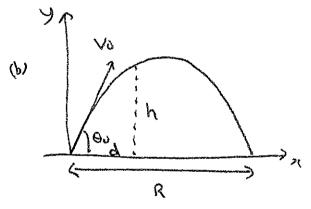


The Speed is 
$$1.3 \times 10^{-4}$$
 m/s = 0.13 mm/s to 2.5f.

Direction is downwords



Initially velocib component  $V_2 = V_0 \cos \theta_0$   $V_3 = V_0 \sin \theta_0$ 

(i) X-motion given by  $X-X_0=V_X$  t since no acceleration in  $d=V_0$  cases t

(1) In y-direction then is uniform acceleration -9

So, applying " $S = ut + 1/2at^{-1}$  behave  $h = y - y_0 = V_y \sin \theta_0 t - 1/2gt^2$ in  $h = V_0 \sin \theta_0 t - 1/2gt^2$ 

(111) Range R given by the time t when returns to grown in When h=0 =)  $V_0 \sin \theta_0 t - V_2 g t^2 = 0$ So t=0 [initial condition] or t=2 Vu sin  $\theta_0/g$ 

(IV) Substituting into the eqn for the or-distance

 $R = V_0 \cos \theta_0 t \quad \text{with} \quad t = 2 V_0 \sin \theta_0 lg$   $= 2 V_0^2 \sin \theta_0 \cos \theta_0 / g$   $= 2 V_0^2 \sin 2\theta_0 / g \quad \text{where} \quad \sin 2\theta_0 = 2 \sin \theta_0 \cos \theta_0$ 

The range is max when Ris at its greatest

in Sin200=1 or 200=900 => 00=450

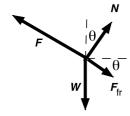
This R<sub>max</sub> =  $\frac{V_0^2}{9}$  =  $\frac{9.50^2}{9.8}$  = 9.21m

world Record is 8.45 m

Hera it is 9.21-8.05 = 26cm shorter

## **Question 2**

a)



(no marks explicitly for the FBD)

i) No acceleration in the normal direction:

$$N - mg \cos \theta = 0$$
 so  $N = mg \cos \theta$ .

In the direction up the plane, apply Newton's second law.

ma = F - F<sub>fr</sub> - mg sin 
$$\theta$$
  
ma = F -  $\mu_k$ N - mg sin  $\theta$   
= F -  $\mu_k$ mg cos  $\theta$  - mg sin  $\theta$   
F = m(a + g( $\mu_k$  cos  $\theta$  + sin  $\theta$ ))

ii) To maximise F with respect to  $\theta$ , take the derivative:

$$dF/dθ = mg(cos θ - μk sin θ) = 0$$
Rearrange 
$$cos θ = μk sin θ$$

$$θ = tan-1 (1/μk)$$

iii) As  $\theta$  increases, the force up the plane is opposed by an increasing component of mg. However, the force up the plane is also opposed by friction and, as  $\theta$  increases, the normal force and therefore the friction decrease.

b)

- i) At maximal compression, the spring is neither compressing nor lengthening, so the relative velocity is zero.
- ii) Let v be the speed at maximum compression.

Here, no non-conservative forces act, so mechanical energy is conserved.

$$\begin{aligned} &U_i + K_i &= U_f + K_f \\ &0 + \frac{1}{2}mv_1^2 + \frac{1}{2}mv_2^2 &= \frac{1}{2}kx^2 + \frac{1}{2}(m+m)v^2 \\ &kx^2 &= mv_1^2 + mv_2^2 - 2mv^2 &= m(v_1^2 + v_2^2 - 2v^2) \end{aligned}$$

External forces in the x direction are negligible, so momentum in x direction is conserved.

