

5. THE FAST FOURIER TRANSFORM

Raveen de Silva, r.desilva@unsw.edu.au

office: K17 202

Course Admin: Anahita Namvar, cs3121@cse.unsw.edu.au

School of Computer Science and Engineering UNSW Sydney

Term 3, 2021

Table of Contents

1. Revision

2. The Fast Fourier Transform

3. Puzzle

Given two polynomials of degree at most n,

$$P_A(x) = A_n x^n + ... + A_0 \text{ and } P_B(x) = B_n x^n + ... + B_0,$$

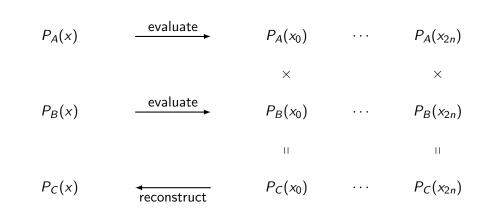
we want to find $P_C(x) = P_A(x) P_B(x)$.

1. Evaluate $P_A(x)$ and $P_B(x)$ at 2n + 1 distinct points

$$x_0, x_1, \ldots, x_{2n}$$

- 2. Multiply them point by point using 2n + 1 multiplications of large numbers, to get 2n + 1 values of $P_C(x)$
- 3. Reconstruct the coefficients of $P_C(x)$, i.e.

$$P_C(x) = C_{2n}x^{2n} + C_{2n-1}x^{2n-1} + \ldots + C_1x + C_0.$$



■ Previously, we chose $x_0, ..., x_{2n}$ to be the 2n + 1 integers which are the smallest by their absolute value, i.e.,

$$-n, -(n-1), \ldots, -1, 0, 1, \ldots, n-1, n.$$

However, this choice requires us to compute values such as

$$P_A(n) = A_0 + A_1 n + \ldots + A_{n-1} n^{n-1} + A_n n^n$$

As the degree n of the polynomials $P_A(x)$ and $P_B(x)$ increases, the value of n^n increases very fast and causes rapid increase of the computational complexity of the algorithm for polynomial multiplication which we used in the generalised Karatsuba algorithm.

Question

What values should we take for x_0, \ldots, x_{2n} to avoid "explosion" of size when we evaluate x_i^n while computing $P_A(x_i) = A_0 + A_1x + \ldots + A_nx_i^n$?

Answer

We would like $|x_i^n| = 1$, but this can't be achieved with only real numbers . . .

Let z=a+ib be a complex number, where $a,b\in\mathbb{R}$. Then we can define the

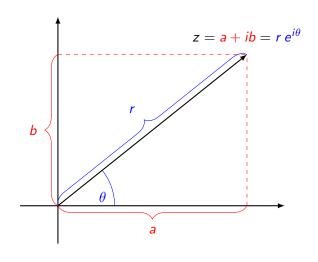
- modulus |z|, a positive real number r such that $r = \sqrt{a^2 + b^2}$ and
- argument arg z, an angle $\theta \in (-\pi, \pi]$ such that $a = r \cos \theta$ and $b = r \sin \theta$.

Then we have

$$z = a + ib$$

$$= r(\cos \theta + i \sin \theta)$$

$$= r e^{i\theta}.$$



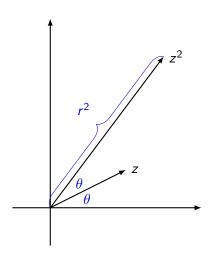
To multiply two complex numbers, we multiply the moduli and add the arguments.

Theorem

If
$$z = r e^{i\theta}$$
 and $w = s e^{i\phi}$, then $z w = (r s) e^{i(\theta + \phi)}$.

Corollary

In particular, if $z = r e^{i\theta}$ then $z^n = r^n e^{i(n\theta)}$.



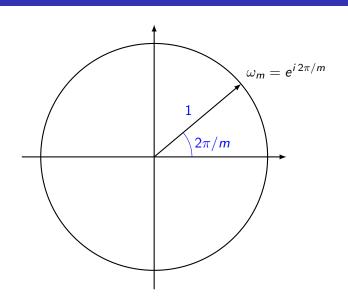
- We are interested in the solutions of $z^m = 1$, known as roots of unity of order m.
- Solving $r^m e^{i(m\theta)} = 1$, we see that

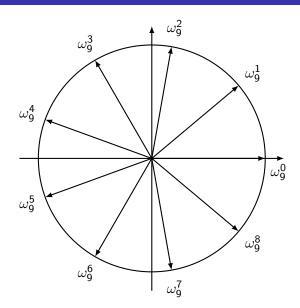
$$r^{m} = 1$$
, i.e. $r = 1$

and

$$m\theta = 2\pi k$$
 i.e. $\theta = \frac{2\pi k}{m}$.

