

**MMAN2300**

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**Engineering Mechanics 2**

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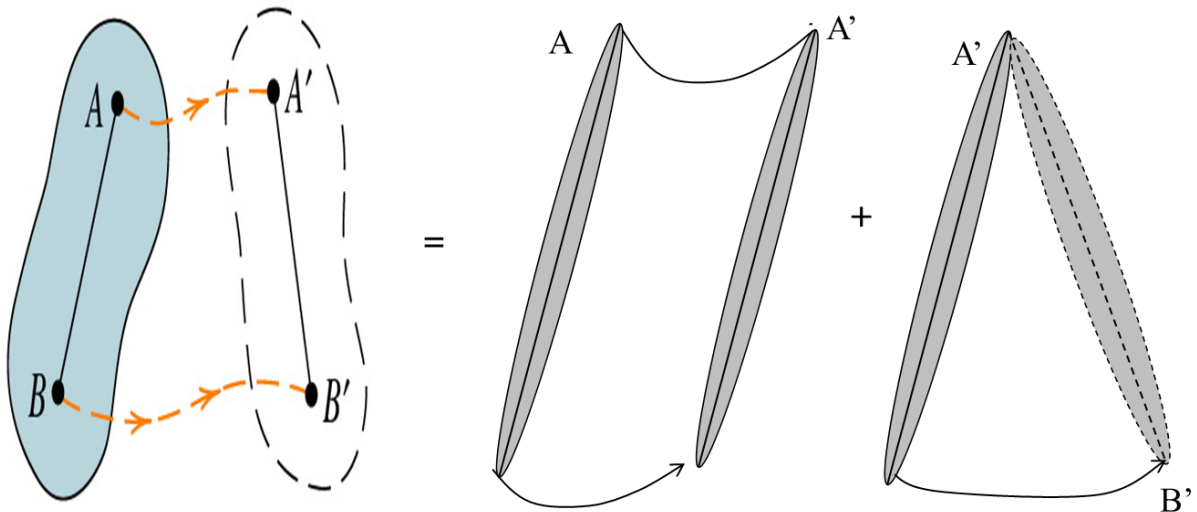
**Part A: Week 1**

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**Velocity analysis of rigid bodies**

(Chapter 5/1-5/4 Meriam and Kraige)

1. General plane motion of a rigid body can be described as a combination of translation and rotation



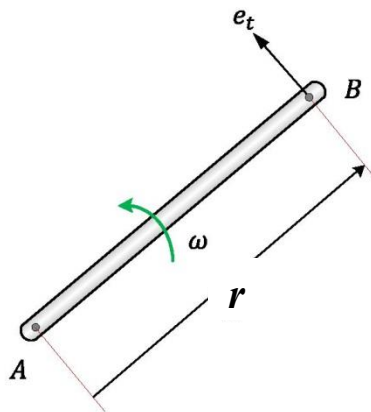
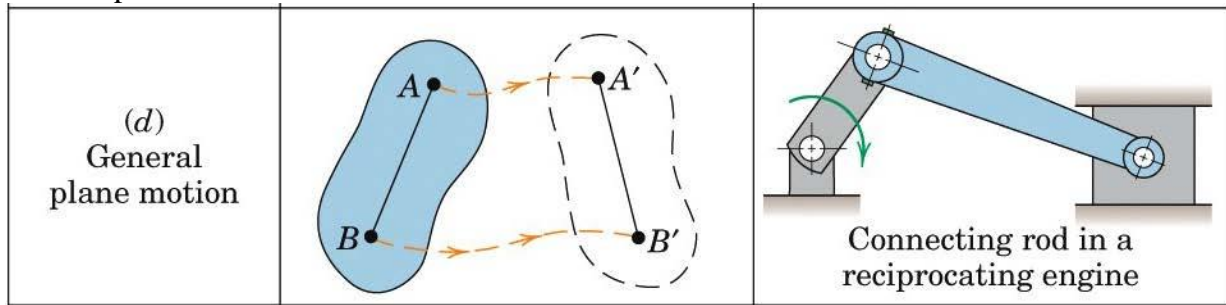
Translation - Defined as any motion in which every line in the body remains parallel to its original position at all times

<p>(a) Rectilinear translation</p>		<p>Rocket test sled</p>
<p>(b) Curvilinear translation</p>		<p>Parallel-link swinging plate</p>

Rotation - All particles in a rigid body move in circular paths about the axis of rotation, and all lines in the body which are perpendicular to the axis of rotation rotate through the same angle in the same time

<p>(c) Fixed-axis rotation</p>		<p>Compound pendulum</p>
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## General plane motion – A combination of translation and rotation



Points  $A$  and  $B$  are fixed on a rigid body.

