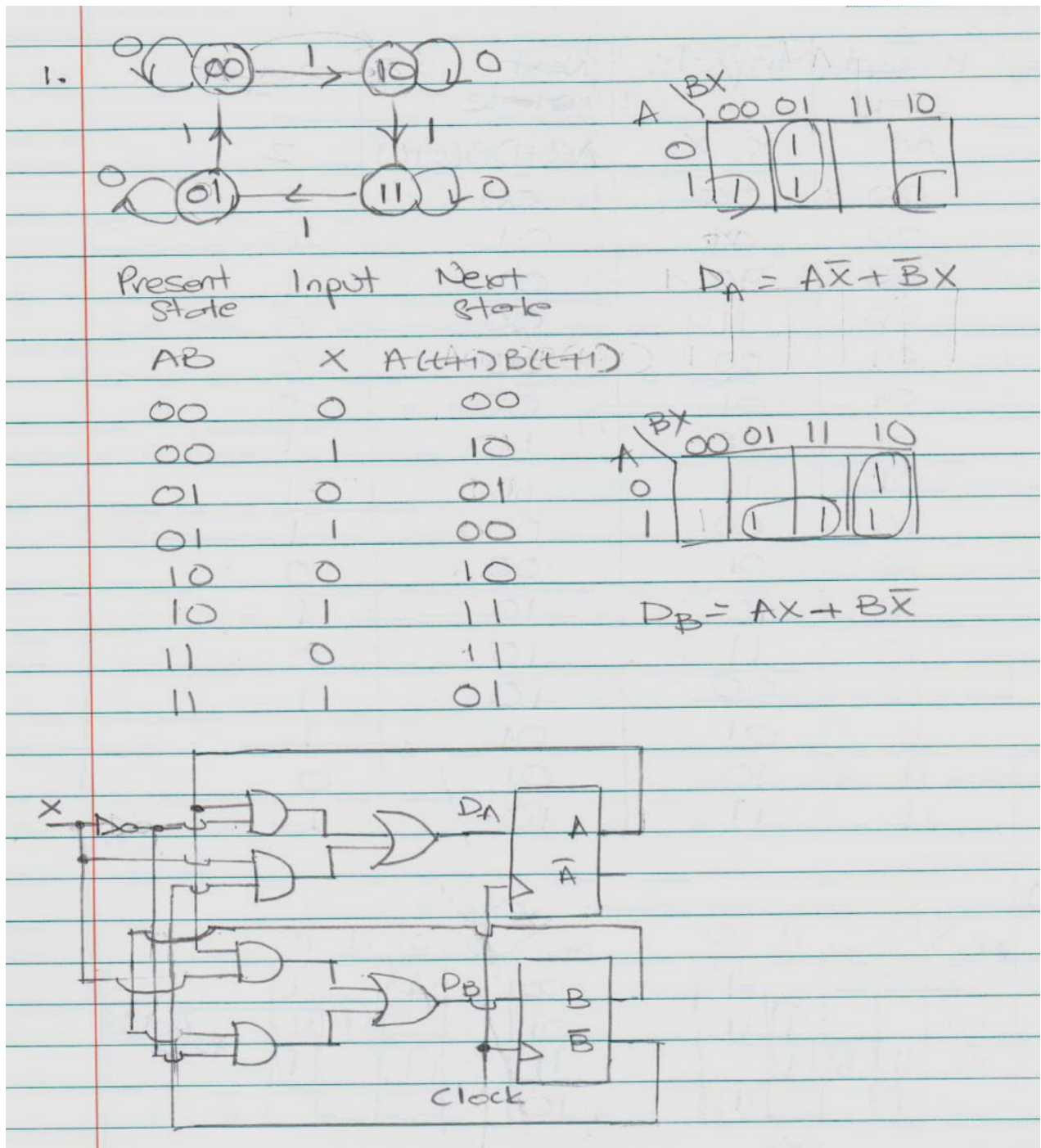


1.



