

# .Waves and Oscillations

## Lecture 10 – Traveling waves

Textbook reference: 16.1-16.4



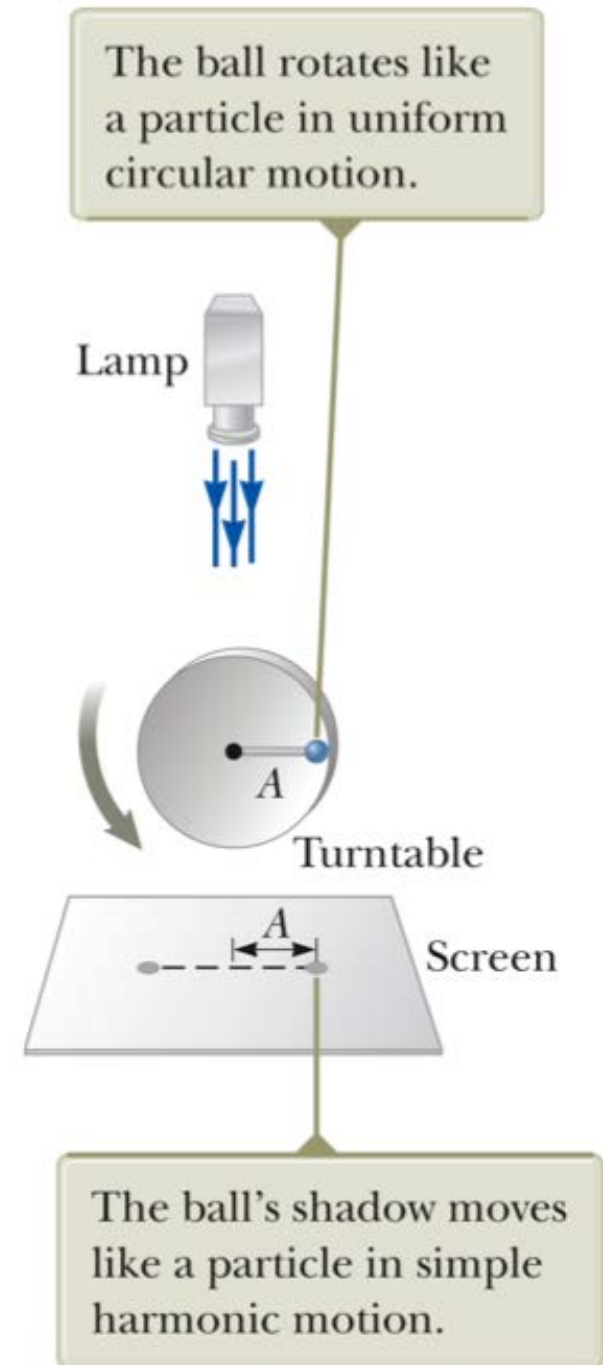
Tacoma Narrows bridge collapse 1940. You are doomed to see this in every engineering course.

# Last lecture...

- **Simple harmonic motion** is the projection of uniform circular motion on a diameter of the circle in which the circular motion occurs.

– Motion of the ball's shadow:  
 $x(t) = A \cos(\omega t + \phi)$

Angular frequency of the SHM  
= angular speed of the circular motion



# Last lecture...

- The motion of a **simple pendulum** is also SHM, if the displacement angle is small ( $\theta \ll 1$  radian).

-Period:

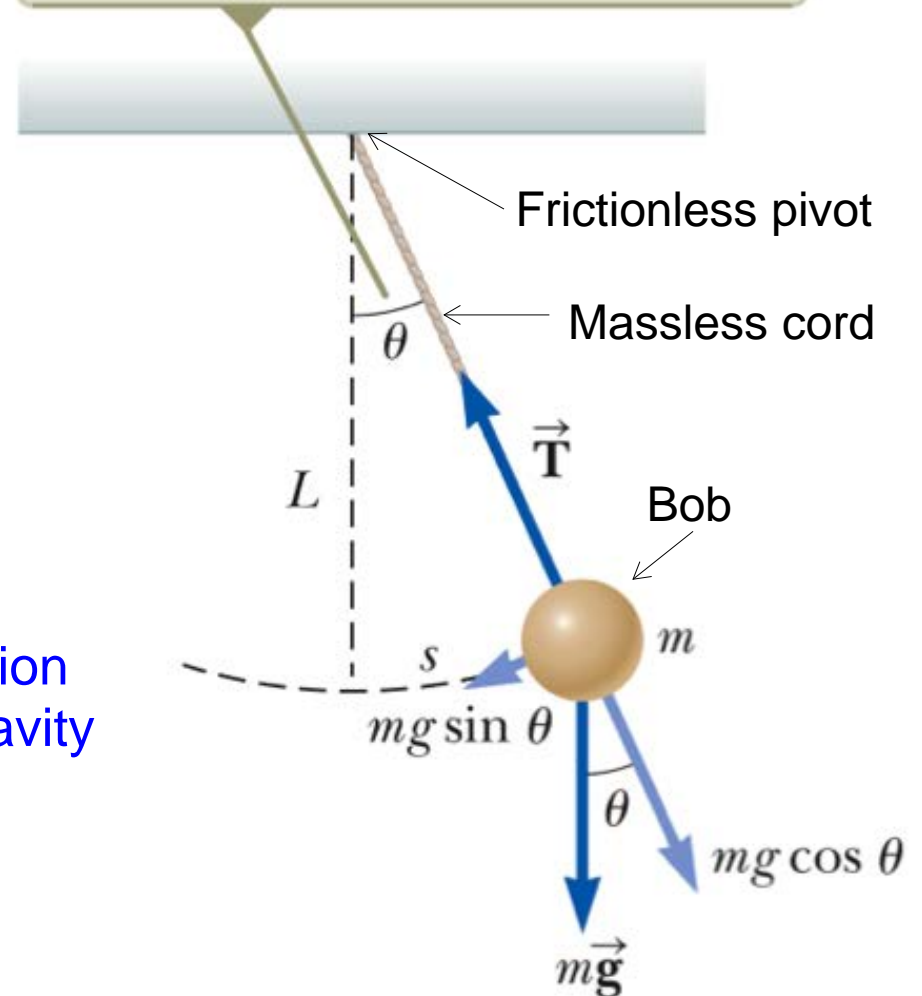
$$T = \frac{2\pi}{\omega} = 2\pi \sqrt{\frac{L}{g}}$$

Length of cord

Acceleration due to gravity

Simple pendulum = a bob at the end of a massless cord suspended from a frictionless pivot.

When  $\theta$  is small, a simple pendulum's motion can be modeled as simple harmonic motion about the equilibrium position  $\theta = 0$ .



# Last lecture...

- A **physical pendulum** swings a pivot  $O$  that is not at the centre-of-mass (CM) of the object.

–Its motion is also SHM (for  $\theta \ll 1$  radian).

