

# Dan Huy NGUYEN

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## EDUCATION

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### University of New South Wales

Feb 2018 – Dec 2023

*Bachelor of Engineering (Hons) (Mechatronics) / Bachelor of Science (Computer Science)*

- Cumulative WAM of 81.758.
- Notable courses: DESN2000(99), ENGG3600 (94), MATH2019 (93).

### Patrician Brothers' College Fairfield

Oct 2017

*Higher School Certificate*

- ATAR of 94.25.
- Subjects: Extension 2 Mathematics, Extension 1 Mathematics, Chemistry, Physics, English Advanced.

## WORK EXPERIENCE

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### UNSW

*Casual Academic*

Sep 2021 – Current

- Lab demonstrator for first-year to post-graduate engineering courses (DESN1000, MTRN2500, MTRN3100, MTRN4110, COMP9024) with an average satisfaction rate of 95%.
- Course planner for robotics courses (MTRN2500, MTRN3100, MTRN4231) involving curriculum development and creation of teaching content for labs and assessments.
- Utilised modern tools to efficiently develop and deliver content to students e.g. Make, GitHub Actions, GitHub Classrooms, and custom sandboxed C++ autotester.

### Sperospace

*Mechanical Engineering Intern*

Jul 2021 – Oct 2021

- Generation and evaluation of end effector concepts using brainstorming, pair-wise comparison charts, and best-of-class matrices.
- Designed end effector rated for technology readiness level 3 for use in space applications.

## PROJECT EXPERIENCE

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### Sumobots

*Sumoltaneous Equations*

May 2022 – July 2022

- Organised team to deliver 1<sup>st</sup> place winning sumobot in MTRNSoc x CREATE Sumobots Competition Advanced Stream.
- Developed and delegated work breakdown structure using waterfall engineering method.
- Participated in concept generation of solution and requirements.
- Soldered and assembled electrical system.
- Implemented robot software architecture and control loop.

### UNSW Competitive Robotics Group

*Robotics Student Engineer*

Sep 2021 – June 2022

- Created ROS control, description, and gazebo packages for end effector and combined UAV/end effector robots.
- Modelled CAD artefacts with URDF/Xacro/SDF for Gazebo simulation.
- Assisting project management with MS Teams management and WBS development.

### Offworld Robotics

*Project Manager*

Dec 2020 – June 2022

- Supervision of a leadership team to conduct operations with respect to project management plan and systems engineering management plan.
- Centralisation and refinement of processes, structures, documentation, and workflows onto GitLab to improve organisational efficiency and standardise quality.
- Development of a learning curriculum covering design and implementation of robotic systems for upskilling of Offworld Robotics students.

*Mechanical & Manufacturing Student Engineer*

**Jan 2020 – Dec 2020**

- Designed ladder-frame chassis, bogie suspension, and limited-slip differential under a hybrid agile-waterfall design process for rapid iteration and 3D-printing manufacturing.
- Simulated and optimised parts in various loading conditions with FEA.
- Invented unique differential as proof-of-concept of kinematic mechanisms for integration with bogie suspension.

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## EXTRACURRICULAR

### CSESoc Peer Mentoring

*Peer Mentor*

**Feb 2022 – May 2022**

- Assisted student transition into university life and strategising their degree plan.
- Help students setup development environments utilising SSH, VSCode, and C build tools.

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## COMPETITION EXPERIENCE

### Accenture Technology Bootcamp

**Feb 2022**

- Developed a proof-of-concept "GitLab Team Management" application in Django/Python connecting to GitLab API to enhance people management capabilities.

### WIESoc x IBM Hackathon

**Oct 2020**

- Developed prize-winning "COVID Safe Link" website in Flask/Python connecting to Google Maps API and NSW Open Data Platforms to plan safe travel through populated areas and public transport.

### WIESoc x Aurecon Design Challenge

**Sep 2019**

- Conceptualised an innovative solution to assist unconfident and learning drivers in adapting to high-speed lane mergers and intersection turns.

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## VOLUNTEER EXPERIENCE

### Engineering World Health Summer Institute

*Biomedical Equipment Technician*

**Dec 2018 – Feb 2019**

- Trained in student volunteer program in Cambodia with acquired skills in soldering, mechanical and electrical repairs of biomedical equipment.
- Repaired and returned to service twenty-seven hospital equipment in four-week rural hospital placement.
- Built AC-to-DC rectifier to extensively test electrical circuits of biomedical equipment.

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## ACADEMIC PROJECTS

### COMP6080 – Web Front-End Programming

**Feb 2023 – Mar 2023**

- Designed a React-inspired architectural model in Vanilla JS for a job seeker website.

### COMP3900 – Computer Science Project

**Feb 2022 – May 2022**

- Revamped "GitLab Team Management" Django project with full-stack boilerplate and upskilled team on Django framework.
- Implemented SSO with GitLab web service using django-oidc, GitLab API calls on top of requests library, text search with django-haystack, and object-level permissions with django-rules.

### MTRN4110 – Robot Design

**May 2021 – Sep 2021**

- Architected the robot software for a maze-solving robot with autonomous navigation using world imaging data processed with OpenCV.
- Hacked Webots build platform to simultaneously execute C++ and Python programs with Cython interface.

#### **MTRN3500 – Computing Applications in Mechatronics Systems**

**May 2020 – Sep 2020**

- Developed multi-process application for LiDAR and GNSS processing, and teleoperation of a robot using shared memory IPC.
- Built TCP/IP client with WinSock2 to connect to robot over WiFi.
- Designed GUI to visualise robot data processing and motion using OpenGL.

#### **COMP1531 – Software Engineering Fundamentals**

**Feb 2020 – May 2020**

- Developed back-end and API in Flask/Python for a Slack-like application achieving a project mark of 97.

#### **ACHIEVEMENTS**

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|--|-------------|
| • UNSW Dean's Honours List.                              | <b>2021</b> |
| • UNSW Dean's Honours List.                              | <b>2020</b> |
| • UNSW Dean's Honours List.                              | <b>2019</b> |
| • New Colombo Plan Scholarship Recipient.                | <b>2018</b> |
| • RACI NSW Schools Titration Competition – Silver Award. | <b>2017</b> |
| • Corporal of Australian Army Cadets.                    | <b>2016</b> |

#### **TECHNICAL SKILLS**

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##### **Robotics**

- ROS, RViz, Gazebo.
- Webots.
- URDF, SDF.

##### **Software Development**

- C++20 (Catch2, GoogleTest, doctest, GoogleBenchmark).
- Python.
- HTML, CSS, Javascript
- MATLAB (Simulink).
- Assembly (MIPS).
- git (GitHub, GitLab).
- GitHub Actions
- VSCode, Visual Studio.
- WSL, Ubuntu, Debian, Windows 10.

##### **Mechanical & Manufacturing**

- 3D CAD (Solidworks, Autodesk Inventor Professional, Fusion360).
- Manual metal machining (Lathe, Mill).
- 3D-printing.
- Laser cutting (Trotec).
- Water jet cutting (ProtoMAX).

##### **Office**

- Microsoft Office (Outlook, Word, Excel, PowerPoint, Teams, SharePoint, Planner, Forms).
- GitLab.
- L<sup>A</sup>T<sub>E</sub>X, ConT<sub>E</sub>Xt.
- Markdown (Mermaid, GitLab Flavoured).

#### **CERTIFICATIONS**

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##### **Coursera | Google – Foundations of Project Management**

**Oct 2021**

##### **TAFE Statement in UNSW Engineering Mechanical**

**Nov 2019**

- Use Hand Tools.
- Use Workshop Machines for Basic Operation.