$$Bu = \left(\frac{Ro}{Fr}\right)^2$$

$$\frac{D}{Dt} \left(\frac{\vec{\omega}_{\alpha} \cdot \nabla \theta}{\rho} \right) = 0$$

$$\frac{D}{Dt} \oint \vec{V} \cdot d\vec{r}$$

$$\mathbf{q} = \beta \mathbf{y} + \begin{bmatrix} \nabla^2 + \frac{\partial}{\partial \mathbf{z}} \left(\frac{\mathbf{f}_0^2}{N^2} \frac{\partial}{\partial \mathbf{z}} \right) \end{bmatrix} \mathbf{\psi} \\ \mathbf{APE} = \frac{\mathbf{g}}{2} \begin{bmatrix} \mathbf{f}_0^2 & \mathbf{g} \\ \mathbf{p} \end{bmatrix} \mathbf{p}^{\kappa - 1} \left(-\mathbf{g} \frac{\partial \overline{\theta}}{\partial \mathbf{p}} \right) \overline{\theta}$$

$$\frac{\mathrm{D}}{\mathrm{Dt}}(\zeta + \mathrm{f}) = -(\zeta + \mathrm{f})\left(\frac{\partial \mathrm{u}}{\partial x} + \frac{\partial \mathrm{v}}{\partial y}\right) + \left(\frac{\partial \mathrm{u}}{\partial z}\frac{\partial \mathrm{w}}{\partial y} - \frac{\partial \mathrm{v}}{\partial z}\frac{\partial \mathrm{w}}{\partial x}\right) + \frac{\mathrm{C}}{\rho^2}\left(\frac{\partial \rho}{\partial x}\frac{\partial \rho}{\partial y} - \frac{\partial \rho}{\partial y}\frac{\partial \rho}{\partial x}\right)$$

$$\vec{\omega} = \nabla \times \vec{v}$$

$$(\underbrace{\frac{\partial \rho}{\partial t}}_{c}) + \underbrace{(\underbrace{\tilde{\partial} \rho u}_{d} - \underbrace{k^{2}}_{d}) \underbrace{\tilde{\partial} \rho v}_{d})}_{dy} + \underbrace{(\beta - \underline{\partial \rho w}_{d})}_{dz} \underbrace{\underline{\tilde{\psi}}}_{\underline{\underline{\psi}}} = 0$$