

### 2004 TRIAL HIGHER SCHOOL CERTIFICATE EXAMINATION

# Marking guidelines/ solutions

Please note: Mapping grid for this examination is on the last page of these Marking

guidelines/solutions

CSSA HSC Trial 2004 Mathematics Extension 1 Marking Guidelines

Question 1

a. Outcomes Assessed: PES, HE4

Marking Guidelines

Criteria	Marks	
		_
$^{\circ}$ Applies the product rule with correct derivative of tan $^{-1}x$	_	
0:1:5:1:5:1:5:		_

Simplifies resulting expression

Answer

$$\frac{d}{dt}(1+x^2)\tan^{-1}x = 2x \tan^{-1}x + (1+x^2)\frac{1}{1+x^2} = 1+2x \tan^{-1}x$$

b. Outcomes Assessed: PE3

Marking Guidelines

Criteria	Marks
<ul> <li>uses the remainder theorem to obtain an equation for a</li> </ul>	_
* solves the equation to evaluate a.	_

Answer

$$P(1) = P(2) \Rightarrow a + 2 = 2a + 9$$
 :  $a = -7$ 

(ii) P4 (i) H5 c. Outcomes Assessed:

Marking Guidelines

Criteria	Marks
i. • writes the expression for tan 45° in terms of the gradients of the lines	-
• obtains the required equation by putting $\tan 45^{\circ} = 1$ and rearranging	_
ii. • finds one of the values of m with the corresponding line	_
• finds the second value of m and the equation of the second line	_

Answer

i. 
$$\left| \frac{m-2}{1+2m} \right| = \tan 45^{\circ} = 1$$
 ii.  $m-2=1+2m$  or  $m-2=-(1+2m)$  .  $|m-2|=|1+2m|$   $m-2=-1-2m$   $3m=1$  .  $|m-2|=|1+2m|$  .  $|m-2|=|1+2m|$ 

The required lines are y = -3x and  $y = \frac{1}{3}x$ 

DISCLAIMER
The information contained in this document is intended for the professional assistance of teaching staff. It does not constitute advice to students.
The information contained in this document is intended for the professional passible frait HSC answers. Rather the purpose is to provide teachers with information so that they can better explore, understand and apply HSC marking requirements, as established by the NSW Board of Students or of the provide statement of the provide statement of the provide statement of the provide of the provide of the superance or warranty is made or implied with respect to the application or use of CSSA Marking Guidelines in relation to any specific trial exam question or answer. The CSSA assumes no liability or responsibility for the accuracy, completeness or usefulness of any Marking Guidelines provided for the Trial HSC papers.

d. Outcomes Assessed: (i) PE3 (ii) PE2, PE3
Marking Guidelines

Criteria	Marks
	0
II. • gives suitable reason referring to appropriate property of cyclic quadrilateral	,
iii. • explains why $\angle BDC = \angle BAC$	-
• explains why $\angle BAC = \angle ABC$	
• uses these facts to make final deduction about DC	

Answer

ii.  $\angle CDE = \angle ABC$  (exterior angle of cyclic quadrilateral ABCD

iii.  $\angle BDC = \angle BAC$  ( $\angle$ 's subtended at circumference by same arc BC is equal to the opposite interior angle).

 $\angle BAC = \angle ABC$  ( $\angle s$  opposite equal sides BC and AC in  $\triangle ABC$ are equal) are equal)

 $\therefore \angle BDC = \angle ABC$   $\therefore \angle BDC = \angle CDE \text{ (both equal to } \angle ABC)$ 

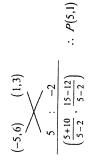
:. DC bisects ∠BDE.

Question 2

a. Outcomes Assessed: P4

Marking Guidelines		
Criteria	Marks	
e applies an appropriate formula or pattern for external division	_	
evaluates the coordinates of <i>P</i> .	_	_
	•	

Answer



b. Outcomes Assessed: PE3

Marking Guidelines

Criteria	Marks	_
• expresses $\sum \frac{1}{\alpha}$ in terms of $\sum \alpha \beta$ and $\alpha \beta \gamma$ .	_	
• reads correct values of $\sum\!lphaeta$ and $lphaeta\gamma$ from coefficients to evaluate $\sumrac{1}{lpha}$	-	

DISCLAIMER
The information contained in this document is intended for the professional assistance of leaching staff. It does not constitute advice to students. Further ties not the intention of CSSA to provide specific marking outcomes for all possible Trial HSC answers. Ruther the purpose is to provide Studier it is not the intention of CSSA to provide specific marking outcomes for all possible Trial HSC answers. Ruther the purpose is to provide Studier with information so that they can better explorer, understand and apply HSC marking requirements, as established by the NSW Board of No guarantee or warranty is made or implied with respect to the application or use of CSSA Marking Guidelines in relation to any specific trial exam question or answer. The CSSA assumes no liability or responsibility for the accuracy, completeness or usefulness of any Marking Guidelines provided for the Trial HSC papers.

$$2x^3 + 2x^2 + 4x + 1 = 0 \text{ has roots } \alpha, \beta, \gamma. \qquad \therefore \frac{1}{\alpha} + \frac{1}{\beta} + \frac{1}{\gamma} = \frac{\beta\gamma + \gamma\alpha + \alpha\beta}{\alpha\beta\gamma} = \frac{\binom{4}{2}}{\binom{-1}{2}} = -4$$

c. Outcomes Assessed: (i) H5 (ii) H5

Marking Guidelines

9	
Criteria	Marks
i. • identifies common ratio as cos2x	-
applies condition for existence of limiting sum	_
ii. • writes expression for S in terms of $\sin 2x$ and $\cos 2x$	
<ul> <li>uses appropriate trig. identities to simplify expression for S.</li> </ul>	

Answer

i. 
$$r = \cos 2x$$
,  $0 < x < \frac{\pi}{2} \Rightarrow |r| < 1$ .  
ii.  $S = \frac{\sin 2x}{1 - \cos 2x}$   $\therefore S = \frac{\cos x}{\sin x}$   
Function in the second in the sec

 $2 \sin^2 x$ 

 $\therefore S = \frac{\cos x}{\cos x} = \cot x$ 

d. Outcomes Assessed: (i) PE3, PE4 (ii) PE3

**Marking Guidelines** 

_	• finds Cartesian equation of locus of M
	ii. • finds x and y coordinates of M in terms of t
_	<ul> <li>finds the equation of the tangent</li> </ul>
<b></b>	i. • finds $\frac{dt}{dt}$ to show that the tangent has gradient $t$
	<i>A</i> .,
Marks	Criteria

Answer

i. 
$$x = 2t \Rightarrow \frac{dx}{dt} = 2$$
  
ii. at  $M$ ,  $(x - y - t^2 = 0)$  and  $(y = -tx)$   

$$y = t^2 \Rightarrow \frac{dy}{dt} = 2t$$

$$\therefore \frac{dy}{dt} = 2t$$

$$\therefore \frac{dy}{dt} = \frac{2t}{2} = t$$

Tangent has gradient  $t$  and equation
$$y - t^2 = t(x - 2t)$$
ii. at  $M$ ,  $(x - y - t^2 = 0)$  and  $(y = -tx)$ 

$$2t(x - \frac{1}{2}t) = 0$$
If  $(x - 0, t)$  and  $(x - \frac{1}{2}t)$  otherwise at  $(x - \frac{1}{2}t)$ ,  $(x - \frac{1}{2}t^2)$ ,  $(x - \frac{1}{2}t^2)$ .

