Mathematical Language and Game Theory

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Abstract

This note complements Game Theory: Analysis of Strategic Thinking, explaining in a concise and systematic way its mathematical notation. The reader should try to prove all the claims, remarks etc. that are reported here without proof.

1 Sets, functions, and correspondences

The building blocks of the language used to describe games are sets, functions, correspondences, and mathematical structures, that is, lists of sets, functions, and (possibly) correspondences. Here we take for granted that the meaning of "set," "function," "correspondence," and "Cartesian product of sets" is understood. We also take for granted that standard set-theoretic notation is understood. Despite this, it is worth clarifying how we use arrows to denote functions, or correspondences.

Functions A function (or map) f from domain X to codomain Y is denoted by $f: X \to Y$. When we want to specify that an element x of X is associated with an element of Y according to a particular formula expressed by function f we use the \mapsto ("mapsto") arrow and write

$$x \mapsto f(x)$$
.

The **image**, or **range** of f is the set

$$f(X) := \{ y \in Y : \exists x \in X, f(x) = y \}.$$

Example 1 For example, if $f : \mathbb{R} \to \mathbb{R}$ is the "square of" function that associates each real number with its square, we write

$$f: \mathbb{R} \to \mathbb{R}$$

$$x \mapsto x^2,$$

where x^2 is the formula expressing the "square of" function. The range of the "square of" function f is $f(\mathbb{R}) = \mathbb{R}_+$.

It is sometimes useful to stack the two representations one below the other to clarify every feature of the given function. In Example 1, $f: \mathbb{R} \to \mathbb{R}$ gives us the domain (\mathbb{R}) , codomain (\mathbb{R}) , and the label (f) that we use to denote the "square of' function, whereas $x \mapsto x^2$ tells us that we associate each real number x with its square. When we are concerned with an abstract analysis of all functions in a given class, we use the general notation $f: X \to Y$. For example, for any real-valued function $f: X \to \mathbb{R}$, we can define $\sup_{x \in X} f(x) := \sup f(X)$ (least upper bound of f(X)) and $\inf_{x \in X} f(x) := \inf f(X)$ (greatest lower bound of f(X)). For every real-valued and continuous function defined on a compact subset X of a topological space, both $\max_{x \in X} f(x) := \max f(X)$ and $\min_{x \in X} f(x) := \min f(X)$ are well defined.

Correspondences A **correspondence** F that associates each element of domain X with a subset of codomain Y is written $F: X \rightrightarrows Y$, where the multiple arrow \rightrightarrows is meant to remind the reader that the image F(x) of x may contain more than one element. However, when we specify the set associated with a particular element of the domain, we still use the \mapsto arrow.

Example 2 If $F : \mathbb{R}^2 \rightrightarrows \mathbb{R}$ is the correspondence that associates each pair of real numbers (a,b) with the closed interval between a and b, we write

$$\begin{array}{cccc} F: & \mathbb{R}^2 & \rightrightarrows & \mathbb{R} \\ & (a,b) & \mapsto & \{x \in \mathbb{R}: a \leq x \leq b\} \end{array}.$$

It is convenient to allow F(x) to be the *empty set*. For example, the "argmax" correspondence may be empty-valued.

¹If f(X) is not bounded above (respectively, below), then $\sup f(X) = +\infty$ (respectively, $\inf f(X) = -\infty$).

²Such as a closed and bounded subsets of a \mathbb{R}^n , or—more generally—a compact subset of a metric space.

Example 3 Fix a real-valued function $u: X \to \mathbb{R}$ and a subset $C \subseteq X$ of its domain. With this,

$$\arg\max_{x\in C}u\left(x\right):=\left\{ x^{*}\in C:\forall x\in C,u\left(x^{*}\right)\geq u\left(x\right)\right\}$$

is the—possibly empty—set of maximizers of u on the "constraint set" C. Let correspondence

$$B: P \Rightarrow X$$

denote a parameterization of the constraint.³ Then,

$$\begin{array}{cccc} F: & P & \rightrightarrows & X \\ & p & \mapsto & \arg\max_{x \in B(p)} u\left(x\right) \end{array}$$

may be empty-valued if, for example, u is not continuous, or B(p) is not compact for some $p \in P$.

