

Denotational validation of higher-order Bayesian inference

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What is probabilistic programming?

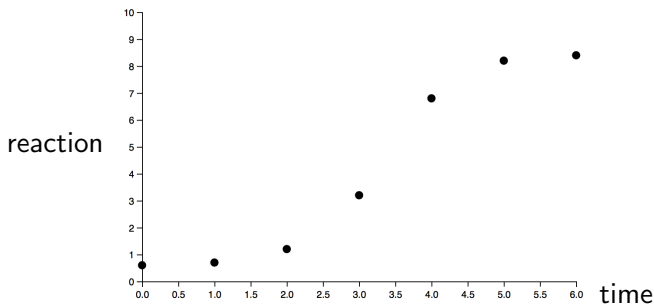
Bayesian data modelling

1. Develop a probabilistic (generative) model.
2. Design an inference algorithm for the model.
3. Using the algorithm, fit the model to the data.

What is probabilistic programming?

Example

Effect of a drug on a patient, given data:



What is probabilistic programming?

Generative model

$$\begin{aligned}s &\sim \text{normal}(0, 2) \\ b &\sim \text{normal}(0, 6) \\ f(x) &= s \cdot x + b \\ y_i &= \text{normal}(f(i), 0.5) \\ &\quad \text{for } i = 0 \dots 6\end{aligned}$$

What is probabilistic programming?

Generative model

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Conditioning

$$y_0 = 0.6, y_1 = 0.7, y_2 = 1.2, y_3 = 3.2, y_4 = 6.8, y_5 = 8.2, y_6 = 8.4$$

Predict f ?

What is probabilistic programming?

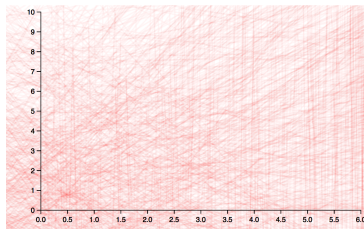
Bayesian inference

$$P(s, b | y_0, \dots, y_6) = \frac{P(y_0, \dots, y_6 | s, b) \cdot P(s, b)}{P(y_0, \dots, y_6)}$$

What is probabilistic programming?

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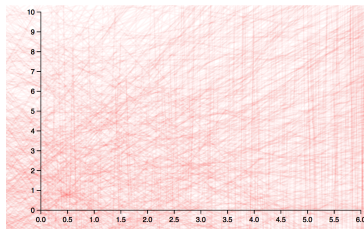


Prior

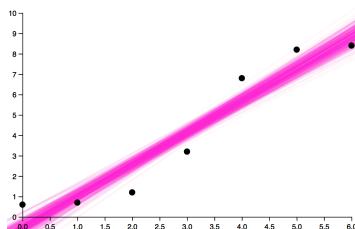
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Prior



Posterior

What is probabilistic programming?

Probabilistic programming models

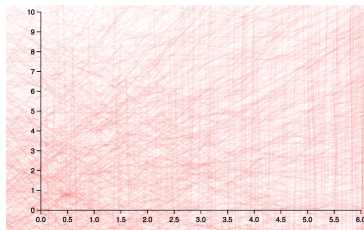
1. Develop a probabilistic (generative) model.
Write a program.
2. ~~Design an inference algorithm for the model.~~
3. Using the `built-in` algorithm, fit the model to the data.

What is probabilistic programming?

In Anglican [Wood et al.'14]

```
(let [s (sample (normal 0.0 2.0))  
      b (sample (normal 0.0 6.0))  
      f (fn [x] (+ (* s x) b)))]
```

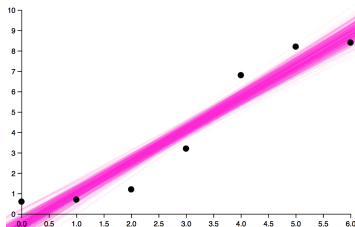
```
(predict :f f))
```



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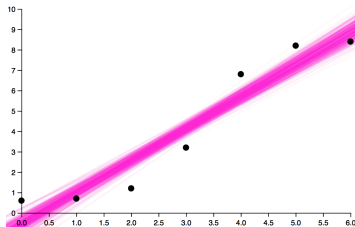
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  (observe (normal (f 1.0) 0.5) 2.5)  
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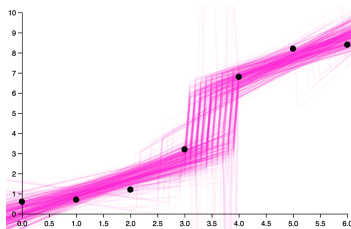
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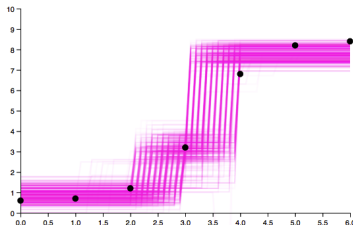