Figure 1 ii. at  $(x - y - t^2 = 0)$  and  $(y = -tx)$ 

$$2t(x - \frac{1}{2}t) = 0$$
If  $(x - 0, t)$  and  $(x - y - t^2 = 0)$  and  $(y = -tx)$ 

$$(x - 1, t) = 0$$

$$(x - 1$$

 $tx-y-t^2=0$ 

DISCLAIMER

DISCLAIMER

The information contained in this document is intended for the professional assistance of teaching staff, It does not constitute advice to students. Further it is not the intention of CSSA to provide specific marking outcomes for all possible Trial HSC answers. Rather the purpose is to provide teachers with information so that they can better explore, understand and apply HSC marking requirements, as established by the NSW Board of

Studies.

No guarantee or warranty is made or implied with respect to the application or use of CSSA Marking Guidelines in relation to any specific trial exam question or answer. The CSSA assumes no liability or responsibility for the accuracy, completeness or usefulness of any Marking Guidelines provided for the Trial HSC papers.

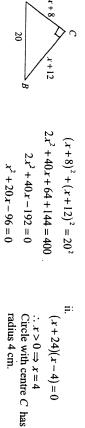
Question 3

a. Outcomes Assessed: (i) P4 (ii) P4

ii. • factors this quadratic (or applies an alternative method) uses Pythagoras to obtain an equation for x simplifies this equation by expanding squares and collecting like terms finds the radius of the circle with centre C. Marking Guidelines Criteria Marks

### Answer

triangle ABC as shown below When circles touch, the line joining centres passes through the point of contact, giving the sides of right



b. Outcomes Assessed: (i) P3 (ii) HE6

Marking Guidelines	
Criteria	Marks
i. • rearranges either LHS or RHS to establish result	
ii. • transforms integral into form $2 \left( \frac{u}{1+u} du \right)$	
• finds primitive in terms of $u$	
• finds primitive in terms of x	

Answer

i. 
$$\frac{u}{1+u} = \frac{(1+u)-1}{1+u}$$
 ii.  $u \ge 0$   $x = u^2$  
$$\int \frac{1}{1+\sqrt{x}} dx = \int \frac{1}{1+u} 2u du$$
$$= 1 - \frac{1}{1+u}$$
 
$$dx = 2u du$$
$$= 2 \int \frac{u}{1+u} du$$
$$= 2 \int (1 - \frac{1}{1+u}) du$$
$$= 2 \{u - \ln(1+u)\} + c$$
$$= 2\sqrt{x} - 2\ln(1+\sqrt{x}) + c$$

DISCLAIMER

The information contained in this document is intended for the professional assistance of teaching staff. It does not constitute advice to students. Further it is not the intention of CSSA to provide specific marking outcomes for all possible Trial HSC answers. Rather the purpose is to provide teachers with information so that they can better explore, understand and apply HSC marking requirements, as established by the NSW Board of teachers with information so that they can better explore, understand and apply HSC marking requirements, as established by the NSW Board of teachers with information so that they can better explore, understand and apply HSC marking requirements, as established by the NSW Board of teachers.

No guarantee or warranty is made or implied with respect to the application or use of CSSA Marking Guidelines in relation to any specific trial exam question or answer. The CSSA assumes no liability or responsibility for the accuracy, completeness or usefulness of any Marking Guidelines provided for the Trial HSC papers.

# c. Outcomes Assessed: HE2

# Marking Guidelines

Criteria	Marks
• shows the statement is true for $n=3$	-
• shows that $5^{k+1} > 5(4^k + 3^k)$ if $S(k)$ is true	_
• completes the explanation that $S(k)$ true implies $S(k+1)$ true	
<ul> <li>makes final statements to complete the Mathematical Induction</li> </ul>	-

Let S(n) be the statement  $5^n > 4^n + 3^n$ , n = 3, 4, 5, ...

Consider S(3):  $S^3 = 125$ ,  $A^3 + 3^3 = 64 + 27 = 91$ . Hence S(3) is true

If S(k) is true:  $5^{k} > 4^{k} + 3^{k} **$ 

Consider S(k+1):  $5^{k+1} = 5.5^{k}$ 

 $> 5(4^k + 3^k)$  if S(k) is true, using \*\*  $=5.4^{t}+5.3^{t}$ 

 $=4^{k+1}+3^{k+1}$  $>4.4^{t}+3.3^{t}$ 

so on. Hence by Mathematical Induction 5">4"+3" for all integers  $n \ge 3$ . Hence if S(k) is true, then S(k+1) is true. But S(3) is true, hence S(4) is true and then S(5) is true and

### Question 4

# a. Outcomes Assessed: PE3

## Marking Guidelines

Criteria	Marks
<ul> <li>writes an expression for the general term in the expansion</li> </ul>	_
identifies the term independent of x	_
• calculates the term independent of x	

### Answer

General term is 
$${}^{15}C_1\left(-\frac{2}{r^2}\right)^r x^{15-r} = {}^{15}C_1\left(-2\right)^r x^{15-3r}, r=0,1,2,...,15$$

Constant term has  $15-3r=0 \Rightarrow r=5$ 

 $\therefore$  term independent of x is  ${}^{15}C_5(-2)^5 = -96096$ 

6

DISCLAIMER

DISCLAIMER

The information contained in this document is intended for the professional assistance of teaching staff. It does not constitute advice to students. Further it is not the intention of CSSA to provide specific marking outcomes for all possible Trial HSC answers. Rather the purpose is to provide teachers with information so that they can better explore, understand and apply HSC marking requirements, as established by the NSW Board of

No guarantee or warranty is made or implied with respect to the application or use of CSSA Marking Guidelines in relation to any specific trial exam question or answer. The CISSA assumes no liability or responsibility for the accuracy, completeness or usefulness of any Marking Guidelines provided for the Trial HSC papers.