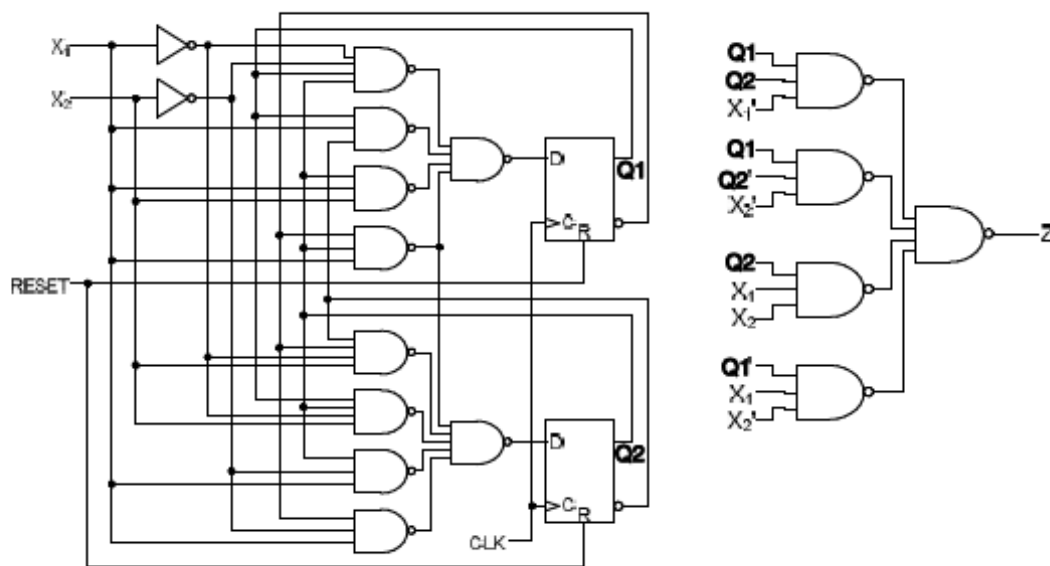
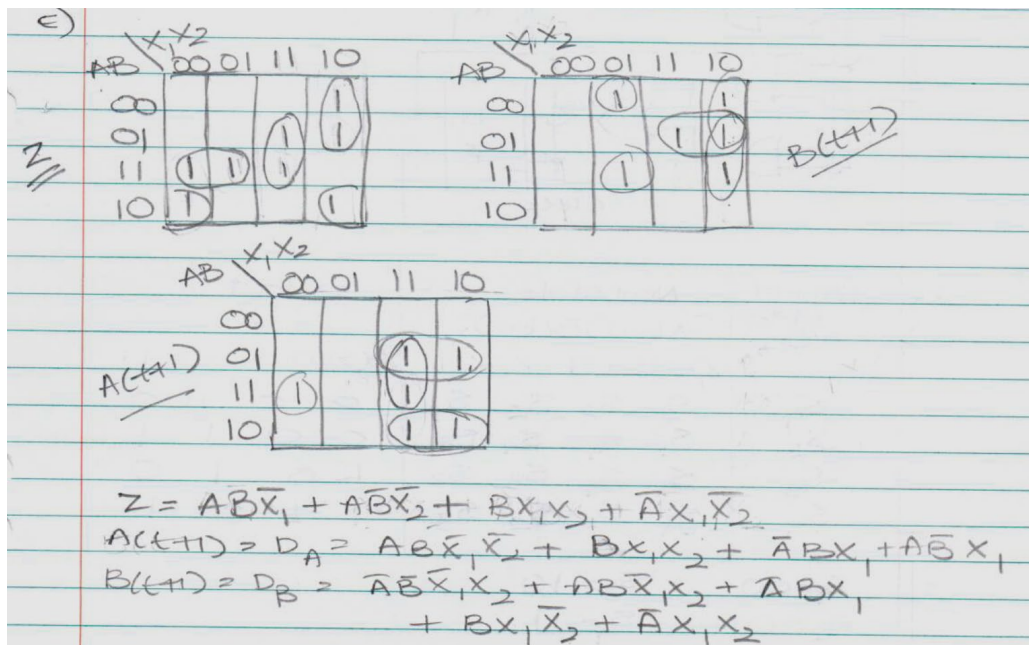
2.