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```



What is probabilistic programming?

Components

- ▶ Control flow, e.g.: simply typed λ -calculus
- ▶ data types, e.g.: lists, functions, thunks
- ▶ Probabilistic choice: `(sample (normal 0.0 2.0))`
- ▶ Conditioning: `(observe (normal (f 2.0) 0.5) 3.8)`

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$$\text{posterior} \propto \text{likelihood} \times \text{prior}$$

What is probabilistic programming?

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$$\text{posterior} \propto \text{likelihood} \times \text{prior}$$

Which we refine to:

$$\text{posterior} = \text{weight} \odot \text{prior}$$

Some measure theory

Rescaling

$$\nu = w \odot \mu$$

when for all $\chi : X \rightarrow [0, \infty]$:

$$\int_X \chi(x) \nu(dx) = \int_X \chi(x) \cdot w(x) \mu(dx)$$

(where X measurable space, $\mu \in MX$ measures on X ,
 $w : X \rightarrow [0, \infty]$ measurable function)

Theorem (Radon-Nikodym)

For all finite ν, μ : if such w exists, then it is unique μ -almost everywhere.

Write: $\nu \ll \mu$, $w = \frac{d\nu}{d\mu}$

What is probabilistic programming?

A probabilistic program is a measure

For $t : X$

$$\llbracket t \rrbracket = w \odot \text{prior} \llbracket t \rrbracket$$

where $\text{prior} \llbracket t \rrbracket$ is the **prior** (ignore conditioning),

and $w = \frac{d \llbracket t \rrbracket}{d(\text{prior} \llbracket t \rrbracket)}$

Conditioning

$$\frac{t : x \quad \varphi : X \rightarrow [0, +\infty]}{\text{observe}(t, \varphi) : 1}$$

and

$$\llbracket \text{observe} \rrbracket (x, \varphi) = \varphi(x) \odot \delta_{()}$$

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Conditioning

Replace observe by score :

$$\frac{r : [0, \infty]}{\text{score } r : 1}$$

and

$$\llbracket \text{score} \rrbracket (r) = r \odot \delta_{()}$$

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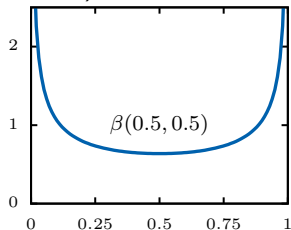
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Note

For probability measures $\text{prior} \llbracket t \rrbracket$:

- It's possible that $\max w > 1$, e.g.:



or even $\max w = \infty$

- If we insist that all measures are sub-probability measures, then w and $\llbracket t \rrbracket$ are **not** compositional (i.e., global)

What is probabilistic programming?

A probabilistic program is an s-finite measure [Staton'17]

For $t : X$

$$\llbracket t \rrbracket = w \odot \text{prior } \llbracket t \rrbracket$$

where $\text{prior } \llbracket t \rrbracket$ is the **prior** (ignore conditioning),

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Sampling manipulates prior.

Conditioning affects w , sequenced multiplicatively.

S-finite measures

$$\sum_{i \in \mathbb{N}} \mu_i$$

μ_i finite: $\mu_i(X) < \infty$

What is inference?

Computing distributions

For $t : X$

$$\llbracket t \rrbracket = w \odot \text{prior} \llbracket t \rrbracket$$

we want to:

- ▶ Plot $\llbracket t \rrbracket$.
- ▶ Sample $\llbracket t \rrbracket$ (e.g., to make prediction)

Challenge

Given a fair coin ($\frac{1}{2}\delta_1 + \frac{1}{2}\delta_0$), how do we sample from a biased coin ($p\delta_1 + (1-p)\delta_0$)?