# b. Outcomes Assessed: (i) HE3 (ii) H3

# Marking Guidelines

6	
Criteria	Marks
i. • uses given information to show one of $A = 100$ or $A + B = 500$	_
<ul> <li>shows the second result about A, B and deduces the values of A and B</li> </ul>	_
ii. • obtains \(\tau \geq 2 \ln 40\)	
• calculates the time to nearest month	

Answer
i. 
$$N = A + Be^{-0.5 i}$$
ii.  $N \le 110 \Rightarrow 100 + 400 e^{-0.5 i} \le 110$ 
 $i = 0, N = 500 \Rightarrow A + B = 500$ 
 $i = 0, N = 100 \Rightarrow A + 0 = 100$ 
 $i = 0, N = 100 \Rightarrow A + 0 = 100$ 
 $i = 0, N = 100 \Rightarrow A + 0 = 100$ 
 $i = 0, N = 100 \Rightarrow A + 0 = 100$ 
 $i = 0, N = 100, B = 400$ 
 $i = 0, N = 100, B = 400$ 
 $i = 0, N = 100, B = 400$ 
 $i = 0, N = 100, B = 400$ 

after  $7.38 \text{ yrs} \approx 7 \text{ yrs } 5 \text{ months}$ . Population falls within 10 of limiting size  $t \ge 2 \ln 40$ 

# c. Outcomes Assessed: (i) PE3 (ii) PE3

# **Marking Guidelines**

Constitution of the second of	
Criteria	Marks
i. • shows $f(0)$ , $f(1)$ have opposite signs	-
$\bullet$ notes continuity of $f$ to justify deduction.	
ii. • obtains expression for $\alpha$ by substitution into Newton's formula	
• calculates at least one of $f(0.7)$ , $f'(0.7)$ correctly	
<ul> <li>approximates α to 2 decimal places</li> </ul>	

### Answer

i. 
$$f(x) = x - \cos x$$
  
f is a continuous function and  
 $f(0) = 0 - 1 < 0$   
 $f(1) = 1 - \cos 1 > 0$ 

DISCLAIMER

The information contained in this document is intended for the professional assistance of teaching staff. It does not constitute advice to students. The information contained in this document is intended for the provide specific marking outcomes for all possible Trial HSC answers. Rather the purpose its to provide Further it is not the intention so that they can better explore, understand and apply HSC marking requirements, as established by the NSW Board of teachers with information so that they can better explore, understand and apply HSC marking requirements, as established by the NSW Board of teachers with information so that they can better explore, understand and apply HSC marking requirements, as established by the NSW Board of the content of

No guazantee or warranty is made or implied with respect to the application or use of CSSA Marking Guidelines in relation to any specific trial exam question or answer. The CSSA assumes no liability or responsibility for the accuracy, completeness or usefulness of any Marking Guidelines provided for the Trial HSC paperts.

### Question 5

a. Outcomes Assessed (i) HE3 (ii) HE3:

Marking Guidelines

2	
Criteria	Marks
i. writes appropriate expression for binomial probability	
11. • interprets at most as either sum or complement of appropriate binomial probabilities	
 <ul> <li>calculates the probability in fraction or decimal form</li> </ul>	

### Answer

Binomial distribution: n = 4,  $p = \frac{2}{5}$ ,  $q = \frac{3}{5}$ 

$${}^{4}C_{3}\left(\frac{2}{5}\right)^{3}\left(\frac{2}{5}\right) = \frac{96}{625}$$
 ii.  $1 - {}^{4}C_{3}\left(\frac{2}{5}\right)^{4} = 1 - \frac{16}{625} = \frac{609}{625}$ 

## b. Outcomes Assessed: (i) P3 (ii) HE 5

# Marking Guidelines

Criteria	Marks
i. obtains required expression for S in terms of h	-
ii. • writes expression for $\frac{dS}{dt}$ in terms of $\frac{dh}{dt}$	
• evaluates $\frac{dS}{dt}$ when $h=2$	
<ul> <li>interprets negative value and provides appropriate units</li> </ul>	

### Answer

i. The surface of the water is a circle with radius x when the depth is y, where  $x^2 = 4 - y$ . When the depth is h,  $S = \pi x^2 = \pi (4 - h)$ 

$$\therefore \frac{dS}{dt} = -\pi \frac{dh}{dt} = -\pi \frac{10}{\pi (4-h)} = -5 \text{ when } h = 2$$

When depth is 2 cm, surface area of the water is decreasing at a rate of 5 cm<sup>2</sup>s<sup>-1</sup>.

# c. Outcomes Assessed: (i) H5 (ii) H5 (iii) PE3 Marking Guidelines

CIRCIA		Marks
1. " linds $f(x)$ and notes $f''(x) > 0$ for all x		-
ii. • finds coordinates of stationary point		-
e states notice of state		-
suits haine of stationary point	•	_
iii. • deduces that $f(x) \ge 1$ for all x		<b>-</b> ,
• uses this result to deduce $\rho^{\tau} > r + 1$ for all $\tau$	4	٠,

### Answer

i. 
$$f(x) = e^x - x$$
  

$$f'(x) = e^x - 1$$
  

$$f''(x) = e^x$$

$$f'(x) = 0 \Rightarrow e^x = 1$$
 . stationary point is (0,1)

Since curve is concave up, (0,1) is a minimum turning point

concave up for all x. f''(x) > 0 for all x, hence curve is

iii. 
$$f(x) \ge 1$$
 for all  $x \Rightarrow e^x - x \ge 1$  for all  $x$   
  $\therefore e^x \ge x + 1$  for all  $x$ .

∞

DISCLAIMER

The information contained in this document is intended for the professional assistance of teaching staff. It does not constitute advice to students. Further it is not the intention of CSSA to provide specific marking outcomes for all possible Trial HSC answers. Rather the purpose is to provide teachers with information so that they can better explore, understand and apply HSC marking requirements, as established by the NSW Board of Studies.

No guarantee or warranty is made or implied with respect to the application or use of CSSA Marking Guidelines in relation to any specific trial exam question or answer. The CSSA assumes no liability or responsibility for the accuracy, completeness or usefulness of any Marking Guidelines

## Question 6

a. Outcomes Assessed: (i) HE4 (ii) HE4 (iii) H8

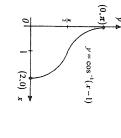
# Marking Guidelines

	Criteria	Marks
i. • states domain of function		-
ii. • sketches curve with correct shape and position	nd position	
<ul> <li>shows endpoints with correct coordinates</li> </ul>	inates	_
iii. • writes integral for $V$ in terms of $y$		
<ul> <li>finds primitive function</li> </ul>		_

i. 
$$f(x) = \cos^{-1}(x-1) \implies -1 \le x-1 \le 1$$
  
The main is  $f(x) = 0 \le x \le 21$ 

evaluates V by substitution of correct limits

$$\therefore$$
 Domain is  $\{x: 0 \le x \le 2\}$ 



$$V = \pi \int_0^1 x^2 dy$$

where  $\cos y = x - 1 \implies x = 1 + \cos y$ .