- Let $\omega_m = e^{i \, 2\pi/m}$. Then $z = \omega_m^k$, i.e., all roots of unity of order m can be written as powers of ω_m . We say that ω_m is a primitive root of unity of order m.
- Note that there are only m distinct values here, as $\omega_m^m = \omega_m^0$





■ For $\omega_m = e^{i \, 2\pi/m}$ and for all k such that $0 \le k \le m-1$,

$$((\omega_m)^k)^m = (\omega_m)^{mk} = ((\omega_m)^m)^k = 1^k = 1.$$

■ Thus, $\omega_m^k = (\omega_m)^k$ is also a root of unity.

Theorem

 ω_m^k is a primitive root of unity of order n if and only if gcd(m, k) = 1.

■ The product of two roots of unity of order *m* is given by

$$\omega_{m}^{i}\omega_{m}^{j}=\omega_{m}^{i+j},$$

which is itself a root of unity of the same order.

- So the set of all roots of unity of order m, i.e., $\{1, \omega_m, \omega_m^2, \ldots, \omega_m^{m-1}\}$ is closed under multiplication (and by extension, under taking powers).
- Note that this is not true for addition, i.e., the sum of two roots of unity is NOT another root of unity!

Note

This is an example of a group.

Cancellation Lemma

For all positive integers k, m and integers ℓ , $\omega_{km}^{k\ell} = \omega_m^{\ell}$.

Proof

$$\omega_{km}^{k\ell} = \left(e^{i\frac{2\pi}{km}}\right)^{k\ell} = e^{i\frac{2\pi k\ell}{km}} = e^{i\frac{2\pi\ell}{m}} = \left(e^{i\frac{2\pi}{m}}\right)^{\ell} = \omega_m^{\ell}.$$

In particular, $(\omega_{2m}^k)^2 = \omega_{2m}^{2k} = (\omega_{2m}^2)^k = \omega_m^k$, i.e. the squares of the roots of unity of order 2m are just the roots of unity of order m.

Table of Contents

1. Revision

2. The Fast Fourier Transform

3. Puzzle

A new way to multiply polynomials fast

Given two polynomials of degree at most n,

$$P_A(x) = A_n x^n + ... + A_0 \text{ and } P_B(x) = B_n x^n + ... + B_0,$$

we want to find $P_C(x) = P_A(x) P_B(x)$.

1. Evaluate $P_A(x)$ and $P_B(x)$ at m=2n+1 distinct points

$$\omega_m^0, \omega_m^1, \dots, \omega_m^{m-1}$$

- 2. Multiply them point by point using 2n + 1 multiplications of large numbers, to get 2n + 1 values of $P_C(x)$
- 3. Reconstruct the coefficients of $P_C(x)$, i.e.

$$P_C(x) = C_{2n}x^{2n} + C_{2n-1}x^{2n-1} + \ldots + C_1x + C_0.$$

The Discrete Fourier Transform

Definition

Let $A = \langle A_0, A_1, \dots, A_{m-1} \rangle$ be a sequence of m real or complex numbers, and let the corresponding polynomial be $P_A(x) = \sum_{j=0}^{m-1} A_j x^j$.

Let $\widehat{A}_k = P_A(\omega_m^k)$ for all $0 \le k \le m-1$, the values of P_A at the roots of unity of order m.

The sequence of values $\widehat{A} = \langle \widehat{A}_0, \widehat{A}_1, \dots, \widehat{A}_{m-1} \rangle$ is called the **Discrete Fourier Transform (DFT)** of A.

The Discrete Fourier Transform

- Our polynomials $P_A(x)$ and $P_B(x)$ have degree n, so the corresponding sequences of coefficients have only n+1 terms.
- However, we defined the DFT of a sequence as having the same length as the original sequence, and we must obtain the values at all m roots of unity of order m.
- This is easily rectified by padding the sequences A and B with zeros at the end, corresponding to the terms $0x^{n+1} + 0x^{n+2} + \ldots + 0x^{2n}$, since m = 2n + 1.
- The DFT \widehat{A} of a sequence A can be computed VERY FAST using a divide-and-conquer algorithm called the **Fast Fourier Transform**.