Generalise:

Given a prior distribution $\text{prior} \llbracket t \rrbracket$, how do we sample from $\llbracket t \rrbracket$?

What is inference?

Programming-language experts needed

In the traditional areas:

- ▶ Verification
- ▶ Correctness
- ▶ Static analysis
- ▶ Semantics
- ▶ Optimisation
- ▶ Programming abstractions
- ▶ Type systems

This talk

Correctness of inference

Inference algorithm: distribution/meaning preserving transformation from one inference representation to another

Requirements

- ▶ Represented data is continuous
- ▶ Compositional inference representations (IRs)
- ▶ IRs are **higher-order**

Traditional measure theory...

This talk

Correctness of inference

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- ▶ Represented data is continuous
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- ▶ IRs are **higher-order**

Traditional measure theory... is unsuitable:

Theorem (Aumann'61)

The set $\mathbf{Meas}(\mathbb{R}, \mathbb{R})$ cannot be made into a measurable space with

$$eval : \mathbf{Meas}(\mathbb{R}, \mathbb{R}) \times \mathbb{R} \rightarrow \mathbb{R}$$

measurable.

Correctness of inference

- ▶ Modular validation of inference algorithms:
Sequential Monte Carlo, Trace Markov Chain Monte Carlo
By combining:
- ▶ Synthetic measure theory [Kock'12]: measure theory without measurable spaces
- ▶ Quasi-Borel spaces: a convenient category for higher-order measure theory [LICS'17]

Talk structure

- ▶ Probabilistic programming and Bayesian inference
- ▶ Synthetic measure theory
- ▶ Quasi-Borel spaces
- ▶ Inference representations
- ▶ Trace Markov Chain Monte Carlo (Trace MCMC)
- ▶ Conclusion

Synthetic measure theory: axioms

Measure category [Kock'12]

A pair $(\mathcal{C}, \underline{\mathbf{M}})$

- ▶ Cartesian-closed category \mathcal{C}

Synthetic measure theory: axioms

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Synthetic measure theory: axioms

Measure category [Kock'12]

A pair $(\mathcal{C}, \underline{M})$

- ▶ Cartesian-closed category \mathcal{C}
- ▶ Countable coproducts and countable limits
- ▶ $\underline{M} = (M, \text{return}, \gg=)$ a strong commutative monad, i.e.:

$$M : |\mathcal{C}| \rightarrow |\mathcal{C}| \qquad \text{return}_X : X \rightarrow M X$$

$$\gg=_{X,Y} : M X \times (M Y)^X \rightarrow M Y$$

satisfying the monad laws and

$$\begin{aligned} \underline{T}.\text{do} \{x \leftarrow a; y \leftarrow b; \text{return}(x, y)\} \\ = \\ \underline{T}.\text{do} \{y \leftarrow b; x \leftarrow a; \text{return}(x, y)\} \end{aligned}$$

Synthetic measure theory: axioms

Measure category [Kock'12]

A pair $(\mathcal{C}, \underline{M})$

- ▶ Cartesian-closed category \mathcal{C}
- ▶ Countable coproducts and countable limits
- ▶ $\underline{M} = (M, \text{return}, \gg=)$ a strong commutative monad, i.e.:
- ▶ Canonical morphisms are invertible:

$$M \, 0 \cong 1 \qquad M\left(\coprod_{n \in \mathbb{N}} X\right) \cong \prod_{n \in \mathbb{N}} M X$$

Synthetic measure theory: consequences

Surprisingly rich structure

- ▶ $0 : \mathbb{1} \rightarrow M 0$
- ▶ $\sum_{n \in \mathbb{N}} X : \prod_{i \in \mathbb{N}} X \cong M(\coprod_{i \in \mathbb{N}} X) \xrightarrow{M \nabla} M X$
- ▶ $R := M \mathbb{1}$ a σ -semiring:

$$(\cdot) : R \times R \xrightarrow{\text{double strength}} R \quad 1 := \text{return}() \in R$$

