

RT_SLAM_AVOC

https://github.com/deploymentqorix/RT_SLAM_qorix_incu

.git/logs/refs/heads/main

```
0000000000000000000000000000000000000000 533a0d96e0beff3ef5f5aa66a021ef808b9d93ab L-100791
<|-100791@Vaibhavi.(none)> 1755452401 +0530 clone: from
https://github.com/deploymentqorix/RT_SLAM_qorix_incu
```

.git/logs/refs/remotes/origin/HEAD

```
0000000000000000000000000000000000000000 533a0d96e0beff3ef5f5aa66a021ef808b9d93ab L-100791
<|-100791@Vaibhavi.(none)> 1755452401 +0530 clone: from
https://github.com/deploymentqorix/RT_SLAM_qorix_incu
```

.git/packed-refs

pack-refs with: peeled fully-peeled sorted

Module/Top comments:

pack-refs with: peeled fully-peeled sorted

.git/refs/heads/main

533a0d96e0beff3ef5f5aa66a021ef808b9d93ab

.git/refs/remotes/origin/HEAD

ref: refs/remotes/origin/main

LICENSE

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Makefile

The main Makefile for the entire project

Module/Top comments:

The main Makefile for the entire project

backend/api_server/main.py

```
from fastapi import FastAPI
```

```
from fastapi.middleware.cors import CORSMiddleware
```

```
app = FastAPI()
```

```
app.add_middleware(
    CORSMiddleware,
    allow_origins=["*"],
```

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```
allow_credentials=True,  
allow_
```

Functions / Methods:

- get_system_health()

backend/data_streamer/main.py

```
import rclpy  
from rclpy.node import Node  
from nav_msgs.msg import Odometry  
from nav_msgs.msg import OccupancyGrid  
import asyncio  
import websockets  
import json
```

```
CONNECTED_CLIENTS = set()
```

```
async def reg
```

Classes:

- DataStreamerNode:

Functions / Methods:

- __init__(self)
- odom_callback(self, msg)
- map_callback(self, msg)

backend/data_streamer/vehicle_pose.py

```
import rclpy  
from rclpy.node import Node  
from geometry_msgs.msg import PoseStamped
```

```
class PoseSubscriber(Node):  
    def __init__(self):  
        super().__init__('pose_subscriber_for_streamer')
```

Classes:

- PoseSubscriber:

Functions / Methods:

- __init__(self)
- listener_callback(self, msg)

This function is called every time a message is received.

- main(args=None)

backend/dev_scripts/mock_backend.py

File: backend/dev_scripts/mock_api.py

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Description: A standalone FastAPI server to provide mock data for frontend development. To run: python3 mock_api.py

Module/Top comments:

File: backend/dev_scripts/mock_api.py

Description: A standalone FastAPI server to provide mock data for frontend development.

To run: python3 mock_api.py

Functions / Methods:

- get_system_health()

This endpoint simulates the real /system/health endpoint.

It returns a hardcoded, fake system health status.

- reset_slam()

This endpoint simulates receiving a reset command from the UI.

backend/install/_local_setup_util_ps1.py

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Module/Top comments:

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Functions / Methods:

- main(argv=sys.argv[1:])

- get_packages(prefix_path, merged_install)

- add_package_runtime_dependencies(path, packages)

Check the path and if it exists extract the packages runtime dependencies.

:param Path path: The resource file containing the runtime dependencies

:param dict packages: A mapping from package names to the sets of runtime dependencies to add to

- order_packages(packages)

Order packages topologically.

:param dict packages: A mapping from package name to the set of runtime dependencies

:returns: The package names

:rtype: list

- reduce_cycle_set(packages)

Reduce the set of packages to the ones part of the circular dependency.

:param dict packages: A mapping from package name to the set of runtime dependencies which is modified in place

- _include_comments()

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- get_commands(pkg_name, prefix, primary_extension, additional_extension)
- handle_dsv_types_except_source(type_, remainder, prefix)
- _append_unique_value(name, value)
- _prepend_unique_value(name, value)
- _remove_ending_separators()
- _set(name, value)
- _set_if_unset(name, value)

backend/install/_local_setup_util_sh.py

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Module/Top comments:

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Functions / Methods:

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- _remove_ending_separators()
- _set(name, value)
- _set_if_unset(name, value)

backend/install/local_setup.ps1

generated from colcon_powershell/shell/template/prefix.ps1.em

This script extends the environment with all packages contained in this prefix path. check environment variable for custom Python executab

Module/Top comments:

generated from colcon_powershell/shell/template/prefix.ps1.em

This script extends the environment with all packages contained in this prefix path.

check environment variable for custom Python executable

Functions / Methods:

- if (\$env:COLCON_PYTHON_EXECUTABLE) {
- if (!(Test-Path "\$env:COLCON_PYTHON_EXECUTABLE" -PathType Leaf)) {
- if (!(Test-Path "\$_colcon_python_executable" -PathType Leaf)) {
- if (!(Get-Command "python3" -ErrorAction SilentlyContinue)) {
- if (Test-Path \$_colcon_prefix_powershell_source_script_param) {
- if (\$env:COLCON_TRACE) {
- if (\$env:COLCON_TRACE) {
- if (\$_colcon_ordered_commands) {

backend/install/local_setup.sh

generated from colcon_core/shell/template/prefix.sh.em

This script extends the environment with all packages contained in this prefix path. since a plain shell script can't determine its own path when

Module/Top comments:

generated from colcon_core/shell/template/prefix.sh.em

This script extends the environment with all packages contained in this prefix path.

since a plain shell script can't determine its own path when being sourced

either use the provided COLCON_CURRENT_PREFIX

or fall back to the build time prefix (if it exists)

Functions / Methods:

- _colcon_prefix_sh_prepend_unique_value() {
- _colcon_prefix_sh_source_script() {

backend/install/ros2_nodes/share/ros2_nodes/package.ps1

generated from colcon_powershell/shell/template/package.ps1.em

function to append a value to a variable

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which uses colons as separators

duplicates as well as leading separators are avoided

first argum

Module/Top comments:

generated from colcon_powershell/shell/template/package.ps1.em

function to append a value to a variable

which uses colons as separators

duplicates as well as leading separators are avoided

first argument: the name of the result variable

second argument: the value to be prepended

Functions / Methods:

- if (Test-Path Env:\$_listname) {
- if (\$_values) {
- if (\$_) {
- if (\$_ -eq \$_value) {
- if (\$_all_values) {
- if (!\$_duplicate) {
- if (\$_all_values) {
- if (Test-Path Env:\$_listname) {
- if (\$_values) {
- if (\$_) {
- if (\$_ -ne \$_value) {
- if (Test-Path \$_colcon_package_source_powershell_script) {
- if (\$env:COLCON_TRACE) {

backend/install/ros2_nodes/share/ros2_nodes/package.sh

generated from colcon_core/shell/template/package.sh.em

This script extends the environment for this package. function to prepend a value to a variable

which uses colons as separators

duplicates as we

Module/Top comments:

generated from colcon_core/shell/template/package.sh.em

This script extends the environment for this package.

function to prepend a value to a variable

which uses colons as separators

duplicates as well as trailing separators are avoided

first argument: the name of the result variable

second argument: the value to be prepended

Functions / Methods:

- _colcon_prepend_unique_value() {

backend/install/setup.ps1

generated from colcon_powershell/shell/template/prefix_chain.ps1.em

This script extends the environment with the environment of other prefix paths which were sourced when this file was generated as we

Module/Top comments:

generated from colcon_powershell/shell/template/prefix_chain.ps1.em

This script extends the environment with the environment of other prefix paths which were sourced when this file was generated as well as all packages contained in this prefix path.

function to source another script with conditional trace output

first argument: the path of the script

Functions / Methods:

- if (Test-Path \$_colcon_prefix_chain_powershell_source_script_param) {
- if (\$env:COLCON_TRACE) {

backend/install/setup.sh

generated from colcon_core/shell/template/prefix_chain.sh.em

This script extends the environment with the environment of other prefix paths which were sourced when this file was generated as well as a

Module/Top comments:

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This script extends the environment with the environment of other prefix paths which were sourced when this file was generated as well as all packages contained in this prefix path.

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either use the provided COLCON_CURRENT_PREFIX

or fall back to the build time prefix (if it exists)

Functions / Methods:

- _colcon_prefix_chain_sh_source_script() {

backend/requirements.txt

Python packages for the backend services

Module/Top comments:

Python packages for the backend services

backend/ros2_nodes/ros2_nodes/slam_node/CMakeLists.txt

cmake_minimum_required(VERSION 3.8)

project(slam_node)

Find all dependencies

find_package(ament_cmake REQUIRED)

find_package(rclcpp REQUIRED)

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find_package(geometry_msgs REQUIRED)

find_package(senso

backend/ros2_nodes/ros2_nodes/slam_node/src/slam_logic.cpp

include <Eigen/Dense>

include <vector>

include "rclcpp/rclcpp.hpp"

include "geometry_msgs/msg/pose_stamped.hpp"

include "sensor_msgs/msg/imu.hpp"

include "sensor_msgs/msg/laser_scan.hpp"

include "nav_

Module/Top comments:

include <Eigen/Dense>

include <vector>

include "rclcpp/rclcpp.hpp"

include "geometry_msgs/msg/pose_stamped.hpp"

include "sensor_msgs/msg/imu.hpp"

include "sensor_msgs/msg/laser_scan.hpp"

include "nav_msgs/msg/occupancy_grid.hpp"

include "nav_msgs/msg/odometry.hpp"

include "tf2_ros/transform_broadcaster.h"

include "tf2/LinearMath/Quaternion.h"

Functions / Methods:

- SlamNode() : Node("slam_node") {

- for (size_t i = 0; i < msg->ranges.size(); ++i) {

- if (map_x >= 0 && map_x < map_width_ && map_y >= 0 && map_y < map_height_) {

- void imu_callback(const sensor_msgs::msg::Imu::SharedPtr msg) {

- void scan_callback(const sensor_msgs::msg::LaserScan::SharedPtr msg) {

- void publish_odometry() {

- int main(int argc, char * argv[]) {

backend/startup.sh

#!/bin/bash

Module/Top comments:

#!/bin/bash

docs/rest_api.md

REST API Endpoints

Get System Health

Module/Top comments:

REST API Endpoints

Get System Health

docs/websocket_api.md

Message for Live Pose Updates

Module/Top comments:

Message for Live Pose Updates

frontend/Dockerfile

Stage 1: Build the React application

Module/Top comments:

Stage 1: Build the React application

frontend/README.md

Getting Started with Create React App

Module/Top comments:

Getting Started with Create React App

frontend/public/robots.txt

<https://www.robotstxt.org/robotstxt.html>

Module/Top comments:

<https://www.robotstxt.org/robotstxt.html>

frontend/src/App.js

```
import React, { useState, useEffect } from 'react';
```

```
import { connectWebSocket, disconnectWebSocket } from '../services/websocketService';
```

```
import MapView from './components/MapView';
```

```
import SystemHealth
```

Functions / Methods:

```
- function App() {
```

```
- if (data.type === 'pose_update') {
```

```
- function App() {
```

frontend/src/App.test.js

```
import { render, screen } from '@testing-library/react';
```

```
import App from './App';
```

```
test('renders learn react link', () => {
```

```
  render(<App />);
```

```
  const linkElement = screen.getByText(/learn react/i);
```

frontend/src/components/MapView.js

