Algebraic geometry (Notes)

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1 Algebraic varieties

1.1 Definition Week4

The varieties we have seen so far have been sub-sets of the affine space. Using these as buildig blocks, we can construct general algebraic varieties. The definition is analogous to the definition of a manifold in differential geometry, using open subsets of \mathbb{R}^n as building blocks.

Let X be a topological space. A quasi-affine chart on X consists of an open subset $U \subset X$, a quasi-affine variety V and a homeomorphism $\phi_{UV} : U \to V$. Via this isomorphism, we can "transport" the algebraic structure (for example, the notion of a regular function) from V to U.

Let $\phi_1: U_1 \to V_1$ and $\phi_2: U_2 \to V_2$ be two quasi-affine charts on X (see Figure 1). Set $U_{12} = U_1 \cap U_2$. Consider the open subsets $V_{12} = \phi_1(U_{12}) \subset V_1$ and $V_{21} = \phi_2(U_{12}) \subset V_2$. Being open subsets of quasi-affine varieties, they are themselves quasi-affine varieties. Furthermore, the map

$$\phi_2 \circ \phi_1^{-1} \colon V_{12} \to V_{21}$$

is a homeomorphism. We say that the two charts are *compatible* if this map is a (bi-regular) isomorphism.

When we have two charts, one on U_1 and another on U_2 , then the intersection $U_1 \cap U_2$ gets two different charts. Compatibility ensures that these two charts are related by a bi-regular isomorphism, so that the algebraic structure coming from one is the same as the one coming from the other.

A quasi-affine atlas on X is a collection of compatible charts $\phi_i : U_i \to V_i$ such that the U_i cover X.

1.1.1 Definition (Algebraic variety) An *algebraic variety* is a topological space with a quasi-affine atlas.

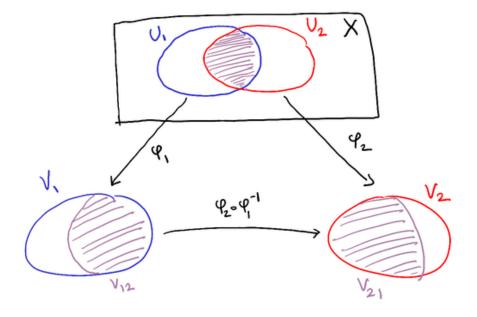


Figure 1: Compatible charts

1.1.2 Example (Quasi-affine varieties) A quasi-affine variety X is itself an algebraic variety. The atlas is the obvious one, consisting of the single chart id: $X \to X$.

1.2 Projective spaces

week4

A fundamental example of an algebraic variety is the projective space.

- **1.2.1 Definition (Projective space)** The projective n-space over a field k, denoted by \mathbb{P}_k^n , is the set of one-dimensional subspaces of k^{n+1} .
- **1.2.2 Intuition** Before describing how \mathbb{P}^n_k is an algebraic variety, let us build some intuition about projective space. For easy visualisations, it helps to take $k = \mathbb{R}$ or $k = \mathbb{C}$. A one dimensional subspace of k^{n+1} is also called a *line*. Note that, by this definition, a line must contain the origin.

Let us take n = 0. Then there is a unique one-dimensional subspace of $k^{n+1} = k$, so \mathbb{P}^0_k is just a single point.

Let us take n=1. Then \mathbb{P}^1_k is the set of lines (through the origin) in k^2 . Let us take $k=\mathbb{R}$. Every line through the origin is uniquely determined by its slope, which can be any element of \mathbb{R} , so it seems like $\mathbb{P}^1_{\mathbb{R}}$ is just a copy of \mathbb{R} . But the vertical line does not have a (finite) slope, so $\mathbb{P}^1_{\mathbb{R}} = \mathbb{R} \cup \{\infty\}$. In other words, \mathbb{P}^1 contains the usual real line, plus "a point at infinity".

It can be more instructive to see this in a picture. Fix a horizontal line L at, say, y = -1. Every line through the origin intersects L at a unique point, except the horizontal line. So if we discard the one point of \mathbb{P}^1_k corresponding to the horizontal line, the rest is just a copy of L. If we had chosen a different reference line L, for example, a vertical one, then we get a similar description of \mathbb{P}^1 away from a single point. In fact, we can discard any one point of \mathbb{P}^1 , and the rest will be a copy of \mathbb{R} .

Let us take n=2. Then \mathbb{P}^2_k is the set of lines (through the origin) in k^3 . We can use the same technique as before: fix a reference plane P at z=-1. Then most lines are uniquely characterised by their intersection point with P. The only exceptions are the lines parallel to z=-1, that is, the lines lying in the plane z=0, which we miss. But these form a small projective space \mathbb{P}^1 . So we see that $\mathbb{P}^2=P\sqcup\mathbb{P}^1$.

