

## Question 5 by Dan Nguyen (z5206032)

There is a given directed graph,  $G(V, E)$ , where each edge,  $e$ , has a weight,  $0 < w_e < 1$ .

The *safety* of a path from  $u$  to  $v$  with edges  $e_1, e_2, \dots, e_k$  is  $\prod_{i=1}^k w_{e_i}$ .

Let there be a matrix,  $D$ , which is initialised by  $G$ 's adjacency matrix representation.

Consider a modified Floyd-Warshall algorithm which stores the *safety* from  $u$  to  $v$  in  $D$  instead of the distance, and the maximum *safety* is preferred i.e. the computed *safety* replaces the original *safety* if the computed value is greater than the original.

Define  $Q(i, j, k)$  as the problem of finding the *safety* from a node  $i$  to  $j$  for  $G[1..k]$  ending with  $G[k]$ .

Define  $\text{opt}(i, j, k)$  as the solution to  $Q(i, j, k)$ .

For all  $1 \leq i, j \leq n$ , and  $0 \leq k \leq n$ , solve for  $Q(i, j, k)$  using dynamic programming where the recurrence is:

$$\text{opt}(i, j, k) = \max\{\text{opt}(i, j, k-1), \text{opt}(i, k, k-1) + \text{opt}(k, j, k-1)\}$$

The base case is:

$$\text{opt}(i, j, 0) = \begin{cases} 1 & \text{if } i = j \\ w(i, j) & \text{if } (i, j) \in E \\ 1 & \text{otherwise} \end{cases}$$

The order of solving  $Q$  is important i.e. subproblems with lesser  $i$  and  $j$  are solved first.

The final answer is:

$$\text{opt}(n, n, k) = \max\{\text{opt}(n, n, k-1), \text{opt}(n, k, k-1) + \text{opt}(k, n, k-1)\}$$

The Floyd-Warshall algorithm has a worst time complexity of  $O(|V|^3) = O(n^3)$  for  $G$  with  $n$  vertices.

For a set of ordered pairs of vertices,  $S = \{(u_1, v_1), \dots\}$ ,  $S$  has a capacity of  $n^2$  pair combinations since there are  $n$  vertices in  $G$ . Looking up  $D(u, v)$  for the maximum *safety* from  $u$  to  $v$  for at worst  $n^2$  pair combinations has a time complexity of  $O(n^2)$ .

The overall worst time complexity is  $O(n^3) + O(n^2) = O(n^3)$  as required.