| 2. | Present state | Next state | output |
|----|---------------|-------------------------|-------------------------|
| a) | AB | $A(t+1)B(t+1)$ | Y |
| | | $X_1X_2=00\ 01\ 10\ 11$ | $X_1X_2=00\ 01\ 10\ 11$ |
| | S_1 | $S_1\ S_2\ S_2\ S_1$ | 0 0 1 0 |
| | S_2 | $S_1\ S_1\ S_4\ S_4$ | 0 0 1 1 |
| | S_3 | $S_1\ S_1\ S_3\ S_3$ | 1 0 1 0 |
| | S_4 | $S_4\ S_2\ S_2\ S_3$ | 1 1 0 1 |
| | $S_1=00$ | $S_3=10$ | |
| | $S_2=01$ | $S_4=11$ | |

| b) | Present state | Inputs | Next state | output |
|----|---------------|------------|----------------|--------|
| | AB | $X_1\ X_2$ | $A(t+1)B(t+1)$ | Y |
| | 00 | 00 | 00 | 0 |
| | 00 | 01 | 01 | 0 |
| | 00 | 10 | 01 | 1 |
| | 00 | 11 | 00 | 0 |
| | 01 | 00 | 00 | 0 |
| | 01 | 01 | 00 | 0 |
| | 01 | 10 | 11 | 1 |
| | 01 | 11 | 11 | 1 |
| | 10 | 00 | 00 | 1 |
| | 10 | 01 | 00 | 0 |
| | 10 | 10 | 10 | 1 |
| | 10 | 11 | 10 | 0 |
| | 11 | 00 | 10 | 1 |
| | 11 | 01 | 01 | 1 |
| | 11 | 10 | 01 | 0 |
| | 11 | 11 | 10 | 1 |

Where referenced, questions are taken from the textbook:

M. Mano, C. R. Kime and T. Martin, *Logic and Computer Design Fundamentals, 5th Edition (Global Edition)*, Pearson, 2016



Where referenced, questions are taken from the textbook:

M. Mano, C. R. Kime and T. Martin, *Logic and Computer Design Fundamentals, 5th Edition (Global Edition)*, Pearson, 2016

d) $S_1 = 0001$; $S_2 = 0010$; $S_3 = 0100$; $S_4 = 1000$

| Present state | Inputs | Next state | Output |
|---------------|-----------|-------------------------------|--------|
| A B C D | $x_1 x_2$ | $A(t+1) B(t+1) C(t+1) D(t+1)$ | Z |
| 0001 | 00 | 0001 | 0 |
| 0001 | 01 | 0010 | 0 |
| 0001 | 10 | 0010 | 1 |
| 0001 | 11 | 0001 | 0 |
| 0010 | 00 | 0001 | 0 |
| 0010 | 01 | 0001 | 0 |
| 0010 | 10 | 1000 | 1 |
| 0010 | 11 | 1000 | 1 |
| 0100 | 00 | 0001 | 1 |
| 0100 | 01 | 0001 | 0 |
| 0100 | 10 | 0100 | 1 |
| 0100 | 11 | 0100 | 0 |
| 1000 | 00 | 0100 | 1 |
| 1000 | 01 | 0010 | 1 |
| 1000 | 10 | 0010 | 0 |
| 1000 | 11 | 0100 | 1 |

$$A(t+1) = Cx_1$$

$$B(t+1) = Bx_1 + Ax_1x_2 + A\bar{x}_1\bar{x}_2$$

$$C(t+1) = D\bar{x}_1x_2 + Dx_1\bar{x}_2 + A\bar{x}_1x_2 + Ax_1\bar{x}_2$$

$$D(t+1) = D\bar{x}_1\bar{x}_2 + Dx_1x_2 + C\bar{x}_1 + B\bar{x}_1$$

$$Z = Dx_1\bar{x}_2 + Cx_1 + B\bar{x}_2 + A\bar{x}_1 + Ax_1x_2$$

Circuit not shown – but can be drawn based on equations

3.

| 3. | | Present state | Next state | | Output |
|----|---|---------------|------------|-------|--------|
| a) | | | $x=0$ | $x=1$ | Z |
| | A | 000 | | | |
| | B | 001 | A | E | 0 |
| | C | 010 | B | D | 1 |
| | D | 011 | C | E | 0 |
| | E | 101 | D | A | 1 |
| | F | 110 | E | B | 1 |
| | | | F | C | 0 |