```
import React, { useRef, useEffect } from 'react';
```

```
const MapView = ({ pose, trail, mapData }) => {
```

```
  const canvasRef = useRef(null);
```

```
useEffect(() => {  
  const canvas = canvasRef.current;  
  cons
```

Functions / Methods:

```
- if (mapData) {  
- for (let i = 0; i < grid_data.length; i++) {  
- if (value === 100) {  
- if (trail.length > 1) {  
- for (let i = 1; i < trail.length; i++) {
```

frontend/src/components/SystemHealthPanel.js

```
import React, { useState, useEffect } from 'react';  
import { fetchSystemHealth } from '../services/apiService';
```

```
const SystemHealthPanel = () => {  
  const [health, setHealth] = useState({  
    cpu_usag
```

frontend/src/index.js

```
import React from 'react';  
import ReactDOM from 'react-dom/client';  
import './index.css';  
import App from './App';  
import reportWebVitals from './reportWebVitals';
```

```
const root = ReactDOM.createRoot(do
```

frontend/src/reportWebVitals.js

```
const reportWebVitals = onPerfEntry => {  
  if (onPerfEntry && onPerfEntry instanceof Function) {  
    import('web-vitals').then(({ getCLS, getFID, getFCP, getLCP, getTTFB }) => {  
      getCLS(onPerfEnt
```

Functions / Methods:

```
- if (onPerfEntry && onPerfEntry instanceof Function) {
```

frontend/src/services/apiService.js

```
const API_URL = "http://localhost:8000";  
const MOCK_MODE = true; // Uses mock data from websocketService
```

```
export const fetchSystemHealth = async () => {  
  if (MOCK_MODE) {  
    // --- MOCK MODE: Return
```

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Functions / Methods:

- if (MOCK_MODE) {
- if (!response.ok) {

frontend/src/services/websocketService.js

```
const MOCK_MODE = false;  
const WEBSOCKET_URL = "ws://localhost:3000/ws";
```