Index sets as domains Finally, many examples of functions and correspondences will be defined on a domain X = I that we interpret as an **index** set, such as the set of all **individuals** in a given group. Note that we do not make any general assumption that I be an ordered set, although it may be an ordered set in some special cases. Prominent examples of such functions in game theory are the **profiles** of actions (or strategies) that associate each player $i \in I$ with an action (or strategy) of i.

1.1 Set of functions (Cartesian products)

Cartesian products are important examples of sets, which can be interpreted as sets of functions.

Sets of profiles Specifically, consider an index set I, a "universal" set⁴ \bar{A} of "alternatives," and a correspondence $i \mapsto A_i$ that associates each element i of I with a nonempty subset $A_i \subseteq \bar{A}$. We interpret the **Cartesian product** $\times_{i \in I} A_i$ as the set of **selections** from the correspondence $i \mapsto A_i$, that is, the set of functions

$$a: I \to \bar{A}$$
$$i \mapsto a_i$$

 $^{^{3}}B$ could be the budget correspondence associating each price vector p with the set of affordable consumption bundles given some endowment ω .

⁴We are using the term "universal" informally to mean that the set contains all the objects that we may want to consider in a given problem.

such that

$$\forall i \in I, a_i \in A_i.$$

We often write such functions as follows:

$$a = (a_i)_{i \in I} .$$

When I is interpreted as a set of individuals, functions with domain I are called "profiles."

Sequences The set of all functions with domain I and codomain \bar{A} is denoted A^{I} . When I is finite, there are at least |I|! bijections between the set of functions \bar{A}^I and the set of ordered |I|-tuples $\bar{A}^{|I|}$, one for each strict order (or permutation) on I.⁵ Indeed, when $I = \{1, ..., n\}$, then \bar{A}^I and $\bar{A}^{|I|} = \bar{A}^n$ are essentially the same mathematical object under the canonical bijection

$$(a_i)_{i\in I} \leftrightarrow (a_1,...,a_n)$$
,

which preserves the order of natural numbers, that is, the set of ordered ntuples (finite sequences of length n) of elements of A. For example, vectors of real numbers are a special case where $I = \{1, ..., n\}$ and $\bar{A} = \mathbb{R}$. Then, the relevant Cartesian product is $\mathbb{R}^{\{1,\ldots,n\}}$, or equivalently \mathbb{R}^n . (Sometimes the set of the first n natural numbers is written $[n] := \{1, ..., n\}$; thus, $\mathbb{R}^{\{1,\dots,n\}} = \mathbb{R}^{[n]}$.) Another important example is the set of all countable **sequences** of elements of \bar{A} , such as the set $\mathbb{R}^{\mathbb{N}}$ of all sequences of real numbers when $\bar{A} = \mathbb{R}$. Such sequences are equivalently denoted by $(a_n)_{n \in \mathbb{N}}$ or $(a_n)_{n=1}^{\infty}$.6

Cardinalities The following observation further explains why the "power notation" for sets of functions is explicative and convenient.

Remark 1 If both the index set (domain) I and the set of alternatives (codomain) \bar{A} are finite, then the number of functions from I to \bar{A} (i.e., the cardinality of \bar{A}^I) is

$$\left|\bar{A}^I\right| = \left|\bar{A}\right|^{|I|}.$$

 $[\]left|\bar{A}^I\right|=\left|\bar{A}\right|^{|I|}.$ 5 |·| denotes the cardinality of a set. Thus, |I| is the number of elements of the finite

⁶It is common in the mathematical literature to write sequences as follows: $\{a_n\}_{n=1}^{\infty}$. Such use of brackets is inconsistent with the standard notation about sets and may induce the reader to confuse a sequence with its range. For example, it is not clear whether $\{(-1)^n\}_{n=1}^{\infty}$ denotes the sequence (1,-1,1,-1,...), or its range, which is the doubleton $\{-1,1\}$. Such confusing notation is just a bad habit. Like all habits, also the bad ones die hard. But this is no reason to knowingly indulge in bad habits.

