

MTRN3500

Computing Applications in Mechatronics Systems

Getting used to CLR Applications

T3 - 2020

Motivation

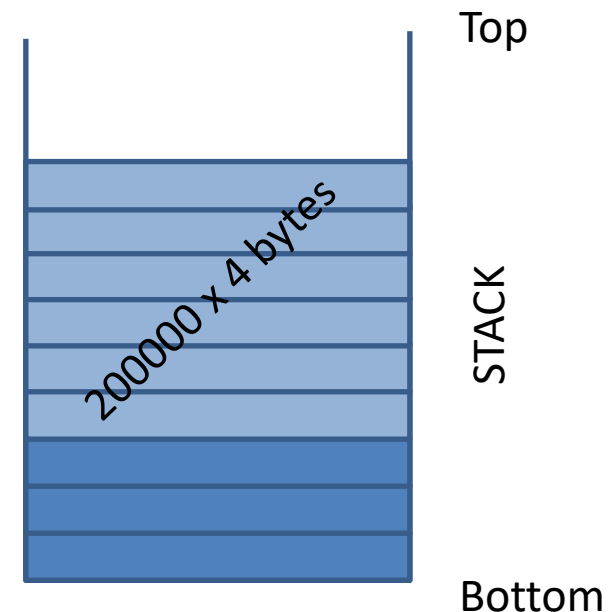
- We would like to use well developed libraries available under CLR (Common Language Runtime)
- We would like the memory management to be done by the system than by us.
- We would like to take advantage of speed of execution that comes with reduced STACK usage and increased HEAP usage.
- We can easily add events.
- We would like to have the reverse engineering made difficult.
- LANGUAGE PROJECTIONS AVAILABLE
 - CLR
 - CX
 - WinRT

What are the differences?

- The C++ we have learnt so far is called **NATIVE C++**. Another word is **UNMANAGED**.
- We call it UNMANAGED because the system does not manage memory for us.
- You may recall, code fragments such as the one below.

```
int main()
{
    int Data[200000]; // Created on the STACK
    // Do some processing
    return 0;
}
```

- A bad habit is that we lavishly create objects requiring large chunks of memory, on the STACK. Anything between curly brackets is created on the stack.
- STACK has limited space and stack management is time consuming.
- Our preference is to minimize the stack usage.