Momentum before collision = momentum at maximum compression

$$mv_1 + mv_2 = 2mv$$
  
 $v = (v_1 + v_2)/2$ 

Combine the two results

$$kx^{2} = m(v_{1}^{2} + v_{2}^{2} - \frac{1}{2}(v_{1} + v_{2})^{2})$$

$$= \frac{1}{2}m(2v_{1}^{2} + 2v_{2}^{2} - v_{1}^{2} - 2v_{1}v_{2} - v_{2}^{2})$$

$$= \frac{1}{2}m(v_{1}^{2} + v_{2}^{2} - 2v_{1}v_{2})$$

$$= \frac{1}{2}m(v_{1} - v_{2})^{2}$$

So, at maximum compression, 
$$x = \sqrt{\frac{m}{2k}}(v_1 - v_2)$$

## **Question 3**

a) i) 
$$F_g = GMm/R^2$$
.

ii) 
$$a = R\omega^2 = R(2\pi/T)^2$$
.

iii) Newton's second law: 
$$F = ma$$

$$GMm/R^2 = mR(2\pi/T)^2$$

$$SO GMT^2 = 4\pi^2 R^3$$

so 
$$R = \sqrt[3]{\frac{GM\hat{T}}{4\pi^2}} = \dots = 42\ 100 \text{ km}$$

iv) Total mechanical energy of an orbit, with respect to zero at infinite distance, is -GMm/2r. On the Earth, and neglecting rotation of the Earth, the spacecraft has only potential energy  $-GMm/R_e$ .

## Easy method

Work energy theorem: total work done by all forces =  $\Delta K = \frac{1}{2} m(R\omega)^2$ 

= 
$$\frac{1}{2}$$
 (145 kg)(42 100 km \*  $2\pi/23.9$  hr)<sup>2</sup>.

$$= 685 \,\mathrm{MJ}$$
 or  $6.85 \,\mathrm{x} \,10^8 \,\mathrm{J}$ 

#### Alternative method:

 $\Delta E$  = total energy of the orbit – (only potential) energy on earth

But this energy includes the gravitational potential energy  $\Delta U_g$ . So the total work done by all forces, including gravity, is

Work done = total energy of the orbit – (only potential) energy on earth –  $\Delta U_g$ ,

$$= -GMm/2R - (-GMm/R_e) - (-GMm/R - (-GMm/R_e))$$

$$= GMm/2R = 685 \,\mathrm{MJ}$$
 or  $6.85 \,\mathrm{x} \, 10^8 \,\mathrm{J}$ 

(Comment only: In practice, however, the work done is by the rockets is much higher because much energy is wasted lifting and accelerating fuel and rocket stages.)

b) i) Moment of inertia  $I = \int_{body} r^2 dn$  where r is the perpendicular

distance from the axis of mass element dm.

ii)

Let the linear mass density by  $\lambda = m/L$ , so

$$dm = \lambda dx$$

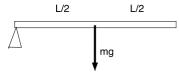
$$I = \int_{body} r^2 dm = \int_{x=0}^{x=L} x^2 dm$$

$$= \int_{x=0}^{\infty} x^2 \lambda dx$$

$$= \frac{\lambda}{3} \left[ x^3 \right]_{r=0}^{r=L}$$

$$= \frac{\lambda}{3} L^3, \quad \text{but by definition } \lambda L = m, \text{ so}$$

$$I = \frac{1}{3} m L^2.$$



Newton's second law for rotation:

$$\Sigma \tau = I\alpha$$

Consider rotation about the point of the wedge. The weight provides the only torque, so

$$mg.(L/2) = (mL^2/3)\alpha$$
  
 $\alpha = (3/2)(g/L)$ 

Acceleration at the end of the rod:  $a = \alpha L = 3g/2$ 

## 1131 Solutions Question 4

a) i)

$$T_A = \frac{P_A V_A}{nR} = \frac{5 \times 1.01 \times 10^5 \times 16.46 \times 10^{-3}}{5 \times 8.314} = 200 K$$
 So as this is a diatomic molecule at 200K it has five degrees of freedom

ii) Three of these degrees of freedom are translational, corresponding to movement in the x, y and z direction.

