

1. The signal $x(n)$ has the autocorrelation function $r_x(l) = 2^{-|l|} + \delta(l)$, where $\delta(l) = 1$ when $l = 0$ and $\delta(l) = 0$ otherwise.

- (a) Compute the power spectrum for the signal $x(n)$.
- (b) *Correlogram* is an estimate for the power spectrum. In the correlogram the values of the correlation function up to delay L are used:

$$\hat{P}_x(e^{j\omega}) = \sum_{l=-L}^L r_x(l) e^{-j\omega l}$$

Thus it can be thought of as a generalization of the periodogram (in the periodogram, $L = N - 1$). Compute the correlogram of $x(n)$ with $L = 2$ using correlation function values $r_x(0), r_x(\pm 1), r_x(\pm 2)$.

2. The periodogram can be written as

$$\hat{P}_x(e^{j\omega}) = \frac{1}{N} |X_N(e^{j\omega})|^2$$

where

$$X_N(e^{j\omega}) = \sum_{n=0}^{N-1} x(n) e^{-j\omega n}.$$

That is, the periodogram can be calculated using the discrete-time Fourier transform of the observed data.

- (a) Write X_N in a form which shows that its value for a frequency ω_0 is obtained by filtering the observed signal $x(n)$ with some LSI-filter $h_{\omega_0}(n)$ and taking the value $y_{\omega_0}(0)$ from the filtered signal. In other words, determine the impulse response $h_{\omega_0}(n)$ so that for the frequency ω_0 ,

$$y_{\omega_0}(0) = [h_{\omega_0}(n) * x(n)]|_{n=0} = X_N(e^{j\omega_0}).$$

- (b) Write the frequency response $H_{\omega_0}(e^{j\omega})$ of the filter $h_{\omega_0}(n)$ in a form that makes it easy to consider the amplitude response $|H_{\omega_0}(e^{j\omega})|$ for different frequencies ω .

Hint: Try to write $H_{\omega_0}(e^{j\omega})$ so that it contains terms of the form $e^{j\omega_k} - e^{-j\omega_k} = 2j \sin \omega_k$ where ω_k is some frequency.

3. (Beamforming: estimation of the direction of arrival.) Assume that we have M sensors measuring a signal. The sensors are aligned in a row with a distance d from each other. A complex sinusoid with a known frequency ω arrives from a very distant source. We may assume that the source is so far away that the sinusoid forms a planar wave, and the signal arrives in all sensors from the same direction θ . The signal has a constant, finite, speed c .
 - (a) Compute the signal arriving at each sensor, as a function of the direction of arrival θ .
 - (b) Form a discrete signal by having each sensor measure the signal simultaneously at a fixed time t . The index is the number of the sensor. What is the spatial frequency (the frequency corresponding to the spatial index variable) of this signal? How would you solve θ ?
4. (Demonstration.) Assume that we observe a sinusoid in noise:

$$x(n) = A \exp(j\omega n) + v(n), \quad n = 0, 1, \dots, N-1$$

where A is a complex constant and $v(n)$ is white Gaussian noise. Estimate the frequency ω , the phase ϕ and the amplitude $|A|$ using the maximum likelihood method.

5. (Bonus point exercise)

Let $x(n)$, $n = 0, 1, \dots, N-1$ be real-valued zero mean normally distributed white noise with unit variance (i.e., $x(n) \sim N(0, 1)$ for all n).

- (a) Write the periodogram at the frequency $\omega = 0$ as a function of the observations.
- (b) Calculate the mean and variance of the periodogram of part (a), that is $E[\hat{P}_x(e^{0j})]$ and $\text{Var}(\hat{P}_x(e^{0j}))$. NB: Many results in the lecture slides concern complex white noise, while real-valued white noise behaves slightly differently.

Hints:

- $\text{Var}(z) = E[z^2] - E[z]^2$.
 - If $z \sim N(0, 1)$ then $E[z^4] = 3$.
- (c) Write the estimator given by the Bartlett method at the frequency $\omega = 0$ when the observations are partitioned into N subsequences with length $L = 1$. Calculate the mean and the variance of the estimator at the frequency $\omega = 0$.