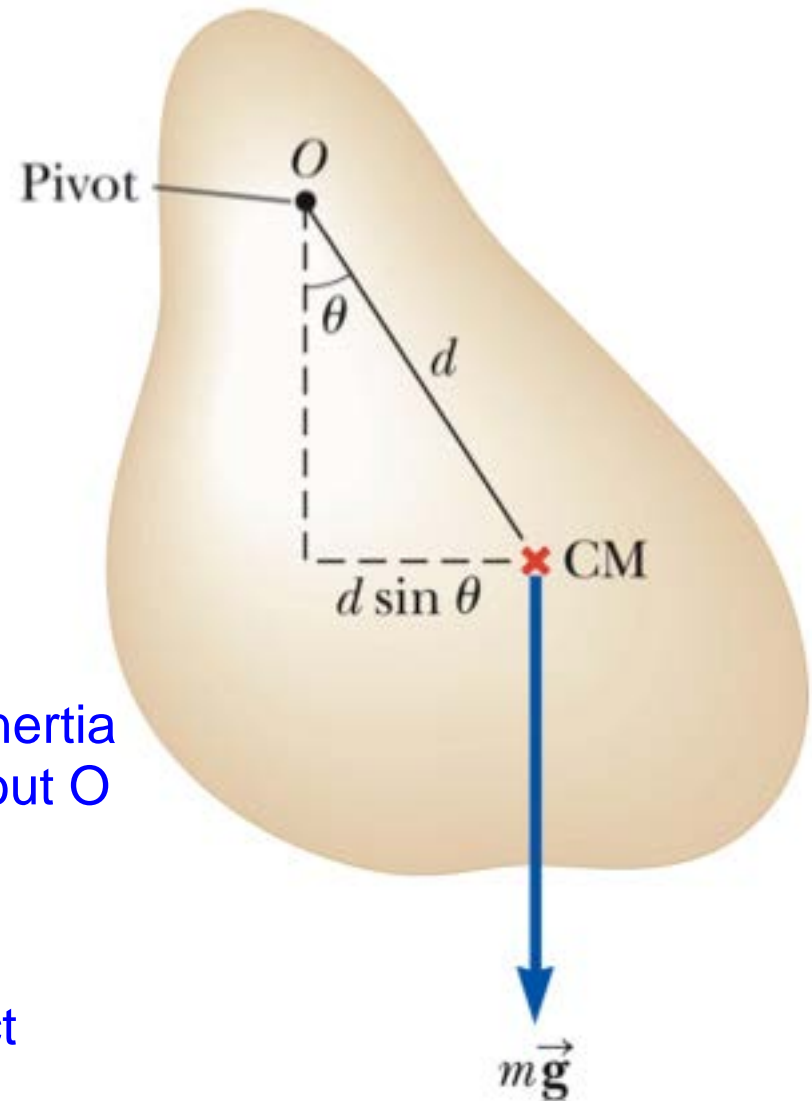
$$T = 2\pi \sqrt{\frac{I}{dmg}}$$

← Moment of inertia of object about  $O$

↗ ↘

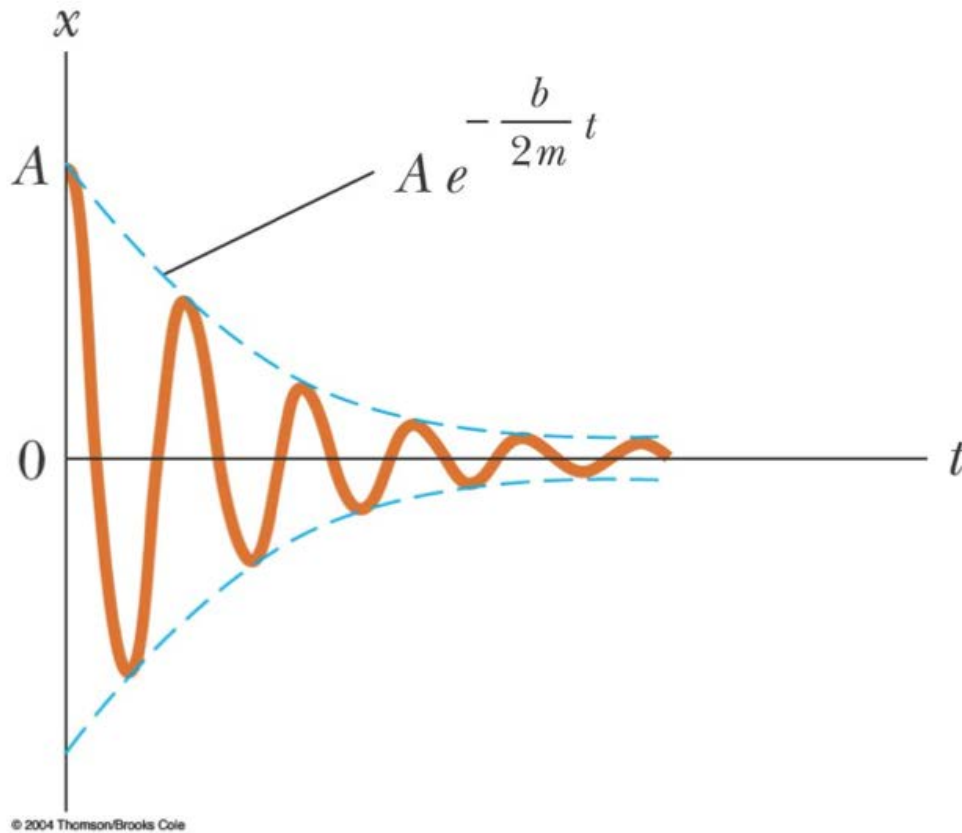
Distance from  $O$  to CM

Mass of object



# This Lecture

## Damped Oscillations



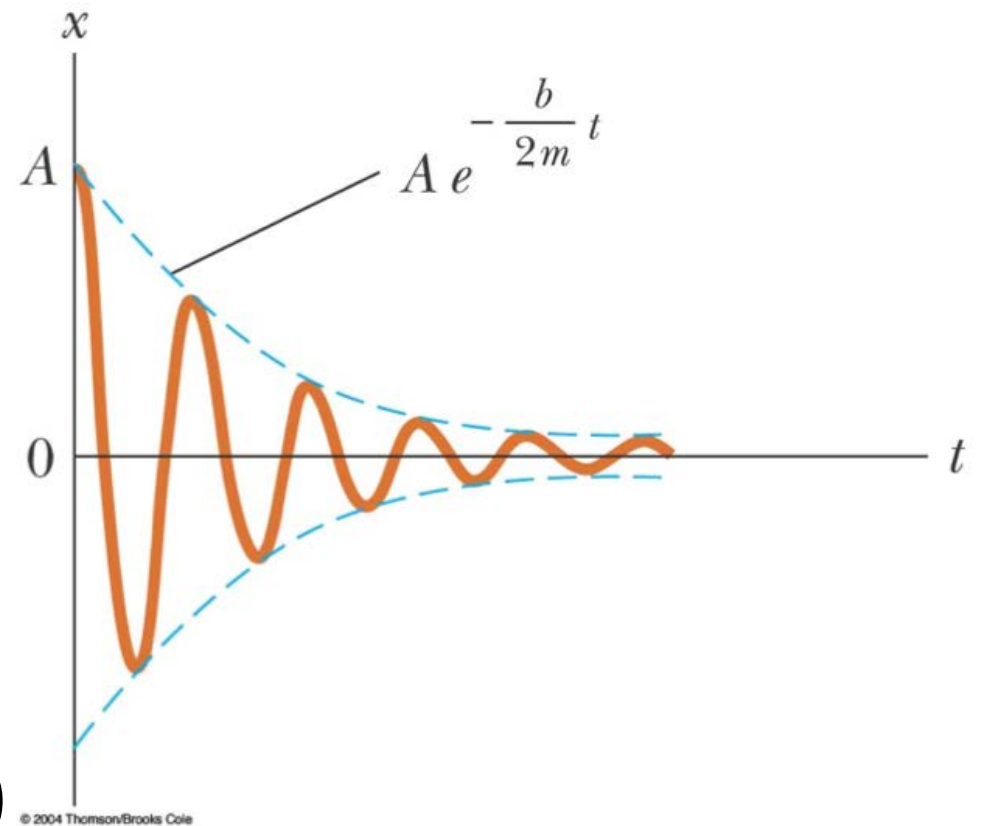
## Travelling waves



# Damped oscillations...

- In realistic systems, **non-conservative forces** such as friction and air resistance are usually present.

- In such cases, the mechanical energy of the system diminishes in time, and the motion of the oscillator is said to be **damped**.



$$x = A e^{(-b/2m)t} \cos(\omega t + \phi)$$

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# Damped oscillations>Example...

## . A spring in a viscous fluid.

The fluid opposes the motion of the block by exerting a “retarding force” proportional to its velocity:

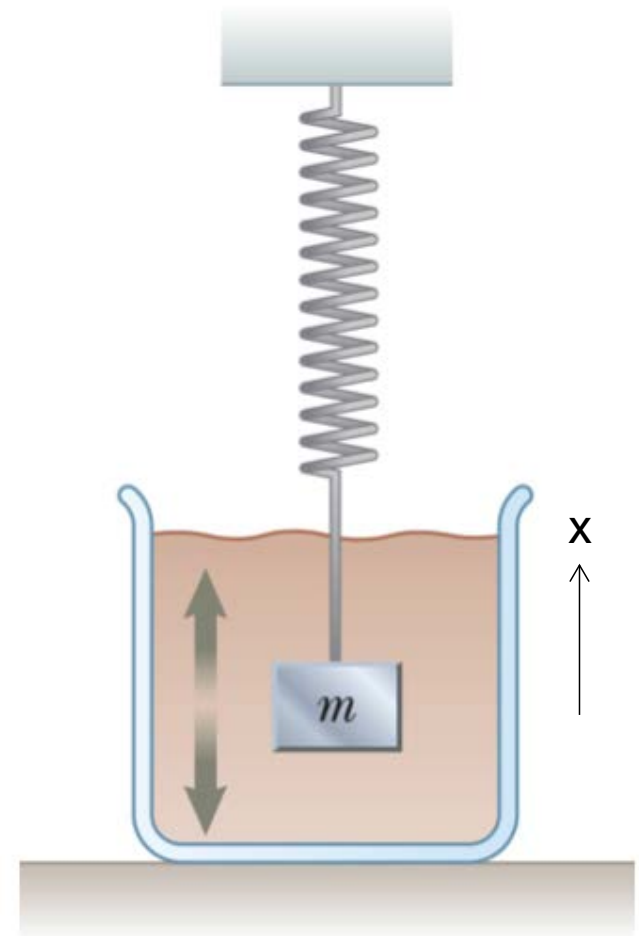
$$\vec{F} = -b\vec{v}$$

Damping constant

- The **total force** on the block is:

$$F_{\text{total}} = -b v_x - kx$$

From fluid      From spring



- **Equation of motion** for the block:

$$ma_x = -bv_x - kx$$

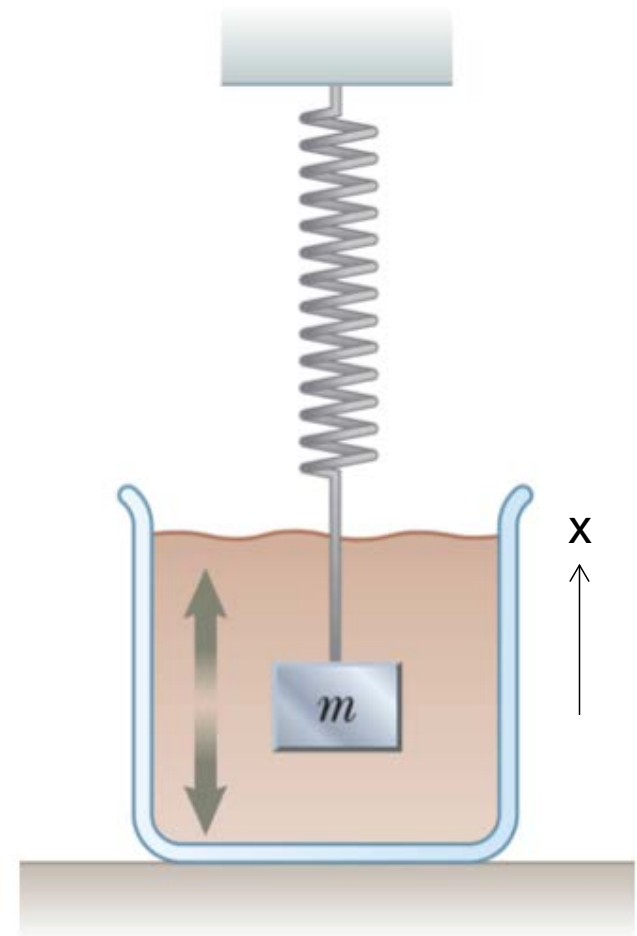
$$\Rightarrow \frac{d^2x}{dt^2} = -\frac{b}{m} \frac{dx}{dt} - \frac{k}{m}x$$