```
let socket = null;  
let mockInterval = null;
```

```
export const connectWebSocket = (onMessageCallback) => {  
  if (MOCK_MODE) {  
    c
```

Functions / Methods:

- if (MOCK_MODE) {
- if (MOCK_MODE) {

frontend/src/setupTests.js

jest-dom adds custom jest matchers for asserting on DOM nodes. allows you to do things like:

expect(element).toHaveTextContent(/react/i)

learn more: <https://github.com/testing-library/jest-dom>

Module/Top comments:

jest-dom adds custom jest matchers for asserting on DOM nodes.

allows you to do things like:

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rest_api.md

REST API Endpoints

Get System Health

Module/Top comments:

REST API Endpoints

Get System Health

websocket_api.md

Message for Live Pose Updates

Module/Top comments:

Message for Live Pose Updates

Design Diagrams

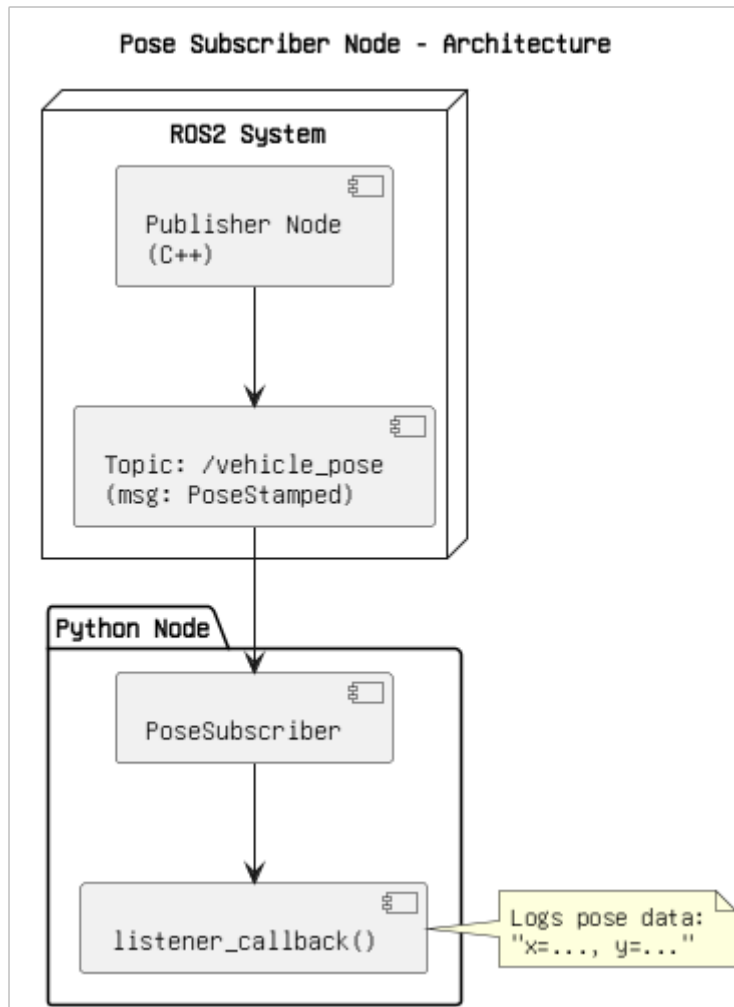


Figure 1. Architecture.png

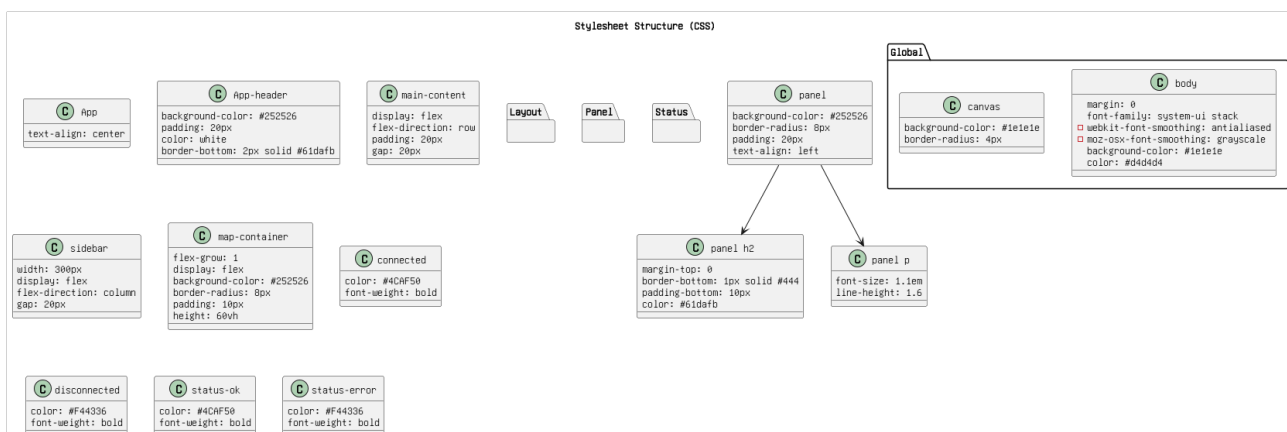


Figure 2. CSS.png

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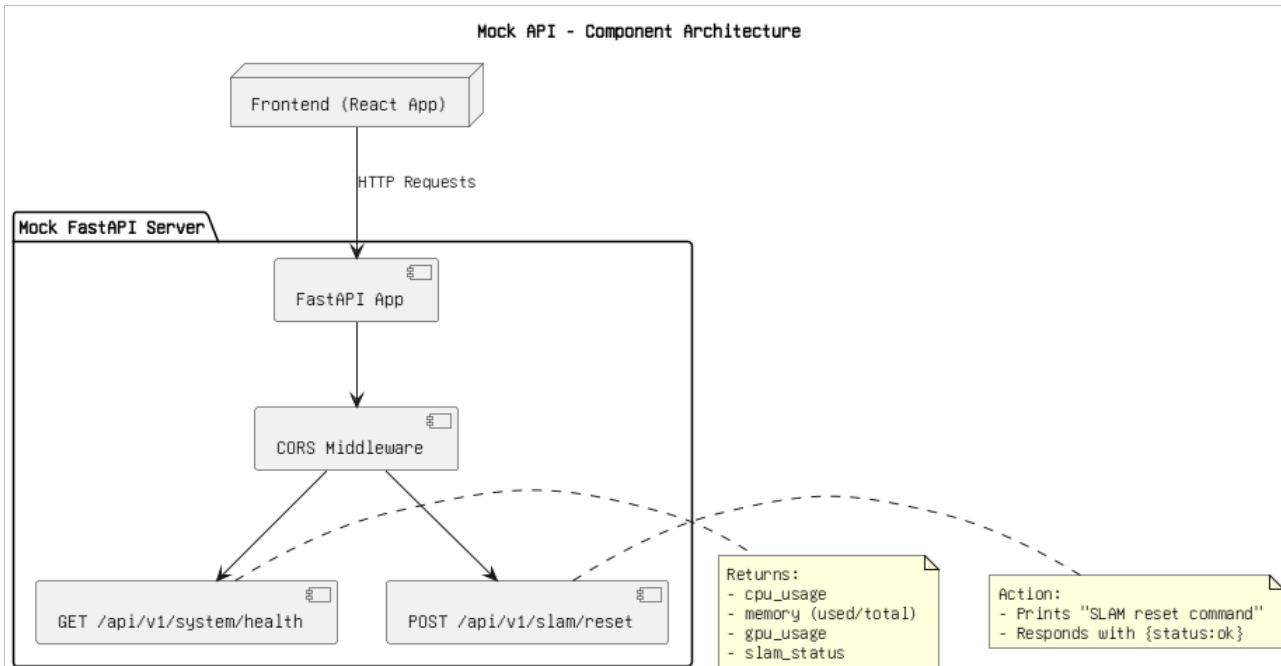


Figure: 3. Component architecture.png

