

HacktheMachine.ai

Data Science & the Seven Seas: Collision Avoidance

Team Redhorse

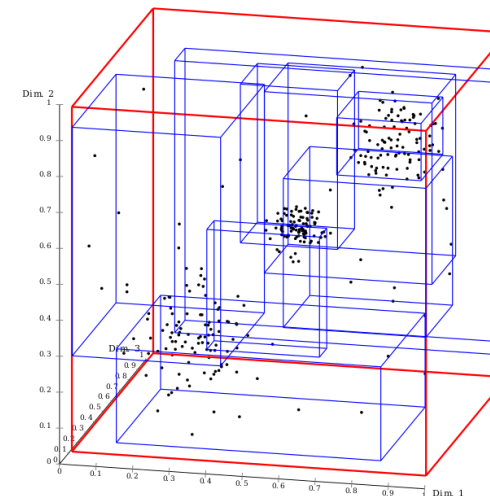
Preprocessing and Data Enrichment

- Focused on Backend and setting up a strong
- Able to fill in missing SOG and COG data
- Label ship encounters via COLREGs
- Set up PostgreSQL database with PostGIS plugin, to index ship routes via R-Trees, this resulted in a rapid spatial search
- Can efficiently search the 3D space for interactions with a CPA of 4nm

```
SELECT *  
FROM analysis AS t1,  
analysis AS t2  
WHERE St_intersects(t1."geom", t2."geom")  
= true  
AND t1."min_hour_basedate" =  
t2."min_hour_basedate"  
AND t1."mmsi" < t2."mmsi"  
AND t1."min_sog" > 1.0  
AND t2."min_sog" > 1.0;
```