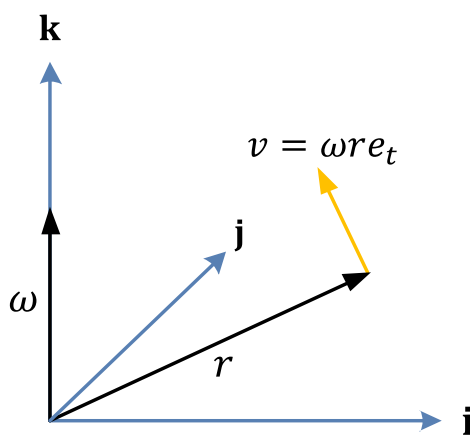
The velocity of point  $B$  is:

$$\mathbf{v}_B = \mathbf{v}_A + \mathbf{v}_{B/A}$$

$$(\text{or } \vec{v}_B = \vec{v}_A + \vec{v}_{B/A}, \quad v_B = v_A + v_{B/A})$$

$$\mathbf{v}_{B/A} = \omega r \mathbf{e}_t = \boldsymbol{\omega} \times \mathbf{r}$$

Right hand rule

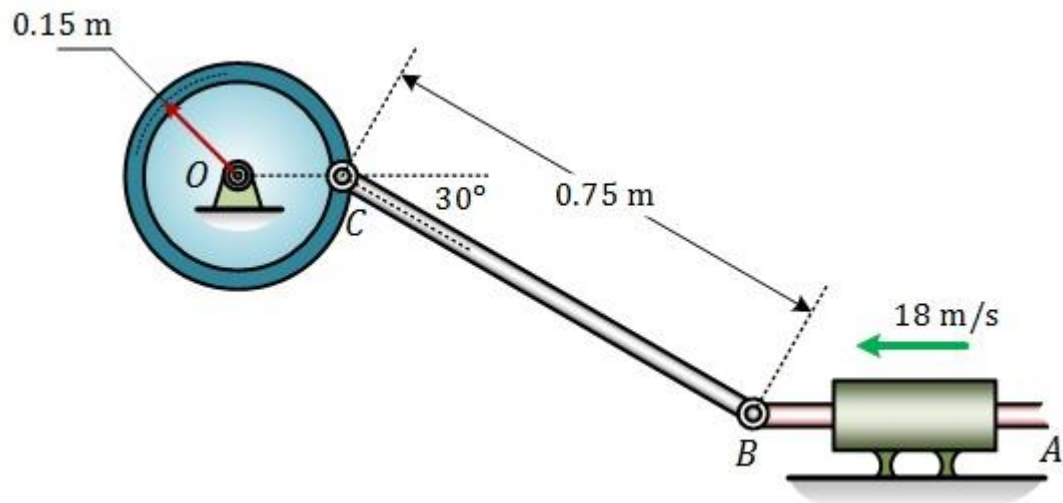


Alternatively, the definition  $\mathbf{v} = \boldsymbol{\omega} \times \mathbf{r}$  gives the direction of  $\mathbf{v}$ . It is at right angles to both  $\boldsymbol{\omega}$  and  $\mathbf{r}$  in the right-handed sense. If you put your right thumb in the direction of  $\boldsymbol{\omega}$  and your forefinger in the direction of  $\mathbf{r}$ , your right middle finger points in the direction of  $\mathbf{v}$ .

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Example 1

If rod  $AB$  slides along the horizontal slot with a velocity of  $18 \text{ m/s}$ , determine the angular velocities of link  $BC$  and the disk at the instant shown.



### Example 2

For the instance represented, crank  $OB$  has a clockwise angular velocity  $\omega = 0.8 \text{ rad/s}$  and is passing the horizontal position.

Determine:

- (a) the corresponding velocity of the guide roller  $A$  in the  $20^\circ$  slot,
- (b) the velocity of point  $C$  midway between  $A$  and  $B$ .