$$V = \pi \int_{0}^{\pi} (1 + \cos y)^{2} dy$$

$$= \pi \int_{0}^{\pi} (1 + 2\cos y + \cos^{2} y) dy$$

$$= \pi \int_{0}^{\pi} (1 + 2\cos y + \frac{1}{2}(1 + \cos 2y)) dy$$

$$= \pi \int_{0}^{\pi} \left(1 + 2\cos y + \frac{1}{2}(1 + \cos 2y)\right) dy$$

$$= \pi \int_{0}^{\pi} \left(\frac{3}{2} + 2\cos y + \frac{1}{2}\cos 2y\right) dy$$

$$= \pi \left[\frac{3}{2}y + 2\sin y + \frac{1}{4}\sin 2y\right]_{0}^{\pi}$$

$$=\pi\left(\frac{3}{2}\pi+0+0\right)$$

Volume is  $\frac{3}{2}\pi^2$  cubic units.

# b. Outcomes Assessed: (i) HE3 (ii) HE3 (iii) HE3 Marking Guidelines

7	Canadamica	
Τ	Criteria	Marks
:-	i. expresses x in terms of cos2/	_
	• expresses $\ddot{x}$ in required form	, 
Ę:	ii. • finds possible values for x	
	• states period of motion	
E:	iii. • finds smallest t for which $x = 0$	
Γ	• finds initial x and deduces distance travelled	

### 9

DISCLAIMER

DISCLAIMER

The information contained in this document is intended for the professional assistance of teaching staff, It does not constitute advice to students. Further it is not the intention of CSSA to provide specific marking outcomes for all possible Trial HSC naswers. Rather the purpose is to provide reachers with information so that they can better explore, understand and apply HSC marking requirements, as established by the NSW Board of

No guarantee or warranty is made or implied with respect to the application or use of CSSA Marking Guidelines in relation to any specific trial exam question or answer. The CSSA assumes no liability or responsibility for the accuracy, completeness or usefulness of any Marking Guidelines provided for the Trial HSC papers.

i. 
$$x = 4\cos^2 t - 2\sin^2 t$$
  
 $= 2(1 + \cos 2t) - (1 - \cos 2t)$   
 $= 1 + 3\cos 2t$   
 $\dot{x} = -6\sin 2t$   
 $\ddot{x} = -12\cos 2t$   
 $= -4(x-1)$   
 $\ddot{x} = -2^2(x-1)$   
iii.  $x = 0 \Rightarrow \cos 2t = -\frac{1}{3}$   
Smallest such  $t$  is  $\frac{2\pi}{1} = \pi$  s  
Smallest such  $t$  is  $\frac{2\pi}{1} = \pi$  s

### Question 7

a. Outcomes Assessed: (i) HE5 (ii) HE5 (iii) HE5, HE7 **Marking Guidelines** 

ı	l	0 0	
T-	l	Criteria	Marks
	-	i. • uses chain rule then simplifies using trig. identities	-
	=:	ii. • writes expression for $\frac{dt}{dt}$	-
		• finds expression for t in terms of x, evaluating the constant of integration	- peed pe
		• finds expression for x in terms of t	_
	ĘΞ	iii. • states limiting position	
		<ul> <li>sketches graph of x against t with correct shape, endpoint and asymmtote</li> </ul>	-

### Answer

			$= \frac{1}{\sin x \cos x}$	$= \frac{1}{\cos^2 x} \frac{\cos x}{\sin x}$	$\frac{\mathrm{i.}}{dx}\ln(\tan x) = \frac{\sec^2 x}{\tan x}$
$x = \tan^{-1}(e')$	$e' = \tan x$	$t = 0,  x = \frac{\pi}{4} \Rightarrow c = 0$ \therefore $t = t = t = 0$	$t = \ln(\tan x) + c$	$\frac{dI}{dx} = \frac{1}{\sin x \cos x}$	ii. $v = \sin x \cos x$ $\frac{dx}{dt} = \sin x \cos x$
	1 0	s ja		*	iii. as $t \to \infty$ , $x \to \frac{\pi}{2}$ $\therefore$ limiting position is $\frac{\pi}{2}$ metres to the right of $O$ .

0

DISCLAIMER

The information contained in this document is intended for the professional assistance of teaching staff. It does not constitute advice to students. Further it is not the intention of CSSA to provide specific marking outcomes for all possible Trial HSC answers. Rather the purpose is to provide teachers with information so that they can better explore, understand and apply HSC marking requirements, as established by the NSW Board of Studies.

to guarantee or warranty is made or implied with respect to the application or use of CSSA Marking Guidelines in relation to any specific trial xam question or answer. The CSSA assumes no liability or responsibility for the accuracy, completeness or usefulness of any Marking Guidelines rovided for the Trial HSC papers.

# b. Outcomes Assessed: (i) HE3 (ii) HE3 (iii) HE3 Marking Guidelines

9	
Criteria	Marks
i. • writes horizontal and vertical displacements for particle projected from A	-
<ul> <li>writes horizontal and vertical displacements for particle projected from O</li> </ul>	
ii. • equates expressions for x and y to obtain equations (1) and (2) if particles collide	
• solves simultaneously to find $\cos \theta$ , $\sin \theta$ and $t$ if collision occurs	
iii. • obtains values for $\dot{x}$ , $\dot{y}$ for each particle for $t=1$ and $\theta=\tan^{-1}2$	-
• deduces that if particles collide, their velocities are perpendicular at that time	

i. Partical projected from A: vertical displacement  $y = 20 - 5t^2$ horizontal displacement x = 10t

when particle has travelled a distance of 4m.

Hence particle first passes through O after 1.0s

Initially particle is at x = 4

vertical displacement  $y = 10\sqrt{5} t \sin \theta - 5t^2$ horizontal displacement  $x = 10\sqrt{5} t \cos\theta$ Particle projected from O

ii. If the particles collide at some time t  $20 - 5t^2 = 10\sqrt{5} t \sin \theta - 5t^2$  $10t = 10\sqrt{5} t \cos\theta$ (l) and

$$20 = 10\sqrt{5} / \sin\theta \qquad (2)$$
  
From (1),  $\cos\theta = \frac{1}{\sqrt{5}}$   $\therefore \sin\theta = \frac{2}{\sqrt{5}}$ 

and in this case they collide after 1 s. Hence the particles collide if  $\theta = \tan^{-1} 2$ , Substituting in (2) gives t = 1

> as shown in the diagrams below: Hence the particles have velocities  $\nu_A$  and  $\nu_O$ the particle from O has  $\dot{x} = 10$  and  $\dot{y} = 20 - 10 = 10$ the particle from A has  $\dot{x} = 10$  and  $\dot{y} = -10$

iii. If  $\theta = \tan^{-1} 2$ , when t = 1



a direction 45° above the horizontal, and their paths of motion are perpendicular to each other. the horizontal while the particle from O is travelling in particle from A is travelling in a direction 45° below Hence if the particles collide, when they do so the

DISCLAIMER

DISCLAIMER

The information contained in this document is intended for the professional assistance of caching staff, It does not constitute advice to students. Further it is not the intention of CSSA to provide specific marking outcomes for all possible Trial HSC answers. Rather the purpose is to provide teachers with information so that they can better explore, understand and apply HSC marking requirements, as established by the NSW Board of

=

No guarantee or warranty is made or implied with respect to the application or use of CSSA Marking Guidelines in relation to any specific trial exam question or answer. The CSSA assumes no liability or responsibility for the accuracy, completeness or usefulness of any Marking Guidelines provided for the Trial HSC papers.