- ▶ Every algebra is an R -module:

$$\odot : R \times M X \xrightarrow{\text{strength}} M X$$

- ▶ Associated affine monad:

$$P X \xrightarrow{\text{sub}_X} M X \xrightarrow[\underline{1}]{M!} R$$

Kock integration

$$\oint_X f(x) \underline{\mu}(\mathrm{d}x) := \underline{\mu} \gg= f$$

- ▶ Measure-valued, hence analogous to

$$\int_X \chi(x) \cdot f(x) \underline{\mu}(\mathrm{d}x)$$

for generic $\chi : X \rightarrow [0, \infty)$

- ▶ η -expanded integrand

Synthetic measure theory: notation

Notation	Meaning	Terminology
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$\oint_Y f(x, y) k(x, \mathrm{d}y)$	$:= \oint_Y f(x, y) k(x)(\mathrm{d}y)$	Kernel integration

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$\iint_{X \times Y} f(x, y) \underline{\mu}(\mathrm{d}x, \mathrm{d}y)$	$:= \oint_{X \times Y} f(z) \underline{\mu}(\mathrm{d}z)$	Iterated integrals

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$\underline{\mu} \otimes \underline{\nu}$	$:= \oint_X \left(\oint_Y \underline{\delta}_{(x,y)} \underline{\nu}(dy) \right) \underline{\mu}(dx)$	Product measure

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$\mathbb{E}_{x \sim \underline{\mu}}^A [f(x)]$	$:= \underline{\mu} \gg= f$	Expectation

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$\mathbb{E}_{x \sim \underline{\mu}}^A[f(x)]$	$:= \underline{\mu} \gg= f$	Expectation
$\int_X f(x) \underline{\mu}(\mathrm{d}x)$	$:= \mathbb{E}_{x \sim \underline{\mu}}^R[f(x)]$	Lebesgue integral

Synthetic measure theory: Radon-Nikodym

Radon-Nikodym derivatives

- ▶ $\underline{\nu} \ll \underline{\mu}$ when $\underline{\nu} = w \odot \underline{\mu}$;
- ▶ w and v are **equal $\underline{\mu}$ -almost everywhere** when $w \odot \underline{\mu} = v \odot \underline{\mu}$.
- ▶ Measurable property: $P : X \rightarrow \text{bool}$, induces $[P] : X \rightarrow [0, \infty]$
- ▶ P over X **holds $\underline{\mu}$ -a.e.** when $[P] = 1$ $\underline{\mu}$ -a.e..

Theorem (Radon-Nikodym)

Let (\mathcal{C}, M) be a well-pointed measure category. For every $\underline{\nu} \ll \underline{\mu}$ in $M X$, there exists a $\underline{\mu}$ -a.e. unique morphism $\frac{d\underline{\nu}}{d\underline{\mu}} : X \rightarrow R$ satisfying $\frac{d\underline{\nu}}{d\underline{\mu}} \odot \underline{\mu} = \underline{\nu}$.

Talk structure

- ▶ Probabilistic programming and Bayesian inference
- ▶ Synthetic measure theory
- ▶ **Quasi-Borel spaces**
- ▶ Inference representations
- ▶ Trace Markov Chain Monte Carlo (Trace MCMC)
- ▶ Conclusion

Measures subsets of \mathbb{R}

Borel subsets $\mathcal{B}(\mathbb{R})$ as closure under:

- ▶ Intervals $[a, b]$.
- ▶ Countable unions.
- ▶ Complements.

$\varphi : \mathbb{R} \rightarrow \mathbb{R}$ is **measurable** when:

$$B \in \mathcal{B}(\mathbb{R}) \quad \implies \quad \varphi^{-1}[B] \in \mathcal{B}(\mathbb{R})$$

Source of randomness

Key idea

Propagating randomness from discrete and continuous sampling:

$$\alpha : \mathbb{I} \rightarrow X$$

along “random elements”:

- ▶ for **measurable spaces**: **derived** through measurable functions;
- ▶ for **quasi-Borel spaces**: **axiomised** through structure.