We can now compute the DFTs of the two (0 padded) sequences:

$$DFT(\langle A_0, A_1, \dots, A_n, \underbrace{0, \dots, 0}_{n} \rangle) = \langle \widehat{A}_0, \widehat{A}_1, \dots, \widehat{A}_{m-1} \rangle$$

and

$$\textit{DFT}(\langle \textit{B}_0, \textit{B}_1, \dots, \textit{B}_n, \underbrace{0, \dots, 0}_{n} \rangle) = \langle \widehat{\textit{B}}_0, \widehat{\textit{B}}_1, \dots, \widehat{\textit{B}}_{m-1} \rangle$$

For each k we multiply the corresponding values $\widehat{A}_k = P_A(\omega_m^k)$ and $\widehat{B}_k = P_B(\omega_m^k)$, thus obtaining $\widehat{C}_{\nu} = \widehat{A}_{\nu}\widehat{B}_{\nu} = P_A(\omega_m^k)P_B(\omega_m^k) = P_C(\omega_m^k)$

■ We then use the inverse transformation for DFT, called IDFT, to recover the coefficients $\langle C_0, C_1, \ldots, C_{m-1} \rangle$ of the product polynomial $P_C(x)$ from the sequence $\langle \widehat{C}_0, \widehat{C}_1, \ldots, \widehat{C}_{m-1} \rangle$ of its

Question

How long does it take to compute the DFT of a sequence A, i.e. find the values

$$P_A(\omega_m^k) = A_0 + A_1 \omega_m^k + A_2 (\omega_m^k)^2 + \ldots + A_{m-1} (\omega_m^k)^{m-1}$$

for all k such that 0 < k < m?

Answer

Even if we were to precompute all powers of ω_m (recall, there are only m distinct values), there are m multiplications required for each of m values $P_A(\omega_m^k)$.

However, we can use divide-and-conquer to find all the required values in $O(n \log n)$ time!

• We can assume that m is a power of 2 - otherwise we can pad $P_A(x)$ with zero coefficients until its number of coefficients becomes equal to the nearest power of 2.

Exercise

Show that for every m which is not a power of two the smallest power of 2 larger or equal to m is smaller than 2m.

Hint

Consider *m* in binary. How many bits does the nearest power of two have?

Problem

Given a sequence $A = \langle A_0, A_1, \dots, A_{m-1} \rangle$, compute its DFT, i.e. find the values $P_A(x)$ at $x = \omega_m^k$ for all k such that $0 \le k < m$.

The main idea

We use divide-and-conquer by splitting the polynomial $P_A(x)$ into the even powers and the odd powers:

$$P_{A}(x) = (A_{0} + A_{2} x^{2} + A_{4} x^{4} + \dots + A_{m-2} x^{m-2})$$

$$+ (A_{1} x + A_{3} x^{3} + \dots + A_{m-1} x^{m-1})$$

$$= A_{0} + A_{2} x^{2} + A_{4} (x^{2})^{2} + \dots + A_{m-2} (x^{2})^{m/2-1}$$

$$+ x \left(A_{1} + A_{3} x^{2} + A_{5} (x^{2})^{2} + \dots + A_{m-1} (x^{2})^{m/2-1} \right)$$

Let us define $A^{[0]} = \langle A_0, A_2, A_4, \dots A_{m-2} \rangle$ and $A^{[1]} = \langle A_1, A_3, A_5, \dots A_{m-1} \rangle$, so that

$$P_{A^{[0]}}(y) = A_0 + A_2 y + A_4 y^2 + \dots + A_{m-2} y^{m/2-1}$$

$$P_{A^{[1]}}(y) = A_1 + A_3 y + A_5 y^2 + \dots + A_{m-1} y^{m/2-1}$$

and hence

$$P_A(x) = P_{A^{[0]}}(x^2) + x P_{A^{[1]}}(x^2)$$

Note that the polynomials $P_{A^{[0]}}(y)$ and $P_{A^{[1]}}(y)$ have m/2 coefficients each, while the polynomial $P_A(x)$ has m coefficients.

Question

Have we successfully reduced a problem of size m to a problem of size m/2?

