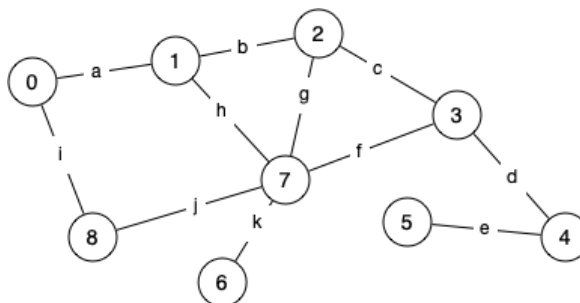


Week 05 Tutorial

Graphs (i)

[\[Show with no answers\]](#) [\[Show with all answers\]](#)

1. Consider the following graph



The edges are labelled simply for convenience in describing graph properties.

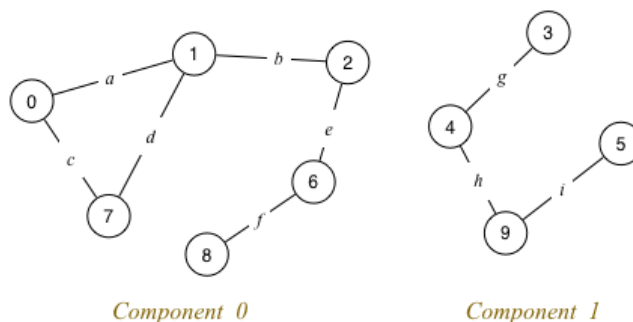
- How many edges does it have?
- How many *cycles* are there in the graph?
- How many *cliques* are there in the graph?
- What is the *degree* of each vertex?
- How many edges in the *longest* path from 5 to 8?
(without traversing any edge more than once)

[\[show answer\]](#)

2. What is the difference between a *connected* graph and a *complete* graph? Give simple examples of each.

[\[show answer\]](#)

3. Consider the following graph with multiple components:



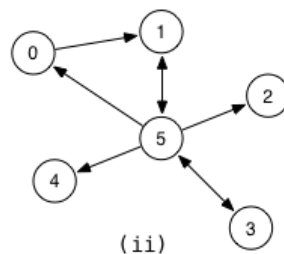
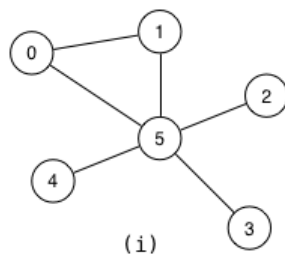
And a vertex-indexed connected components array that might form part of the Graph representation structure for this graph:

```
cc[] = {0, 0, 0, 1, 1, 1, 0, 0, 0, 1}
```

- show how the `cc[]` array would change if edge *d* was removed
- show how the `cc[]` array would change if edge *b* was removed
- show how the `cc[]` array would change if an edge was added between 2 and 4

[\[show answer\]](#)

4. For each of the following graphs:



Show the concrete data structures if the graph was implemented via:

- adjacency matrix representation (assume full $V \times V$ matrix)
- adjacency list representation (if non-directional, include both (v, w) and (w, v))

[\[show answer\]](#)

5. Consider the following map of streets in the Sydney CBD:



Represent this as a directed graph, where intersections are vertices and the connecting streets are edges. Ensure that the directions on the edges correctly reflect any one-way streets (this is a driving map, not a walking map). You only need to make a graph which includes the intersections marked with red letters. Some things that don't show on the map: Castlereagh St is one-way heading south and Hunter St is one-way heading west.

For each of the following pairs of intersections, indicate whether there is a path from the first to the second. If there is a path, enumerate it as a set of vertices. If there is more than one path, show two different paths.

- from intersection *D* on Margaret St to intersection *L* on Pitt St
- from intersection *J* to the corner of Margaret St and York St (intersection *A*)
- from the intersection of Margaret St and York St (*A*) to the intersection of Hunter St and Castlereagh St (*M*)
- from intersection *M* on Castlereagh St to intersection *H* on York St

[\[show answer\]](#)

6. Consider the following simple algorithm for web crawling:

```

crawl(startURL)
{
    add startURL to Queue
    while (Queue is not empty) {
        nextURL = remove head of Queue
        page = open(nextURL)
        while ((url = scanForHyperlinks(page)) != NULL) {
            if (alreadySeen(url)) continue
            add url to Queue
        }
    }
}

```

```

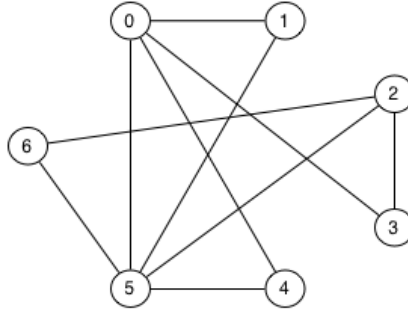
    }
}

```

Suggest how you might implement the `alreadySeen()` test.