Where referenced, questions are taken from the textbook:

M. Mano, C. R. Kime and T. Martin, *Logic and Computer Design Fundamentals, 5th Edition (Global Edition)*, Pearson, 2016

A ~ C ~ F
B ~ E

| Present State | Next State | | Output |
|---------------|------------|-----|--------|
| | X=0 | X=1 | |
| A | A | B | 0 |
| B | B | D | 1 |
| D | A | A | 1 |

Choosing assignment so one variable matches output

$$A = 72 = 00; \quad B = 61; \quad D = 11$$

$\Rightarrow Z = \text{output}$

| Present State | Input x | Next State | Output |
|---------------|---------|----------------|--------|
| Y2 | | $Y(t+1)Z(t+1)$ | Z |
| 00 | 0 | 00 | 0 |
| 00 | 1 | 01 | 0 |
| 01 | 0 | 01 | 1 |
| 01 | 1 | 11 | 1 |
| 11 | 0 | 00 | 1 |
| 11 | 1 | 00 | 1 |

$$y(t+1) = D_y = x \bar{y}_2$$

$$2(41) = D_2 = x\bar{y}\bar{z} + \bar{x}y\bar{z} + x\bar{y}z$$

$$= \overline{x} \overline{y} \overline{z} + \overline{y} z = \overline{y} (\overline{x} \overline{z} + z) = \overline{y} (\overline{x} + z)$$

$$= \bar{X}\bar{Y} + \bar{Y}Z$$

4.

state assignment: binary coding

A ~ 00 B ~ 01 C ~ 10

Write the state table and the flip-flop inputs:

| Present state q_1, q_0 | next state, output Q, q_0, z | | $x=0$ | | $x=1$ | |
|-----------------------------|-----------------------------------|-------|------------|------------|------------|------------|
| | $x=0$ | $x=1$ | D_1, D_0 | D_1, D_0 | T_1, T_0 | T_1, T_0 |
| A 00 | 01, 0 | 00, 1 | 01 | 00 | 01 | 00 |
| B 01 | 00, 1 | 10, 0 | 00 | 10 | 01 | 11 |
| C 10 | 00, 1 | 10, 1 | 00 | 10 | 10 | 00 |
| 11 | XX, X | XX, X | XX | XX | XX | XX |

2)

| D_1 | q_1, q_0 | |
|-------|------------|-------|
| | q_1 | q_0 |
| x | 0 0 x 0 | |
| x | 0 1 x 1 | |

$$D_1 = q_0 x + q_1 x$$

| D_0 | q_1, q_0 | |
|-------|------------|-------|
| | q_1 | q_0 |
| x | 1 0 x 0 | |
| x | 0 0 x 0 | |

$$D_0 = \bar{q}_1 \bar{q}_0 \bar{x}$$

b) T_1

| | | | | |
|--|-----|------------|---|---|
| | x | g_1, g_0 | | |
| | | g_1 | | |
| | | 0 | 0 | X |
| | | 0 | 1 | X |
| | | g_0 | | |

$$T_1 = x g_0 + \bar{x} g_1$$

T_0

| | | | | |
|--|-----|------------|---|---|
| | x | g_1, g_0 | | |
| | | g_1 | | |
| | | 1 | 1 | X |
| | | 0 | 1 | X |
| | | g_0 | | |

$$T_0 = \bar{x} \bar{g}_1 + g_0$$

For both (a) and (b), the output functions

Z

| | | | | |
|--|-----|------------|---|---|
| | x | g_1, g_0 | | |
| | | g_1 | | |
| | | 0 | 1 | X |
| | | 1 | 0 | X |
| | | g_0 | | |

$$Z = g_1 + \bar{x} g_0 + \bar{g}_0 x$$

$$= g_1 + g_0 \oplus x$$

5.