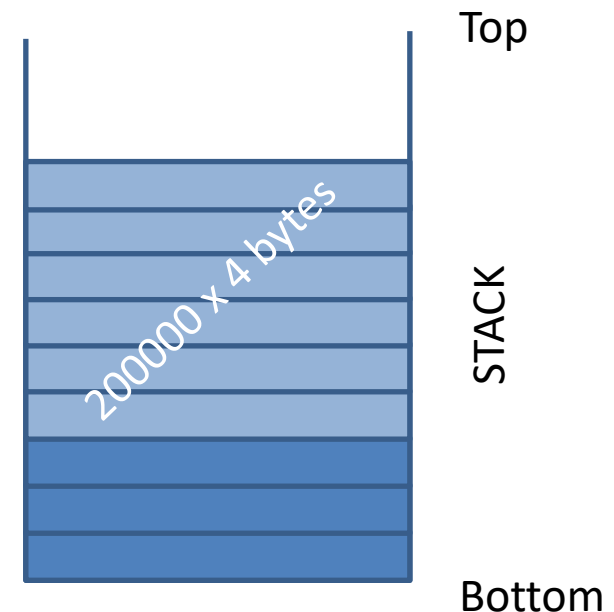


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int main()
{
    int Data[200000]; // Created on the STACK
    // Do some processing
    return 0;
} ← Close curly bracket
```

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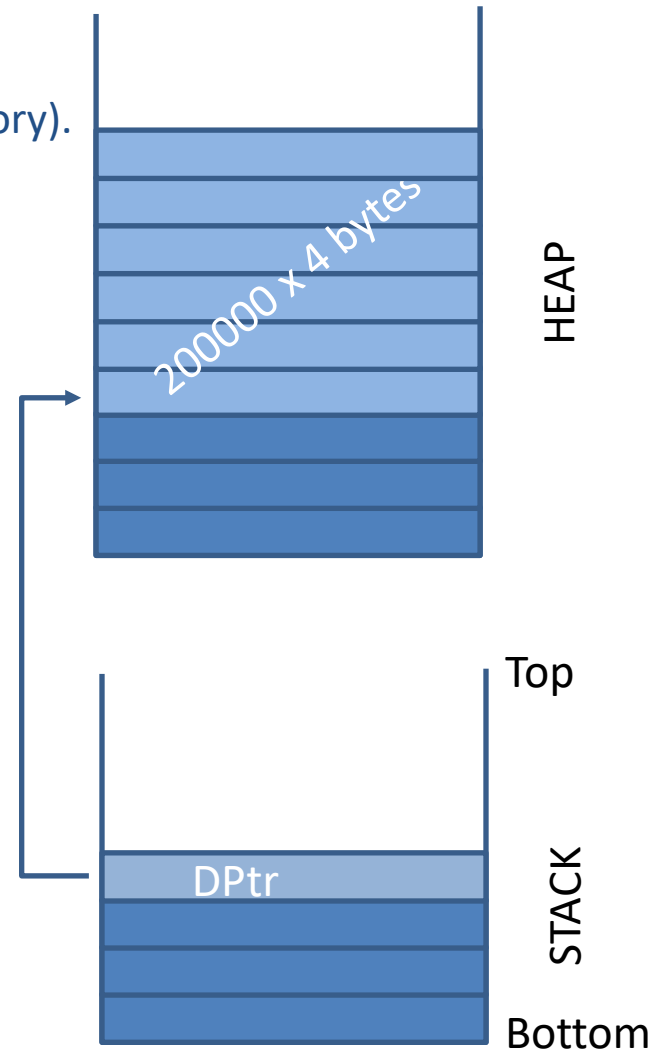
What are the differences?

- In C++ we have a way to not use STACK.
- We create data on the HEAP (on available UNUSED memory).
- We do it through dynamic memory allocation.

```
int main()
{
    //declare a pointer
    int *DPtr = NULL;
    //create data on heap
    DPtr = new int[200000];

    // Do some processing

    return 0;
}
```



What are the differences?

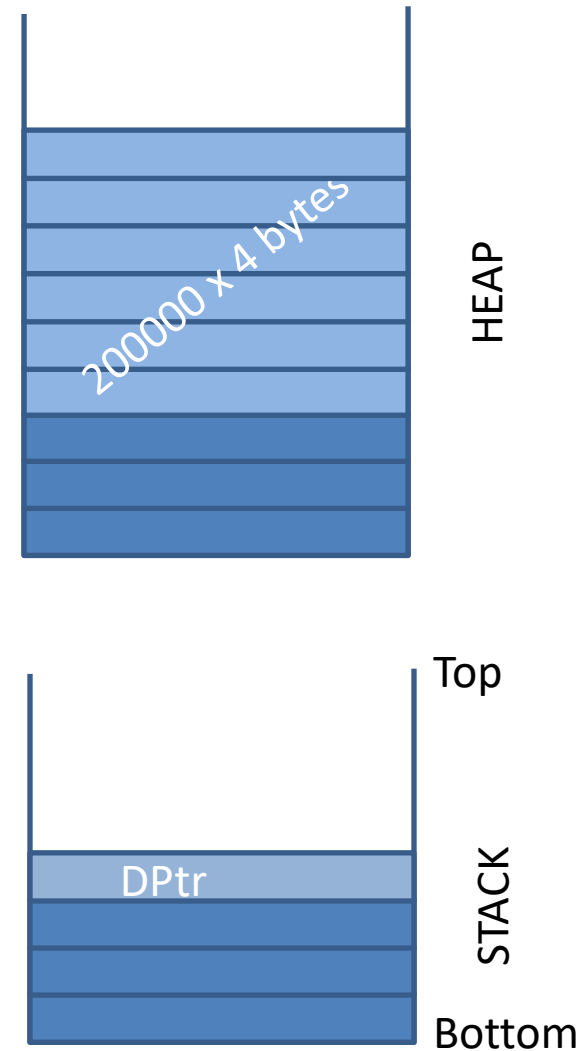
- In C++ we have a way to not use STACK.
- We create data on the HEAP (on available UNUSED memory).
- We do it through dynamic memory allocation.

