Denny Cao

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EDUCATION

Harvard University

Anticipated May 2027

Bachelor of Arts in Computer Science and Statistics with Quantitative Finance Track

Cambridge, MA

Julia R. Masterman High School

June 2023

High School Diploma - GPA: 3.9/4.0

Philadelphia, PA

• Relevant Coursework: MATH 163 and 263: Discrete Mathematics 1 and 2 at Community College of Philadelphia, MATH 1410: Multivariable Calculus at University of Pennsylvania, AP CS A, AP Calculus BC, AP Physics C

SKILLS

 $\textbf{Programming:} \ \ Python \cdot \ Java \cdot C/C++ \cdot \ ROS \cdot SQL \cdot \ JavaScript \cdot \ HTML/CSS \cdot \ L^{\!\!\!A}T_{\!\!\!E}X$

 $\textbf{Tools}: \ Git \cdot Linux \cdot Jira \cdot Vim \cdot OnShape \cdot Fusion 360 \cdot KiCad \cdot Adobe \ Suite \cdot MS \ Office$

 $\textbf{Libraries} : \ TensorFlow \cdot OpenCV \cdot pandas \cdot NumPy \cdot Matplotlib \cdot PIL$

Languages: English (Native) · Fuzhounese (Native) · French (Conversational) · Mandarin Chinese (Beginner)

EXPERIENCE

Programming Lead/Marketing & Fundraising Manager

Sept. 2019 — June 2023

SLAM Robotics Team

Philadelphia, PA

- Developed comprehensive documentation for team's codebase using GitBook to streamline the onboarding process for new team members
- Utilized Java and OpenCV to program robot's autonomous and teleop code, incorporating AprilTag detection
- Oversaw team of 5 in rebranding, designing a new website, and creating a new logo to better convey team's values
- Reached FTC Pennsylvania Championship in 2023

Robotics Research Assistant

June 2022 — Aug. 2022

GRASP Lab at University of Pennsylvania

Philadelphia, PA

- Researched extrinsic contact estimation for robotic manipulation to advance the field of general-purpose robotics
- Developed a Python script to generate heightmaps for environments in Gazebo simulator, enabling creation of diverse training data
- Programmatically generated URDFs of objects on a desk using procedural generation techniques, allowing for practical scenarios and real-world testing
- Provided visualization tools in RViz that facilitated understanding of Franka Panda current and target positions, aiding in error analysis and fine-tuning of robotic movements

Projects

 $\textbf{Trash Collector} \mid \textit{Java} \cdot \textit{Python} \cdot \textit{TensorFlow} \cdot \textit{pandas} \cdot \textit{CAD} \cdot \textit{Git}$

May 2023

- Developed a robot that can autonomously collect trash and sort it into recyclables and non-recyclables
- Utilized TensorFlow to train an object detection model to detect trash and recyclables
- Implemented a PID controller to control robot's movements
- Worked with a team of 7 using Git for version control, enabling efficient and organized collaboration

RoboDog | $C \cdot Java \cdot Arduino \cdot CAD \cdot KiCad$

June 2022 — Dec. 2022

- Built a robot guide dog to assist visually impaired for MIT Online Science, Technology, and Engineering Community (MOSTEC) 2022 Capstone Project
- Implemented a communication system using Bluetooth to establish a connection between robot and an Android phone, allowing for real-time exchange of GPS coordinates and goal information
- CADed using OnShape to design robot's chassis
- Employed KiCad to map out schematics and for Arduino-based control systems

AWARDS AND HONORS

2023 Wharton Global High School Investment Competition Semifinalist: Selected as one of 55 teams out of roughly 1,400 competing from 53 countries for creating a unique investment strategy and portfolio for a fictitious client

2023 MathWorks Math Modeling Challenge Second Round Qualifier: Top 25% of submissions, implementing a Vector Autoreggresion (VAR) model to predict future sales of e-bikes