$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	Question	Marks	Syllabus Content	Syllabus Outcomes	Targeted Performance Bands
1(b)   2	1(a)	2	Inverse functions	PE5, HE4	
(ii)         2         Basic arithmetic and algebra         P4         E2 — E3 $I(d)(ii)$ 1         Circle geometry         PE3         E2 — E3 $I(iii)$ 2         Circle geometry         PE2 , PE3         E2 — E3 $I(iii)$ 2         Internal and external division of lines         P4         E2 — E3 $I(ii)$ 2         Polynomials         PE3         E2 — E3 $I(ii)$ 2         Polynomials         PE3         E2 — E3 $I(ii)$ 2         Further trigonometry         H5         E2 — E3 $I(ii)$ 2         Parametric representation         PE3         F2 — E3 $I(ii)$ 2         Parametric representation         PE3         F2 — E3 $I(ii)$ 2         Basic arithmetic and algebra         P4         E2 — E3 $I(ii)$ 2         Basic arithmetic and algebra         P4         E2 — E3 $I(ii)$ 2         Basic arithmetic and algebra         P3         E2 — E3 $I(ii)$ 3         Methods of integration         H66         E2 — E3 $I(ii)$ 3         Binomial theorem	1(b)	2 ··	Polynomials		
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	1(c)(i)	2		H5	E2 — E3
(iii) 3   Circle geometry   PE2 , PE3   E2 − E3    2(a) 2   Internal and external division of lines   P4   E2 − E3    2(b) 2   Polynomials   PE3   E2 − E3    2(c)(i) 2   Series   H5   E2 − E3    (ii) 2   Further trigonometry   H5   E2 − E3    (ii) 2   Parametric representation   PE3 , PE4   E2 − E3    (ii) 2   Parametric representation   PE3 , PE4   E2 − E3    (ii) 2   Parametric representation   PE3 , PE4   E2 − E3    (ii) 2   Basic arithmetic and algebra   P4   E2 − E3    (ii) 2   Basic arithmetic and algebra   P4   E2 − E3    (ii) 3   Methods of integration   HE6   E2 − E3    (ii) 3   Methods of integration   HE6   E2 − E3    (ii) 4   Induction   HE2   E3 − E4    (4(a) 3   Binomial theorem   PE3   E2 − E3    (4(b)(i) 2   Equation d	(ii)	2	Basic arithmetic and algebra	P4	E2 — E3
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$			Circle geometry	PE3	E2 — E3
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	(iii)	3	Circle geometry	PE2, PE3	E2 — E3
2(b)         2         Polynomials         PE3         E2 — E3 $2(c)(i)$ 2         Series         H5         E2 — E3 $(ii)$ 2         Further trigonometry         H5         E2 — E3 $2(d)(i)$ 2         Parametric representation         PE3 , PE4         E2 — E3 $(ii)$ 2         Parametric representation         PE3 , PE4         E2 — E3 $3(a)(i)$ 2         Basic arithmetic and algebra         P4         E2 — E3 $(ii)$ 2         Basic arithmetic and algebra         P4         E2 — E3 $3(b)(i)$ 1         Basic arithmetic and algebra         P3         E2 — E3 $3(c)$ 4         Induction         HE6         E2 — E3 $3(c)$ 4         Induction         HE2         E3 — E4 $4(a)$ 3         Binomial theorem         PE3         E2 — E3 <tr< td=""><td>2(a)</td><td>2</td><td>Internal and external division of lines</td><td>P4</td><td>E2 — E3</td></tr<>	2(a)	2	Internal and external division of lines	P4	E2 — E3
$2(c)(i)$ 2         Series         H5         E2—E3           (ii)         2         Further trigonometry         H5         E2—E3           (ii)         2         Parametric representation         PE3, PE4         E2—E3           (ii)         2         Parametric representation         PE3, PE4         E2—E3           3(a)(i)         2         Basic arithmetic and algebra         P4         E2—E3           3(b)(i)         1         Basic arithmetic and algebra         P4         E2—E3           3(b)(i)         1         Basic arithmetic and algebra         P3         E2—E3           (ii)         3         Methods of integration         HB6         E2—E3           3(c)         4         Induction         HB2         E3—E4           4(a)         3         Binomial theorem         PE3         E2—E3           4(b)(i)         2         Equation $\frac{dN}{dt} = k(N-P)$ HE3         E2—E3           4(b)(i)         2         Logarithmic and exponential functions         H3         E2—E3           4(c)(i)         2         Polynomials         PE3         E2—E3           4(c)(i)         2         Further probability         HE3         E2—E3	2(b)	2	Polynomials	PE3	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	2(c)(i)	2	Series	H5	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	(ii)	2	Further trigonometry	H5	
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	2(d)(i)	2		PE3, PE4	
