Heapsort

- HeapSort
- Cost Analysis

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### HeapSort

Heapsort uses a priority queue (PQ) implemented as a heap.

Reminder: heap is a top-to-bottom ordered tree

• that has a simple implementation as an array of **Items** 

Reminder: priority queues ...

- implement a key-ordered queue structure
- items added to queue in arrival order
- items removed from queue in max-first order

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#### ... HeapSort

Heapsort (really PQ-sort) approach:

- insert all array items into priority queue
- one-by-one, remove all items from priority queue
- inserting each into successive array element

Priority queue operations ...

```
PQueue newPQueue();
void PQJoin(PQueue q, Item it);
Item PQLeave(PQueue q); // remove max Item
int PQIsEmpty(PQueue q);
```

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# ... HeapSort

Implementation of HeapSort:

```
void HeapSort(Item a[], int lo, int hi)
{
    PQueue pq = newPQueue();
    int i;
    for (i = lo; i <= hi; i++) {
        PQJoin(pq, a[i]);
    }
    for (i = hi; i >= lo; i--) {
        Item it = PQLeave(pq);
        a[i] = it;
    }
}
```

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... HeapSort

Problem: requires an additional data structure (O(N) space)

Recall that earlier we defined **fixDown()** 

• forces value at a[k] into correct position in heap

Allowed us to work with arrays as heap structures, hence as PQs.

Can we use these ideas to build an in-array PQ-sort?

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## ... HeapSort

#### Reminder: fixDown() function

```
// force value at a[i] into correct position in a[1..N]
// note that N gives max index *and* number of items
void fixDown(Item a[], int i, int N)
{
    while (2*i <= N) {
        // compute address of left child
        int j = 2*i;
        // choose larger of two children
        if (j < N && less(a[j], a[j+1])) j++;
        if (!less(a[i], a[j])) break;
        swap(a, i, j);
        // move one level down the heap
        i = j;
    }
}</pre>
```

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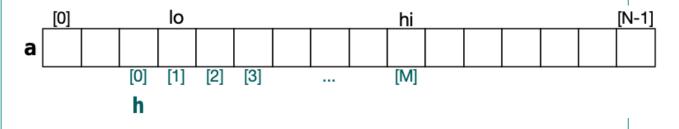
### ... HeapSort

Heapsort: multiple iterations over a shrinking heap

- initially use whole array as a heap
- uses **fixDown** to set max value at end
- reduce size of heap, and repeat

One minor complication: **a[lo..hi]** vs **h[1..M]** (where M=hi-lo+1)

To solve: pretend that heap starts one location earlier.



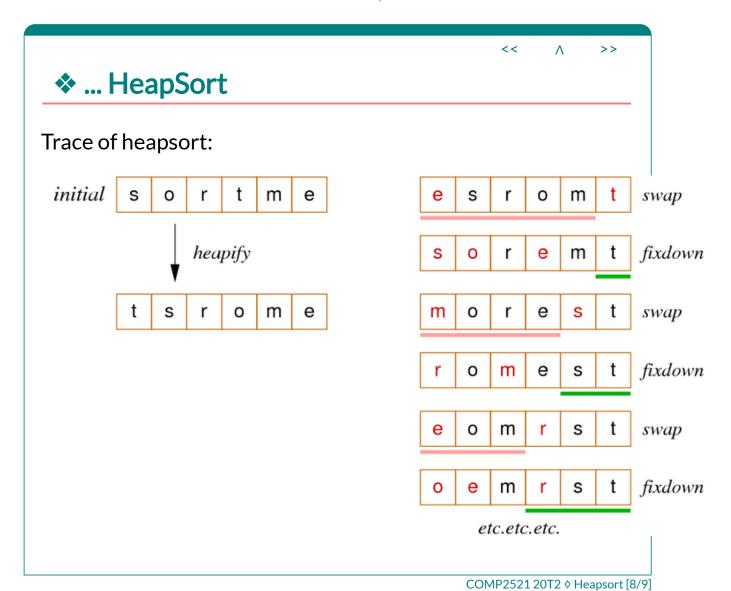
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## ... HeapSort

#### Heapsort algorithm:

```
void heapsort(Item a[], int lo, int hi)
{
   int i, N = hi-lo+1;
   Item *h = a+lo-1;    //start addr of heap
   // construct heap in a[0..N-1]
   for (i = N/2; i > 0; i--)
        fixDown(h, i, N);
   // use heap to build sorted array
   while (N > 1) {
        // put largest value at end of array
        swap(h, 1, N);
        // heap size reduced by one
        N--;
        // restore heap property after swap
        fixDown(h, 1, N);
   }
}
```

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www.cse.unsw.edu.au/~cs2521/20T2/lecs/heapsort/slides.html

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### Cost Analysis

#### Heapsort involves two stages

- build a heap in the array
  - iterates N/2 times, each time doing **fixDown()**
  - each fixDown() is O(logN), so overall O(NlogN)
  - o note: can write *heapify* more efficiently than we did O(N)
  - note: each fixDown() involves at most log<sub>2</sub>(2C + S)
- use heap to build sorted array
  - iterates N times, each time doing swap() and fixDown()
  - swap() is O(1), fixDown() is  $O(\log N)$ , so overall O(NlogN)

Cost of heapsort = O(NlogN)

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