The category \mathbf{Qbs}

Objects

A **quasi-Borel space** $X = (|X|, X^{\mathbb{I}})$ consists of:

- ▶ a **carrier set** X ;
- ▶ a set of **random elements** $X^{\mathbb{I}} \subseteq |X|^{\mathbb{I}}$

such that the random elements are closed under:

The category Qbs

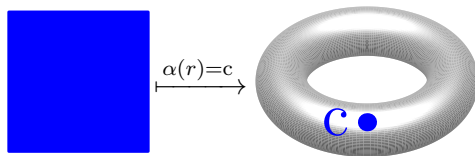
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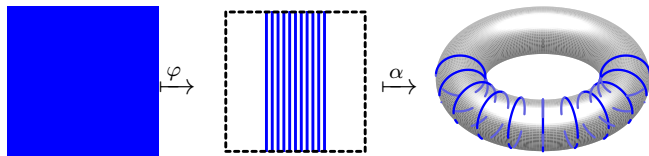
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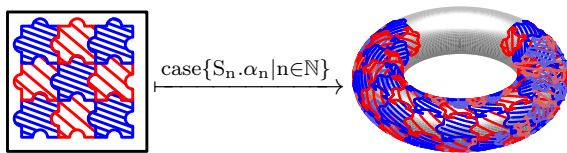
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such that the random elements are closed under:

- ▶ constant functions \underline{c} ;
- ▶ precomposition with a measurable $\varphi : \mathbb{I} \rightarrow \mathbb{I}$
- ▶ countable measurable case split.



The category Qbs

Morphisms $f : X \rightarrow Y$

Functions $f : |X| \rightarrow |Y|$ such that:

$$\alpha \in X^{\mathbb{R}} \quad \implies \quad f \circ \alpha \in Y^{\mathbb{R}}$$

Subspaces

Every subset $S \subseteq |X|$ inherits the subspace structure:

$$S^{\mathbb{R}} := \left\{ \alpha : \mathbb{R} \rightarrow S \mid \alpha \in X^{\mathbb{I}} \right\}$$

The commutative monad

Measures

(Ω, α, μ) :

- ▶ Ω is a standard Borel space
- ▶ $\alpha \in X^\Omega$
- ▶ and μ is a σ -finite measure on Ω

Induced integration operator

For $f : X \rightarrow [0, \infty]$:

$$\int f \, d(\Omega, \alpha, \mu) := \int_{\Omega} f(\alpha(x)) \, \mu(dx)$$

Monad of measures

$(\Omega, \alpha, \mu) \approx (\Omega', \alpha', \mu')$ when they determine the same integration operator.

$\mathbf{M} X$ consists of equivalence classes of \approx .

A synthetic model

The measure category ($\mathbf{Qbs}, \underline{\mathbf{M}}$)

- ▶ $\mathbf{Qbs}(\mathbb{1}, R) \cong_{\sigma} [0, \infty]$;
- ▶ $\mathbf{Qbs}(R, \mathbb{1} + \mathbb{1}) \cong \mathcal{B}([0, \infty])$ as characteristic functions
- ▶ $\mathbf{Qbs}(R, R) \cong \mathbf{Meas}([0, \infty], [0, \infty])$
- ▶ $\text{Giry } [0, \infty] \rightarrow \mathbf{Qbs}(\mathbb{1}, \mathbf{M}(R)) \rightarrow \text{Measures } [0, \infty]$
- ▶ $R^R \times \mathbf{M}(R) \rightarrow R, (f, \underline{\mu}) \mapsto \int f(x) \underline{\mu}(dx)$ is the Lebesgue integral

Talk structure

- ▶ Probabilistic programming and Bayesian inference
- ▶ Synthetic measure theory
- ▶ Quasi-Borel spaces
- ▶ **Inference representations**
- ▶ Trace Markov Chain Monte Carlo (Trace MCMC)
- ▶ Conclusion

Program representation

A **representation** \underline{T} ($T, \text{return}^{\underline{T}}, \gg=^{\underline{T}}, m^{\underline{T}}$) consists of:

- ▶ $(T, \text{return}^{\underline{T}}, \gg=^{\underline{T}})$: monadic interface;
 - ▶ $m^{\underline{T}}_X : T\ X \rightarrow M\ X$: meaning morphism for every space X
- and $m^{\underline{T}}$ preserves $\text{return}^{\underline{T}}$ and $\gg=^{\underline{T}}$:

$$\text{return}^M x = m(\text{return}^{\underline{T}} x)$$

$$m(a \gg=^{\underline{T}} f) = (m a) \gg=^M \lambda x. m(f\ x)$$

Example representation: lists

instance *Rep* (List) **where**
 return x $= [x]$
 $x_s \gg= f$ $= \text{foldr } []$
 $(\lambda(x, y_s).$
 $f(x) \text{ ++ } y_s) \ x_s$
 $m_{\text{List}}[x_1, \dots, x_n] = \sum_{i=1}^n \delta_{x_i}$