Cartesian products and products of numbers are related in a similar way.

Remark 2 The number of selections from the correspondence $i \mapsto A_i$, that is, the number of elements of the Cartesian product $\times_{i \in I} A_i$, is given by the product formula

$$|\times_{i\in I} A_i| = \prod_{i\in I} |A_i|.$$

In words, the cardinality of a Cartesian product of sets is the product of the cardinalities of such sets.

Power sets Another convenient "power notation" is used to denote the collection of all subsets of I, including the empty set \emptyset and I itself, that is, the **power set** 2^{I} .

Remark 3 If I is finite,

$$\left|2^{I}\right|=2^{\left|I\right|}.$$

Indicator functions The natural number $2^{|I|}$ (with I finite) is also the cardinality of the set of functions from I to a binary codomain. In particular, let $\bar{A} = \{0, 1\}$, and recall that the **indicator function 1**_J : $I \to \{0, 1\}$ of a subset $J \subseteq I$ is

$$\mathbf{1}_{J}(i) = \left\{ \begin{array}{ll} 1 & \text{if } i \in J \\ 0 & \text{if } i \in I \backslash J \end{array} \right..$$

With this, $\bar{A}^I = \{0,1\}^I$ can be interpreted as the set of all indicator functions of subsets of I. Specifically, for each $J \subseteq I$, $a = \mathbf{1}_J$ if and only if $a^{-1}(1) = J$.

1.2 Sections and projections

Fix a (nonempty-valued) correspondence $i \mapsto A_i \subseteq \bar{A}$, the corresponding Cartesian product $A = \times_{i \in I} A_i$ and a strict subset $J \subset I$ of the index set. To ease notation, let $A_J = \times_{j \in J} A_j$ denote the "sub-product" over the index subset J, with typical element a_J . When $J = I \setminus \{i\}$ for some $i \in I$, we further simplify and write A_{-i} , with typical element a_{-i} . For all sub-functions (profiles) $a_J = (a_j)_{j \in J} \in A_J$ and $a_{I \setminus J} = (a_k)_{k \in I \setminus J} \in A_{I \setminus J}$, we obtain a function (profile) $i \mapsto a_i$ denoted by $(a_J, a_{I \setminus J})$, where a_i is determined by a_J if $i \in J$, and by $a_{I \setminus J}$ if $i \in I \setminus J$. Since $A = \times_{i \in I} A_i$ is the set of functions from I to \bar{A} such that $a_i \in A_i$ for each i, it is clear that $(a_J, a_{I \setminus J}) \in A$, because $(a_J, a_{I \setminus J})$ is one such function.

⁷Do not be distracted by the fact that a_J is written before $a_{I\setminus J}$. This is irrelevant, because we are not assuming any order on I, hence the order in which symbols are written

Sections of sets Now fix any subset $B \subseteq A = \times_{i \in I} A_i$; hence, B may be a Cartesian product or not. For each $i \in I$ and $a_i \in A_i$, the **section at** a_i of set B is the subset $B_{a_i} \subseteq A_{-i}$ of all the a_{-i} that form with a_i an element of B, that is,

$$B_{a_i} := \{a_{-i} \in A_{-i} : (a_i, a_{-i}) \in B\}.$$

Example 4 If $A = \mathbb{R}^3$, B is the unit ball centered at (0,0,0), and $a_3 = 0$, then B_{a_3} is the unit disk in \mathbb{R}^2 centered at (0,0).