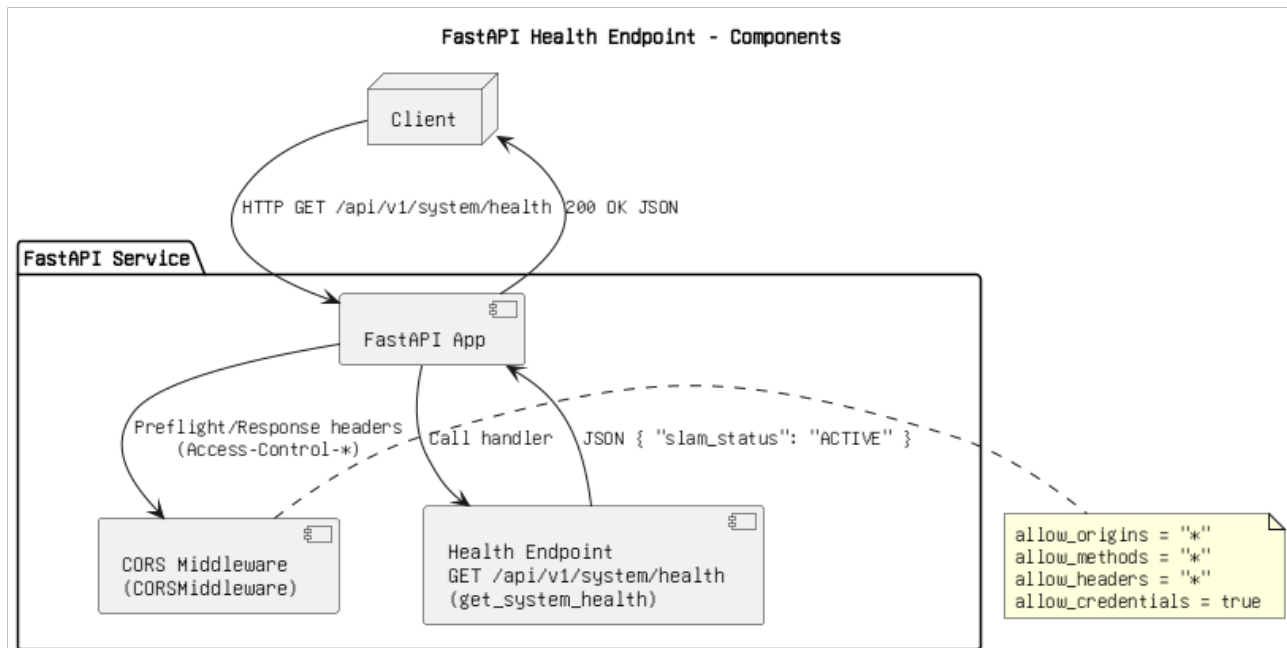


Figure: 4. Components.drawio.png

RT_SLAM_AVOC

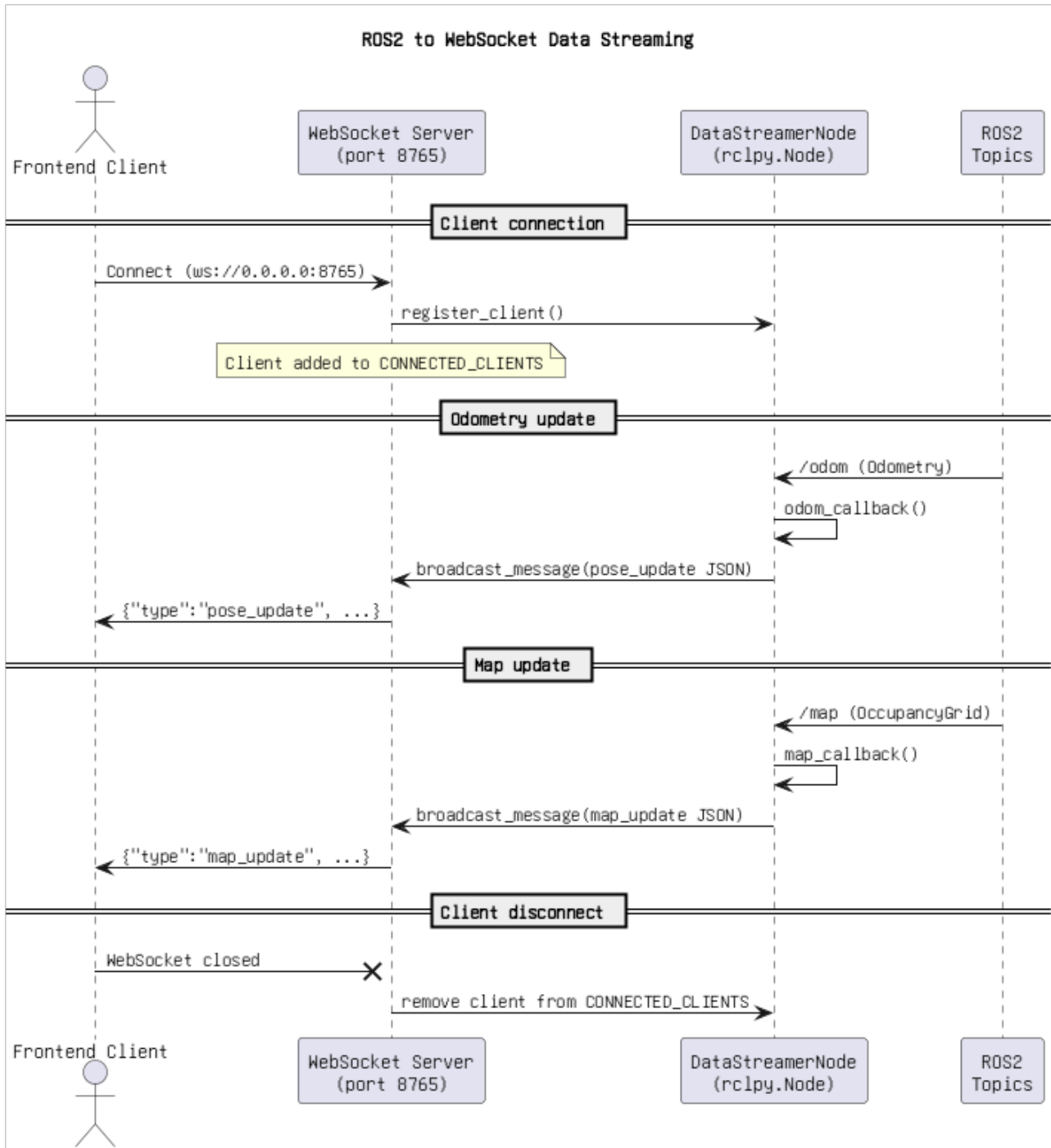


Figure: 5. Data Streaming.png

RT_SLAM_AVOC

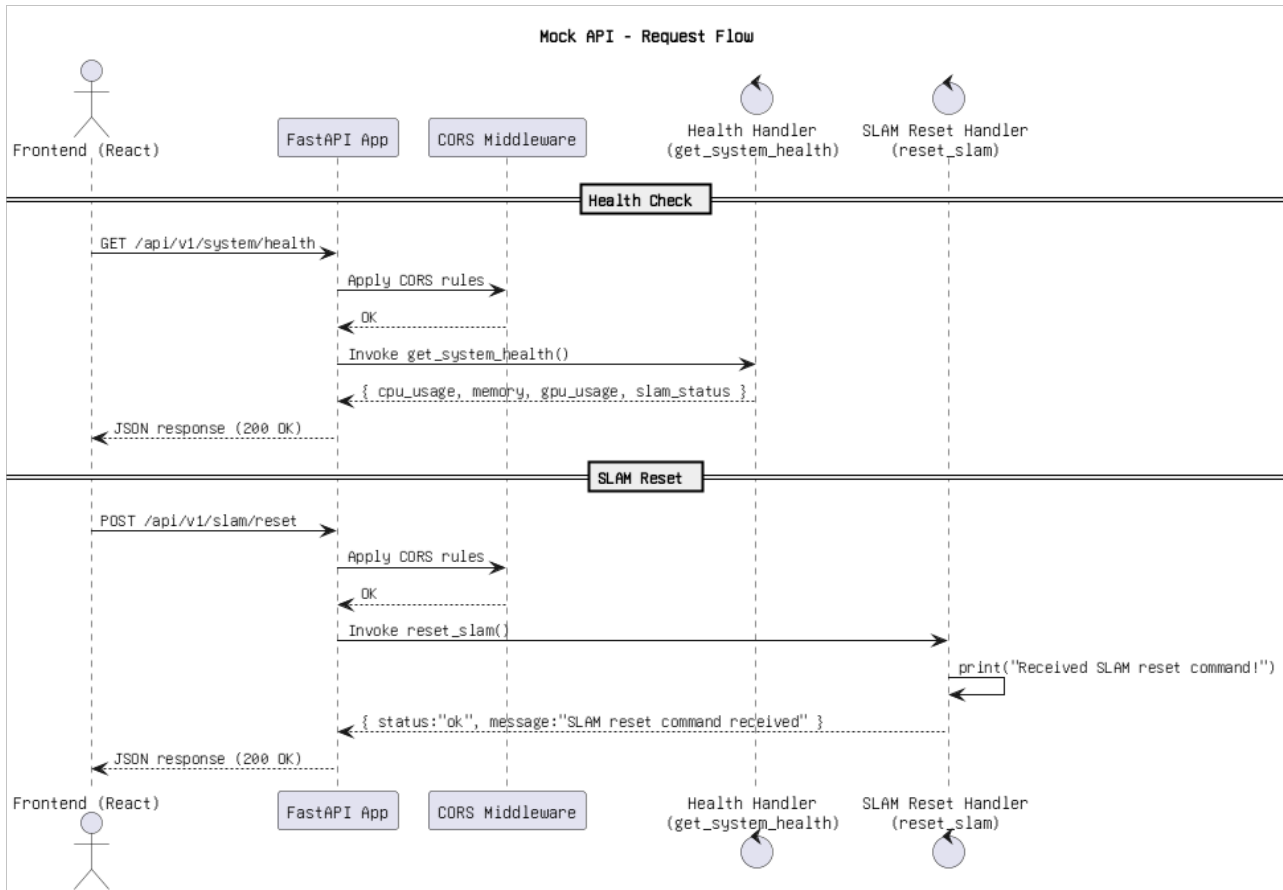


Figure: 6. Mock api request flow.png

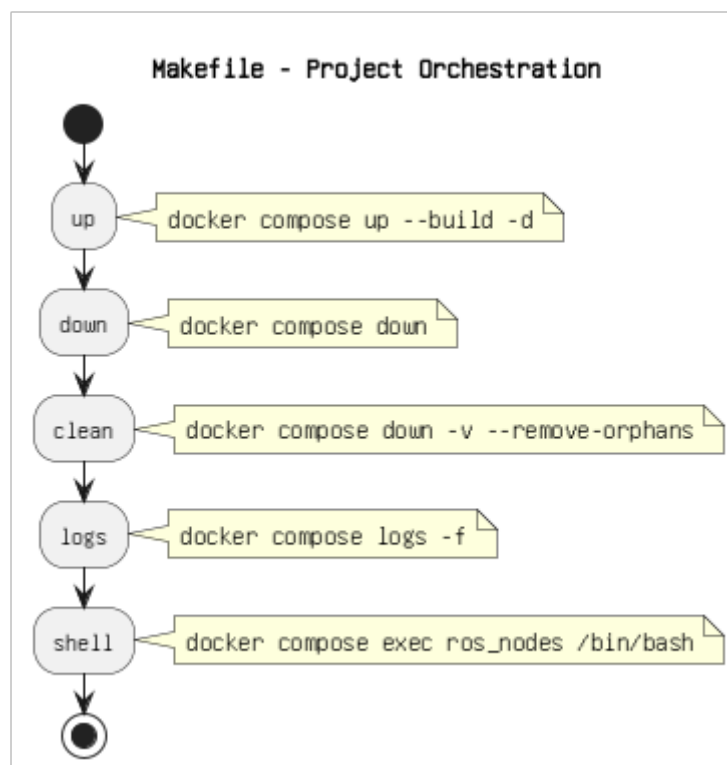


Figure: 7. Project Orchestration.png

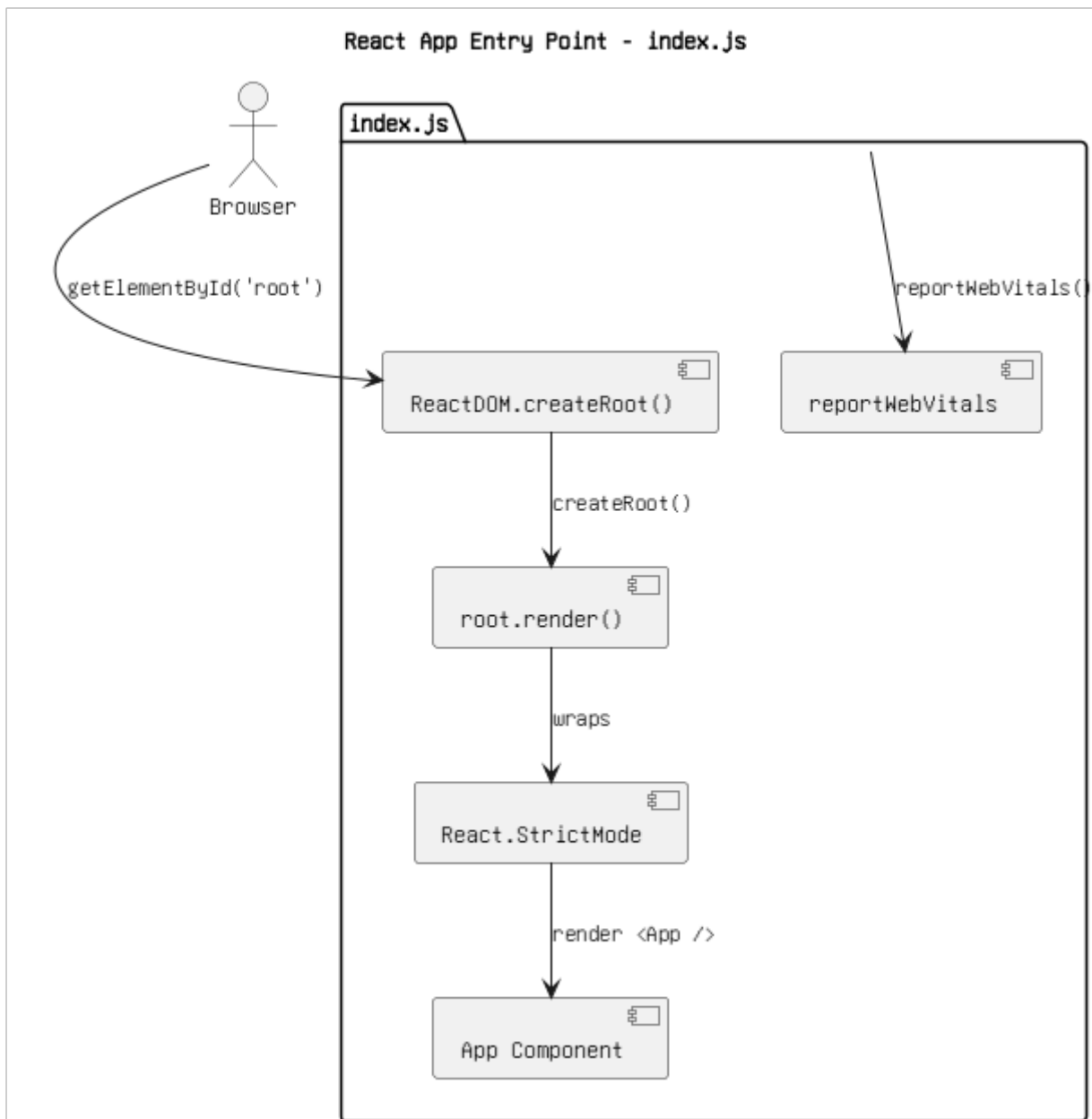


Figure: 8. React App Entry Point - index.js.png

RT_SLAM_AVOC

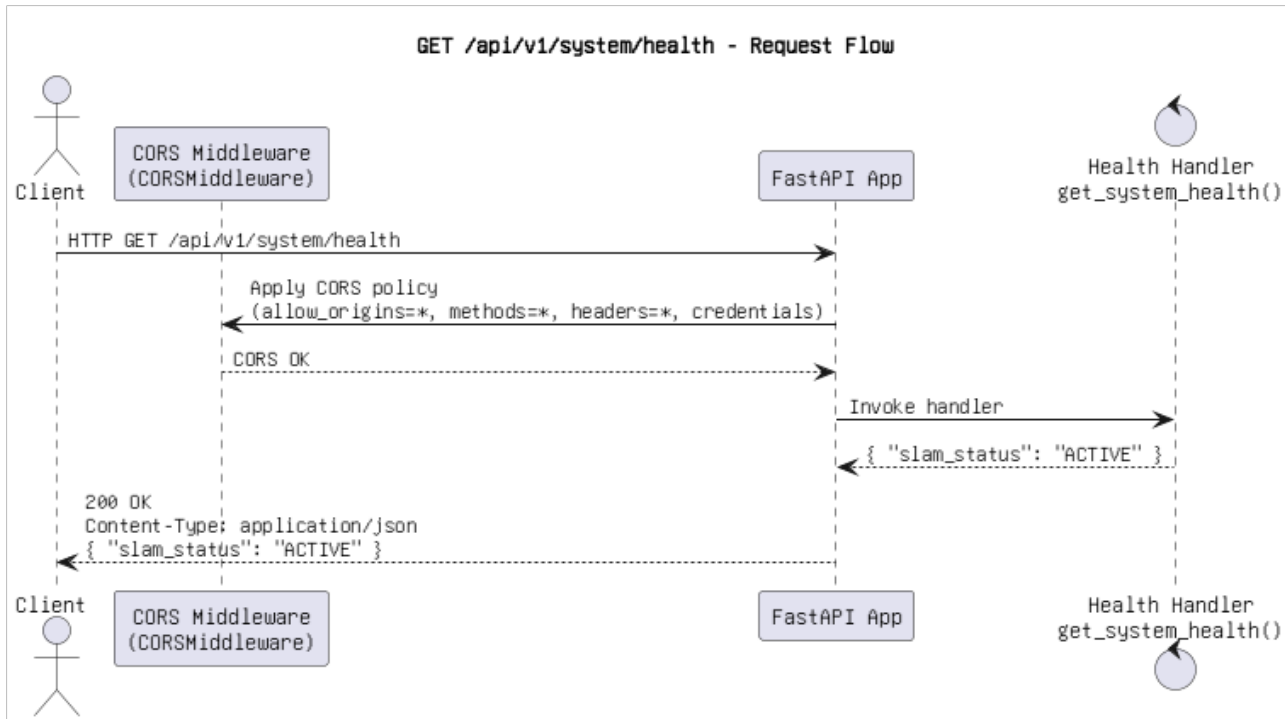


Figure: 9. Request flow .drawio.png