1.2.3 Topology A one-dimensional subspace of k^{n+1} is spanned by a non-zero vector (a_0, \ldots, a_n) . Two vectors (a_0, \ldots, a_n) and (b_0, \ldots, b_n) span the same subspace if and only if there exists $\lambda \in k^{\times}$ such that

$$(b_0,\ldots,b_n)=(\lambda a_0,\ldots,\lambda a_n).$$

So, we can identify \mathbb{P}^n with the equivalence classes of non-zero vectors (a_0, \ldots, a_n) where two non-zero vectors are considered equivalent if one is a scalar multiple of the other. In other words, we have

$$\mathbb{P}_k^n = (\mathbb{A}^{n+1} \setminus 0)/\text{scaling}.$$

We denote the equivalence class of (a_0, \ldots, a_n) by $[a_0 : \cdots : a_n]$.

We give \mathbb{P}_k^n the quotient topology inherited from $\mathbb{A}^{n+1} \setminus 0$. That is, a set $U \subset \mathbb{P}_k^n$ is open/closed if and only if its pre-image in $\mathbb{A}^{n+1} \setminus 0$ is open/closed.

For example, consider the subset U_n of \mathbb{P}^n_k consisting of $[a_0 : \cdots : a_n]$ with $a_n \neq 0$. Its preimage in the set of $(a_0, \ldots, a_n) \in \mathbb{A}^{n+1} \setminus 0$ with $a_n \neq 0$, which is a (Zariski) open set. Hence U_n is open in \mathbb{P}^n_k . Likewise, U_0, U_1, \ldots are also open. Note that we have

$$\mathbb{P}_k^n = U_0 \cup \cdots \cup U_n;$$

that is, the sets U_0, \ldots, U_n form an open cover of \mathbb{P}^n .

Consider a point $[a_0 : \cdots : a_n] \in U_0$, so that $a_0 \neq 0$. By scaling by $\lambda = a_0^{-1}$, we have a distinguished representative of this point of the form $[1 : b_1 : \cdots : b_n]$, which we can think of as a point $(b_1, \ldots, b_n) \in \mathbb{A}^n$. Thus, we have a bijection $\phi_0 : U_0 \to \mathbb{A}^n$, and similarly $\phi_1 U_i \to \mathbb{A}^n$.

1.2.4 Proposition (Charts of the projective space)

- 1. The bijections $\phi_i : U_i \to \mathbb{A}^n$ defined above are homeomorphisms.
- 2. The charts $\phi_i : U_i \to \mathbb{A}^n$ are mutually compatible, and hence give an atlas on \mathbb{P}^n .

- 1. This is not obvious, also not hard, but also not very enlightening. Let us skip this.
- 2. Do this! (1)
- **1.2.5** Open and closed subvarieties Let X be an algebraic variety, and $Y \subset X$ an open or closed subset. Then Y inherits the structure of an algebraic variety. To get, the atlas for Y, let $\phi_i : U_i \to V_i$ be an atlas for X. For Y, we just take $\phi_i : U_i \cap Y \to \phi(U_i \cap Y)$.

Explain why this is an atlas for Y — (2)

1.2.6 Proposition (Closed subvarieties of projective space 1) Let $F \in k[X_0, ..., X_n]$ be a homogeneous polynomial. Let $V(F) \subset \mathbb{P}^n$ be the set of points $\{[a_0 : \cdots : a_n] \mid F(a_0, ..., a_n) = 0\}$. Then V(F) is a closed subset.

Explain why V(F) is well-defined (that is, the condition $F(a_0, ..., a_n) = 0$ does not depend on the chosen representative of the equivalence class). Then explain why V(F) is closed. — (3)

1.2.7 Proposition (Closed subvarieties of projective space 2) Let $I \subset k[X_0, \ldots, X_n]$ be a homogeneous ideal.

Define $V(I) \subset \mathbb{P}^n$ and show that it is a closed subset. — (4)

1.2.8 Proposition (Closed subvarieties of projective space 3) Conversely, let $X \subset \mathbb{P}^n$ be a closed subset. Then there exists a homogeneous ideal $I \subset k[X_0, \ldots, X_n]$ such that X = V(I).

Proof. Assume that X is non-empty. Let $\pi: \mathbb{A}^{n+1} \setminus 0 \to \mathbb{P}^n$ be the quotient map. Let $C \subset \mathbb{A}^n$ be the closure of $\pi^{-1}(X)$.

Prove that C is conical, that is, if $x \in C$ then $\lambda x \in C$ for every scalar $\lambda \in k$. Conclude using Homework 1 that C = V(I) for a homogeneous ideal I. Prove that X = V(I) in \mathbb{P}^n . — (5)

1.2.9 Example (Linear subspaces) Suppose $I \subset k[X_0, ..., X_n]$ is generated by (homogeneous) linear equations. Then $V(I) \subset \mathbb{A}^{n+1}$ is a sub-vector space $W \subset \mathbb{A}^{n+1}$, and $V(I) \subset \mathbb{P}^n$ is naturally the projective space of W. We call such $V(I) \subset \mathbb{P}^n$ linear subspaces, or "lines", "planes", etc. See that any two distinct lines in \mathbb{P}^2 intersect at a unique point, and through any two distinct points in \mathbb{P}^2 passes a unique line.

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