Student Name:	R	
Student ID:		
PSS Room/Demonstrator:	R	

THE UNIVERSITY OF NEW SOUTH WALES

SCHOOL OF MECHANICAL AND MANUFACTURING ENGINEERING

March 2018

MMANI300 - ENGINEERING MECHANICS 1

Block Test - 1

Instructions:

Time allowed: 45 minutes

Total number of questions: 3

Answer ALL the questions in the spaces provided

The marks allocations shown will be scaled to 6 basic marks.

Candidates may bring drawing instruments, rules and UNSW approved calculators to the test

Print your name, student ID and PSS allocation on top right corner of the question paper

Record your answers (with appropriate units) in the ANSWER BOXES provided

Notes:

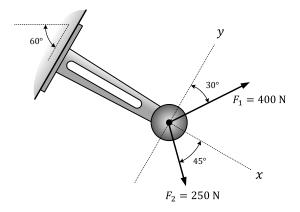
Your work must be complete, clear and logical

Do not skip steps, sign conventions, units and relevant diagrams and clearly state the final answers

No part of this paper is to be retained by candidates until handed back after marking

Question 1: (2 Marks)

A member is subjected to forces $F_1 = 400 \text{ N}$ and $F_2 = 250 \text{ N}$, as shown. Determine the magnitude and direction of the resultant force measured counterclockwise from the positive x-axis



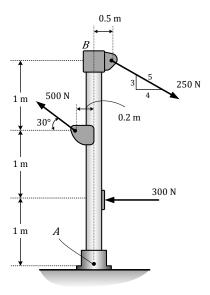
Solution:

Present your solution to Qu	estion 1 nere:		

Answers:	$ F_R =$	$\theta =$
Continue your solution to	Question 1 here:	

Question 2: (2 Marks)

Replace the force system acting on the post by a resultant force, and specify where its line of action intersects the post *AB* measured from point *B.* (*Proceed according to the steps in solution boxes*)



Solution:

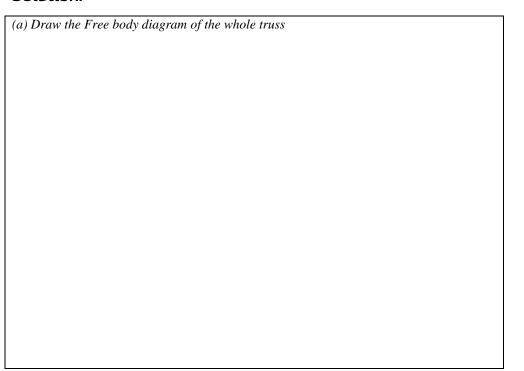
(a) Determine the magnitude of the equivalent resultant force			

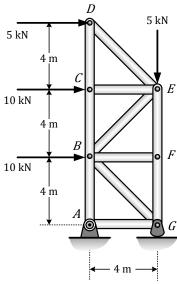
(c) Location of the resul	ltant force	

Question 3:	(2 Marks)

The truss is loaded by the four forces as shown. Determine the following (Proceed according to the steps in solution boxes):

Solution:





(b) Determine the support reactions at A and G	

(d) Use your resu	elts from (a), (b) and (c) to	o check equilibrium of join	t A.	

Equation Sheet

Linear motion

$$v = \frac{ds}{dt}$$
 $a = \frac{dv}{dt}$ $vdv = ads$

$$a = \frac{dv}{dt}$$

$$vdv = ads$$

Constant linear acceleration equations ($t_o = 0$)

$$v = v_o + at$$

$$v^2 = v_o^2 + 2a(s - s_o)$$

$$v = v_o + at$$
 $v^2 = v_o^2 + 2a(s - s_o)$ $s = s_o + v_o t + \frac{1}{2}at^2$

Angular motion

$$\omega = \frac{d\theta}{dt}$$

$$\alpha = \frac{d\omega}{dt}$$

$$\omega = \frac{d\theta}{dt} \qquad \alpha = \frac{d\omega}{dt} \qquad \omega d\omega = \alpha d\theta$$

Displacement, velocity and acceleration components

Rectangular coordinates

$$\mathbf{r} = x\mathbf{i} + y\mathbf{j}$$

$$\mathbf{v} = \dot{x}\mathbf{i} + \dot{y}\mathbf{j}$$

$$\mathbf{v} = \dot{x}\mathbf{i} + \dot{y}\mathbf{j} \qquad \mathbf{a} = \ddot{x}\mathbf{i} + \ddot{y}\mathbf{j}$$

Normal and tangential coordinates

$$\mathbf{v} = v\mathbf{e}$$

$$\mathbf{a} = a_t \mathbf{e}_t + a_n \mathbf{e}$$

$$v = \omega r$$

$$a_t = \dot{v} = \alpha r$$

$$\mathbf{v} = v\mathbf{e_t}$$
 $\mathbf{a} = a_t\mathbf{e_t} + a_n\mathbf{e_n}$ $v = \omega r$ $a_t = \dot{v} = \alpha r$ $a_n = \frac{v^2}{Q} = \omega^2 r$

Relative motion

$$\mathbf{r}_{A} = \mathbf{r}_{B} + \mathbf{r}_{A/B}$$

$$\mathbf{v}_A = \mathbf{v}_B + \mathbf{v}_{A/B}$$
 $\mathbf{a}_A = \mathbf{a}_B + \mathbf{a}_{A/B}$

$$\mathbf{a}_A = \mathbf{a}_B + \mathbf{a}_{A/A}$$

Equation of motion (Newton's 2nd law)

$$\sum \mathbf{F} = m\mathbf{a}$$

$$\frac{\text{Work-Energy}}{W_{1-2} = \Delta T + \Delta V_g + \Delta V_e} \qquad \qquad W_{1-2} = F \Delta s \quad \text{and/or} \quad M \Delta \theta$$

$$W_{i,a} = F\Delta s$$
 and/or $M\Delta \theta$

$$\Delta T = \frac{1}{2} m (v_2^2 - v_1^2)$$
 and/or $\frac{1}{2} I (\omega_2^2 - \omega_1^2)$

$$\Delta V_{\sigma} = mg(h_2 - h_1)$$

$$\Delta V_e = \frac{1}{2} k \left(x_2^2 - x_1^2 \right)$$
 for a linear spring

For a rigid body in plane motion

$$\sum \mathbf{F} = m\mathbf{a}$$
 $\sum M = I\alpha$

$$\sum M = I\alpha$$

Mass moment of inertia $I = \int r^2 dm$

$$I = \int r^2 dn$$

Centroid of a cross-section:

$$\overline{x} = \frac{\int x dA}{\int dA} = \frac{\sum_{i} x_{i} A_{i}}{\sum_{i} A_{i}}$$
 , $\overline{y} = \frac{\int y dA}{\int dA} = \frac{\sum_{i} y_{i} A_{i}}{\sum_{i} A_{i}}$

DATA:

Acceleration in free fall due to gravity $g = 9.81 \text{ m/s}^2$