- If the damping constant  $b$  is small (I'll tell you what “small” means in a moment), then the **solution** looks like this:

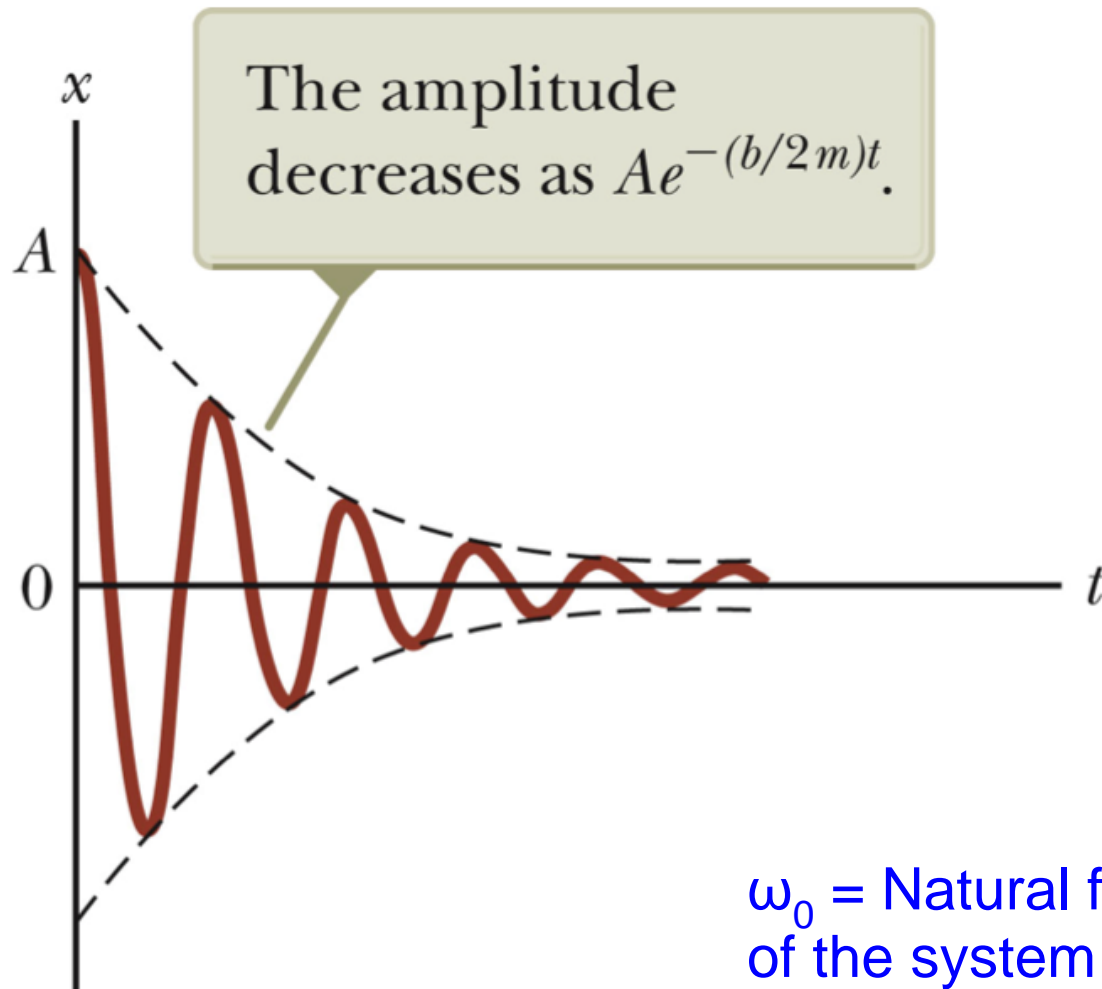
$$x(t) = Ae^{-\frac{b}{2m}t} \cos(\omega t + \phi)$$

$$\omega = \sqrt{\frac{k}{m} - \left(\frac{b}{2m}\right)^2}$$

Angular frequency







$$x(t) = Ae^{-\frac{b}{2m}t} \cos(\omega t + \phi)$$

$$\omega = \sqrt{\frac{k}{m} - \left(\frac{b}{2m}\right)^2}$$

.This solution holds when

$$\omega_0^2 \equiv \frac{k}{m} > \left(\frac{b}{2m}\right)^2 \quad \text{"Small" damping constant}$$

$\omega_0$  = Natural frequency of the system

- When the retarding force is small, the oscillatory character of the motion is preserved, but the amplitude decreases exponentially with time. **What if the retarding force is large?**

# Types of damping...

- In general, there are **three types** damping:

–Underdamping (we've just seen it):

$$\omega_0^2 > \left(\frac{b}{2m}\right)^2 \Rightarrow \omega = \sqrt{\omega_0^2 - \left(\frac{b}{2m}\right)^2} = \text{Real}$$

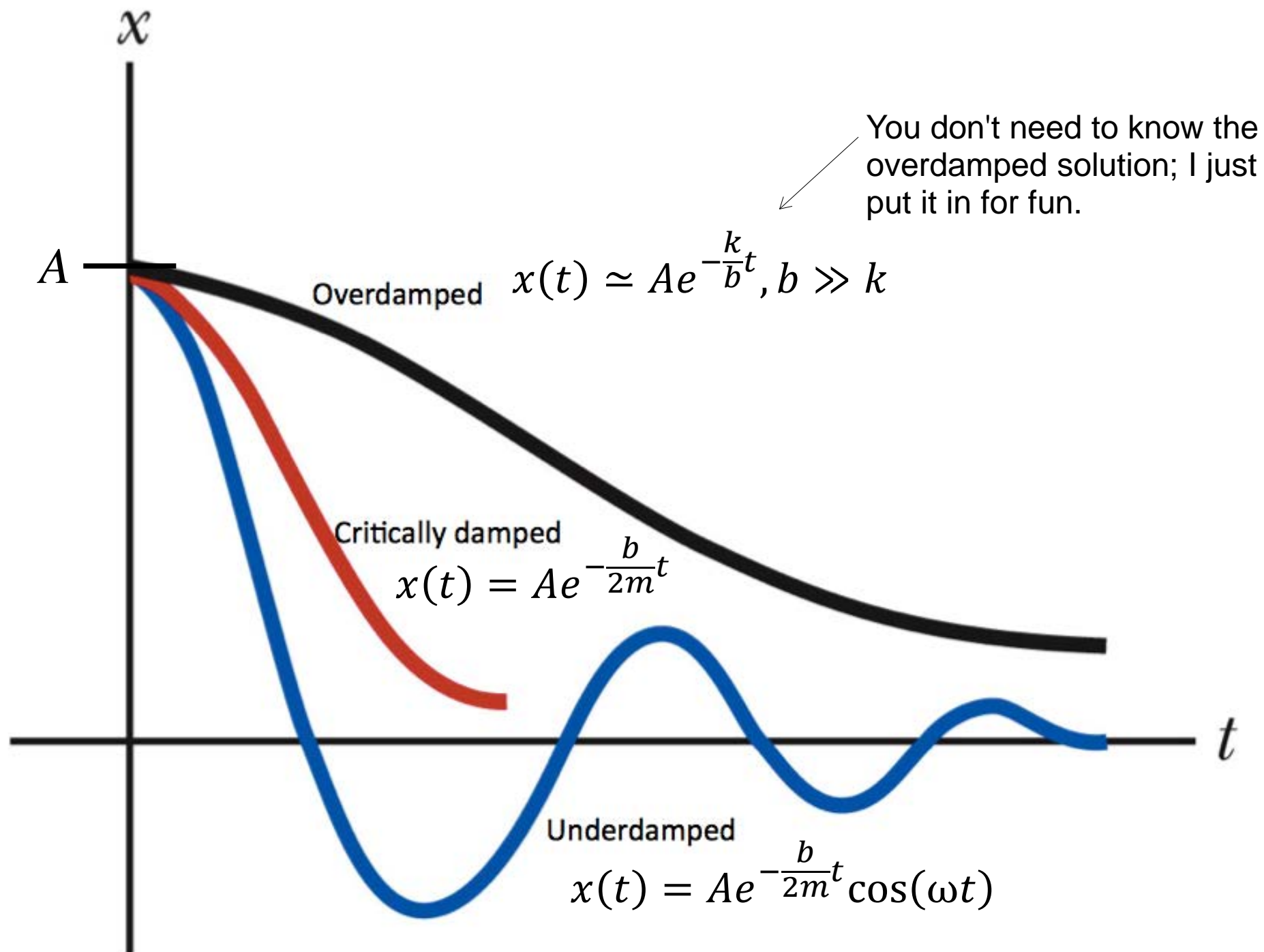
–Critical damping:

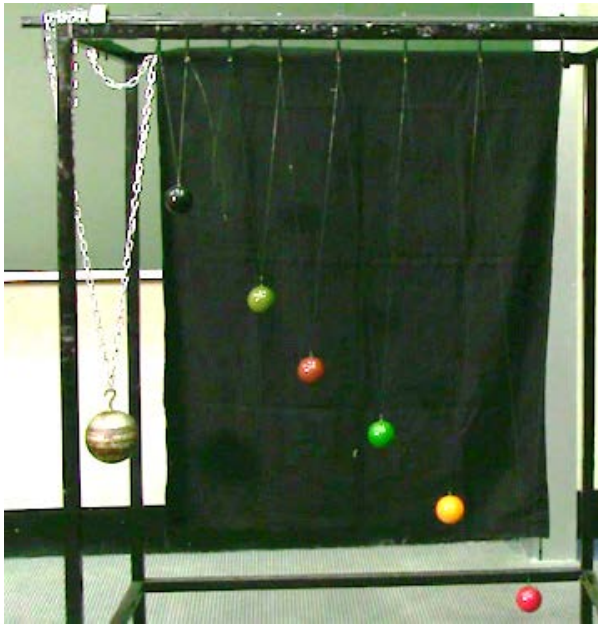
$$\omega_0^2 = \left(\frac{b}{2m}\right)^2 \Rightarrow \omega = 0$$