Two of these degrees of freedom are rotational, corresponding to rotations about two axes.

iii) 
$$W = -\int PdV$$

$$= -5 \times 1.01 \times 10^5 \times (32 - 16.46) \times 10^{-3}$$

$$= -7848J$$

$$= -7850J (3 \text{ sig fig})$$

## iv) 0 Jit's isothermal

v) 
$$\Delta E_{int} = Q + W$$
  
 $Q = 0$  it's adiabatic  
Two methods to calculate  $\Delta E_{int}$   
method 1:  
 $\Delta E_{int} = \frac{f}{2}nR(T_A - T_D)$   
 $T_D = \frac{P_dV_D}{nR} = 153.9K$   
 $\Rightarrow \Delta E_{int} = \frac{5}{2} \times 5 \times 8.314 \times (200 - 153.9) = 4792J$   
method 2:  
As A  $\rightarrow$  B  $\rightarrow$  C  $\rightarrow$  D  $\rightarrow$  A is cyclic, total  $\Delta E_{int} = 0$   
 $\Delta E_{intA \rightarrow B} = -7.850 + 27.5 = 19.65kJ$   
 $\Delta E_{intC \rightarrow D} = -34.2 - 2 \times 1.01 \times 10^5 \times (31.67 - 80) \times 10^{-3} = -24.44kJ$   
 $so\Delta E_{intD \rightarrow A} = -(-24.44 + 19.65) = 4.79kJ$   
As  $\Delta E_{int} = W$   
 $\Rightarrow W = 4.79kJ$ 

Or it is possible to calculate it directly by integrating PdV using PV^1.4 = constant, but this is harder.

b) i) 
$$P = kA \frac{\Delta T}{\Delta x}$$
$$= 50.2 \times 100.0 \times 10^{-4} \times \frac{30.00}{0.020}$$
$$= 753W$$

ii) 
$$Q = Pt = mL$$
  
 $m = \frac{Pt}{L} = \frac{753 \times 60}{3.33 \times 10^5}$   
 $= 0.136kg$ 

iii)

Energy needed to melt ice =  $m_i L_{fus}$  $=0.500\times3.33\times10^{5}$ 

= 166500J

energy that water can lose as it goes to  $0^{\circ}C = m_{w}c_{w}\Delta T$ 

 $= 1.000 \times 4186 \times 30 = 125580J$ 

energy that steel can loose as it goes to  $0^{\circ}C = m_{st}c_{st}\Delta T$ 

$$= 1.56 \times 456 \times 15 = 10670J$$

As the water at the top and steel combined can not lose enough energy to melt all the ice the system has a final temperature of  $0^{\circ}C$ .

iv)

$$Q = \int_0^t P(t)dt = m_w c_w (T_h - T) + m_{st} c_{st} (\frac{T_h}{2} - \frac{T}{2})$$

 $Q = \int_0^t P(t)dt = m_w c_w (T_h - T) + m_{st} c_{st} (\frac{T_h}{2} - \frac{T}{2})$ Note that P and T are functions of time, P(t) is the power through the steel at time tand T(t) is the temperature of the water at time t.

Differentiate both sides with respect to 
$$t$$
.  

$$\Rightarrow P = -m_w c_w \frac{dT}{dt} - \frac{m_{st} c_{st}}{2} \frac{dT}{dt}$$

Now: 
$$P = \frac{kAT}{d}$$

Substitute this into the differential equation.  

$$\Rightarrow \frac{kAT}{d} = -m_w c_w \frac{dT}{dt} - \frac{m_{st}c_{st}}{2} \frac{dT}{dt}$$

Rearrange putting the T and dT terms on the left hand side, then integrate between

t=0 and t=60s 
$$T_f$$
 is the temperature at 60s.  

$$\Rightarrow \int_{T_h}^{T_f} \frac{dT}{T} = \int_0^{60} \frac{-kA}{d(m_w c_w + m_{st} c_{st}/2)} dt$$

$$\ln(\frac{T_f}{T_h}) = \frac{-60kA}{d(m_w c_w + m_{st} c_{st}/2)}$$

$$\Rightarrow T_f = T_h e^{\frac{-60kA}{d(m_w c_w + m_{st} c_{st}/2)}}$$

$$\frac{-60kA}{d(m_w c_w + m_{st} c_{st}/2)} = \frac{50.2 \times 100 \times 10^{-4} \times 60}{0.02 \times (4186 \times 1 + 1.56 \times 486/2)} = 0.331595$$

$$T_f = 30.0 \times e^{-0.331595} = 21.533^{\circ}C$$

$$Q = 1 \times 4186 \times (30 - 21.533) + \frac{1.56 \times 456}{2} \times (30.0 - 21.533)$$

$$= 38452.9J$$

$$= 38.5kJ \text{ (3 sig. fig.)}$$

Question 5 T1 2014

a)