- Problem of size m: Evaluate a polynomial with m coefficients at all roots of unity of order m.
- Problem of size m/2: Evaluate a polynomial with m/2 coefficients at all roots of unity of order m/2.

The original problem was to evaluate the polynomial $P_A(x)$ with m coefficients at inputs $x = \omega_m^k$ for each $0 \le k < m$. We have reduced it to the evaluation of two polynomials $P_{A^{[0]}}(y)$ and $P_{A^{[1]}}(y)$ each with m/2 coefficients at points

$$y = x^2 = \omega_m^{2k}.$$

Recall that we assumed m is a power of 2, and hence even.
We can therefore use the cancellation lemma

$$y = \omega_m^{2k} = \omega_{m/2}^k$$

to deduce that y is a root of unity of order m/2.

Note that k goes up to m-1, but there are only m/2 distinct roots of unity of order m/2. Since $\omega_{m/2}^{m/2}=1$, we can easily simplify the later terms as repetitions of the earlier terms.

Therefore we can write

$$P_{A}(\omega_{m}^{k}) = P_{A^{[0]}}\left((\omega_{m}^{k})^{2}\right) + \omega_{m}^{k} \cdot P_{A^{[1]}}\left((\omega_{m}^{k})^{2}\right)$$
$$= P_{A^{[0]}}\left(\omega_{m/2}^{k}\right) + \omega_{m}^{k} \cdot P_{A^{[1]}}\left(\omega_{m/2}^{k}\right).$$

■ Thus, we have reduced a problem of size m to two such problems of size m/2, plus a linear overhead to multiply the ω_m^k terms.

FFT algorithm

```
1: function FFT(A)
2: m \leftarrow \text{length}(A) % assumed to be a power of 2
3: if m = 1 then return A
4: else
5: A^{[0]} \leftarrow (A_0, A_2, \dots A_{m-2});
6: A^{[1]} \leftarrow (A_1, A_3, \dots A_{m-1});
7: y^{[0]} \leftarrow FFT(A^{[0]});
8: y^{[1]} \leftarrow FFT(A^{[1]});
9: \omega_m \leftarrow e^{i\frac{2\pi}{m}};
```

FFT algorithm

```
\omega \leftarrow 1; % a variable to hold powers of \omega_m
10:
                         for k = 0 to k = m/2 - 1 do:
11:

\% \underbrace{P_{A}\left(\omega_{m}^{k}\right)}_{y_{k}} = \underbrace{P_{A^{[0]}}\left(\omega_{m/2}^{k}\right)}_{v^{[0]}} + \underbrace{\omega_{m}^{k}}_{\omega} \underbrace{P_{A^{[1]}}\left(\omega_{m/2}^{k}\right)}_{v^{[1]}}

                                  y_k \leftarrow y_k^{[0]} + \omega \cdot y_k^{[1]};
12:
13:
                                  \omega \leftarrow \omega \cdot \omega_m:
                          end for
14:
```

FFT algorithm

How fast is the Fast Fourier Transform?

- We have recursively reduced evaluation of a polynomial $P_A(x)$ with m coefficients at m roots of unity of order m to evaluations of two polynomials $P_{A^{[0]}}(y)$ and $P_{A^{[1]}}(y)$, each with m/2 coefficients, at m/2 many roots of unity of order m/2.
- Once we get these m/2 values of $P_{A^{[0]}}(y)$ and $P_{A^{[1]}}(y)$ we need m additional multiplications to obtain the values of

$$\underbrace{P_{A}\left(\omega_{m}^{k}\right)}_{y_{k}} = \underbrace{P_{A^{[0]}}\left(\omega_{m/2}^{k}\right)}_{y_{k}^{[0]}} + \omega_{n}^{k} \underbrace{P_{A^{[1]}}\left(\omega_{m/2}^{k}\right)}_{y_{k}^{[1]}}$$

for all $0 \le k \le m$.

How fast is the Fast Fourier Transform?

- Thus, we have reduced a problem of size m to two such problems of size m/2, plus a linear overhead.
- Consequently, our algorithm's run time satisfies the recurrence

$$T(m)=2 T\left(\frac{m}{2}\right)+c m.$$

■ Case 2 of the Master Theorem gives $T(m) = \Theta(m \log m) = \Theta(n \log n)$.