No oscillations

–Overdamping:

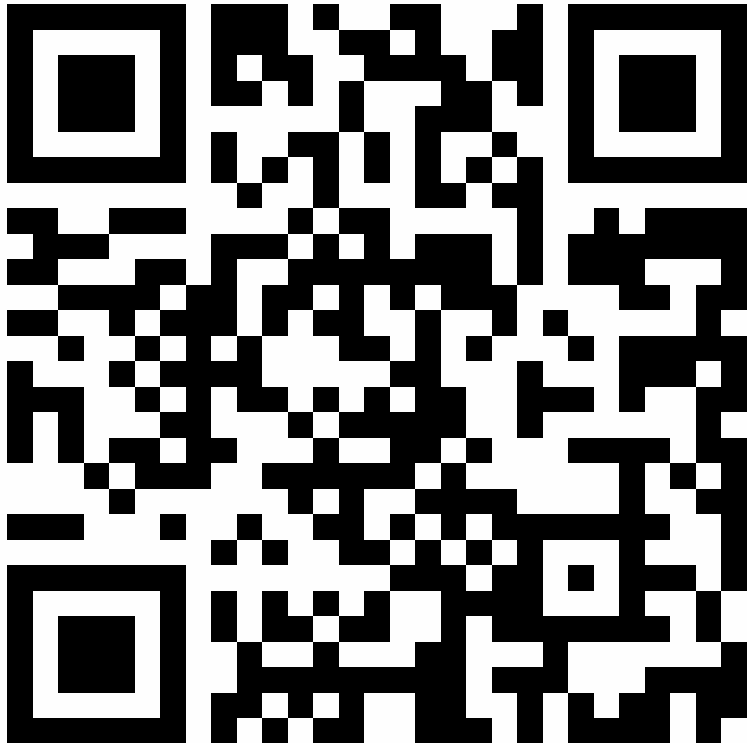
$$\omega_0^2 < \left(\frac{b}{2m}\right)^2 \Rightarrow \omega = \text{Imaginary}$$





What will happen  
when the heavy ball is swung?

- ☐ All the balls will start to swing similar amounts
- ☐ The black ball will swing the most
- ☐ The khaki green ball will swing the most
- ☐ The brown ball will swing the most
- ☐ The bright green ball will swing the most
- ☐ The yellow ball will swing the most
- ☐ The red ball will swing the most
- ☐ Only the heavy silver ball will swing



<https://goo.gl/forms/v4LMBaax2FKzTCYy2>

# Forced oscillations...

- In a damped oscillator, the system loses mechanical energy.
- It is also possible to add energy to the system by doing work in each cycle.

–For example:

$$\underbrace{F_0 \sin \omega_d t}_{\text{A periodic driving force}} - \underbrace{b \frac{dx}{dt} - kx}_{\text{Damped oscillator}} = m \frac{d^2 x}{dt^2}$$

- This is very hard to solve...

....but it will reach a steady state when the energy added each cycle is equal to the energy lost . Then,

$$x(t) = A \cos(\omega_d t + \phi)$$

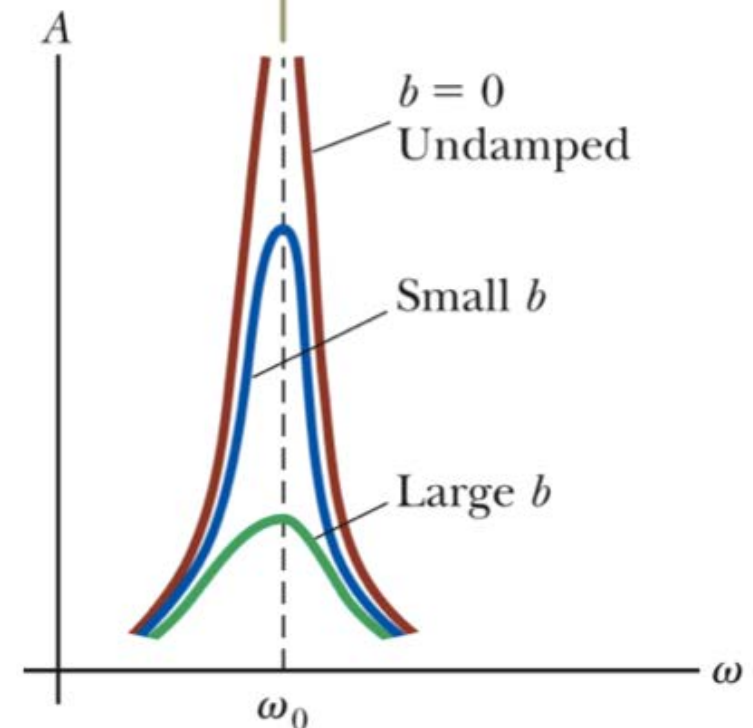
Angular frequency of driving force

$$A = \frac{F_0/m}{\sqrt{(\omega_d^2 - \omega_0^2)^2 + b^2/(4m^2)}}$$

Natural frequency of the undamped system

→ **Resonance** happens when  $\omega_d$  is close to  $\omega_0$  → Dramatic increase in the amplitude.

When the frequency  $\omega$  of the driving force equals the natural frequency  $\omega_0$  of the oscillator, resonance occurs.





# Forced Oscillations

$$A = \frac{F_0/m}{\sqrt{(\omega^2 - \omega_0^2)^2 + \left(\frac{b\omega}{m}\right)^2}}$$

If the wind was **constant**, was the bridge failure due to resonance (forced oscillation)?

<https://youtu.be/6ai2QFxStxo>



# A different topic: Travelling waves



Waves and Oscillations topic: Less fire, more math

# Waves...

- A wave is a *periodic disturbance* that **transports energy** between two points in space.
- But there is **no** accompanying transfer of matter.
- **All** waves carry energy, but the amount and mechanism of transport depends on the **type of wave**.

# Waves > Types of waves...

- **Mechanical waves**, e.g., sounds waves.

- Propagation requires a medium.

We're mainly  
dealing with  
these.

- **Electromagnetic waves**, e.g., visible light, X-rays.

- What is the medium? The “Aether”? Spacetime?

- Propagation doesn't require a medium

- **Matter waves**, i.e., all fundamental particles.

- Follows from wave-particle duality of quantum mechanics.

- Seriously cool.

# .Wa5: Transverse wave pulses and standing waves

Also notice reflection from fixed end + harmonics up to 4



# But first.... A pulse

A pulse is not periodic but is very similar to a wave. It is simpler to visualize so we will occasionally discuss pulses.