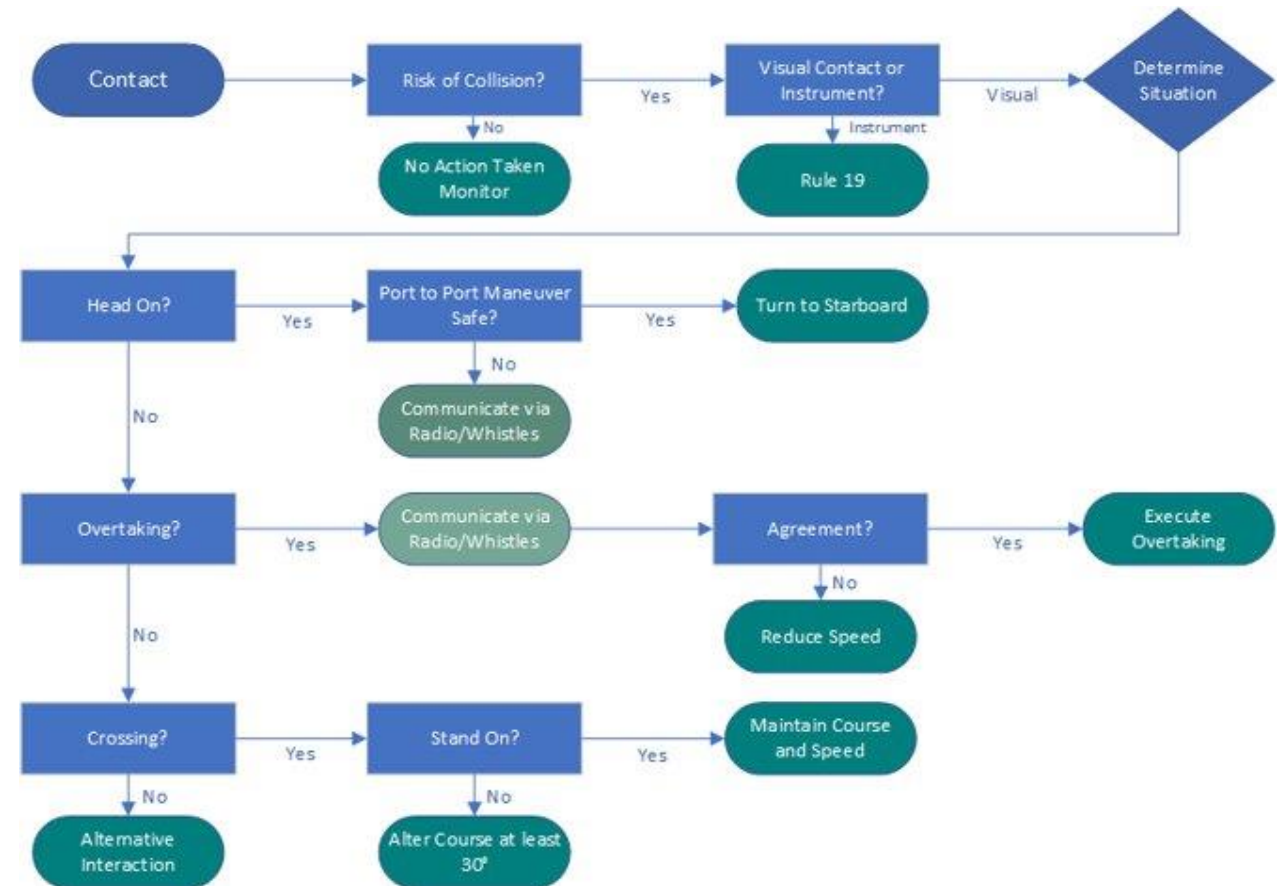
9/23/2018

Jodi Deprizio, Julia Fletcher, Dennis Silva Jr., John Michael Kovachi,
Joseph Haaga, Nicolas Westin, Brett Schultz, Eliot Voelker

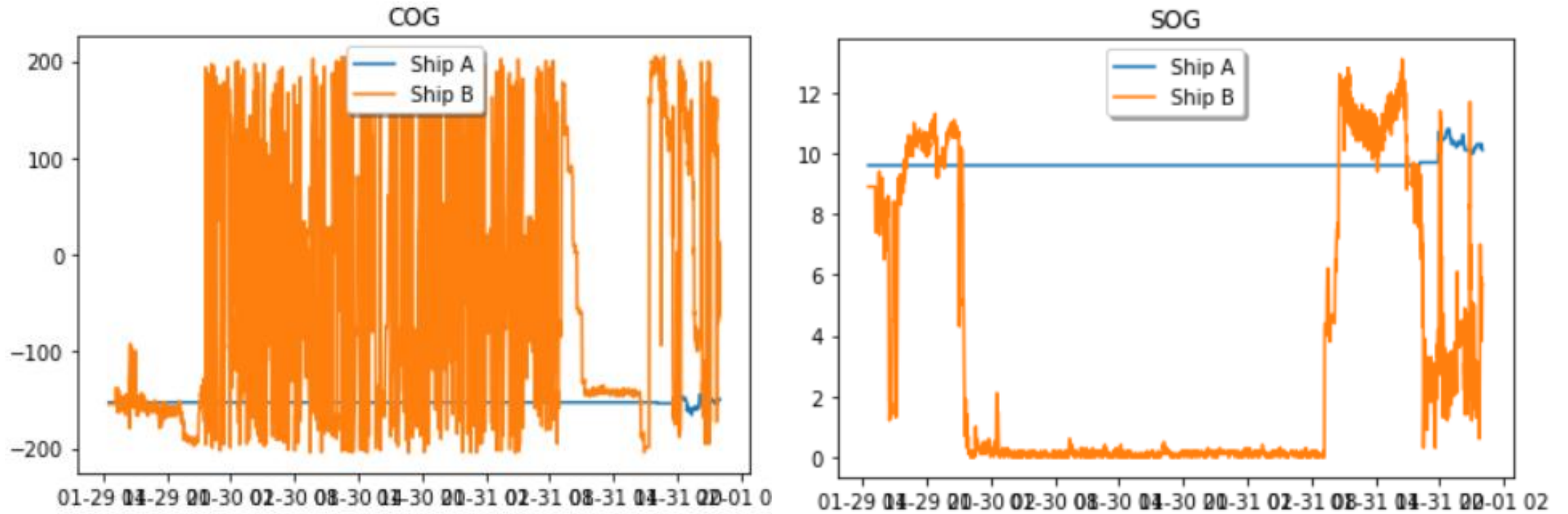


Exploratory Data Analysis

- Rules based approach used to define which COLREGS interaction is taking place
- Statistical analysis on change in SOG and COG
- Started to build a tool to compare the reported SOG and COG with a calculated SOG and COG based off GPS data