Matrix representation of polynomial evaluation

The evaluation of a polynomial $P_A(x) = A_0 + A_1x + \ldots + A_{m-1}x^{m-1}$ at roots of unity ω_m^k of order m can be represented using the following matrix-vector product:

$$\underbrace{\begin{pmatrix} 1 & 1 & 1 & \cdots & 1 \\ 1 & \omega_{m} & \omega_{m}^{2} & \cdots & \omega_{m}^{m-1} \\ 1 & \omega_{m}^{2} & \omega_{m}^{2 \cdot 2} & \cdots & \omega_{m}^{2 \cdot (m-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \omega_{m}^{m-1} & \omega_{m}^{2(m-1)} & \cdots & \omega_{m}^{(m-1)(m-1)} \end{pmatrix}}_{A_{m}} \begin{pmatrix} A_{0} \\ A_{1} \\ A_{2} \\ \vdots \\ A_{m-1} \end{pmatrix} = \begin{pmatrix} P_{A}(1) \\ P_{A}(\omega_{m}) \\ P_{A}(\omega_{m}^{2}) \\ \vdots \\ P_{A}(\omega_{m}^{m-1}) \end{pmatrix}$$

The FFT is just a method of replacing this matrix-vector multiplication taking m^2 many multiplications with a $\Theta(m \log m)$ procedure.

Matrix representation of polynomial evaluation

- We also need a way to 'reconstruct' the coefficients from these values, i.e. perform the inverse DFT.
- Since *M* is a square Vandermonde matrix with distinct rows, it is invertible, so we can write:

$$\begin{pmatrix} A_0 \\ A_1 \\ A_2 \\ \vdots \\ A_{m-1} \end{pmatrix} = M^{-1} \begin{pmatrix} P_A(1) \\ P_A(\omega_m) \\ P_A(\omega_m^2) \\ \vdots \\ P_A(\omega_m^{m-1}) \end{pmatrix}.$$

■ How do we find M^{-1} ?

Claim

The inverse of matrix M is found by simply changing the signs of the exponents and dividing by m.

Let

$$Q = \frac{1}{m} \begin{pmatrix} 1 & 1 & 1 & \dots & 1 \\ 1 & \omega_m^{-1} & \omega_m^{-2} & \dots & \omega_m^{-(m-1)} \\ 1 & \omega_m^{-2} & \omega_m^{-2\cdot 2} & \dots & \omega_m^{-2\cdot (m-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \omega_m^{-(m-1)} & \omega_m^{-2(m-1)} & \dots & \omega_m^{-(m-1)(m-1)} \end{pmatrix}.$$

We need to prove that MQ = I(=QM), where I is the identity matrix.

When we multiply MQ, the (i,j) entry in the product matrix is given by the product of the ith row of M and the jth column of Q:

$$(MQ)_{i,j} = \frac{1}{m} \begin{pmatrix} 1 & \omega_m^i & \omega_m^{2\cdot i} & \cdots & \omega_m^{i\cdot (m-1)} \end{pmatrix} \begin{pmatrix} 1 & \omega_m^{-j} & \omega_m^{-2j} & \omega_m^{-2j} & \cdots & \omega_m^{-2j} & \cdots & \omega_m^{-2j} & \cdots & \cdots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ \omega_m^{-(m-1)j} \end{pmatrix}$$

$$= \frac{1}{m} \sum_{k=0}^{m-1} \omega_m^{ik} \omega_m^{-jk} = \frac{1}{m} \sum_{k=0}^{m-1} \omega_m^{(i-j)k}$$

We have established that $(MQ)_{i,j} = \frac{1}{m} \sum_{k=0}^{m-1} \omega_m^{(i-j)k}$. We now have two possibilities:

1. if i = j, then

$$(MQ)_{i,j} = \frac{1}{m} \sum_{k=0}^{m-1} \omega_m^0$$

= $\frac{1}{m} \sum_{k=0}^{m-1} 1$
= $\frac{1}{m} \cdot m = 1$;

2. if $i \neq j$, then $\sum_{k=0}^{m-1} \omega_m^{(i-j)k}$ represents the sum of a geometric progression with m terms and common ratio ω_m^{i-j} . Recalling that

$$1+r+r^2+\ldots+r^{m-1}=\frac{1-r^m}{1-r},$$

we have

$$(MQ)_{i,j} = \frac{1}{m} \cdot \frac{1 - \omega_m^{(i-j)m}}{1 - \omega_m^{i-j}}$$

$$= \frac{1}{m} \cdot \frac{1 - (\omega_m^m)^{i-j}}{1 - \omega_m^{i-j}}$$

$$= \frac{1}{m} \cdot \frac{1 - 1}{1 - \omega_m^{i-j}} = 0.$$

We have now proven that

$$(MQ)_{i,j} = \begin{cases} 1 & \text{if } i = j \\ 0 & \text{otherwise} \end{cases}$$

that is, MQ = I. Therefore Q is the inverse of M, i.e.