Sampling representation

$(T, \text{return}^T, \gg^T, m^T, \text{sample}^T)$

- ▶ $(T, \text{return}^T, \gg^T, m^T)$: program representation
- ▶ $\text{sample}^T : \mathbb{1} \rightarrow T \mathbb{1}$

and $m^T \circ \text{sample}^T = \mathbf{U}_{\mathbb{1}}$

Representations

Example: free sampler

$\text{Sam } \alpha := \{\text{Return } \alpha \mid \text{Sample } (\mathbb{I} \rightarrow \text{Sam } \alpha)\}$:

instance *Sampling Rep* (Sam) **where**

return $x = \text{Return } x$

$a \gg= f = \text{match } a \text{ with } \{$
 $\text{Return } x \rightarrow f(x)$
 $\text{Sample } k \rightarrow$
 $\text{Sample } (\lambda r. k(r) \gg= f)\}$

$\text{sample} = \text{Sample } \lambda r. (\text{Return } r)$

$m a = \text{match } a \text{ with } \{$
 $\text{Return } x \rightarrow \underline{\delta}_x$
 $\text{Sample } k \rightarrow \oint_{\mathbb{I}} m(k(x)) \mathbf{U}(\mathrm{d}x)\}$

Conditioning representation

$(T, \text{return}^T, \gg^T, m^T, \text{score}^T)$

- ▶ $(T, \text{return}^T, \gg^T, m^T)$: program representation
- ▶ $\text{score}^T : [0, \infty) \rightarrow T \mathbb{1}$

and $m^T \circ \text{score}^T r = r \odot \underline{\delta}_{()}$

Representations

Weighted values

For every representation \underline{T} , $\mathsf{W} \underline{T} X := T(\mathbb{R}_+ * X)$

instance *Conditioning Rep* ($\mathsf{W} \underline{T}$) **where**

return $_{\mathsf{W} \underline{T}}$ $x = \text{return}^{\underline{T}}(1, x)$

$a \gg=_{\mathsf{W} \underline{T}} f = \underline{T}.\text{do} \{ (r, x) \leftarrow a;$

$(s, y) \leftarrow f(x);$

return $(r \cdot s, y) \}$

$m_{\mathsf{W} \underline{T}} a = \lambda x. \oint_{\mathbb{R}_+ \times X} r \odot \underline{\delta}_x m^{\underline{T}}(a)(dr, dx)$

score $_{\mathsf{W} \underline{T}} r = \text{return}^{\underline{T}}(r, ())$

Inference representation

$(T, \text{return}^T, \gg^T, \text{sample}^T \text{score}^T, m^T)$: sampling and conditioning

Example: weighted sampler

$\text{WSam } X := \text{WSam } X = \text{Sam}([0, \infty) \times X)$

Inference transformations

$$\underline{t} : \underline{T} \rightarrow \underline{S}$$

$\underline{t} : T X \rightarrow S X$ for every space X such that:

$$m_{\underline{S}} \circ \underline{t} = m_{\underline{T}}$$

A single compositional step in an inference algorithm

Inference transformations

$$\underline{t} : \underline{T} \rightarrow \underline{S}$$

$\underline{t} : T X \rightarrow S X$ for every space X such that:

$$m_S \circ \underline{t} = m_T$$

A single compositional step in an inference algorithm

Unnaturality

$\text{aggr}_X : \text{List}(\mathbb{R}_+ * X) \rightarrow \text{List}(\mathbb{R}_+ * X)$

aggregating (r, x) , (s, x) to $(r + s, x)$

Then $\text{aggr} : \underline{\text{List}} \rightarrow \underline{\text{List}}$ but not natural:

$$\begin{aligned} & \text{aggr} \circ \text{List!} \left[\left(\frac{1}{2}, \text{False} \right), \left(\frac{1}{2}, \text{True} \right) \right] [(1, ())] \\ & \neq \left[\left(\frac{1}{2}, () \right), \left(\frac{1}{2}, () \right) \right] \text{Enum!} \circ \text{aggr} \left[\left(\frac{1}{2}, \text{False} \right), \left(\frac{1}{2}, \text{True} \right) \right] \end{aligned}$$