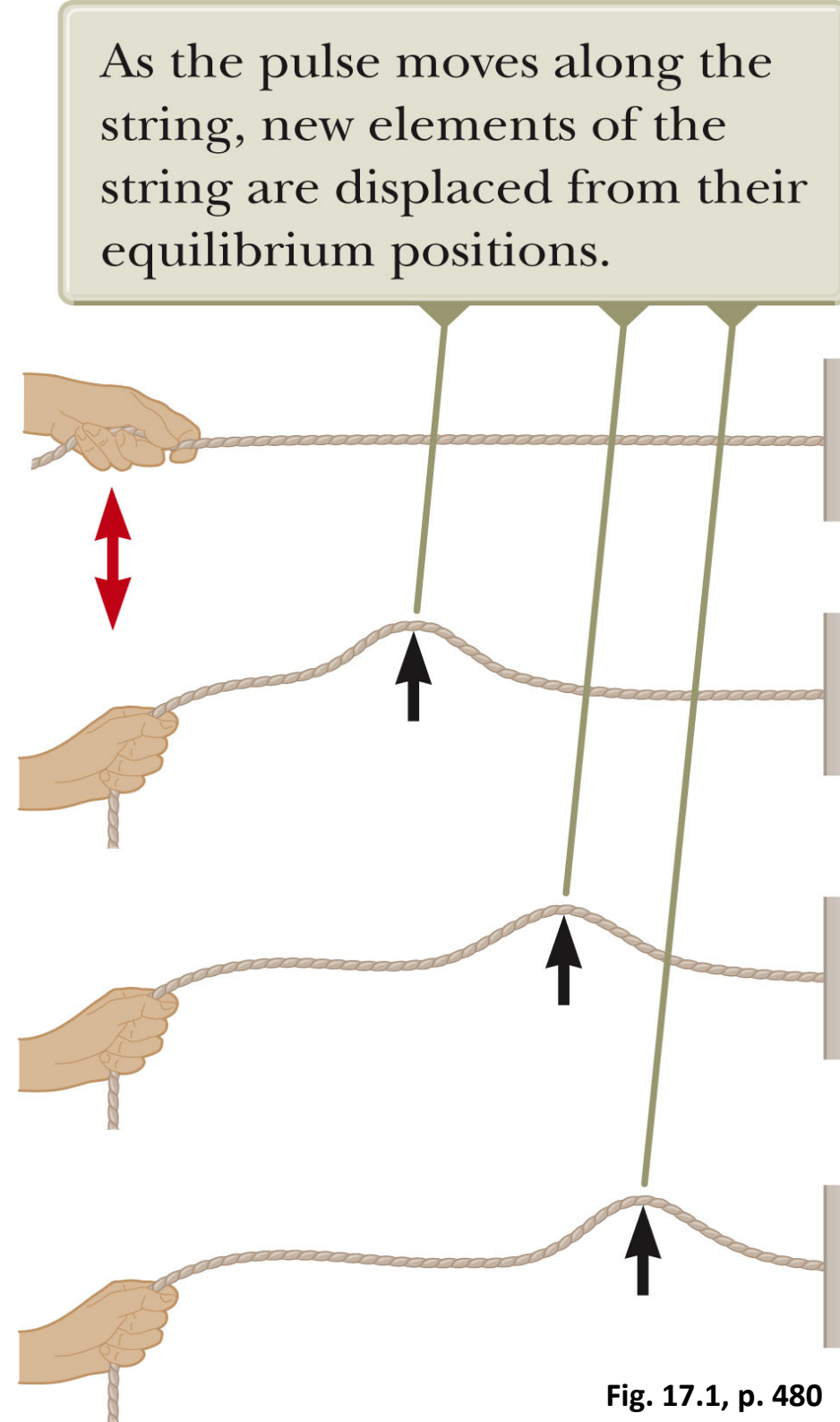


Fig. 17.1, p. 480

# Waves>Mechanical waves...

• To produce a mechanical wave, we need

1. Some **source** of disturbance.

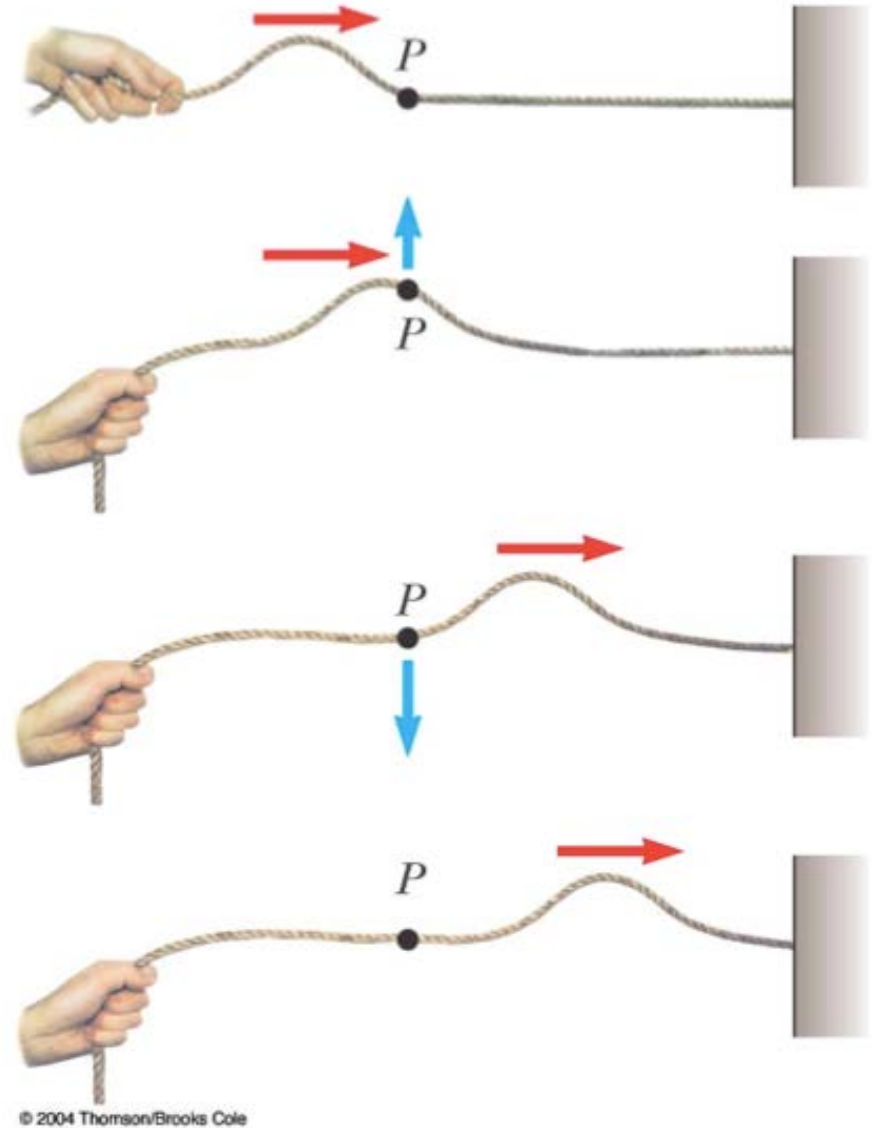
You flick the rope.

2. A **medium** that can be disturbed.

The rope is the medium.

3. Some physical **coupling** mechanism through which elements of the medium can influence each other.

Tension of the rope.



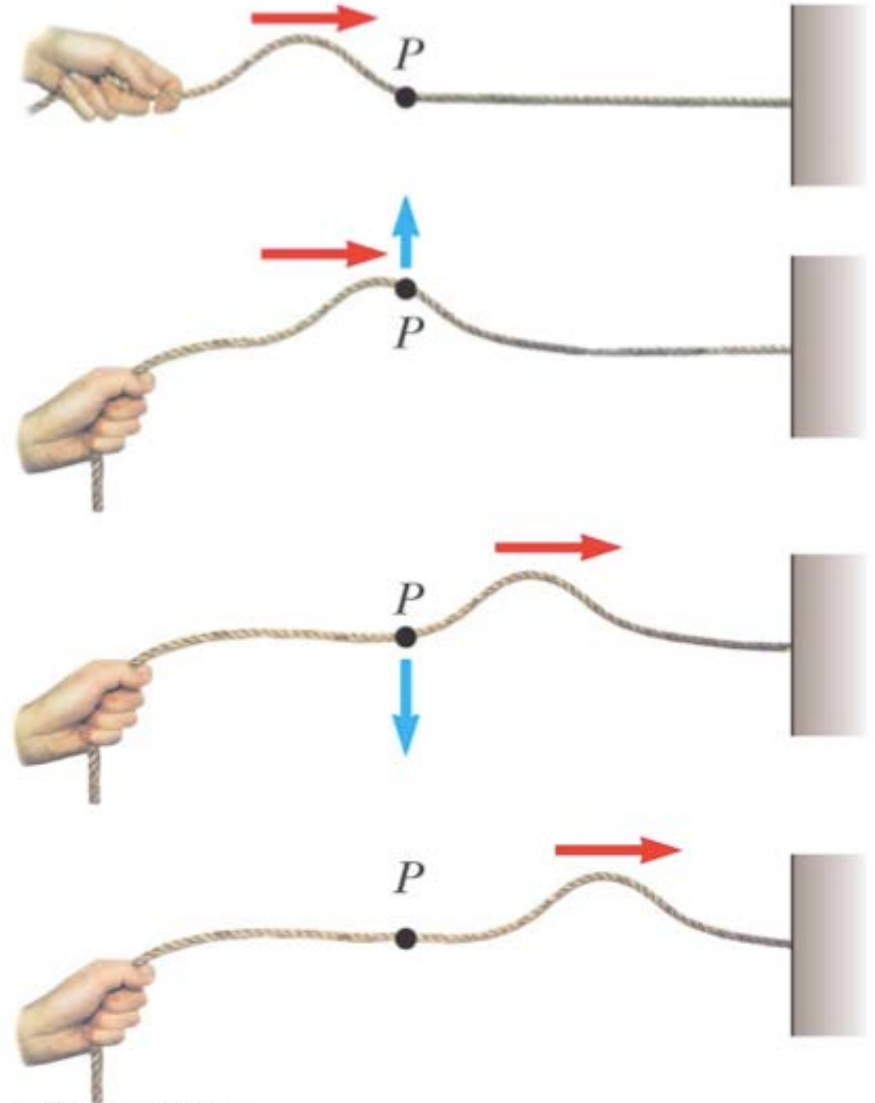
# Waves>Pulse on a rope...

The rope is the medium through which the pulse travels

The pulse:

- Carries energy
- Has a definite height
- Has a definite speed of propagation
- Does not change shape as it travels

Continuous flicking would produce a periodic disturbance →  
**A wave**



# Transverse vs longitudinal waves...

- Two basic propagation modes:

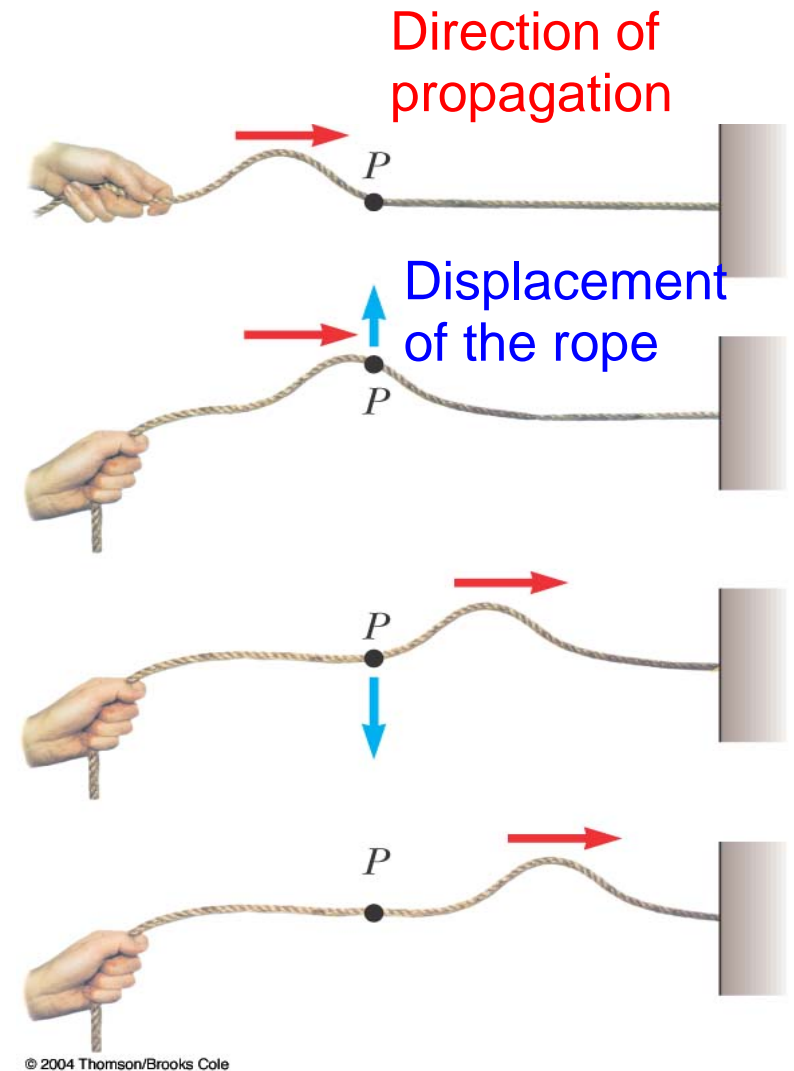
- Transverse**: displacement perpendicular to direction of propagation.