(ii) 2 Basic arithmetic and algebra P4 E2 E3 (ii) 3 Methods of integration HE6 E2 E3 (iii) 2 Induction PE3 E2 E3 (iii) 2 Logarithmic and exponential functions H3 E2 E3 (iii) 3 Iterative methods PE3 E2 E3 (iii) 3 Iterative methods PE3 E2 E3 (iii) 4 Further probability HE3 E2 E3 (iii) 5 Further probability HE3 E2 E3 (iii) 3 Applications of calculus to the physical world HE5 E3 E4 (iii) 2 Logarithmic and exponential functions H5 E2 E3 (iii) 3 Applications of calculus to the physical world HE5 E3 E4 (iii) 2 Inequalities PE3 E3 E4 (iii) 2 Inequalities PE3 E3 E4 (iii) 2 Inverse functions H5 E2 E3 (iii) 2 Inverse functions HE4 E2 E3 (iii) 2 Inverse functions HE5 E3 E4 (iii) 2 Inverse functions HE4 E2 E3 (iii) 2 Simple harmonic motion HE3 E2 E3 (iii) 2 Simple harmonic motion HE3 E2 E3 (iii) 2 Simple harmonic motion HE3 E2 E3 (iii) 3 Velocity and acceleration as a function of $x$ HE5 E3 E4 (iii) 2 Velocity and acceleration as a function of $x$ HE5 HE7 E3 E4 (iii) 2 Projectile motion HE3 E2 E3	(ii)	2	Parametric representation		
(ii) 2 Basic arithmetic and algebra P4 E2 E3 (ii) 3 Methods of integration HE6 E2 E3 (iii) 2 Induction PE3 E2 E3 (iii) 2 Logarithmic and exponential functions H3 E2 E3 (iii) 3 Iterative methods PE3 E2 E3 (iii) 3 Iterative methods PE3 E2 E3 (iii) 4 Further probability HE3 E2 E3 (iii) 5 Further probability HE3 E2 E3 (iii) 3 Applications of calculus to the physical world HE5 E3 E4 (iii) 2 Logarithmic and exponential functions H5 E2 E3 (iii) 3 Applications of calculus to the physical world HE5 E3 E4 (iii) 2 Inequalities PE3 E3 E4 (iii) 2 Inequalities PE3 E3 E4 (iii) 2 Inverse functions H5 E2 E3 (iii) 2 Inverse functions HE4 E2 E3 (iii) 2 Inverse functions HE5 E3 E4 (iii) 2 Inverse functions HE4 E2 E3 (iii) 2 Simple harmonic motion HE3 E2 E3 (iii) 2 Simple harmonic motion HE3 E2 E3 (iii) 2 Simple harmonic motion HE3 E2 E3 (iii) 3 Velocity and acceleration as a function of $x$ HE5 E3 E4 (iii) 2 Velocity and acceleration as a function of $x$ HE5 HE7 E3 E4 (iii) 2 Projectile motion HE3 E2 E3	3(a)(i)	2	Basic arithmetic and algebra	D/I	F2 F2
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$					
(ii) 3 Methods of integration HE6 E2 E3 3(c) 4 Induction HE2 E3 E4 4(a) 3 Binomial theorem PE3 E2 E3 4(b)(i) 2 Equation $\frac{dN}{dt} = k(N-P)$ HE3 E2 E3 4(c)(i) 2 Logarithmic and exponential functions H3 E2 E3 (ii) 3 Iterative methods PE3 E2 E3 (ii) 2 Further probability HE3 E2 E3 (ii) 2 Further probability HE3 E2 E3 (ii) 2 Further probability HE3 E2 E3 (ii) 3 Applications of calculus to the physical world HE5 E2 E3 (ii) 2 Logarithmic and exponential functions H5 E2 E3 (ii) 2 Logarithmic and exponential functions H5 E2 E3 (iii) 2 Logarithmic and exponential functions H5 E2 E3 (iii) 2 Inequalities PE3 E3 E3 E4 (iii) 2 Inequalities PE3 E3 E3 E4 (iii) 2 Simple harmonic motion HE4 E2 E3 (iii) 2 Simple harmonic motion HE3 E3 E4 (iii) 2 Velocity and acceleration as a function of $x$ HE5 E2 E3 (iii) 2 Velocity and acceleration as a function of $x$ HE5 E3 E4 (iii) 2 Projectile motion HE3 E2 E3 (iii) 2 Projectile motion HE5 E3 E3 E4	<u>`</u>				
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$					
4(a) 3 Binomial theorem PE3 E2—E3  4(b)(i) 2 Equation $\frac{dN}{dt} = k(N-P)$ (ii) 2 Logarithmic and exponential functions H3 E2—E3  4(c)(i) 2 Polynomials PE3 E2—E3  (ii) 3 Iterative methods PE3 E2—E3  (ii) 2 Further probability HE3 E2—E3  (iii) 2 Further probability HE3 E2—E3  (ii) 3 Applications of calculus to the physical world HE5 E3—E4  5(a)(i) 1 Logarithmic and exponential functions H5 E2—E3  (ii) 2 Logarithmic and exponential functions H5 E2—E3  (iii) 2 Logarithmic and exponential functions H5 E2—E3  (iii) 2 Inequalities PE3 E3—E4  5(a)(i) 1 Inverse functions H5 E2—E3  (iii) 2 Inverse functions HE4 E2—E3  (iii) 2 Inverse functions HE5 E2—E3  (iii) 2 Simple harmonic motion HE3 E2—E3  (iii) 3 Velocity and acceleration as a function of $x$ HE5 E2—E3  (iii) 2 Velocity and acceleration as a function of $x$ HE5 E3—E4  (b)(i) 2 Projectile motion HE3 E2—E3  (iii) 2 Projectile motion HE3 E2—E3	3(c)			<del></del>	
4(b)(i)2Equation $\frac{dN}{dt} = k(N-P)$ HE3E2 - E3(ii)2Logarithmic and exponential functionsH3E2 - E34(c)(i)2PolynomialsPE3E2 - E3(ii)3Iterative methodsPE3E2 - E35(a)(i)1Further probabilityHE3E2 - E3(ii)2Further probabilityHE3E2 - E3(ii)3Applications of calculus to the physical worldHE5E3 - E45(b)(i)1Logarithmic and exponential functionsH5E2 - E3(ii)2Logarithmic and exponential functionsH5E2 - E3(iii)2Logarithmic and exponential functionsH5E2 - E3(iii)2InequalitiesPE3E3 - E45(a)(i)1Inverse functionsHE4E2 - E3(iii)2Inverse functionsHE4E2 - E3(iii)3Primitive of $\sin^2 x$ H8E3 - E45(b)(i)2Simple harmonic motionHE3E2 - E3(iii)2Simple harmonic motionHE3E2 - E3(iii)2Simple harmonic motionHE3E2 - E3(iii)2Simple harmonic motionHE5E2 - E3(iii)2Simple harmonic motionHE5E2 - E3(iii)3Velocity and acceleration as a function of xHE5E2 - E3(iii)2Velocity and acceleration as a function of xHE5HE5HE5					