```
int main()
{
    //declare a pointer
    int *DPtr = NULL;

    //create data on heap
    DPtr = new int[200000];

    // Do some processing
    //free up space on heap
    if (Dptr != NULL)
        delete Dptr;

    return 0;
} ← curly brace
```



What are the differences?

- The C++/CLR we want to use is called **MANAGED**.
- We call it MANAGED because the system does manage the memory for us.
- It also force us to use the HEAP by creating reference objects in contrast to value objects.

```
int main()
{
    int ^DPtr = nullptr; // This is how we declare HANDLES
    DPtr = gcnew <int>[200000]; // we ask for memory on HEAP
    // It is not necessary to use delete
    return 0;
}
```

- It is preferred to create objects on the managed heap using gcnew.
- gc stands for garbage collector.
- Our preference is to minimize the stack usage.
- We can easily mix and match the native and managed code. Generally, mixed mode code is hard to reverse engineer.

A sample CLR program

```
#include <iostream> //Native
using namespace System; //Managed

int main()
{
    std::cout << "Program executed!" << std::endl; //Native
    Console::WriteLine("Program executed!"); //Managed

    Console::ReadKey(); //Managed
    return 0; //Native & Managed
}
```


A sample CLR program

```
#include <conio.h>

using namespace System;
using namespace System::Threading::Tasks;

int main()
{
    Console::WriteLine("Program started!");

    while (1)
    {
        System::Threading::Thread::Sleep(10);
        if (_kbhit()) break;
    }

    Console::ReadKey();
    Console::ReadKey();
    return 0;
}
```

A sample CLR program

```
#include <Windows.h>
#include <conio.h>

using namespace System;
using namespace System::Threading::Tasks;

int main()
{
    UINT64 Frequency, Counter = 0, OldCounter;
    double TimeStamp;
    Console::WriteLine("Program started!");
    QueryPerformanceFrequency((LARGE_INTEGER*)&Frequency);
    QueryPerformanceCounter((LARGE_INTEGER*)&OldCounter);

    while (1)
    {
        QueryPerformanceCounter((LARGE_INTEGER*)&Counter);
        TimeStamp = (double)(Counter - OldCounter) / Frequency;
        OldCounter = Counter;
        Console::WriteLine("{0, 12:F3} ", TimeStamp);
        System::Threading::Thread::Sleep(20);
        if (_kbhit()) break;
    }

    Console::ReadKey();
    Console::WriteLine("Program Terminated Normally!");
    Console::ReadKey();
    return 0;
}
```

A sample CLR program

```
#include <Windows.h>
#include <conio.h>

using namespace System;
using namespace System::Threading::Tasks;

int main(array<String^> ^args)
{
    UINT64 Frequency, Counter = 0, OldCounter;
    double TimeStamp;
    Console::WriteLine("Program started!");
    QueryPerformanceFrequency((LARGE_INTEGER*)&Frequency);
    QueryPerformanceCounter((LARGE_INTEGER*)&OldCounter);

    while (1)
    {
        QueryPerformanceCounter((LARGE_INTEGER*)&Counter);
        TimeStamp = (double)(Counter - OldCounter) / Frequency;
        OldCounter = Counter;
        Console::WriteLine("{0, 12:F3} ", TimeStamp);
        System::Threading::Thread::Sleep(20);
        if (_kbhit()) break;
    }

    Console::ReadKey();
    Console::ReadKey();
    return 0;
}
```

EVENTS

```
#using <System.dll>
#include <conio.h>

using namespace System;
using namespace System::Timers;

void OnElapsed(System::Object^ sender, System::Timers::ElapsedEventArgs^ e);

int main(array<String^>^ args)
{
    Timer^ MyTimer;
    Console::WriteLine("Program started!");
    MyTimer = gcnew Timer(500);
    //Timer configuration
    MyTimer->Enabled = true;
    MyTimer->AutoReset = true;
    MyTimer->Elapsed += gcnew System::Timers::ElapsedEventHandler(&OnElapsed);

    while (1)
    {
        if (_kbhit()) break;
    }
    MyTimer->Enabled = false;
    Console::ReadKey();
    Console::ReadKey();

    return 0;
}

void OnElapsed(System::Object^ sender, System::Timers::ElapsedEventArgs^ e)
{
    Console::WriteLine("Time now {0:HH:mm:ss.fff} ", e->SignalTime);
}
```