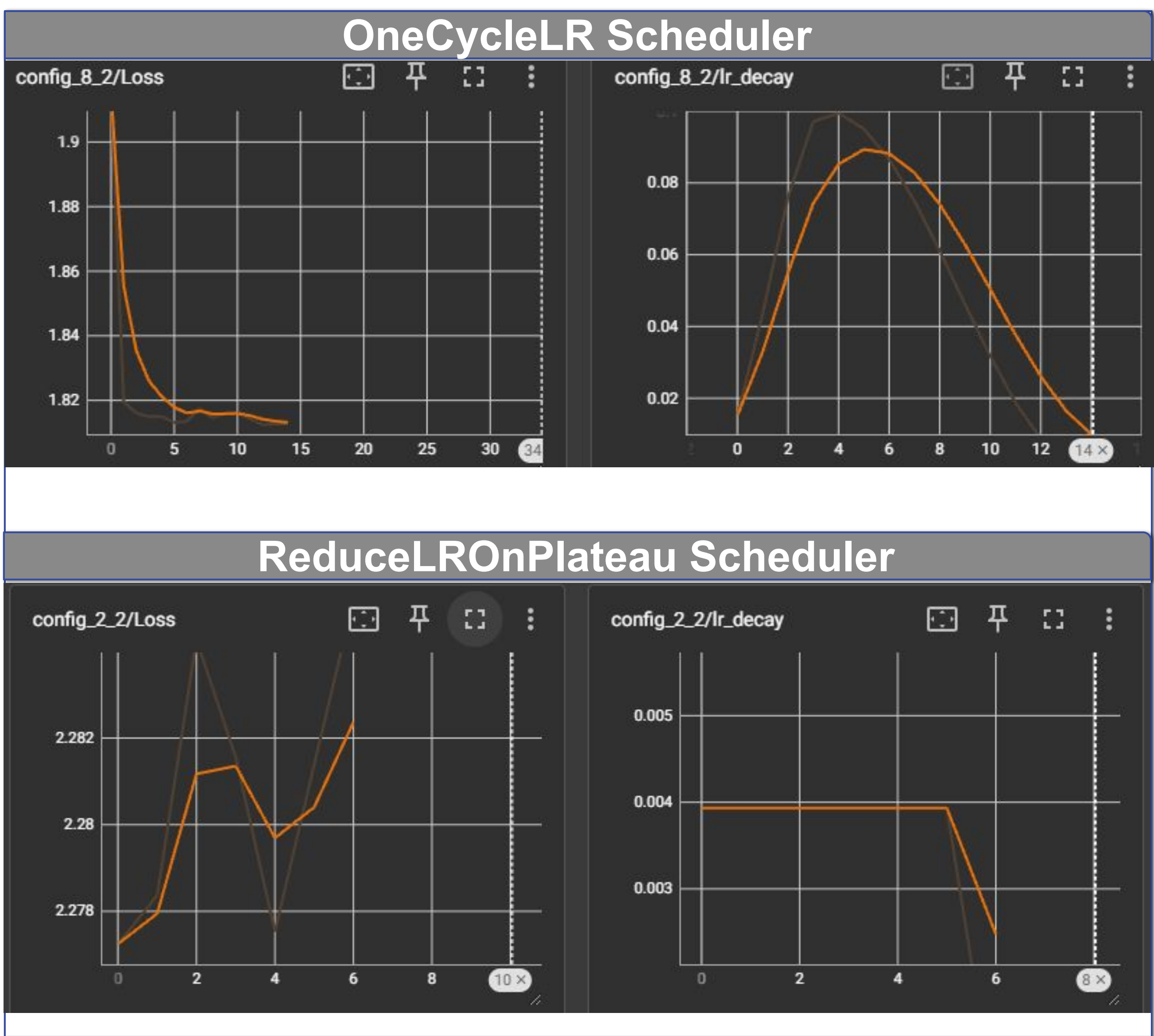
- Google Colab (A100 + L4)
- 12h

Workforce:

- 1 full week on average

Number of queries for test score generation: 3

## Empirical Results



Best configuration & Evaluation															
	epochs	batch size	optimizer	scheduler	time elapsed (s)	LR	last LR	loss	top_1_acc	top_5_acc	precision	recall	F1	device	total pipeline runtime (s)
Emotions	15	64	ADAM	oneCycleLR	1007	0.02094	0.0099	1,8126	0.24	0.86	0.035	0.14	0.05	A100	5578
Flowers	5	128	ADAM	oneCycleLR	201	0.0773	0.0273	3,8777	0.9678	0.9963	0.9660	0.961	0.962	A100	3150
Fashion	1	64	ADAM	reduceLRonPlateau	258	0.0039	0.0039	2,2772	0.7996	0.993	0.8039	0.7996	0.7993	L4	15512
Skin Cancer	15	32	SGD	oneCycleLR	616	0.01525	0.0099	1,1424	?	?	?	?	?	A100	3825