[\[show answer\]](#)

7. Show what would be printed by the iterative depth-first and breadth-first traversals in the functions below on the following graph:



When choosing which neighbour to visit next, always choose the smallest unvisited neighbour. At each step, show the state of the Stack (DFS) or the Queue (BFS).

```

void breadthFirst (Graph g, Vertex v)
{
    int *visited = calloc (g->nV, sizeof (int));
    Queue q = newQueue ();
    QueueJoin (q, v);
    while (QueueLength (q) > 0) {
        Vertex x = QueueLeave (q);
        if (visited[x])
            continue;
        visited[x] = 1;
        printf ("%d\n", x);
        for (Vertex y = 0; y < g->nV; y++) {
            if (!g->edges[x][y])
                continue;
            if (!visited[y])
                QueueJoin (q, y);
        }
    }
}

```

```

void depthFirst (Graph g, Vertex v)
{
    int *visited = calloc (g->nV, sizeof (int));
    Stack s = newStack ();
    StackPush (s, v);
    while (!StackIsEmpty (s)) {
        Vertex x = StackPop (s);
        if (visited[x])
            continue;
        visited[x] = 1;
        printf ("%d\n", x);
        for (Vertex y = g->nV - 1; y >= 0; y--) {
            if (!g->edges[x][y])
                continue;
            if (!visited[y])
                StackPush (s, y);
        }
    }
}

```

Show the results for each of the following function calls:

```

depthFirst (g, 0);
depthFirst (g, 3);
breadthFirst (g, 0);
breadthFirst (g, 3);

```

[\[show answer\]](#)

8. Write a C function that takes a Graph and a starting Vertex and returns a set containing all of the vertices that can be reached by following a path from the starting point. Use the function template:

```

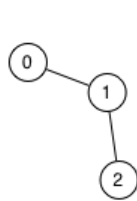
Set reachable (Graph g, Vertex v) { ... }

```

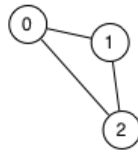
You may use any of the ADTs mentioned at the start of the tute questions.

[\[show answer\]](#)

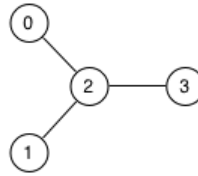
9. What is the difference between a Euler path/tour and a Hamilton path/tour? Identify any Euler/Hamilton paths/tours in the following graphs:



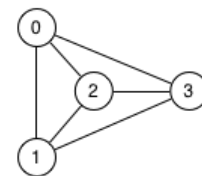
Graph 1



Graph 2



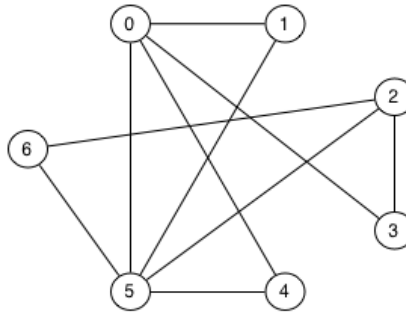
Graph 3



Graph 4

[\[show answer\]](#)

10. Find a Hamilton path and a Hamilton tour (if they exist) in the following graph:



If there is no Hamilton path or tour for the above graph, modify the edges so that such a path/tour exists.

[\[show answer\]](#)

11. Write a function to check whether a path, supplied as an array of Edges is an Euler path. Assume the function has interface:

```
bool isEulerPath (Graph g, Edge e[], int nE)
```

where $e[]$ is an array of nE edges, in path order.

[\[show answer\]](#)

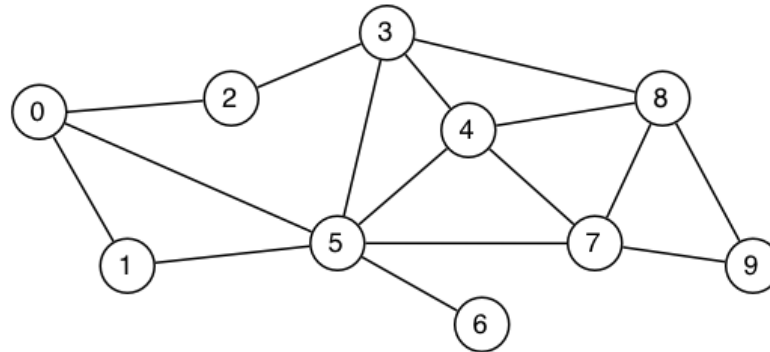
12. Using the following algorithm for finding a Hamiltonian path

```
hasHamiltonianPath(G,src,dest):
| input: graph G, plus src/dest vertices
| output: true if Hamiltonian path src...dest, false otherwise
|
| for all vertices v ∈ G do
|   visited[v]=false
| end for
| return hamiltonR(G,src,dest,#vertices(G)-1)

hamiltonR(G,v,dest,d)
| input: G    graph
|         v    current vertex considered
|         dest destination vertex
|         d    distance "remaining" until path found
|
| if v=dest then
| | if d=0 then return true else return false
| else
| | visited[v]=true
| | for each (v,w) ∈ edges(G) where not visited[w] do
| | | if hamiltonR(G,w,dest,d-1) then
| | | | return true
| | | end if
| | end for
| end if
```

```
| visited[v]=false  
| return false
```

trace the execution of the algorithm when searching for a Hamiltonian path from 1 to 6 on the following graph:



Consider neighbours in ascending order

[\[show answer\]](#)

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