- Longitudinal**: displacement in the parallel to direction of propagation.



# Transverse Wave

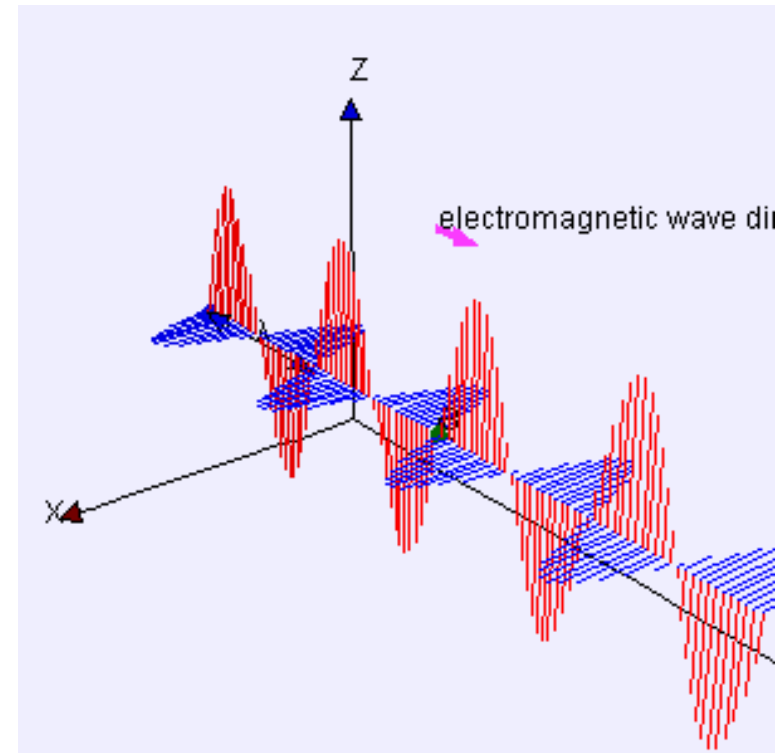
- A travelling wave or pulse that causes the elements of the disturbed medium to move **perpendicular** to the direction of propagation is called a **transverse wave**
- The particle motion is shown by the **blue arrow**
- The direction of propagation is shown by the **red arrow**
- e.g., wave on a string, ripples in a pond.



# Transverse waves > EM waves...

- **Electromagnetic waves** are also transverse waves, although in this case there is **no** disturbed medium.

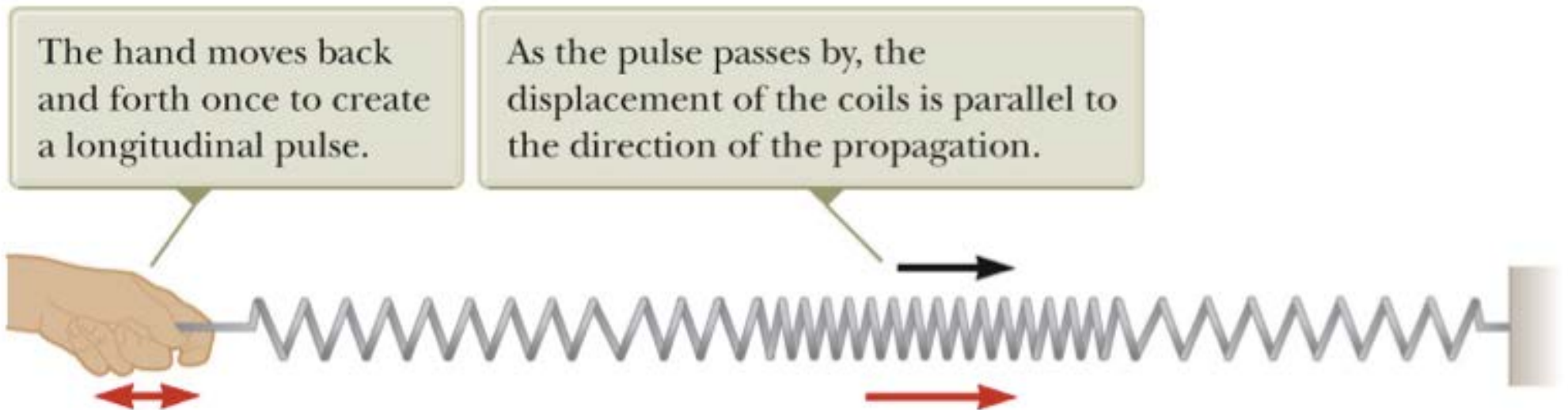
–It is the **electric** and **magnetic** fields that oscillate in directions perpendicular to the direction of propagation.



**Red** = Electric field  
**Blue** = Magnetic field

# Longitudinal waves...

- Elements of the disturbed medium move **parallel** to the direction of propagation.
- e.g., wave travelling down a spring coil



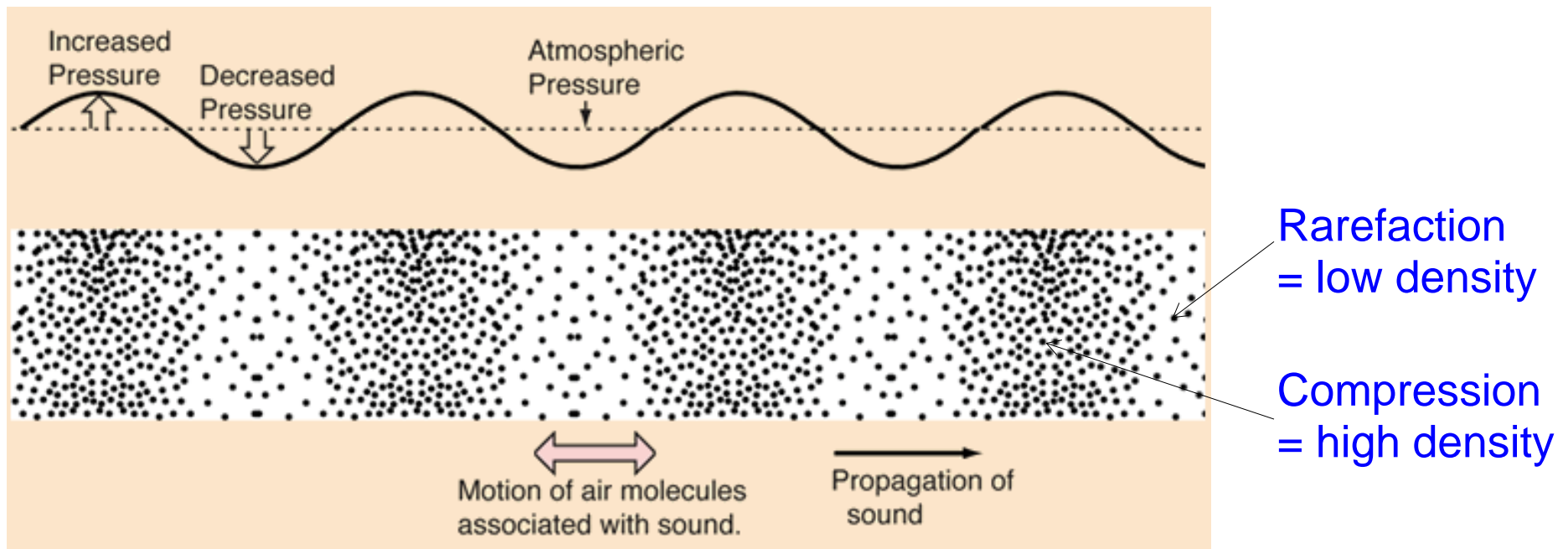
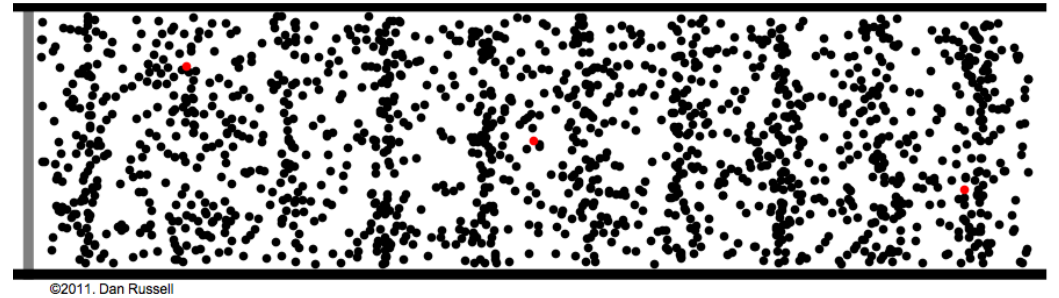
# Wa4: The slinky