RT_SLAM_AVOC

Docker Compose - SLAM System Architecture

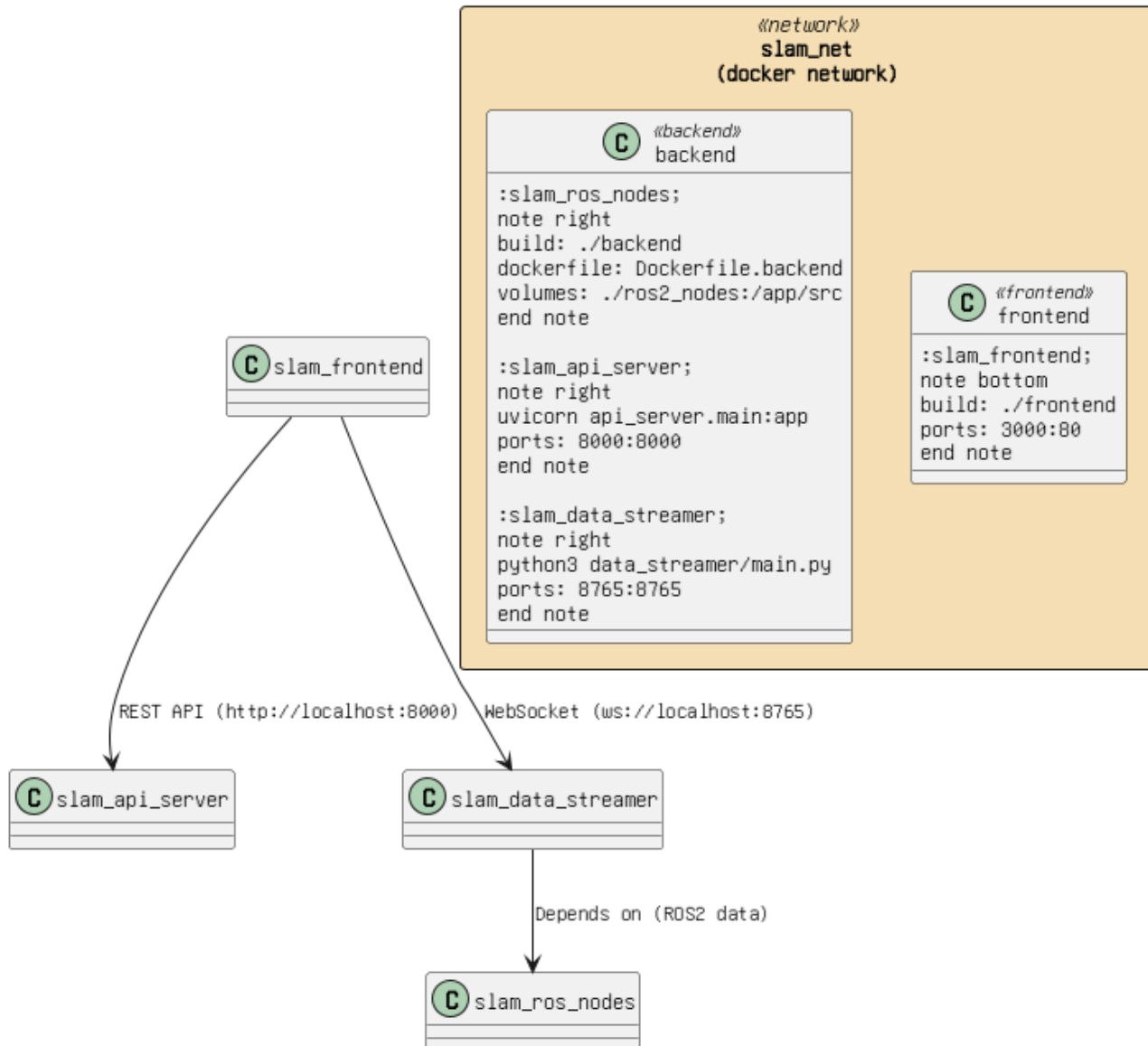


Figure: 10. SLAM System Architecture.png

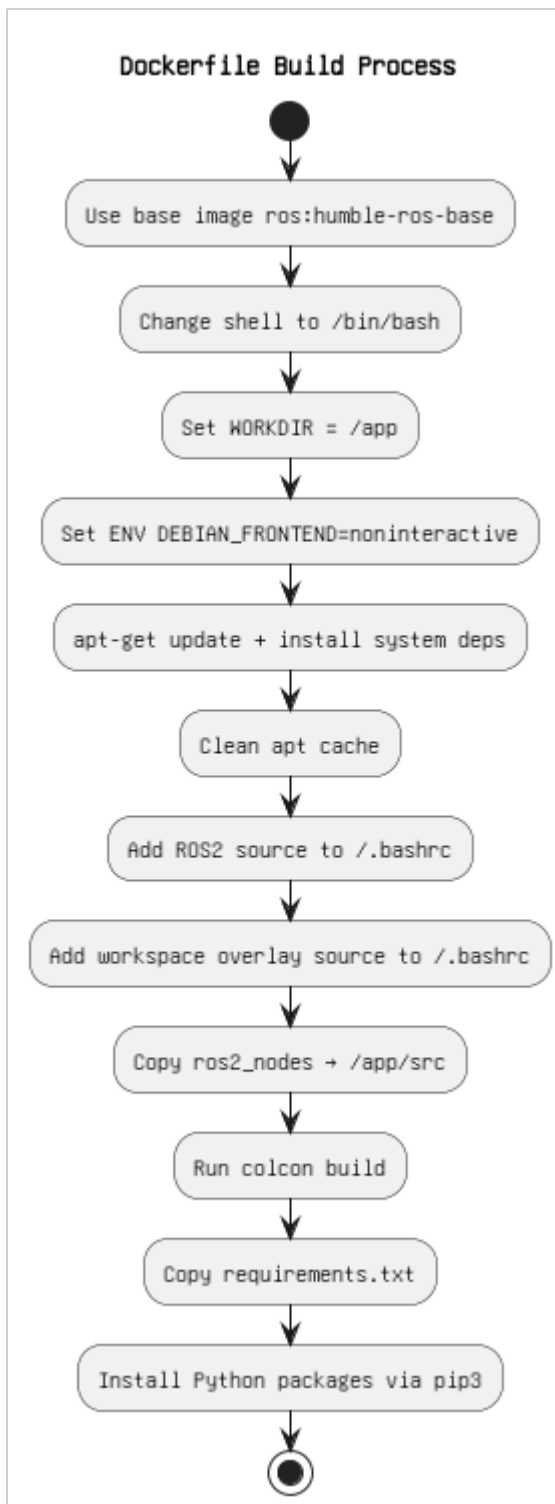


Figure: 11. build process flow.png

ROS2 Docker Image - Deployment

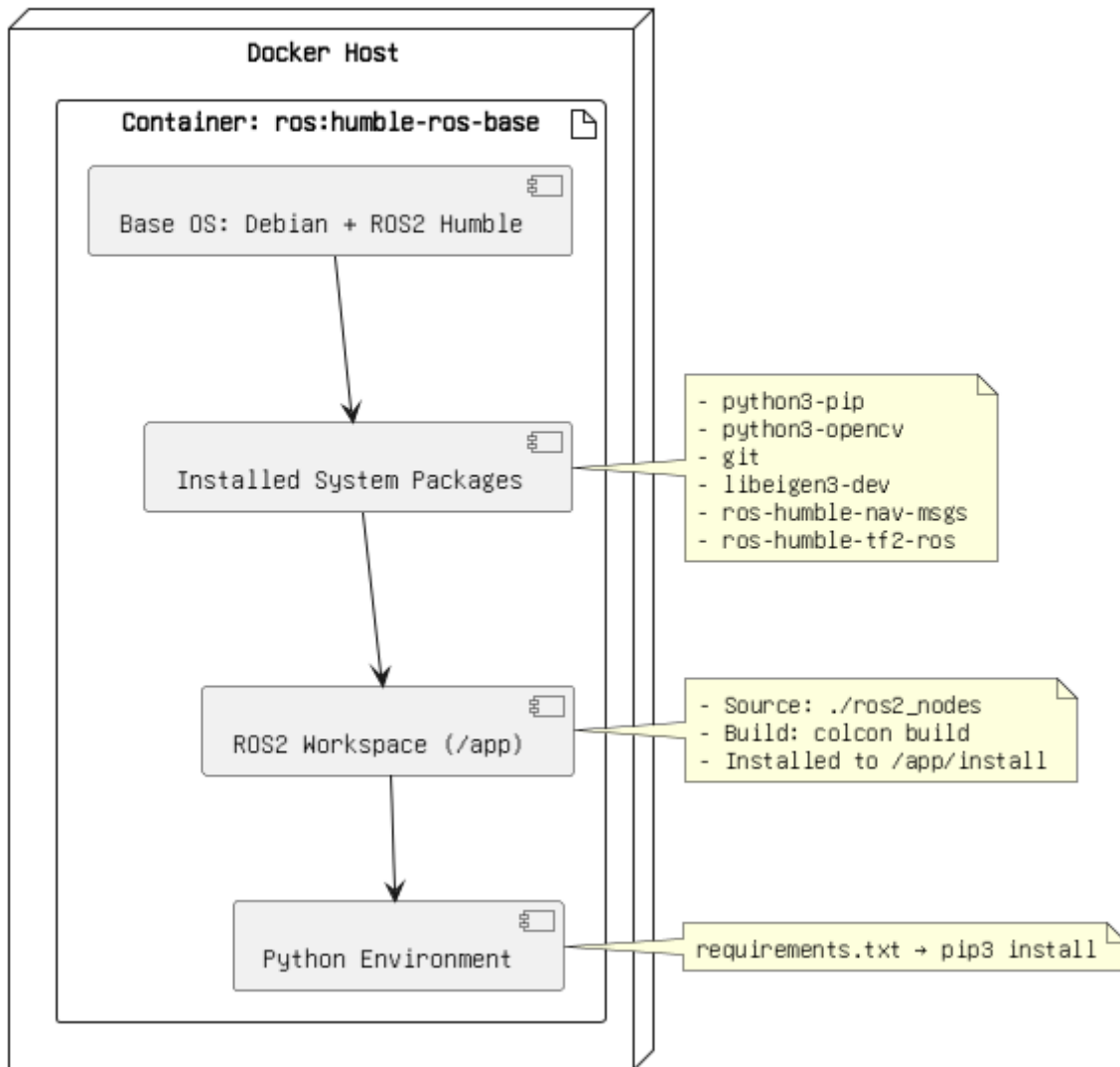


Figure: 12. container setup.png

RT_SLAM_AVOC

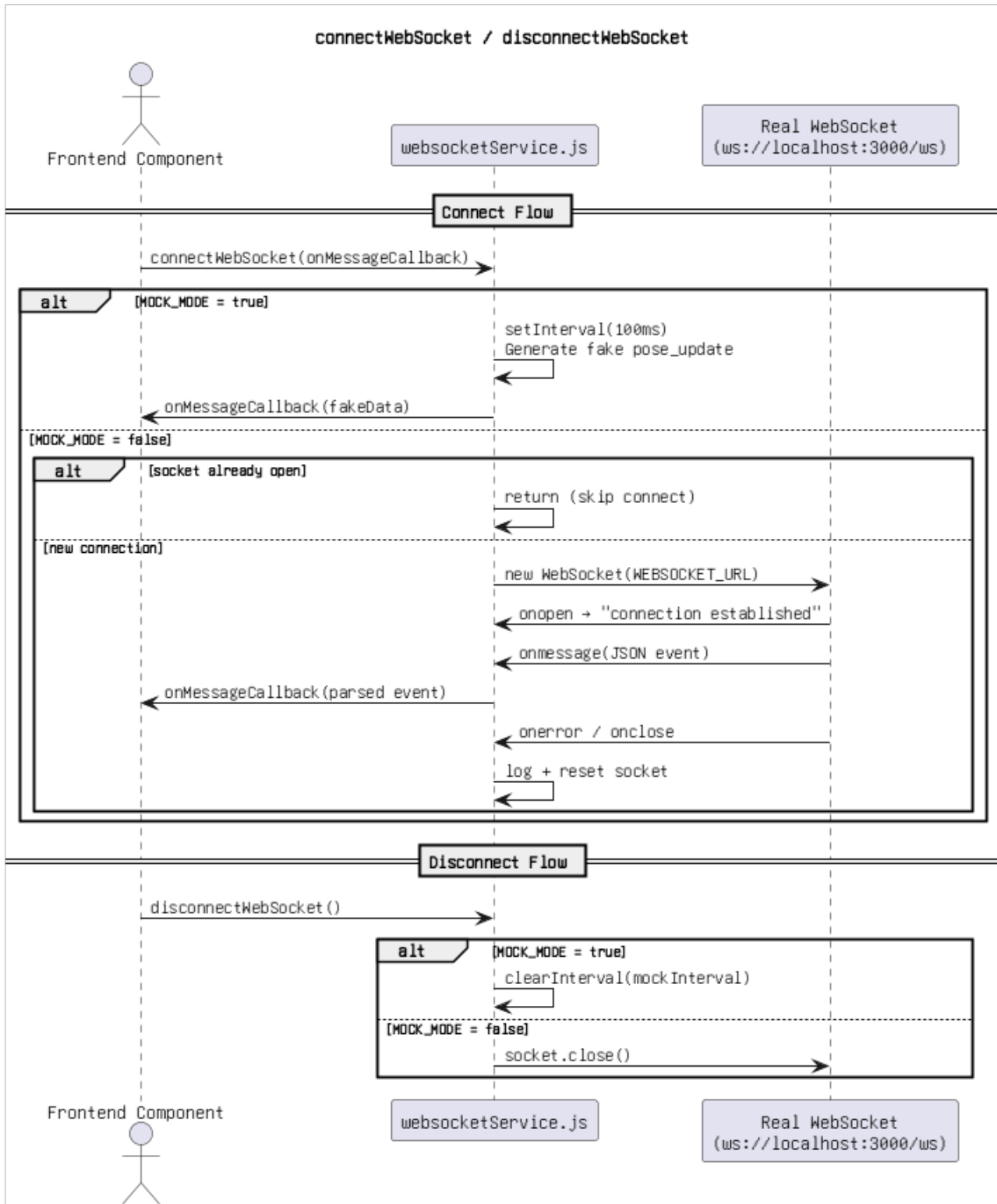


Figure: 13. disconnect websocket.png

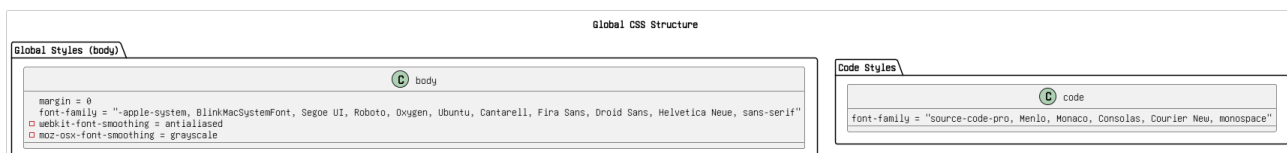


Figure: 14. global css structure.png

RT_SLAM_AVOC

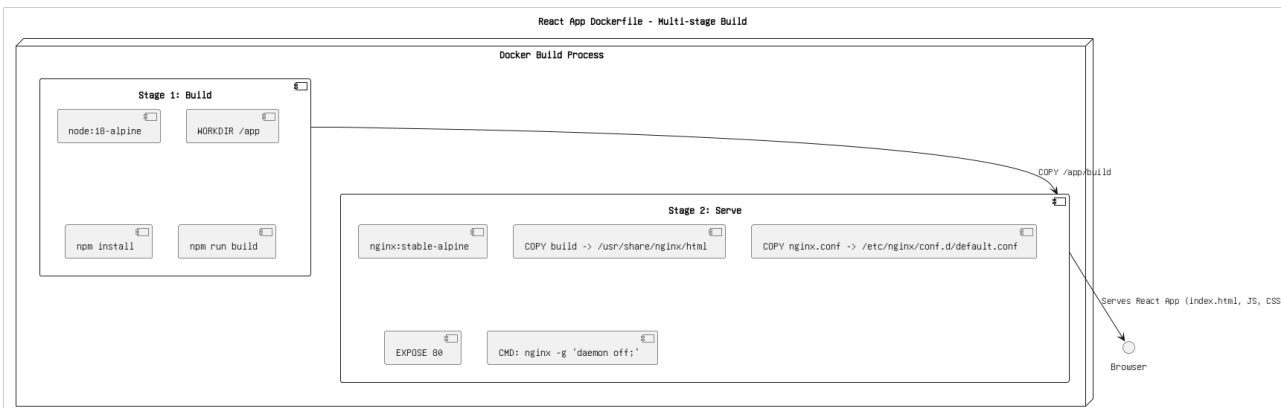