Talk structure

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Metropolis-Hastings update

```
 $\underline{T}.$ do {  $x \leftarrow a$ ;  
          $y \leftarrow \psi_a(x)$ ;  
          $r \leftarrow \text{sample}$ ;  
         if  $r < \min(1, \rho_a(x, y))$   
         then return  $y$   
         else return  $x$  }
```

where $\psi_a : X \rightarrow T X$ and $\rho_a : X \times X \rightarrow \overline{\mathbb{R}}_+$

Markov Chain Monte Carlo: abstract foundation

Theorem (Metropolis-Hastings-Green for quasi-Borel spaces)

Given X , $a \in \mathsf{M} X$, $\psi_a : X \rightarrow \mathsf{M} X$, and $\rho_a : X \times X \rightarrow \overline{\mathbb{R}}_+$, set $\underline{\mu}_a := [\rho \neq 0] \odot (\prod_{(x,y)} \delta_{(x,y)} a(\mathrm{d}x) \psi(x, \mathrm{d}y))$.

Assume that:

1. ψ_a is Markov: $\psi(x, X) = 1$;
2. $[1 = (\rho \circ \text{swap}) \cdot \rho]$ holds $\underline{\mu}_a$ -a.e.;
3. $\rho = \frac{\mathrm{d}(\text{swap}_* \underline{\mu}_a)}{\mathrm{d}\underline{\mu}_a}$;
4. $\rho(x, y) = 0 \iff \rho(y, x) = 0$ for all $x, y \in X$.

Then $(\eta_{\psi_a, \rho_a})(a) = a$.

Proof mimicks measure theoretic proof, e.g. [Geyer'11]

Trace Markov Chain Monte Carlo: Representation

Program traces

- ▶ $t \in \text{WSam } X$: program structure representation

Trace Markov Chain Monte Carlo: Representation

Program traces

- ▶ $t \in \text{WSam } X$: program structure representation
- ▶ $p : \text{List } \mathbb{I}$ a trace in program t

$$p \in t = \mathbf{match} (p, t) \mathbf{with} \{$$
$$\begin{array}{l} ([\] \quad , \text{Return } x \quad) \rightarrow \text{True} \\ (r :: r_s, \text{Sample } f \quad) \rightarrow [r_s \in f(r)] \\ \text{--- any other case:} \\ (- \quad , - \quad) \rightarrow \text{False} \end{array}$$

Trace Markov Chain Monte Carlo: Representation

Program traces

- ▶ $t \in \text{WSam } X$: program structure representation
- ▶ $p : \text{List } \mathbb{I}$ a trace in program t
- ▶ $\sum_{t \in \text{WSam } X} \text{Paths } t := \{(t, p) \in \text{WSam } X \times \text{List } \mathbb{I} \mid p \in t\}$
 $\subseteq \text{WSam } X \times \text{List } \mathbb{I}$

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$$\subseteq \text{WSam } X \times \text{List } \mathbb{I}$$
- ▶ $w_- : \sum_{t \in \text{WSam } X} \text{Paths } t \rightarrow \mathbb{R}_+$
 $w_{\text{Return}(r, x)}([\]) = r$
 $w_{\text{Sample } t_-}(s :: r_s) = w_{t_s}(r_s)$

Trace Markov Chain Monte Carlo: Representation

Program traces

- ▶ $t \in \text{WSam } X$: program structure representation
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- ▶
$$\sum_{t \in \text{WSam } X} \text{Paths } t := \{(t, p) \in \text{WSam } X \times \text{List } \mathbb{I} \mid p \in t\}$$
$$\subseteq \text{WSam } X \times \text{List } \mathbb{I}$$
- ▶ $w_- : \sum_{t \in \text{WSam } X} \text{Paths } t \rightarrow \mathbb{R}_+$
- ▶ $v_- : \sum_{t \in \text{WSam } X} \text{Paths } t \rightarrow X$
 $v_{\text{Return}(r, x)}([\]) = x$
 $v_{\text{Sample } t_-}(s :: r_s) = v_{t_s}(r_s)$