state assignment: Use "good" Coding

| | | | | |
|---|----|----|----|----|
| | 00 | 01 | 11 | 10 |
| 0 | A | B | C | |
| 1 | E | D | | |

~~place~~ Assign state
place next state and present
state in adjacent squares
~~of the map~~ in the k-map

A ~ 000
B ~ 010
C ~ 110
D ~ 011
E ~ 001

Write the state table and the flip-flop inputs:

| | q_2, q_1, q_0 | q_2, q_1, q_0, z $x=0$ | q_2, q_1, q_0, z $x=1$ | J_2, k_2 | J_1, k_1 | J_0, k_0 | J_2, k_2 | J_1, k_1 | J_0, k_0 |
|---|-----------------|-----------------------------|-----------------------------|------------|------------|------------|------------|------------|------------|
| A | 000 | 000, 0 | 010, 0 | 0X | 0X | 0X | 0X | 1X | 0X |
| E | 001 | 011, 0 | 000, 0 | 0X | 1X | X0 | 0X | 0X | X1 |
| B | 010 | 011, 1 | 110, 1 | 0X | X0 | 1X | 1X | X0 | 0X |
| D | 011 | 010, 1 | 001, 1 | 0X | X0 | X1 | 0X | X1 | X0 |
| | 100 | xxx, x | xxx, x | xx | xx | xx | xx | xx | xx |
| | 101 | xxx, x | xxx, x | xx | xx | xx | xx | xx | xx |
| C | 110 | 010, 1 | 011, 0 | x1 | X0 | 0X | x1 | X0 | 1X |
| | 111 | xxx, x | xxx, x | xx | xx | xx | xx | xx | xx |

D_2

| | | |
|------------|-------|---|
| q_2, q_1 | q_0 | |
| x, q_2 | | |
| 00 | 00 | 0 |
| 01 | 00 | 0 |
| 10 | 00 | 0 |
| 11 | 00 | 0 |
| 00 | 01 | 0 |
| 01 | 01 | 0 |
| 10 | 01 | 0 |
| 11 | 01 | 0 |
| 00 | 10 | 0 |
| 01 | 10 | 0 |
| 10 | 10 | 0 |
| 11 | 10 | 0 |
| 00 | 11 | 0 |
| 01 | 11 | 0 |
| 10 | 11 | 0 |
| 11 | 11 | 0 |

$D_2 = x \bar{q}_2 \bar{q}_1 \bar{q}_0$

D_1

| | | |
|------------|-------|---|
| q_2, q_1 | q_0 | |
| x, q_2 | | |
| 00 | 00 | 0 |
| 01 | 00 | 0 |
| 10 | 00 | 0 |
| 11 | 00 | 0 |
| 00 | 01 | 0 |
| 01 | 01 | 0 |
| 10 | 01 | 0 |
| 11 | 01 | 0 |
| 00 | 10 | 0 |
| 01 | 10 | 0 |
| 10 | 10 | 0 |
| 11 | 10 | 0 |
| 00 | 11 | 0 |
| 01 | 11 | 0 |
| 10 | 11 | 0 |
| 11 | 11 | 0 |

$D_1 = \bar{x} \bar{q}_0 + x \bar{q}_0 + q_1 \bar{q}_0$
 $= x \oplus q_0 + q_1 \bar{q}_0$

D_0

| | | |
|------------|-------|---|
| q_2, q_1 | q_0 | |
| x, q_2 | | |
| 00 | 00 | 0 |
| 01 | 00 | 0 |
| 10 | 00 | 0 |
| 11 | 00 | 0 |
| 00 | 01 | 0 |
| 01 | 01 | 0 |
| 10 | 01 | 0 |
| 11 | 01 | 0 |
| 00 | 10 | 0 |
| 01 | 10 | 0 |
| 10 | 10 | 0 |
| 11 | 10 | 0 |
| 00 | 11 | 0 |
| 01 | 11 | 0 |
| 10 | 11 | 0 |
| 11 | 11 | 0 |

$$D_0 = \bar{x} \bar{q}_2 \bar{q}_1 \bar{q}_0 + \bar{x} \bar{q}_1 \bar{q}_0 + x q_2 + x q_1 q_0$$

b.