$$M^{-1} = \frac{1}{m} \begin{pmatrix} 1 & 1 & 1 & \dots & 1 \\ 1 & \omega_m^{-1} & \omega_m^{-2} & \dots & \omega_m^{-(m-1)} \\ 1 & \omega_m^{-2} & \omega_m^{-2 \cdot 2} & \dots & \omega_m^{-2 \cdot (m-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \omega_m^{-(m-1)} & \omega_m^{-2(m-1)} & \dots & \omega_m^{-(m-1)(m-1)} \end{pmatrix}.$$

So we get

$$\begin{pmatrix} A_0 \\ A_1 \\ A_2 \\ \vdots \\ A_{m-1} \end{pmatrix} = \frac{1}{m} \begin{pmatrix} 1 & 1 & 1 & \dots & 1 \\ 1 & \omega_m^{-1} & \omega_m^{-2} & \cdots & \omega_m^{-(m-1)} \\ 1 & \omega_m^{-2} & \omega_m^{-2\cdot 2} & \cdots & \omega_m^{-2\cdot (m-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \omega_m^{-(m-1)} & \omega_m^{-2(m-1)} & \cdots & \omega_m^{-(m-1)(m-1)} \end{pmatrix} \begin{pmatrix} P_A(1) \\ P_A(\omega_m) \\ P_A(\omega_m^2) \\ \vdots \\ P_A(\omega_m^{m-1}) \end{pmatrix}.$$

This is not so different to the original matrix-vector product!

The Inverse Fast Fourier Transform

The 'reconstruct' step requires us to convert from the sequence of values

$$\langle P_A(1), P_A(\omega_m), P_A(\omega_m^2), \dots, P_A(\omega_m^{m-1}) \rangle$$

which we denoted by

$$\langle \widehat{A}_0, \widehat{A}_1, \widehat{A}_2, \dots, \widehat{A}_{m-1} \rangle$$

back to the sequence of coefficients

$$\langle A_0, A_1, A_2, \ldots, A_{m-1} \rangle$$

i.e. to compute the inverse DFT. We can use **the same** FFT algorithm with just two changes:

- 1. the root of unity ω_m is replaced by $\overline{\omega_m} = e^{-i\frac{2\pi}{m}}$,
- 2. the resulting output values are divided by m.

Inverse Fast Fourier Transform (IFFT)

```
1: function IFFT*(\widehat{A})
      m \leftarrow \operatorname{length}(A)
2:
     if m=1 then return \widehat{A}
3:
          else
4:
                     \widehat{A}^{[0]} \leftarrow (\widehat{A}_0, \widehat{A}_2, \dots \widehat{A}_{m-2});

\widehat{A}^{[1]} \leftarrow (\widehat{A}_1, \widehat{A}_3, \dots \widehat{A}_{m-1});
5:
6:
                     v^{[0]} \leftarrow IFFT^*(\widehat{A}^{[0]});
7:
                    y^{[1]} \leftarrow IFFT^*(\widehat{A}^{[1]});
8:
                    \omega_m \leftarrow e^{-i\frac{2\pi}{m}}
                                                                                            different from FFT
9:
```

Inverse Fast Fourier Transform (IFFT)

```
10:
                 \omega \leftarrow 1:
                 for k = 0 to k = m/2 - 1 do;
11:
                      y_k \leftarrow y_k^{[0]} + \omega \cdot y_k^{[1]};
12:
13:
                       \omega \leftarrow \omega \cdot \omega_m;
                 end for
14:
                 for k = 0 to k = m/2 - 1 do;
15:
                      y_{m/2+k} \leftarrow y_k^{[0]} + \omega \cdot y_k^{[1]}
16:
17:
                       \omega \leftarrow \omega \cdot \omega_m:
                 end for
18:
19:
                 return y;
           end if
20:
21: end function
```

Inverse Fast Fourier Transform (IFFT)

```
1: function IFFT(\widehat{A})
2: return IFFT^*(\widehat{A})/length(\widehat{A})
```

- 3: end function

Important note

Computer science books take the forward DFT operation to be the evaluation of the corresponding polynomial at all roots of unity $\omega_m^k = \exp(2\pi k\,i/m)$ and the inverse DFT to be the evaluation of the polynomial at the complex conjugates of the roots of unity, i.e. at $\omega_m^{-k} = \exp(-2\pi k\,i/m)$.

