

1 Introduction

Unweighted principal components analysis is performed by applying appropriate row and/or column centering and/or scaling to obtain suitable transformed matrix X and then solving for the singular value decomposition (SVD)

$$X = UDV^T \quad (1)$$

with the solution satisfying various relationships with the eigenvalue decompositions of the symmetric matrices $X^T X$ and XX^T ; for example,

$$XX^T U = U D^2 \quad (2a)$$

$$X^T X V = V D^2 \quad (2b)$$

One approach to weighted principal components analysis results from replacing the matrices $X^T X$ (proportional to the column-wise covariance matrix) with $X^T W^2 X$ and XX^T (proportional to row-wise covariance) with $W X X^T W$, where W is a diagonal matrix with w_{ii}^2 representing the weight assigned to row i .

Weighted problem then replaces (2) with

$$W X X^T W U = U D^2 \quad (3a)$$

$$X^T W^2 X V = V D^2 \quad (3b)$$

These weighted eigenproblems may be solved via the SVD of WX :

$$WX = UDV^T \quad (4)$$

(with U, V orthogonal and D diagonal), or

$$w_{ii} x_{ig} = \sum_q u_{iq} d_{qq} v_{gq} \quad (5)$$

2 Differentiate Eigenproblems

We are interested here in the changes ΔU , ΔD , and ΔV to U , D , and V which result from an infinitesimal change ΔW to the weight matrix W .

First note that

$$0 = (U + \Delta U)^T (U + \Delta U) - I = (\Delta U)^T U + U^T \Delta U \quad (6)$$

or

$$(\Delta U)^T U = -U^T \Delta U \quad (7)$$

shows that $(\Delta U)^T U$ is antisymmetric. Similarly, for V :

$$(\Delta V)^T V = -V^T \Delta V \quad (8)$$

Now,

$$(\Delta W) X X^T W + W X X^T (\Delta W) = (\Delta U) D^2 U^T + 2UD(\Delta D)U^T + UD^2(\Delta U)^T \quad (9)$$

Writing $M = (\Delta W) X X^T W + W X X^T (\Delta W)$, let's try

$$U^T M U = U^T \Delta U D^2 + 2D \Delta D + D^2 (\Delta U)^T U \quad (10a)$$

$$= U^T \Delta U D^2 + 2D \Delta D - D^2 U^T \Delta U \quad (10b)$$

or

$$\sum_{i,j} u_{iq} m_{ij} u_{jr} = \sum_i u_{iq} \Delta u_{ir} d_{rr}^2 - \sum_i u_{iq} \Delta u_{ir} d_{qq}^2 + 2\delta_{qr} d_{qq} \Delta d_{qq} \quad (11)$$

For $q = r$,

$$\sum_{i,j} u_{iq} m_{ij} u_{jq} = 2d_{qq} \Delta d_{qq} \quad (12)$$

implying

$$\Delta d_{qq} = \frac{\sum_{i,j} u_{iq} m_{ij} u_{jq}}{2d_{qq}} \quad (13)$$

For $q \neq r$,

$$\sum_{i,j} u_{iq} m_{ij} u_{jr} = \sum_i u_{iq} \Delta u_{ir} (d_{rr}^2 - d_{qq}^2) \quad (14)$$

or

$$\sum_i u_{iq} \Delta u_{ir} = \frac{1}{d_{rr}^2 - d_{qq}^2} \sum_{i,j} u_{iq} m_{ij} u_{jr} \quad (15)$$

Premultiplying by u_{kq} and summing over q ,

$$\Delta u_{kr} = u_{kr} \sum_i u_{ir} \Delta u_{ir} + \sum_{q \neq r} \frac{u_{kq}}{d_{rr}^2 - d_{qq}^2} \sum_{i,j} u_{iq} m_{ij} u_{jr} \quad (16)$$

but $\sum_i u_{iq} \Delta u_{ir} = -\sum_i \Delta u_{iq} u_{ir}$ implies that $\sum_i u_{ir} \Delta u_{ir} = 0$, so

$$\Delta u_{kr} = \sum_{q \neq r} \frac{u_{kq}}{d_{rr}^2 - d_{qq}^2} \sum_{i,j} u_{iq} m_{ij} u_{jr} \quad (17)$$

Similarly, defining $N = 2X^T W \Delta W X$

$$\Delta d_{qq} = \frac{\sum_{g,h} v_{gq} n_{gh} v_{hq}}{2d_{qq}} \quad (18)$$

and

$$\Delta v_{fr} = \sum_{q \neq r} \frac{v_{fq}}{d_{rr}^2 - d_{qq}^2} \sum_{g,h} v_{gq} n_{gh} v_{hr} \quad (19)$$

3 Differentiate SVD Directly

Analysis above complicated by non-square X . In this case, can use equations above for ΔD and whichever of ΔU or ΔV is square; the remaining derivative can be calculated directly from the definition of SVD:

$$(W + \Delta W) X = (U + \Delta U)(D + \Delta D)(V + \Delta V)^T \quad (20a)$$

$$\Delta W X = \Delta U D V^T + U \Delta D V^T + U D (\Delta V)^T \quad (20b)$$

$$\Delta U = \Delta W X V D^{-1} - U \Delta D D^{-1} - U D (\Delta V)^T V D^{-1} \quad (20c)$$

$$(\Delta V)^T = D^{-1} U^T \Delta W X - D^{-1} U^T \Delta U D V^T - D^{-1} \Delta D V^T \quad (20d)$$

4 Arbitrary Changes to X

In order to approximate the changes to the SVD under a perturbation $X \mapsto X + \Delta X$, replace equation (9) with

$$\Delta X X^T + X(\Delta X)^T = (\Delta U) D^2 U^T + 2UD(\Delta D)U^T + UD^2(\Delta U)^T \quad (21)$$

Defining $A = \Delta X X^T + X(\Delta X)^T$, we can follow the same logic as above to obtain

$$\Delta d_{qq} = \frac{\sum_{i,j} v_{iq} a_{ij} v_{jq}}{2d_{qq}} \quad (22a)$$

$$\Delta u_{kr} = \sum_{q \neq r} \frac{u_{kq}}{d_{rr}^2 - d_{qq}^2} \sum_{i,j} u_{iq} a_{ij} u_{jr} \quad (22b)$$

and, with $B = (\Delta X)^T X + X^T \Delta X$

$$\Delta d_{qq} = \frac{\sum_{g,h} v_{gq} b_{gh} v_{hq}}{2d_{qq}} \quad (23a)$$

$$\Delta v_{fr} = \sum_{q \neq r} \frac{v_{fq}}{d_{rr}^2 - d_{qq}^2} \sum_{g,h} v_{gq} b_{gh} v_{hr} \quad (23b)$$

Again, if X is not square, can use whichever of (22) or (23) deals with smaller matrix U or V and then obtain the remaining matrix directly from

$$X + \Delta X = (U + \Delta U)(D + \Delta D)(V + \Delta V)^T \quad (24a)$$

$$\Delta X = \Delta U D V^T + U \Delta D V^T + U D (\Delta V)^T \quad (24b)$$

$$\Delta U = \Delta X V D^{-1} - U \Delta D D^{-1} - U D (\Delta V)^T V D^{-1} \quad (24c)$$

$$(\Delta V)^T = D^{-1} U^T \Delta X - D^{-1} U^T \Delta U D V^T - D^{-1} \Delta D V^T \quad (24d)$$