$$J_2:$$

| | | | |
|-------|-------|-----------|---|
| | q_1 | $q_1 q_0$ | |
| q_2 | 0 | 0 | 0 |
| x | x | x | x |
| | x | x | x |
| | 0 | 0 | 0 |
| | | | 1 |
| | q_0 | | |

$$J_2 = x \bar{q}_0 q_1$$

$$J_1:$$

| | | | |
|-------|-------|-----------|---|
| | q_1 | $q_1 q_0$ | |
| q_2 | 0 | 1 | x |
| x | x | x | x |
| | x | x | x |
| | 1 | 0 | x |
| | q_0 | | |

$$J_1 = \bar{x} q_0 + x \bar{q}_0 = x \oplus q_0$$

$$J_0:$$

| | | | |
|-------|-------|-----------|---|
| | q_1 | $q_1 q_0$ | |
| q_2 | 0 | x | 1 |
| x | x | x | 0 |
| | x | x | 1 |
| | 0 | x | 0 |
| | q_0 | | |

$$J_0 = x q_2 + \bar{x} q_1 \bar{q}_2$$

$$K_2:$$

| | | | |
|-------|-------|-----------|---|
| | q_1 | $q_1 q_0$ | |
| q_2 | x | x | x |
| x | x | x | 1 |
| | x | x | 1 |
| | x | x | x |
| | q_0 | | |

$$K_2 = q_2$$

$$K_1:$$

| | | | |
|-------|-------|-----------|---|
| | q_1 | $q_1 q_0$ | |
| q_2 | x | x | 0 |
| x | x | x | 0 |
| | x | x | 0 |
| | x | 1 | 0 |
| | q_0 | | |

$$K_1 = x q_0$$

$$K_0:$$

| | | | |
|-------|-------|-----------|---|
| | q_1 | $q_1 q_0$ | |
| q_2 | x | 0 | 1 |
| x | x | x | x |
| | x | x | x |
| | x | 1 | 0 |
| | q_0 | | |

$$K_0 = x \bar{q}_1 + \bar{x} q_1 = x \oplus q_1$$

For both (a) and (b), the output Z,

$$Z:$$

| | | | |
|-------|-------|-----------|---|
| | q_1 | $q_1 q_0$ | |
| q_2 | 0 | 0 | 1 |
| x | x | x | 1 |
| | x | x | 0 |
| | 0 | 0 | 1 |
| | q_0 | | |

$$Z = \bar{x} q_1 + q_2 q_1$$

or

$$= \bar{x} q_2 + q_2 q_1$$

Where referenced, questions are taken from the textbook:

M. Mano, C. R. Kime and T. Martin, Logic and Computer Design Fundamentals, 5th Edition (Global Edition), Pearson, 2016

6.

Use implication Chart

| | | | | | | | |
|---|------------|-----|-----|------------|---|---|---|
| B | X | | | | | | |
| C | X | H=D | | | | | |
| D | X | X | X | | | | |
| E | X | X | X | X | | | |
| F | H=D A~E | X | X | X | X | | |
| G | X | ✓ | D~H | X | X | X | |
| H | X | X | X | A~F G~B | X | X | X |
| | A | B | C | D | E | F | G |

Read off equivalent states

A ~ F
B ~ C ~ G
D ~ H
E

New State table :

| Current State | next state, output | |
|---------------|--------------------|------|
| | X=0 | X=1 |
| A | D, 1 | A, 0 |
| B | E, 1 | D, 1 |
| D | A, 0 | B, 0 |
| E | B, 0 | E, 1 |

7.

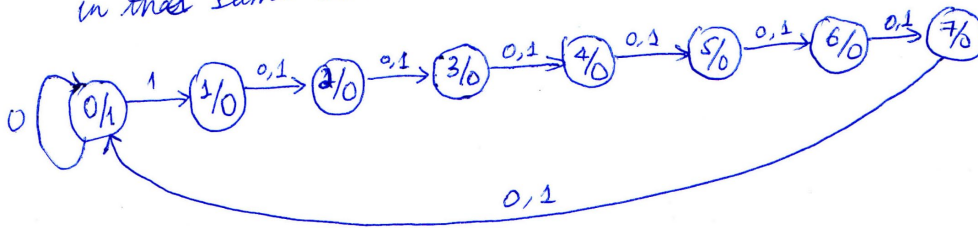
Use implication Chart

| | | | | |
|---|------------------------|------------|---|----------------|
| B | X | | | |
| C | X | A~B C~E | | |
| D | C~D | X | X | |
| E | E~D C~B | X | X | D~E |
| | A | B | C | D |

the state machine can not be minimised further,

8.