(ii) 2 Logarithmic and exponential functions H3 E2 E3  (ii) 3 Iterative methods PE3 E2 E3  (ii) 3 Iterative methods PE3 E2 E3  (iii) 2 Further probability HE3 E2 E3  (iii) 3 Applications of calculus to the physical world HE5 E3 E4  (iii) 2 Logarithmic and exponential functions H5 E2 E3  (iii) 2 Logarithmic and exponential functions H5 E2 E3  (iii) 2 Logarithmic and exponential functions H5 E2 E3  (iii) 2 Inequalities PE3 E3 E3 E4  (iii) 2 Inverse functions HE4 E2 E3  (iii) 2 Inverse functions HE4 E2 E3  (iii) 2 Inverse functions HE4 E2 E3  (iii) 2 Simple harmonic motion HE3 E3 E4  (iii) 2 Simple harmonic motion HE5 E2 E3  (iii) 2 Simple harmonic motion HE3 E3 E4  (iii) 2 Simple harmonic motion HE5 E2 E3  (iii) 2 Simple harmonic motion HE3 E3 E4  (iii) 2 Velocity and acceleration as a function of $x$ HE5 E2 E3  (iii) 2 Velocity and acceleration as a function of $x$ HE5 E2 E3  (iii) 2 Projectile motion HE3  (iii) 2 Projectile motion HE3				PE3	
$4(c)(i)$ 2PolynomialsPE3 $E2-E3$ $(ii)$ 3Iterative methodsPE3 $E2-E3$ $5(a)(i)$ 1Further probabilityHE3 $E2-E3$ $5(b)(i)$ 1Basic arithmetic and algebraP3 $E2-E3$ $5(b)(i)$ 1Basic arithmetic and algebraP3 $E2-E3$ $5(b)(i)$ 1Logarithmic and exponential functionsHE5 $E3-E4$ $5(c)(i)$ 1Logarithmic and exponential functionsH5 $E2-E3$ $(ii)$ 2Logarithmic and exponential functionsH5 $E2-E3$ $(iii)$ 2InequalitiesPE3 $E3-E4$ $5(a)(i)$ 1Inverse functionsHE4 $E2-E3$ $(iii)$ 2Inverse functionsHE4 $E2-E3$ $(iii)$ 3Primitive of $\sin^2 x$ H8 $E3-E4$ $5(b)(i)$ 2Simple harmonic motionHE3 $E2-E3$ $(iii)$ 2Simple harmonic motionHE3 $E2-E3$ $(iii)$ 2Simple harmonic motionHE3 $E3-E4$ $7(a)(i)$ 1Velocity and acceleration as a function of $x$ HE5 $E3-E4$ $7(b)(i)$ 2Projectile motionHE5 $E3-E4$ $7(b)(i)$ 2Projectile motionHE3 $E2-E3$ $8(b)(i)$ 2Projectile motionHE3 $E3-E4$	4(b)(1)	2		HE3	E2 — E3
$4(c)(i)$ 2PolynomialsPE3 $E2-E3$ $(ii)$ 3Iterative methodsPE3 $E2-E3$ $5(a)(i)$ 1Further probabilityHE3 $E2-E3$ $5(b)(i)$ 1Basic arithmetic and algebraP3 $E2-E3$ $5(b)(i)$ 1Basic arithmetic and algebraP3 $E2-E3$ $5(b)(i)$ 1Logarithmic and exponential functionsHE5 $E3-E4$ $5(c)(i)$ 1Logarithmic and exponential functionsH5 $E2-E3$ $(ii)$ 2Logarithmic and exponential functionsH5 $E2-E3$ $(iii)$ 2InequalitiesPE3 $E3-E4$ $5(a)(i)$ 1Inverse functionsHE4 $E2-E3$ $(iii)$ 2Inverse functionsHE4 $E2-E3$ $(iii)$ 3Primitive of $\sin^2 x$ H8 $E3-E4$ $5(b)(i)$ 2Simple harmonic motionHE3 $E2-E3$ $(iii)$ 2Simple harmonic motionHE3 $E2-E3$ $(iii)$ 2Simple harmonic motionHE3 $E3-E4$ $7(a)(i)$ 1Velocity and acceleration as a function of $x$ HE5 $E3-E4$ $7(b)(i)$ 2Projectile motionHE5 $E3-E4$ $7(b)(i)$ 2Projectile motionHE3 $E2-E3$ $8(b)(i)$ 2Projectile motionHE3 $E3-E4$	(ii)		Logarithmic and exponential functions	H3	E2 — E3
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	4(c)(i)	<del></del>	Polynomials	PE3	E2 — E3
(ii) 2 Further probability HE3 E2—E3 $(5(b) (i)$ 1 Basic arithmetic and algebra P3 E2—E3  (ii) 3 Applications of calculus to the physical world HE5 E3—E4 $(5(c) (i)$ 1 Logarithmic and exponential functions H5 E2—E3  (iii) 2 Logarithmic and exponential functions H5 E2—E3  (iii) 2 Inequalities PE3 E3—E4 $(6(a) (i)$ 1 Inverse functions HE4 E2—E3  (iii) 2 Inverse functions HE4 E2—E3  (iii) 3 Primitive of $\sin^2 x$ H8 E3—E4 $(6(b) (i)$ 2 Simple harmonic motion HE3 E2—E3  (iii) 2 Simple harmonic motion HE3 E2—E3  (iii) 2 Simple harmonic motion HE3 E2—E3  (iii) 3 Velocity and acceleration as a function of $x$ HE5 E2—E3  (iii) 3 Velocity and acceleration as a function of $x$ HE5, HE7 E3—E4  (iii) 2 Projectile motion HE3 E2—E3  (iii) 2 Projectile motion HE3 E2—E3	(ii)	3	Iterative methods	PE3	E2 — E3
(ii) 2 Further probability HE3 E2—E3 $(5(b) (i)$ 1 Basic arithmetic and algebra P3 E2—E3  (ii) 3 Applications of calculus to the physical world HE5 E3—E4 $(5(c) (i)$ 1 Logarithmic and exponential functions H5 E2—E3  (iii) 2 Logarithmic and exponential functions H5 E2—E3  (iii) 2 Inequalities PE3 E3—E4 $(6(a) (i)$ 1 Inverse functions HE4 E2—E3  (iii) 2 Inverse functions HE4 E2—E3  (iii) 3 Primitive of $\sin^2 x$ H8 E3—E4 $(6(b) (i)$ 2 Simple harmonic motion HE3 E2—E3  (iii) 2 Simple harmonic motion HE3 E2—E3  (iii) 2 Simple harmonic motion HE3 E2—E3  (iii) 3 Velocity and acceleration as a function of $x$ HE5 E2—E3  (iii) 3 Velocity and acceleration as a function of $x$ HE5, HE7 E3—E4  (iii) 2 Projectile motion HE3 E2—E3  (iii) 2 Projectile motion HE3 E2—E3	5(a)(i)	1	Further probability	HF3	F2 F3
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$		2			
(ii) 3 Applications of calculus to the physical world $E3 - E4$ $E3 - E4$ $E5$ $E5$ $E6$ $E5$ $E6$ $E5$ $E6$ $E5$ $E6$ $E5$ $E6$ $E5$ $E6$ $E7$ $E8$ $E8$ $E8$ $E9$ $E9$ $E9$ $E9$ $E9$ $E9$ $E9$ $E9$		1			
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	4.67001110-10110110-10110110-10110-10110-10110-10110-10110-10110-10110-10110-10110-10110-10110-10110-10110-101	3			<del></del>