## Longitudinal Waves



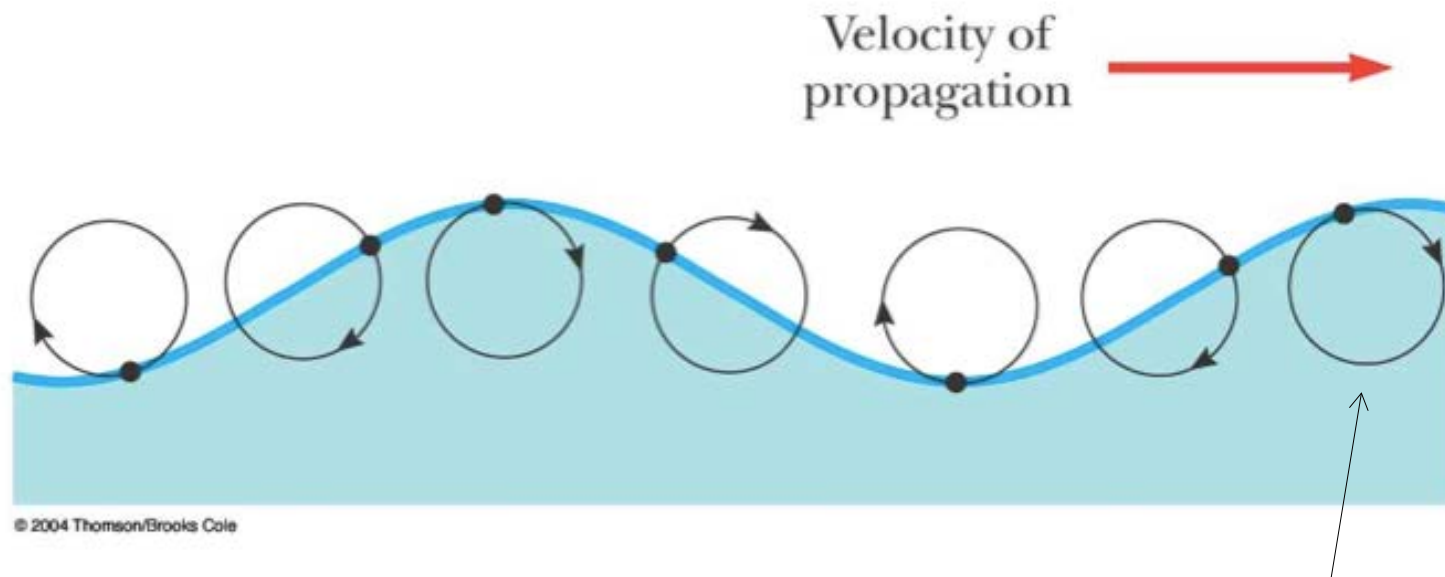
# Longitudinal waves>Sound waves...

- **Sound waves** are mechanical waves that disturb the air density and pressure.



# Complex waves>Examples...

- Surface water waves are a combination of transverse and longitudinal waves.



Water molecules move around in circles.

• In a long line of people waiting to buy tickets, the first person leaves and a frantic pulse of motion occurs as people step forward to fill the gap. As each person steps forward, the gap moves through the line. The propagation of this gap is:

1. transverse.
2. longitudinal.

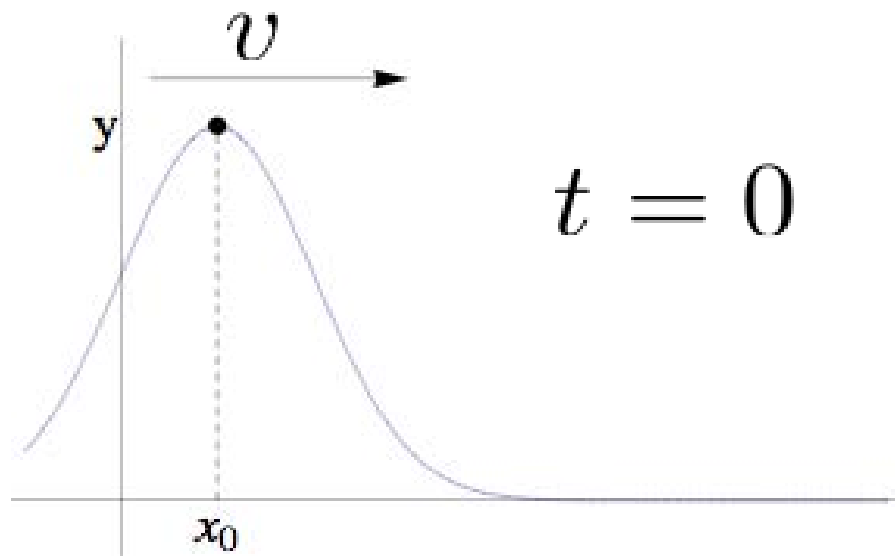
Consider the (Mexican) “wave” at a football game: people stand up and raise their arms as the wave arrives at their location, and the resultant pulse moves around the stadium. This wave is:

1. transverse.
2. longitudinal.

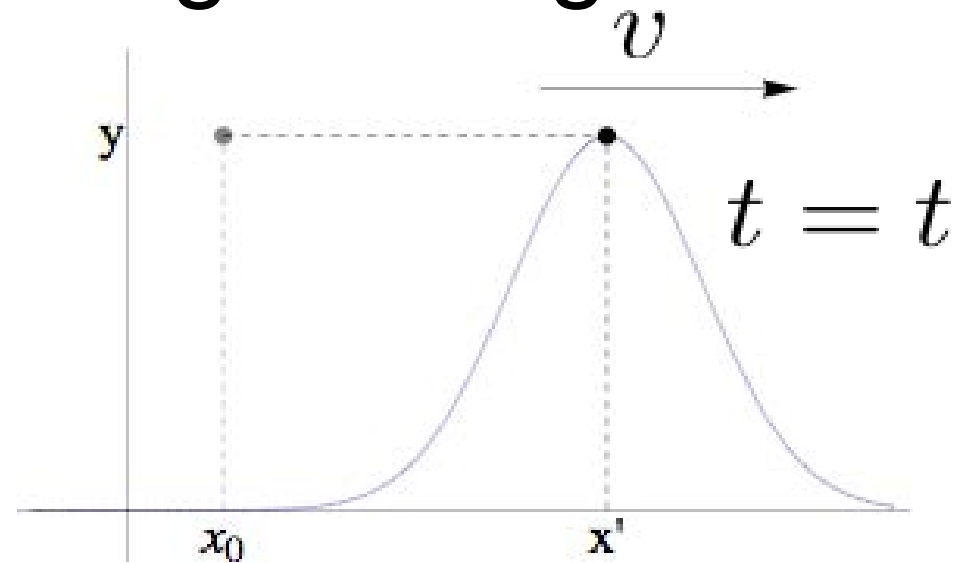




# A pulse traveling along a string



$$y(x_0, 0) = f(x_0)$$



$$x' = x_0 + vt$$

$$y(x', t) = f(x_0) = f(x' - vt)$$

$f(x)$  = “height function”

When the wave travels to the right we need to **subtract**  $vt$  from  $x$ .

# A pulse traveling along a string

$$y(x, t) = f(x + vt)$$

Is a pulse traveling to the left.

Sometimes this function is called the “**wave function**” as it describes the shape of the wave.

The “**waveform**” is the shape of the wave, it can be determined at a particular time.

# A pulse travelling along a string...

- In general:

- A pulse travelling in the **positive x-direction**:

$$y(x, t) = f(x - vt)$$

- A pulse travelling in the **negative x-direction**:

$$y(x, t) = f(x + vt)$$

- The function  $y(x, t)$  is called the **wavefunction**. It describes the transverse displacement.

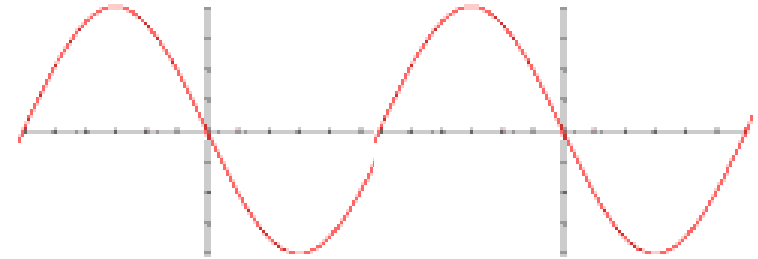
# Question

At  $t = 0$ , a transverse pulse in a wire is described by the function:

$$y = \frac{6.00}{x^2 + 3.00}$$

Where  $x$  and  $y$  are in meters. If the pulse is traveling in the positive  $x$  direction with a speed of  $4.50$  m/s, write the function  $y(x,t)$  that describes this pulse.

# Travelling waves...



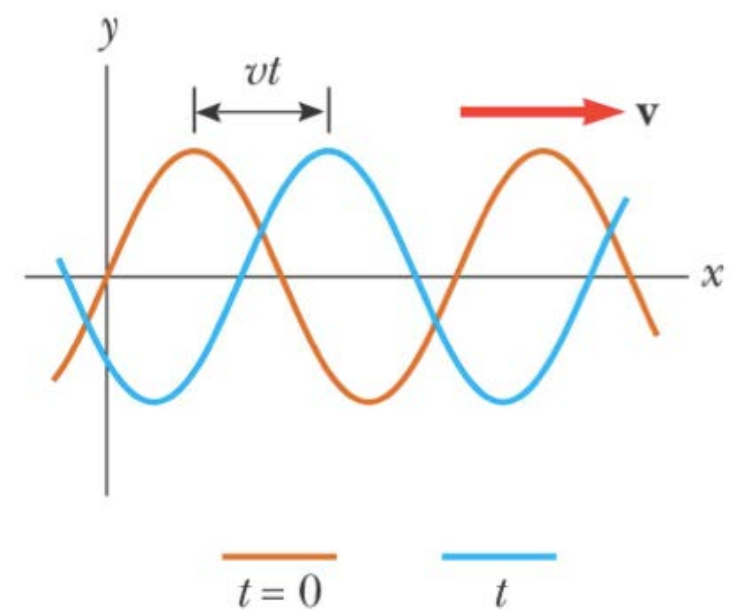
- A sinusoidal wave is a simple type of travelling wave.