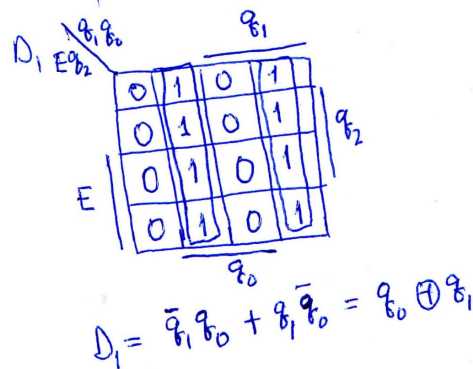
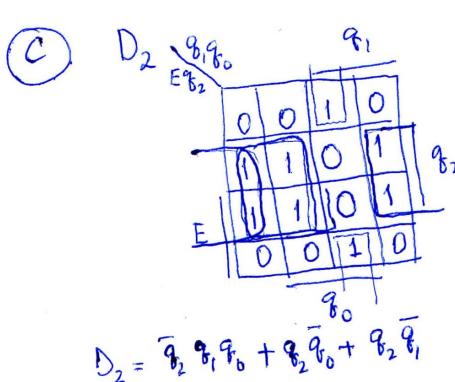
1. (a) When $E=1$, the circuit will output the required sequence regardless of input E
 When $E=0$, the circuit outputs constant 1 and remains in that same state



- (b) Use binary coding assignment. The state table is

| q_2, q_1, q_0 | $E=0$ | | | $E=1$ | | | Z |
|-----------------|-------|-------|-------|-------|-------|-------|-----|
| | Q_2 | Q_1 | Q_0 | Q_2 | Q_1 | Q_0 | |
| 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 |
| 1 | 0 | 0 | 1 | 0 | 1 | 0 | 0 |
| 2 | 0 | 1 | 0 | 0 | 1 | 1 | 0 |
| 3 | 0 | 1 | 1 | 1 | 0 | 0 | 0 |
| 4 | 1 | 0 | 0 | 1 | 0 | 1 | 0 |
| 5 | 1 | 0 | 1 | 1 | 1 | 0 | 0 |
| 6 | 1 | 1 | 0 | 1 | 1 | 1 | 0 |
| 7 | 1 | 1 | 1 | 0 | 0 | 0 | 0 |