(ii)2Logarithmic and exponential functionsH5E2 — E3(iii)2InequalitiesPE3E3 — E4 $G(a)(i)$ 1Inverse functionsHE4E2 — E3(ii)2Inverse functionsHE4E2 — E3(iii)3Primitive of $\sin^2 x$ H8E3 — E4 $G(b)(i)$ 2Simple harmonic motionHE3E2 — E3(iii)2Simple harmonic motionHE3E2 — E3(iii)2Simple harmonic motionHE3E3 — E4 $I(a)(i)$ 1Velocity and acceleration as a function of $x$ HE5E2 — E3(iii)3Velocity and acceleration as a function of $x$ HE5E3 — E4 $I(a)(i)$ 2Velocity and acceleration as a function of $x$ HE5, HE7E3 — E4 $I(b)(i)$ 2Projectile motionHE3E2 — E3(iii)2Projectile motionHE3E2 — E3(iii)2Projectile motionHE3E3 — E4	5(c)(i)	1			
(iii)2InequalitiesPE3E3 — E4 $5(a)(i)$ 1Inverse functionsHE4E2 — E3(ii)2Inverse functionsHE4E2 — E3(iii)3Primitive of $\sin^2 x$ H8E3 — E4 $5(b)(i)$ 2Simple harmonic motionHE3E2 — E3(ii)2Simple harmonic motionHE3E3 — E4 $7(a)(i)$ 1Velocity and acceleration as a function of $x$ HE5E2 — E3(ii)3Velocity and acceleration as a function of $x$ HE5E3 — E4 $7(b)(i)$ 2Velocity and acceleration as a function of $x$ HE5HE5 — E4 $7(b)(i)$ 2Projectile motionHE3E2 — E3(ii)2Projectile motionHE3E2 — E3(iii)2Projectile motionHE3E2 — E3(iii)2Projectile motionHE3E3 — E4		2			<del> </del>
(ii)2Inverse functionsHE4E2 — E3(iii)3Primitive of $\sin^2 x$ H8E3 — E4 $5(b)(i)$ 2Simple harmonic motionHE3E2 — E3(ii)2Simple harmonic motionHE3E2 — E3(iii)2Simple harmonic motionHE5E3 — E4 $7(a)(i)$ 1Velocity and acceleration as a function of $x$ HE5E2 — E3(ii)3Velocity and acceleration as a function of $x$ HE5E3 — E4 $(iii)$ 2Velocity and acceleration as a function of $x$ HE5, HE7E3 — E4 $(iii)$ 2Projectile motionHE3E2 — E3(ii)2Projectile motionHE3E3 — E4	(iii)	2			<del></del>
(ii)2Inverse functionsHE4E2 — E3(iii)3Primitive of $\sin^2 x$ H8E3 — E4 $5(b)(i)$ 2Simple harmonic motionHE3E2 — E3(ii)2Simple harmonic motionHE3E2 — E3(iii)2Simple harmonic motionHE5E3 — E4 $7(a)(i)$ 1Velocity and acceleration as a function of $x$ HE5E2 — E3(ii)3Velocity and acceleration as a function of $x$ HE5E3 — E4 $(iii)$ 2Velocity and acceleration as a function of $x$ HE5, HE7E3 — E4 $(iii)$ 2Projectile motionHE3E2 — E3(ii)2Projectile motionHE3E3 — E4	6(a)(i)	1	Inverse functions	TIE4	F0 F0
(iii) 3 Primitive of $\sin^2 x$ H8 E3 — E4  (b(b)(i) 2 Simple harmonic motion  (ii) 2 Simple harmonic motion  (iii) 3 Velocity and acceleration as a function of $x$ (ii) 3 Velocity and acceleration as a function of $x$ (iii) 2 Velocity and acceleration as a function of $x$ (iii) 2 Velocity and acceleration as a function of $x$ (iii) 2 Projectile motion  (iii) 2 Projectile motion  (iii) 2 Projectile motion  (iii) 2 Projectile motion  (iii) 3 Projectile motion  (iii) 4 Projectile motion  (iii) 5 Projectile motion  (iii) 6 Projectile motion  (iii) 7 Projectile motion  (iii) 8 Projectile motion  (iii) 9 Projectile motion  (iii) 1 Projectile motion  (iii) 2 Projectile motion  (iii) 2 Projectile motion  (iii) 3 Projectile motion  (iii) 4 Projectile motion  (iii) 5 Projectile motion					<del>                                     </del>
(i) $(i)$ <th< td=""><td></td><td></td><td></td><td>4</td><td></td></th<>				4	
(ii)2Simple harmonic motionHE3E2 — E3(iii)2Simple harmonic motionHE3E3 — E4 $f(a)(i)$ 1Velocity and acceleration as a function of $x$ HE5E2 — E3(ii)3Velocity and acceleration as a function of $x$ HE5E3 — E4(iii)2Velocity and acceleration as a function of $x$ HE5, HE7E3 — E4 $f(b)(i)$ 2Projectile motionHE3E2 — E3(ii)2Projectile motionHE3E3 — E4					
(iii)2Simple harmonic motionHE3E3 — E4 $f(a)(i)$ 1Velocity and acceleration as a function of $x$ HE5E2 — E3(ii)3Velocity and acceleration as a function of $x$ HE5E3 — E4(iii)2Velocity and acceleration as a function of $x$ HE5, HE7E3 — E4 $f(b)(i)$ 2Projectile motionHE3E2 — E3(ii)2Projectile motionHE3E3 — E4	THE RESERVE THE PERSON NAMED IN COLUMN TWO IS NOT THE PERSON NAMED IN COLUMN TWO IS NAMED IN COLUMN			<del> </del>	
f(a)(i)1Velocity and acceleration as a function of $x$ HE5E3 — E4 $(ii)$ 3Velocity and acceleration as a function of $x$ HE5E3 — E4 $(iii)$ 2Velocity and acceleration as a function of $x$ HE5, HE7E3 — E4 $f(b)(i)$ 2Projectile motionHE3E2 — E3 $f(b)(i)$ 2Projectile motionHE3E3 — E4	The state of the s				
(ii)3Velocity and acceleration as a function of $x$ HE5E3 — E4(iii)2Velocity and acceleration as a function of $x$ HE5, HE7E3 — E4(b)(i)2Projectile motionHE3E2 — E3(ii)2Projectile motionHE3E3 — E4					
(iii)2Velocity and acceleration as a function of $x$ HE5, HE7E3—E4 $f(b)(i)$ 2Projectile motionHE3E2—E3(ii)2Projectile motionHE3E3—E4					
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$					
(ii) 2 Projectile motion HE3 E3—E4			Projectile motion		
	(iii)	2	Projectile motion	HE3	E3 — E4 E3 — E4

4 . .