Trace Markov Chain Monte Carlo: Representation

Program traces

- ▶ $t \in \text{WSam } X$: program structure representation
- ▶ $p : \text{List } \mathbb{I}$ a trace in program t
- ▶
$$\sum_{t \in \text{WSam } X} \text{Paths } t := \{(t, p) \in \text{WSam } X \times \text{List } \mathbb{I} \mid p \in t\}$$
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- ▶ $w_- : \sum_{t \in \text{WSam } X} \text{Paths } t \rightarrow \mathbb{R}_+$
- ▶ $v_- : \sum_{t \in \text{WSam } X} \text{Paths } t \rightarrow X$

Tracing representation

$\text{Tr } \underline{T} \ X :=$

$$\left\{ (t, a) \in \text{WSam } X \times T(\text{List } \mathbb{I}) \left| \begin{array}{l} [\in t] \ m_{\underline{T}}(a)\text{-a.e., and} \\ m_{\text{WSam}}(t) = \oint_{\text{List } \mathbb{I}} \delta_{v_t(p)} m_{\underline{T}}(a)(dp) \end{array} \right. \right\}$$

Trace Markov Chain Monte Carlo: Representation

Tracing representation

$\text{Tr } \underline{T} \ X :=$

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instance $\text{Inf} \implies \text{Inf Monad } (\text{Tr } \underline{T})$ **where**

return x = $(\text{return}_{\text{WSam}} x, \text{return}_{\underline{T}} [])$

$(t, a) \gg= (f, g) = (t \gg=_{\text{WSam}} f, \underline{T}.\text{do } \{p \leftarrow a;$
 $q \leftarrow g \circ v_t(p);$
 $\text{return}(p \mathbin{++} q)\})$

$m((, t), a) = m_{\text{WSam}}(t) = \oint_{\text{List } \mathbb{I}} \delta_{v_t(p)} m_{\underline{T}}(a)(dp)$

sample = $(\text{sample}_{\text{WSam}},$
 $\underline{T}.\text{do } \{r \leftarrow \text{sample}; \text{return}[r]\})$

score r = $(\text{sample}_{\text{WSam}},$
 $\underline{T}.\text{do } \{\text{score } r; \text{return}[]\})$

Markov Chain Monte Carlo: Transformation

Trace MCMC morphism

$$\eta_{\psi, \rho}^{\text{Tr } T} : \text{Tr } T X \rightarrow \text{Tr } T X$$
$$\eta_{\psi, \rho}^{\text{Tr } T}(t, a) := (t, \eta_{\psi_t, \rho_t}(a))$$

Concrete proposal kernel and derivative

$$\psi_t : \text{List}(\mathbb{I}) \rightarrow T(\text{List}(\mathbb{I}))$$
$$\psi_t(p) := \underline{T}.\mathbf{do} \{ i \leftarrow \text{U}_D^{\underline{T}}(|p|)$$
$$q \leftarrow \text{pri}^T(\text{sub}(t, \text{take}(i, p)))$$
$$\mathbf{return}(\text{take}(i, p) + q) \}$$

$$\rho_t : \text{List}(\mathbb{I}) \times \text{List}(\mathbb{I}) \rightarrow \overline{\mathbb{R}}_+$$
$$\rho_t(p, q) := \frac{w_t(q) \cdot (|p| + 1)}{w_t(p) \cdot (|q| + 1)}$$

Correctness of inference

- ▶ Modular validation of inference algorithms:
Sequential Monte Carlo, Trace Markov Chain Monte Carlo
By combining:
- ▶ Synthetic measure theory [Kock'12]: measure theory without measurable spaces
- ▶ Quasi-Borel spaces: a convenient category for higher-order measure theory [LICS'17]

Conclusion

Summary

- ▶ Bayesian inference: (continuous) sampling and conditioning
- ▶ Inference representation: monadic interface, sampling, conditioning, and meaning
- ▶ Plenty of opportunities for traditional programming language expertise

Further topics

- ▶ Sequential Monte Carlo (SMC)
- ▶ Combining SMC and MCMC into Move-Resample SMC
- ▶ Categorical structure of quasi-borel spaces