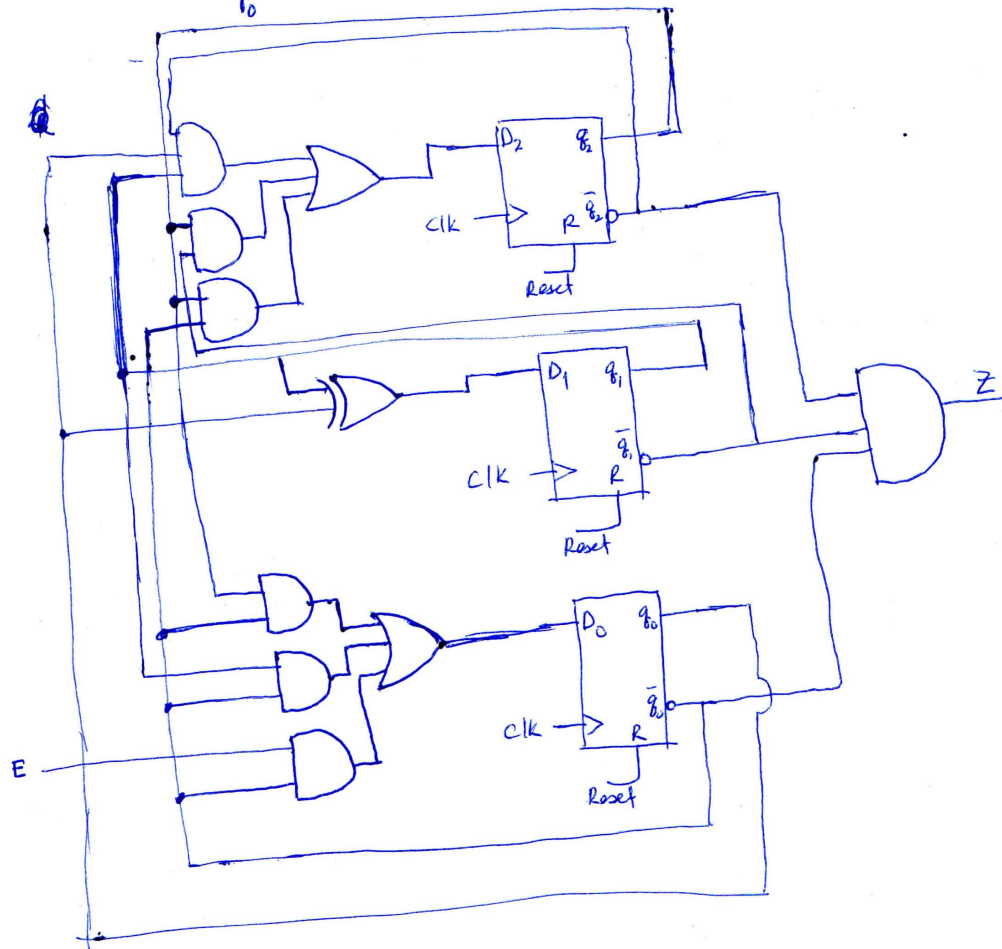
$$Z = \bar{q}_2 \cdot \bar{q}_1 \cdot \bar{q}_0$$



Truth Table for D_0 :

| q_2 | q_1 | q_0 | D_0 |
|-------|-------|-------|-------|
| 0 | 0 | 0 | 1 |
| 0 | 0 | 1 | 1 |
| 0 | 1 | 0 | 1 |
| 0 | 1 | 1 | 1 |
| 1 | 0 | 0 | 1 |
| 1 | 0 | 1 | 1 |
| 1 | 1 | 0 | 1 |
| 1 | 1 | 1 | 1 |

$$D_0 = q_1 \bar{q}_0 + E \bar{q}_0 + q_2 \bar{q}_0$$

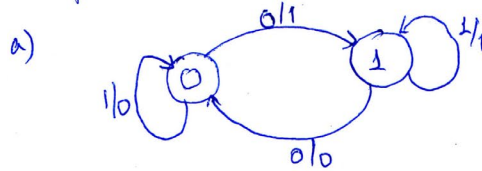


Where referenced, questions are taken from the textbook:

M. Mano, C. R. Kime and T. Martin, *Logic and Computer Design Fundamentals, 5th Edition (Global Edition)*, Pearson, 2016

9.

Define the states as the last value at the NRZI message.
2 possible states: 0 and 1



b) state table

| q | X=0 Q, z | X=1 Q, z |
|---|-------------|-------------|
| 0 | 1, 1 | 0, 0 |
| 1 | 0, 0 | 1, 1 |

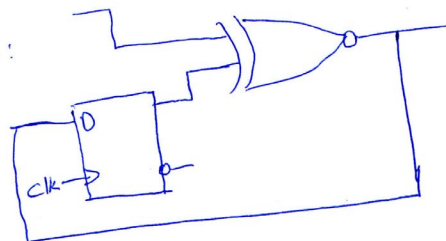
c) Derive flip-flop input equation and output equation:

| q \ x | 0 | 1 |
|-------|---|---|
| 0 | 1 | 0 |
| 1 | 0 | 1 |

| q \ x | 0 | 1 |
|-------|---|---|
| 0 | 1 | 0 |
| 1 | 0 | 1 |

$$Z = D = \overline{q \oplus x}$$

Logic diagram:



1. Simple Moore model:

| q | X=0 Q | X=1 Q | z |
|---|----------|----------|---|
| 0 | 1 | 0 | 0 |
| 1 | 0 | 1 | 1 |