For planet GJ832c:

$$g = \frac{GM_{\text{planet}}}{R^2} = 13.22 \frac{\text{m}}{\text{s}^2}$$

Simple pendulum:

$$T=2\pi\sqrt{rac{L}{g}}$$

Find L:

$$T^2 = \frac{4\pi^2 L}{g}$$

$$L = \frac{T^2g}{4\pi^2} = 33.49 \text{ m} \rightarrow 33.5 \text{ m} \text{ (3 sig. figs)}$$

b)

1st harmonic  $\rightarrow \lambda = 2L$ 

$$v=\sqrt{rac{T}{\mu}}=f\lambda$$
 and  $T=mg$ 

From a): L = 33.5 m

Solve for  $\mu$  :

$$\sqrt{\frac{T}{\mu}} = 2Lf$$

$$\frac{T}{U} = 4L^2f^2$$

$$\mu = \frac{T}{4L^2f^2} = \frac{mg}{4L^2f^2}$$
 (L = 33.5 m, g = 13.22  $\frac{m}{s^2}$ , f = 4.40 Hz, m = 66 kg)

$$\mu =$$
 0.0100  ${{
m kg}\over{
m m}}$  (3 sig. figs)

After rope splits: 
$$\mu' = \frac{2}{3}\mu$$

1st harmonic: 
$$f_{\rm n}=rac{{
m n}}{2L}\sqrt{rac{T}{\mu}}
ightarrow f_{1}=rac{1}{2L}\sqrt{rac{T}{\mu}}$$
 and  $T=mg$ 

$$f_1^{\prime}=rac{1}{2L}\sqrt{rac{mg\cdot 3}{2\mu}}$$
,  $\mu=0.0100rac{ ext{kg}}{ ext{m}}$  from part b)

$$f_1' = \frac{1}{2(33.5)} \sqrt{\frac{66 \cdot 13.22 \cdot 3}{2 \cdot 0.0100}} \text{ Hz}$$

$$f_1 = 5.40 \text{ Hz}$$

# d)

Speed at time t: 
$$v = gt = 13.2t$$

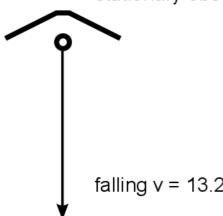
Doppler: 
$$v_{\text{source}} = 13.2t$$
, observer stationary

$$f' = \left(\frac{v - v_0}{v + v_S}\right) f$$
,  $f = 440.0 \text{ Hz}$ ,  $v = 380.0 \frac{\text{m}}{\text{s}}$ 

$$f=\left(\frac{380-0}{380+13.2t}\right)f$$

$$f = \frac{167200}{380 + 13.2t}$$
 Hz

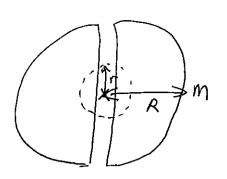
stationary observer  $v_{observer} = 0$ 



(9

Take center of the Earth as r=0.

As the particle undergoes SHM it will oscillate between +R and -R.



We need to work out force acting

on the particle. The force is the gravitational force so:

$$F = \frac{G m_1 m_2}{r^2}$$

However, only the mass insides the radius 'r' will contribute so:

$$M_z = \rho V = \frac{M}{4\pi R^3} = \frac{Mr^3}{R^3}$$

$$F = \frac{Gm_0Mr^3}{r^2R^3} = \frac{Gm_0Mr}{R^3} = m_0CL$$

Now for SHM  $a=-w^2r$  where -ve sign shows acceleration/ force and displacement are in the opposite direction to each other so

$$|a| = w^2 r = \frac{GMr}{R^3}.$$

$$W^{2} = GM$$

$$R^{3}$$

$$W = \sqrt{GM}$$