

Tutorial3 ROSBag Link:

https://drive.google.com/file/d/1vnQ_LFLC7HVXAABdzMpm-54QAMhFz40n/view?usp=sharing

For the RealSense camera:

- **Install driver:**

```
sudo apt-get install ros-$ROS_DISTRO-realsense2-camera roslaunch realsense2_camera  
rs_camera.launch
```

- **Launch:**

```
roslaunch realsense2_camera rs_camera.launch
```