- Take a snapshot at  $t = 0$ . → The **waveform** is a sine function:

$$f(x) = A \sin(kx + \phi)$$

Some constant  
(more on this later)

Phase constant in  
case  $f(x) \neq 0$  at  $x = 0$



$$\Rightarrow y(x, t) = f(x - vt) = A \sin[k(x - vt) + \phi]$$

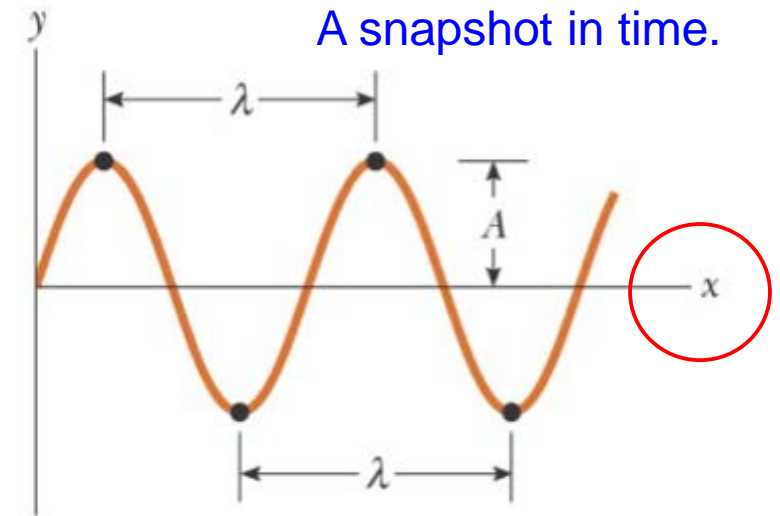
$$y(x, t) = f(x + vt) = A \sin[k(x + vt) + \phi]$$

Propagation in  
the + x-direction

Propagation in  
the - x-direction

# Travelling waves>Some terminology...

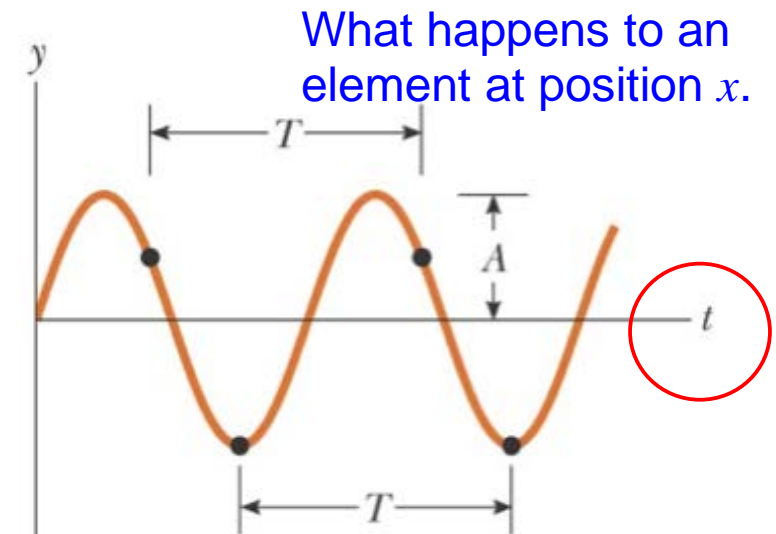
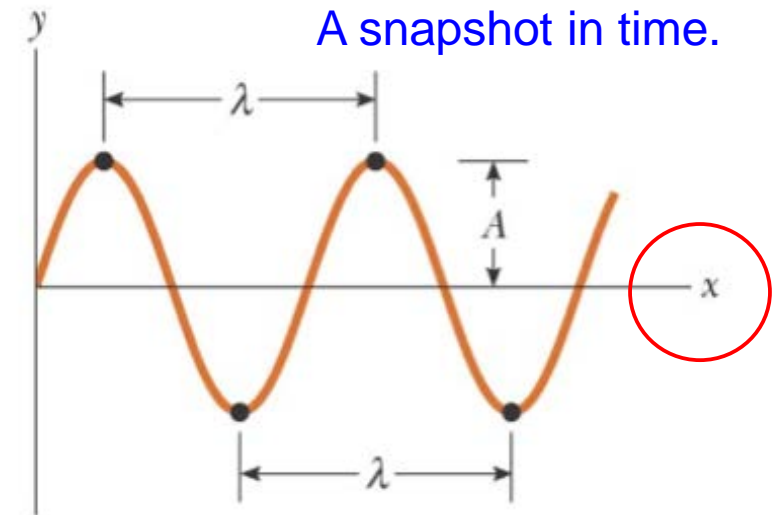
- The **wavelength**  $\lambda$  of a wave is the **distance** between adjacent crests or troughs.



# Travelling waves>Some terminology...

- The **wavelength**  $\lambda$  of a wave is the **distance** between adjacent crests or troughs.
- The **period**  $T$  is the **time interval** needed for an element at position  $x$  to complete one cycle of oscillations in the  $y$ -direction.
- → Also time interval for a wave to travel a distance of one wavelength.

$$f = \frac{1}{T}$$



# Travelling waves > Equation of a wave...

- We have worked out that a travelling sine wave is described by

$$y(x, t) = A \sin[k(x - vt) + \phi]$$

Propagation in  
the + x-direction

$$y(x, t) = A \sin[k(x + vt) + \phi]$$

Propagation in  
the - x-direction

- What is  $k$ ?      BLACKBOARD



# Travelling waves > Equation of a wave...

- We have worked out that a travelling sine wave is described by

$$y(x, t) = A \sin[k(x - vt) + \phi]$$

Propagation in  
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$$y(x, t) = A \sin[k(x + vt) + \phi]$$

Propagation in  
the - x-direction

- What is  $k$ ? BLACKBOARD

- $k$  is called the **wavenumber**:

$$k = \frac{2\pi}{\lambda}$$

Wavelength

# Travelling waves > Equation of a wave...

- This is what we have so far:

$$y(x, t) = A \sin \left[ \frac{2\pi}{\lambda} x - \frac{2\pi v}{\lambda} t + \phi \right]$$

Propagation in  
the + x-direction

- The wave travels one wavelength in a period:

$$v = \frac{\lambda}{T} = f\lambda$$

$f$  = Frequency

$$\Rightarrow y(x, t) = A \sin \left[ \frac{2\pi}{\lambda} x - 2\pi f t + \phi \right]$$

$$\Rightarrow y(x, t) = A \sin(kx - \omega t + \phi)$$

$$\omega = 2\pi f$$

Angular  
frequency

# Travelling waves>Summary...

- A sinusoidal wave travelling in the **positive** x-direction is described by

$$\begin{aligned}y(x, t) &= A \sin \left[ \frac{2\pi}{\lambda} x - 2\pi f t + \phi \right] \\&= A \sin(kx - \omega t + \phi)\end{aligned}$$

- A sinusoidal wave travelling in the **negative** x-direction is described by

$$\begin{aligned}y(x, t) &= A \sin \left[ \frac{2\pi}{\lambda} x + 2\pi f t + \phi \right] \\&= A \sin(kx + \omega t + \phi)\end{aligned}$$



.Warning!



Frequency of a wave depends on the **source** of the wave.

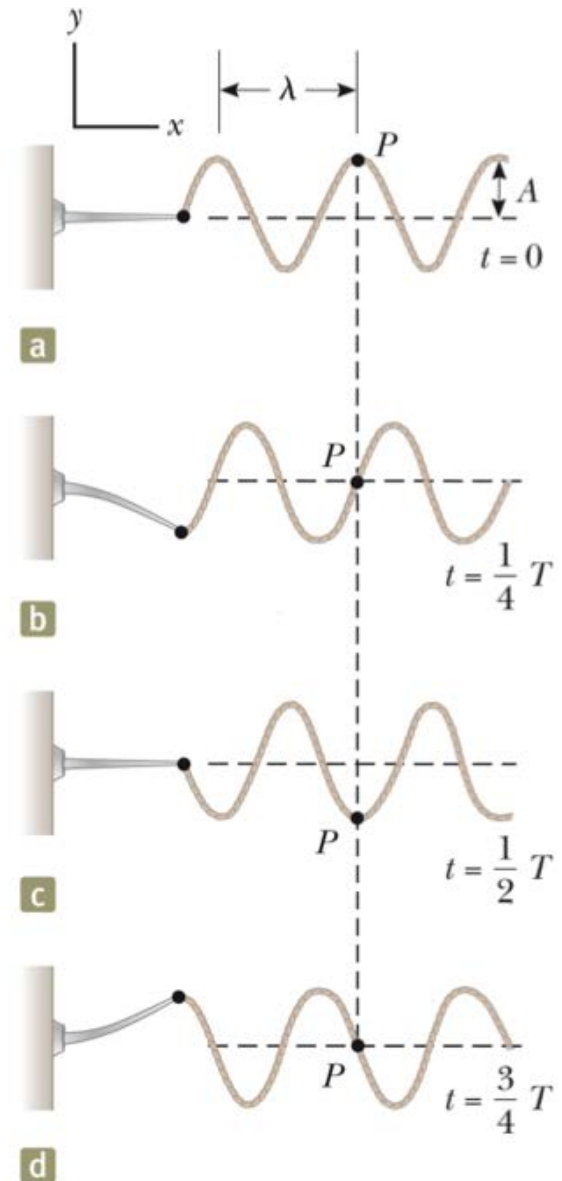
The **speed** depends on the medium, not the frequency or wavelength.

Demo Wa5

# Relationship between waves & SHM...

- Sinusoidal waves can be generated by a generator set to oscillate in simple harmonic motion.

–If you consider one point  $P$  on the string, then its motion in the  $y$ -direction is SHM. (Prove it yourself!)



# Question

The wave function for a traveling wave on a taut string is (in SI units)

$$y(x, t) = 0.350 \sin(10\pi t - 3\pi x + \frac{\pi}{4})$$

- (a) What are the speed and direction of travel of the wave?
- (b) What is the vertical position of an element of the string at  $t = 0$ ,  $x = 0.100$  m? What are
- (c) The wavelength and
- (d) The frequency of the wave?
- (e) What is the maximum transverse speed of an element of the string?

## Question

- (a) Write the expression for  $y$  as a function of  $x$  and  $t$  in SI units for a sinusoidal wave traveling along a rope in the negative  $x$  direction with the following characteristics:  $A = 8.00$  cm,  $\lambda = 80.0$  cm,  $f = 3.00$  Hz, and  $y(0, t) = 0$  at  $t = 0$ .
- (b) Write the expression for  $y$  as a function of  $x$  and  $t$  for the wave in part (a) assuming  $y(x, 0) = 0$  at the point  $x = 10.0$  cm.