Figure: 15. multi stage build.png

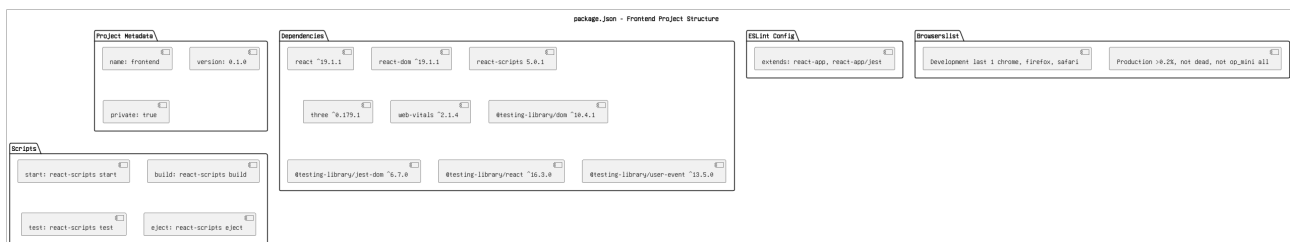


Figure: 16. package.json.png

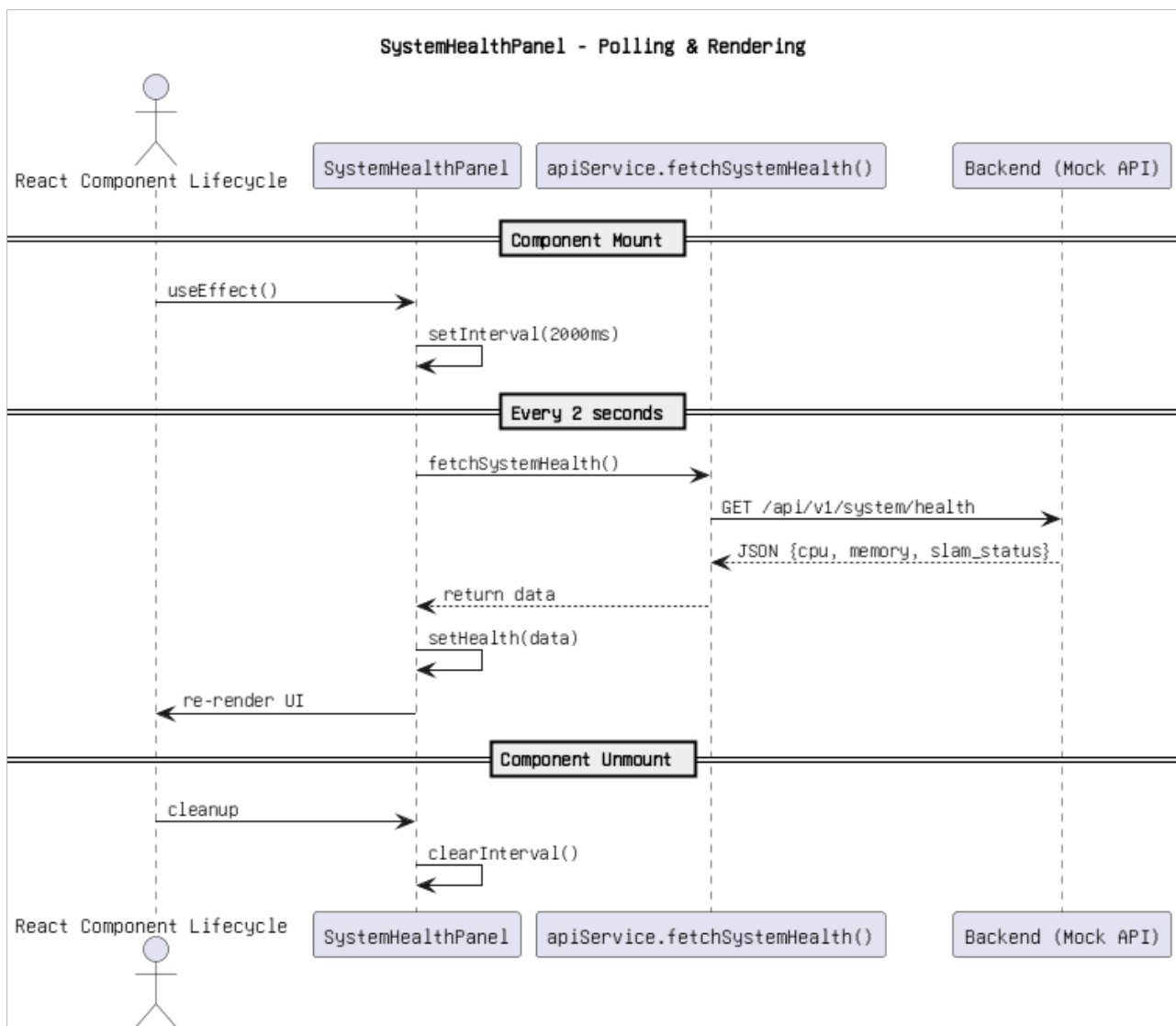


Figure: 17. polling & rendering.png

RT_SLAM_AVOC

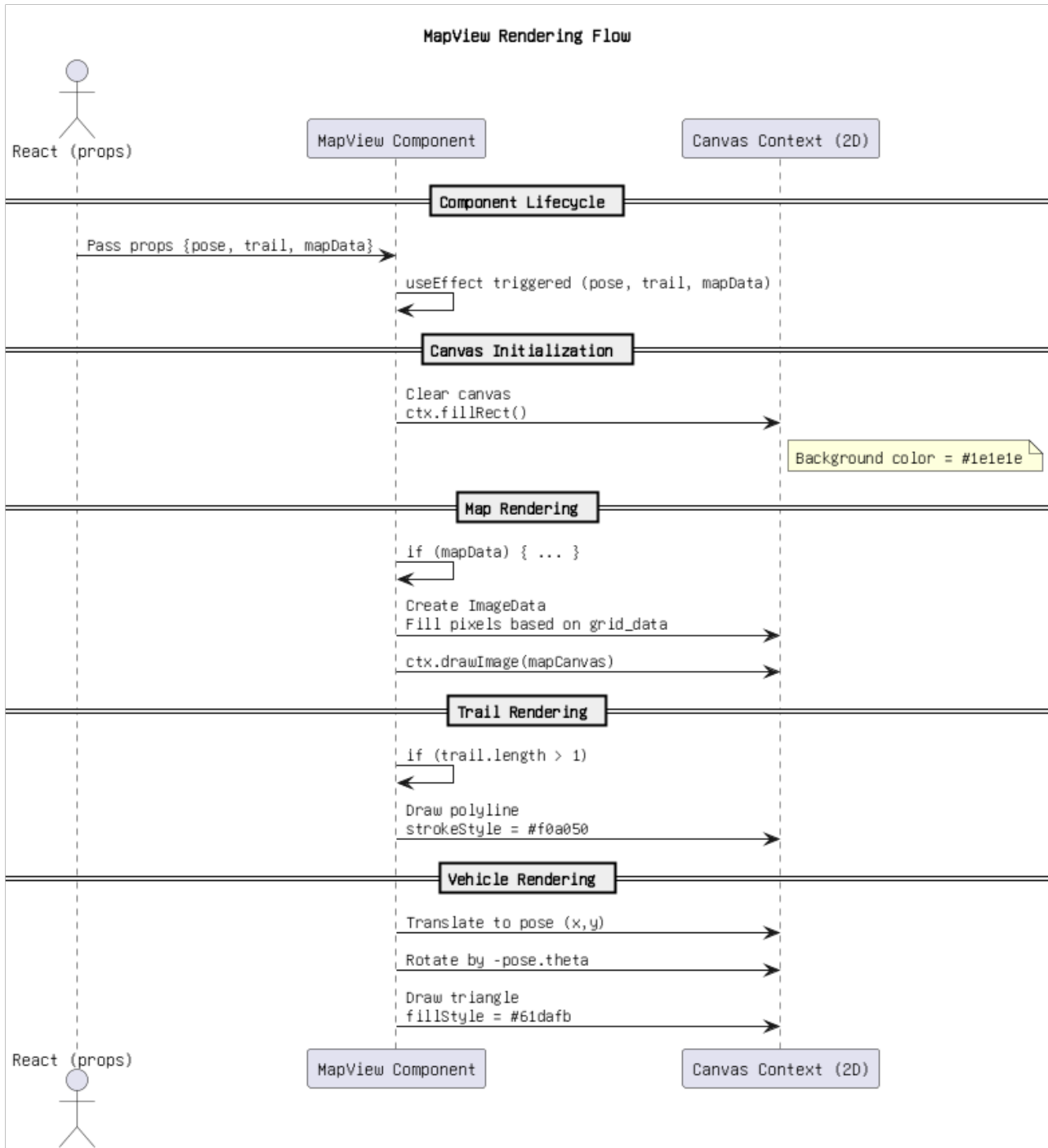


Figure: 18. rendering flow.png

RT_SLAM_AVOC

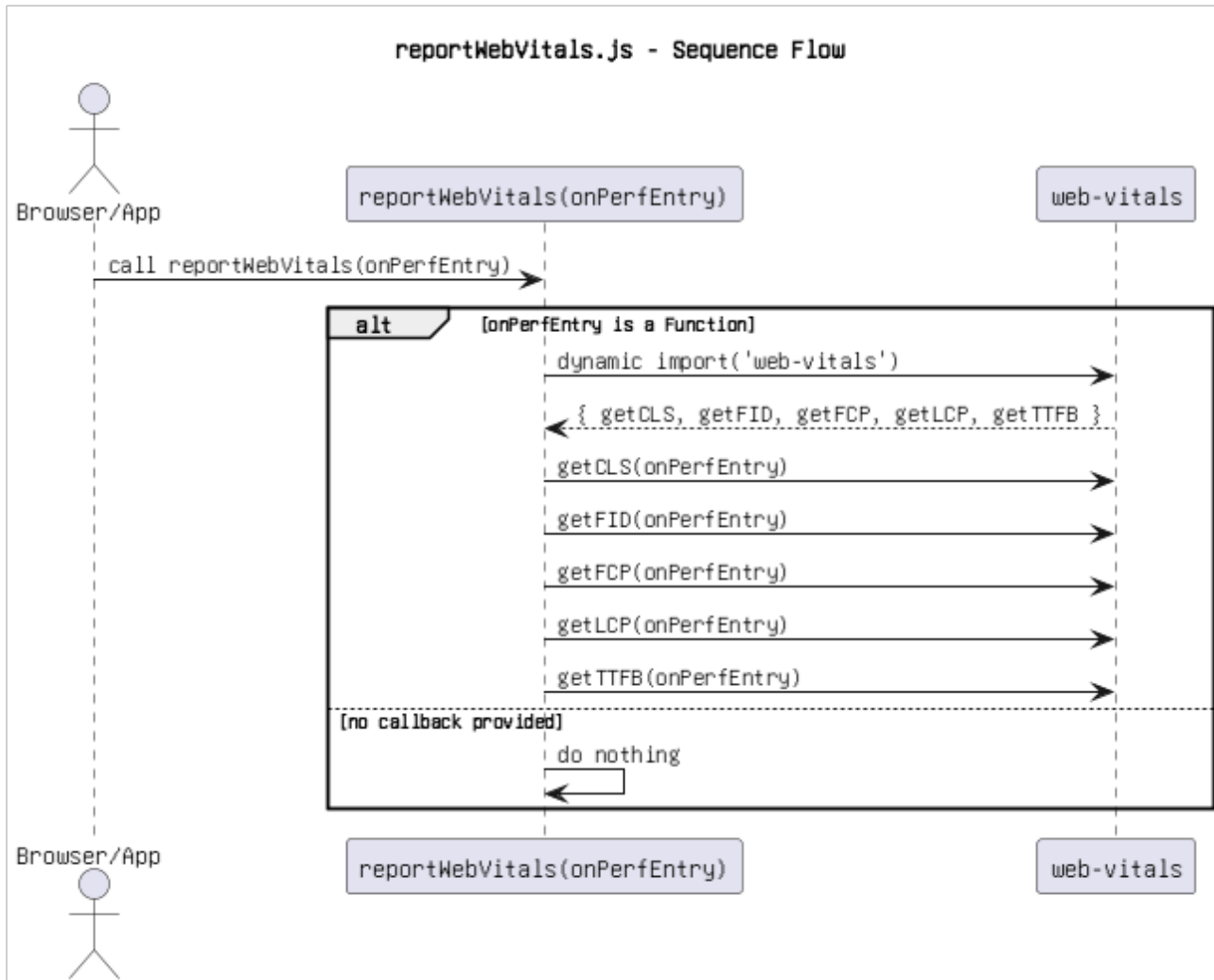
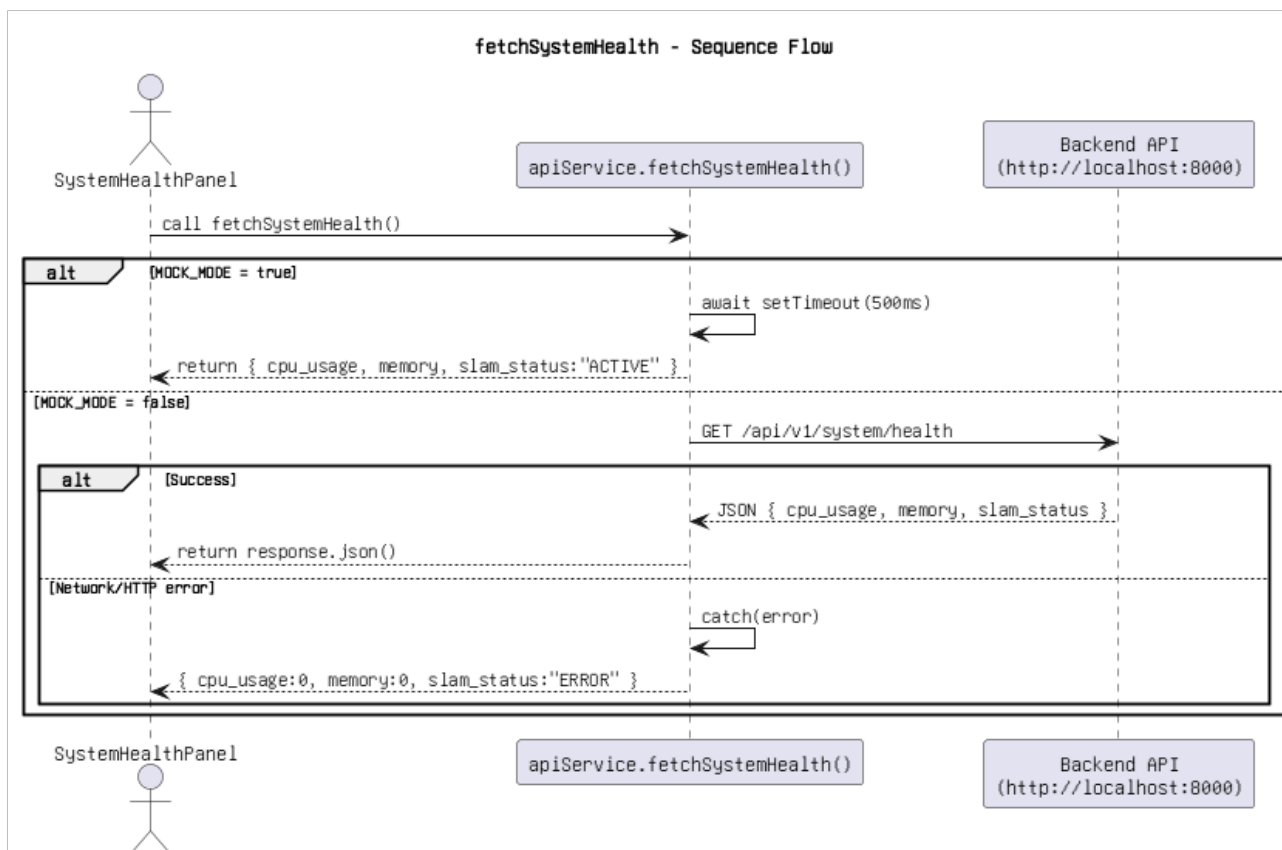


Figure: 19. reportWebVitals.js - Sequence Flow.png



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Figure 20. sequence flow.png