However, electrical engineering books do the opposite, with the direct DFT evaluating the polynomial at ω_m^{-k} and the inverse DFT at ω_m^k .

While for the purpose of multiplying polynomials both choices are equally good, the choice made by the electrical engineers is otherwise better. This will be explained in COMP4121 Advanced & Parallel Algorithms in the context of JPEG compression.

Important note

We did only the multiplication of polynomials, and did not apply it to multiplication of large integers. This is possible to do but one has to be careful because roots of unity are represented by floating point numbers. You have to show that if you do FFT with sufficient precision you can round off the results and obtain correct integer values, but all of this is tricky.

Earlier results along this line produced algorithms for multiplication of large (i.e. n-bit) integers which operate in time $\Theta(n \log n \log \log n)$ but very recently David Harvey of the School of Mathematics at UNSW came up with an algorithm to multiply large integers which runs in time $\Theta(n \log n)$.

Back to fast multiplication of polynomials

$$P_{A}(x) \qquad \frac{\text{DFT}}{\Theta(n \log n)} \qquad \widehat{A} \qquad \times \\ P_{B}(x) \qquad \frac{\text{DFT}}{\Theta(n \log n)} \qquad \widehat{B} \qquad \Theta(n) \\ P_{C}(x) \qquad \frac{\text{IDFT}}{\Theta(n \log n)} \qquad \widehat{C}$$

Back to fast multiplication of polynomials

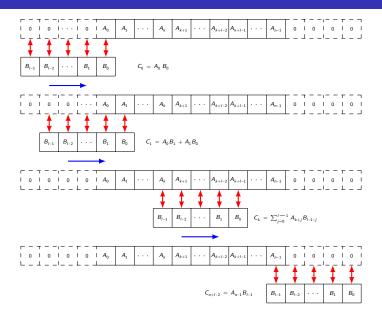
- We can now compute the product $P_C(x) = P_A(x) P_B(x)$ of two polynomials $P_A(x)$ and $P_B(x)$ in time $\Theta(n \log n)$.
- Recall that the coefficients of $P_C(x)$ are given by

$$C_t = \sum_{i+j=t} A_i B_j.$$

The coefficient sequence C is the convolution of the sequences A and B, denoted $A \star B$.

- So we can find the convolution of two *n*-term sequences in $\Theta(n \log n)$.
- Indeed, none of this requires that the two sequences be of the same length!

Visualizing Convolution $C = A \star B$



An Exercise

Problem

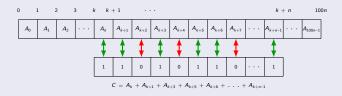
Suppose you are given a map of a straight sea shore of length 100n meters as a sequence on 100n numbers such that A_i is the number of fish between i^{th} meter of the shore and $(i+1)^{th}$ meter, $0 \le i \le 100n-1$.

You also have a net of length n meters but unfortunately it has holes in it. The net is described as a sequence N of n ones and zeros, where 0's denote where the holes are.

If you throw the net starting at meter k and ending at meter k+n, then you will catch only the fish in one meter stretches of the shore where the corresponding bit of the net is 1.

An Exercise

Problem (continued)



Find the spot where you should place the left end of your net in order to catch the largest possible number of fish using an algorithm which runs in time $O(n \log n)$.

Hint

Let N' be the net sequence N in the reverse order. Compute $A \star N'$ and look for the peak of that sequence.

Table of Contents

1. Revision

2. The Fast Fourier Transform

3. Puzzle

PUZZLE!!

On a circular highway there are *n* petrol stations, unevenly spaced, each containing a different quantity of petrol. It is known that the total quantity of petrol on all stations is enough to go around the highway once, and that the tank of your car can hold enough fuel to make a trip around the highway.

Prove that there always exists a station among all of the stations on the highway, such that if you take it as a starting point and take the fuel from that station, you can continue to make a complete round trip around the highway, never emptying your tank before reaching the next station to refuel.



That's All, Folks!!