Statistical Analysis on Change in COG and SOG



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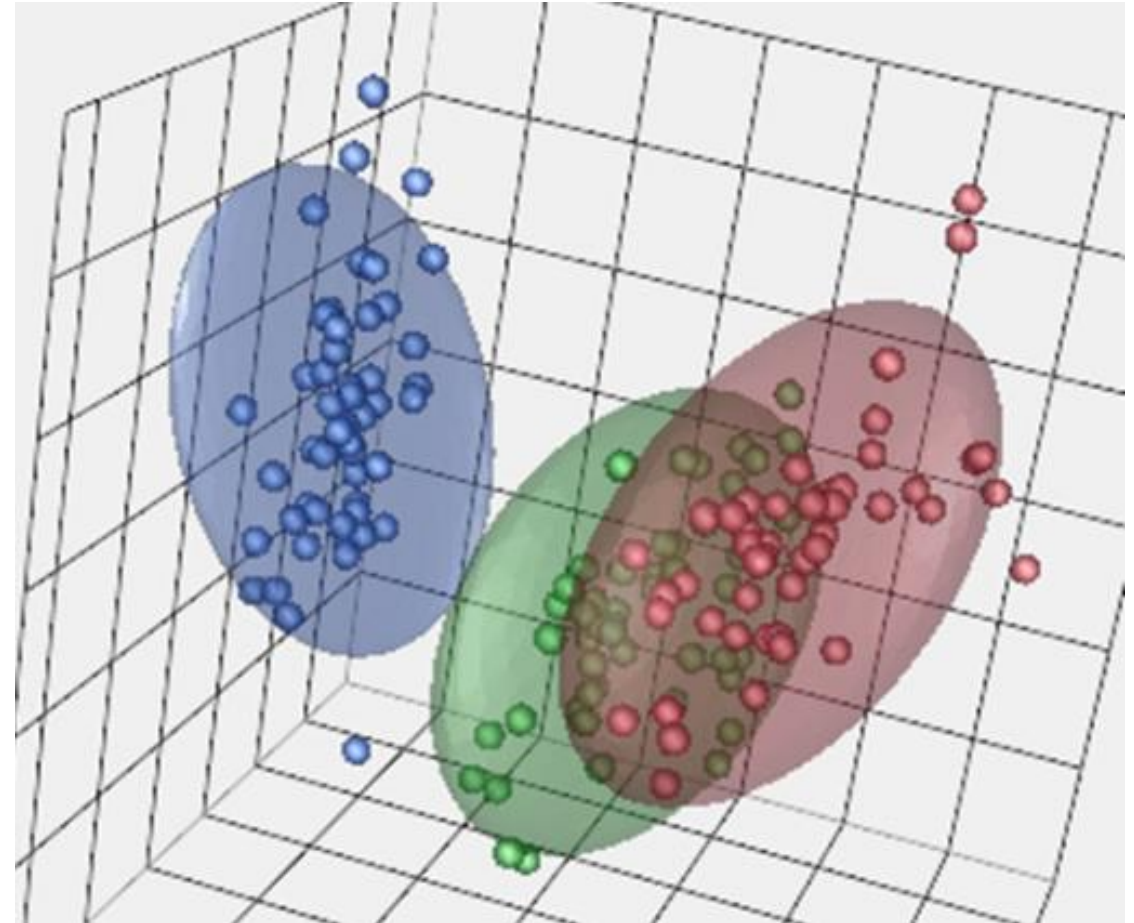
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Voelker

Machine Learning Approach

1. K-Means Clustering ($k=3$) on aggregate interactions to label them as Overtaking, Crossing, or MeetingHead-On
2. Decision Tree – Evaluate feature_importances in determining label of a particular interaction



ML Dataset Issues

- With such a large dimension of data within a 3D space, we end up running into the Curse of Dimensionality
- Running ML requires some sort of pattern recognition in the data
- Without previous knowledge of Naval ship interactions, important variables are unknown
- Data has so many dimensions that patterns are difficult to recognize without large datasets
 - Rate of data required to make insights rises exponentially with every new potential variable added

Further Work

- Post-processing to visualize the data tracks into ARCGIS
- Classified Machine Learning Approaches
 - Bayesian Classifier
 - Recurrent Neural Network with enforcement learning
- Integration of tools into a centralized application
- Automate creation of points to polygon via python script