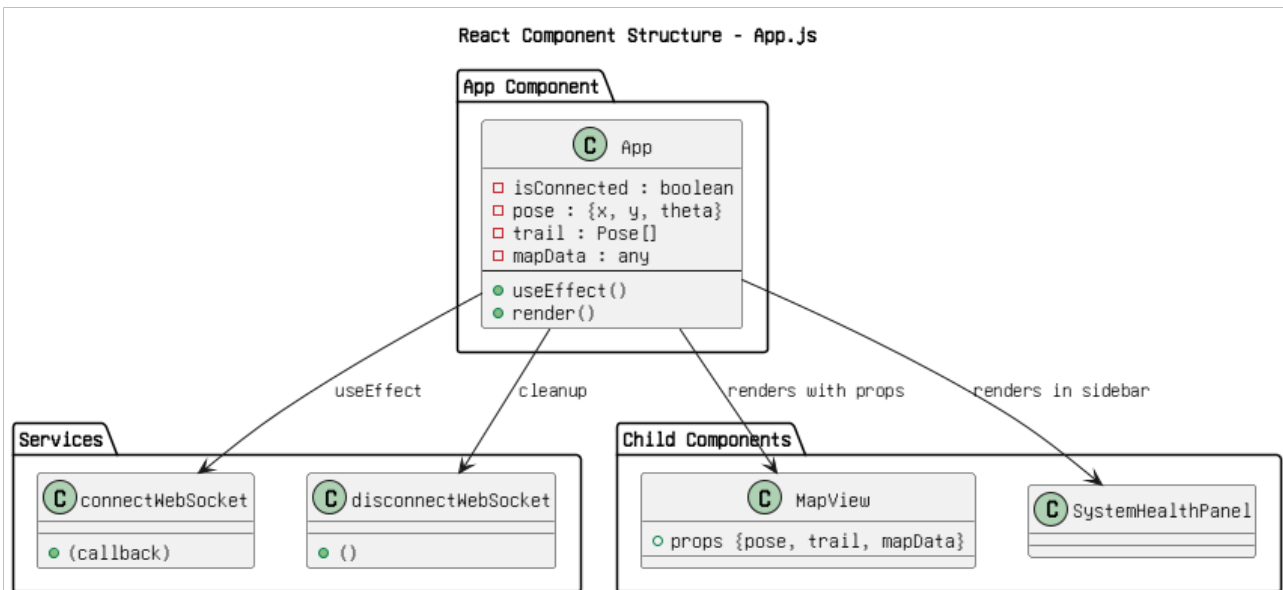


Figure 21. structure app.js.png

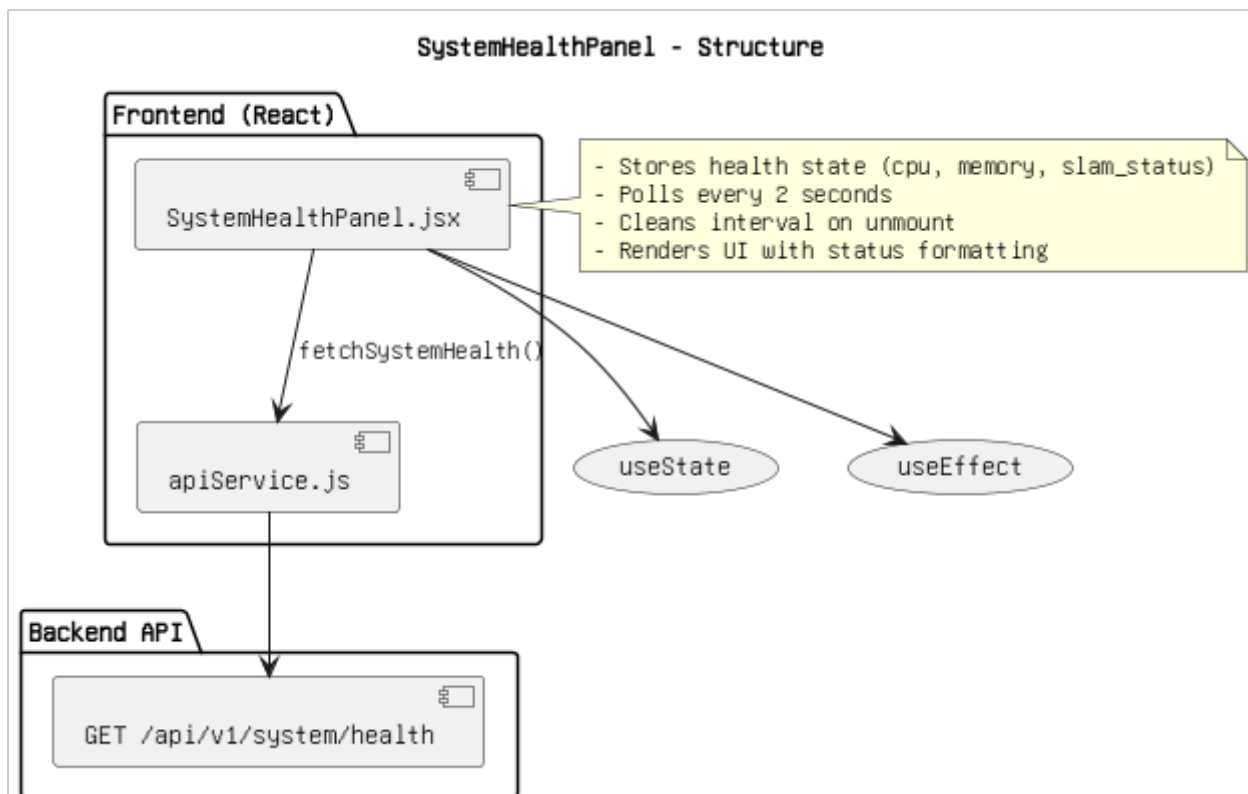


Figure 22. structure(1).png

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apiService.js - Structure

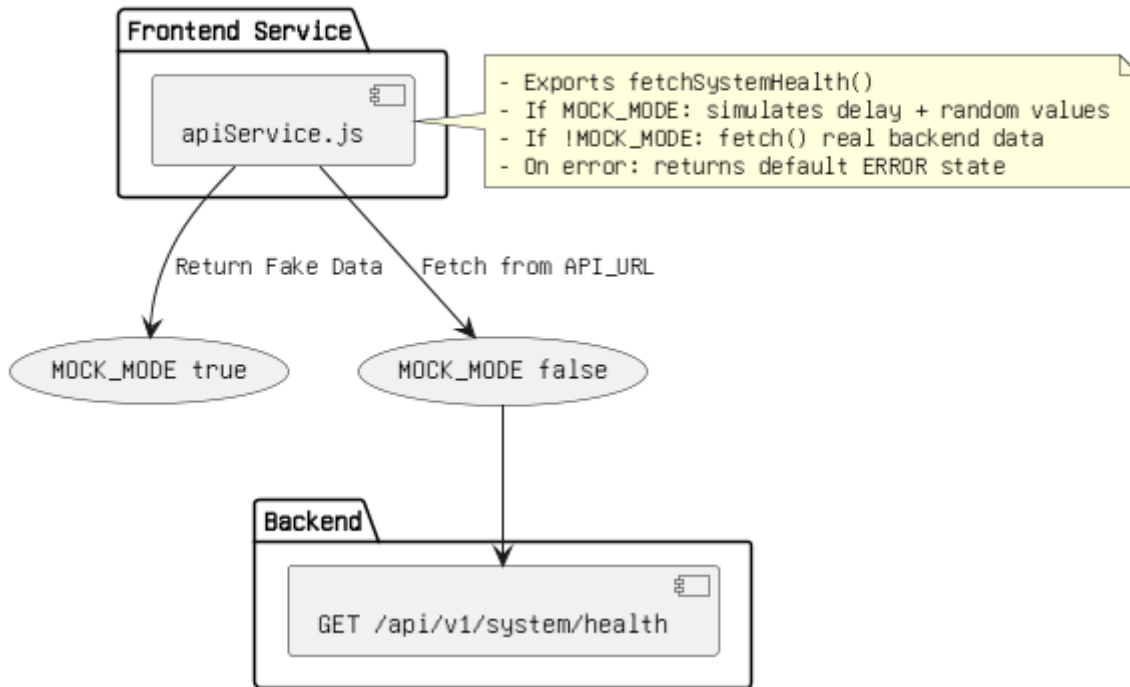


Figure: 23. structure(2).png

websocketService.js - Structure

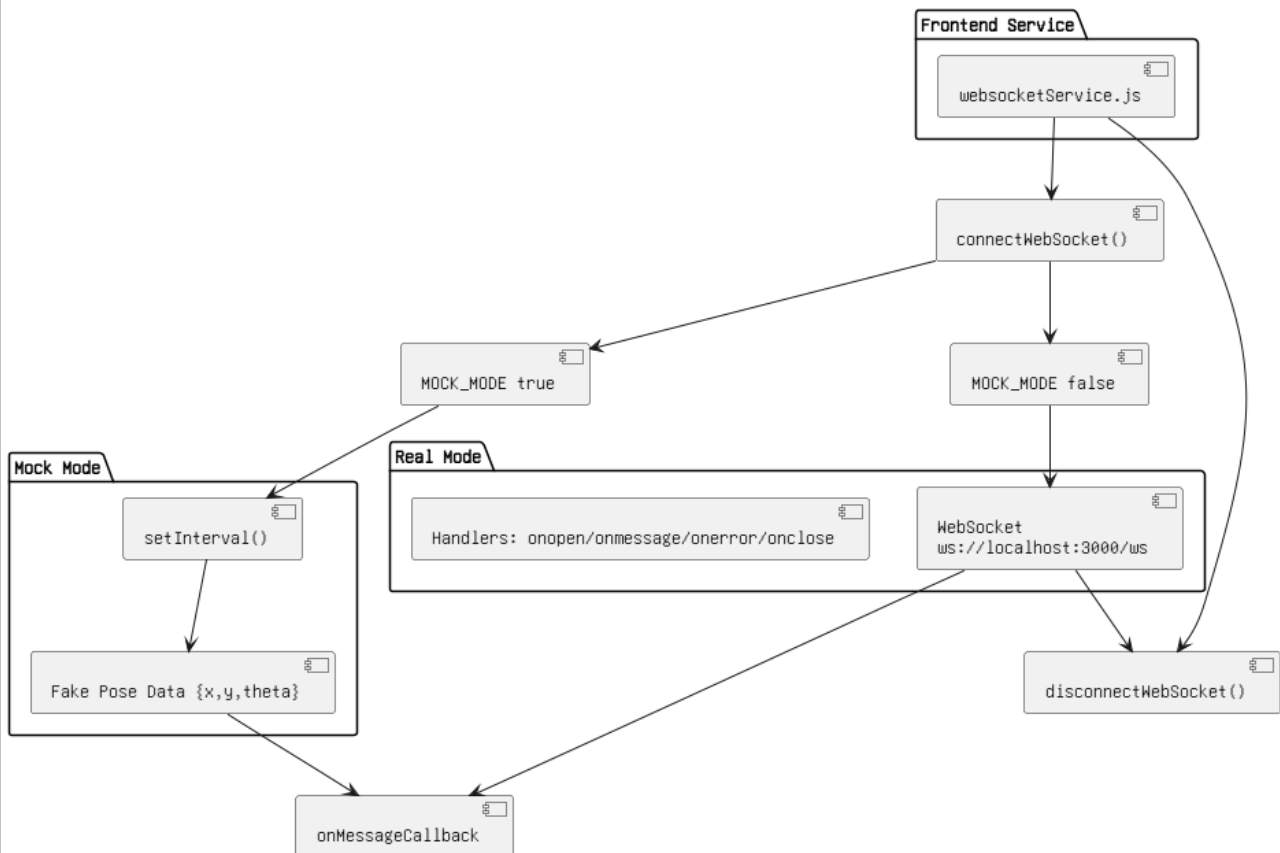


Figure: 24. structure(3).png

RT_SLAM_AVOC

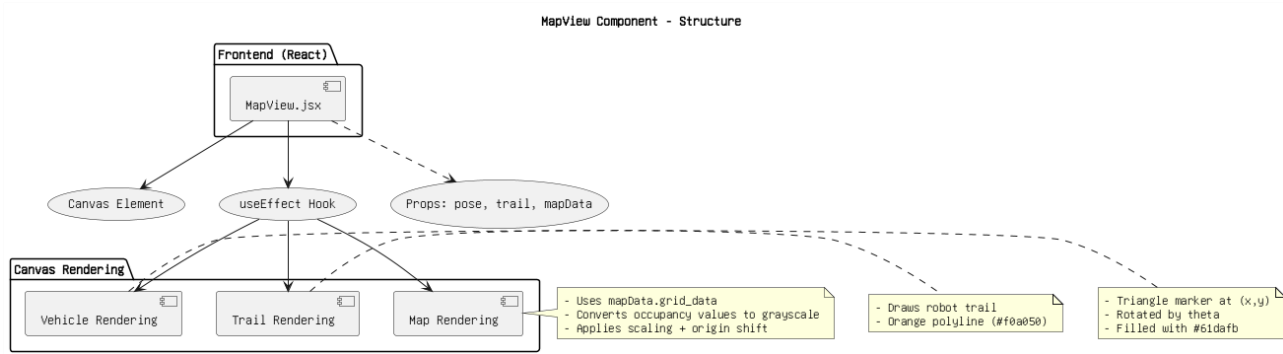


Figure: 25. structure.png

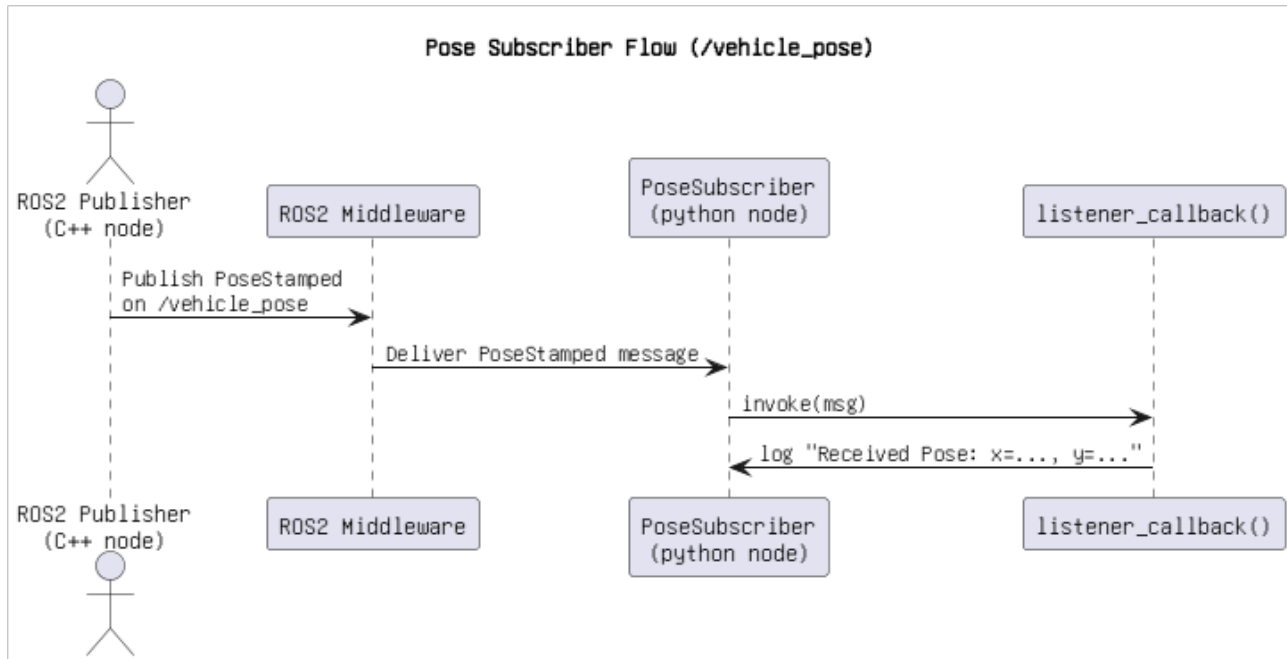


Figure: 26. vehicle_pose.png