More generally, for each index subset $J \subset I$ and $a_J \in A_J$, the section of B at a_J is

$$B_{a_J} := \left\{ a_{I \setminus J} \in A_{I \setminus J} : \left(a_J, a_{I \setminus J} \right) \in B \right\}.$$

Projections The **projection function** from $A = \times_{i \in I} A$ onto A_J is the map that associates each profile $a = (a_J, a_{I \setminus J})$ with its component $a_J \in A_J$:

$$\operatorname{proj}_{A_J}: A \longrightarrow A_J \\ (a_J, a_{I \setminus J}) \mapsto a_J.$$

Recall that, for every function $f: X \to Y$ and subset $B \subseteq X$, the image of B through f is denoted

$$f(B) := \{y \in Y : \exists x \in B, f(x) = y\} = \bigcup_{x \in B} \{f(x)\}.$$

With this, the **projection of set** $B \subseteq A$ **onto** A_J is the image of B through the projection function $\operatorname{proj}_{A_J}: A \to A_J$, that is, the set of profiles a_J such that $(a_J, a_{I \setminus J}) \in B$ for at least one $a_{I \setminus J} \in A_{I \setminus J}$:

$$\operatorname{proj}_{A_{J}}\left(B\right)=\left\{ a_{J}\in A_{J}:\exists a_{I\backslash J}\in A_{I\backslash J},\left(a_{J},a_{I\backslash J}\right)\in B\right\}.$$

Often we suppress the parentheses and write $\operatorname{proj}_{A_J}B$ instead of $\operatorname{proj}_{A_J}(B)$.

Example 5 The projection of the unit ball in \mathbb{R}^3 centered at (2,2,2) onto \mathbb{R}^2 is the unit disk centered at (2,2). One can check by inspection of the definitions that the projection of a set is a union of sections.

Remark 4
$$\operatorname{proj}_{A_J} B = \bigcup_{a_{I \setminus J} \in A_{I \setminus J}} B_{a_{I \setminus J}}.$$

does not matter. What matters and has to be clear is how each $i \in I$ is associated with some element of the universal set of alternatives \bar{A} .

Sections of functions Fix a function $f: A \to Y$, where $A = \times_{i \in I} A_i$ and Y is an arbitrary codomain, e.g., a set of "outcomes" or "outputs." For each i and $a_i \in A_i$, we obtain from f a function f_{a_i} of a_{-i} called the **section at** a_i of function f:

$$f_{a_i}: A_{-i} \to Y$$

 $a_{-i} \mapsto f_{a_i}(a_{-i}) = f(a_i, a_{-i})$

Example 6 Consider a Cobb-Douglas production function

$$f: \mathbb{R}_{+}^{\{K,L\}} \to \mathbb{R}_{+}$$

$$(k,\ell) \mapsto (k\ell)^{\frac{1}{2}},$$

where K and L are respectively the indexes for capital and labor. If capital is fixed at k = 1 in the short run, then the short-run production function depends only on labor, and it is the section of f at k = 1:

$$f_{k=1}: \mathbb{R}_+ \longrightarrow \mathbb{R}_+ \\ \ell \longmapsto \sqrt{\ell} .$$

Similarly, for each strict subset $J \subset I$, we can consider the section at $a_J = (a_j)_{j \in J}$ of f:

$$f_{a_{J}}: A_{I\setminus J} \to Y$$

$$a_{I\setminus J} \mapsto f_{a_{J}}(a_{I\setminus J}) = f(a_{I\setminus J}, a_{J}).$$

We obtain an important special case when $J = I \setminus \{i\}$, that is, when we fix all the values of profile a except a_i .

The section notation is convenient in several cases. One of them is when we have a function $f: A \to Y$, we fix a_i and y, and we want to consider all the a_{-i} such that $f(a_i, a_{-i}) = y$, that is, the set

$$\{a_{-i} \in A_{-i} : f(a_i, a_{-i}) = y\}$$
.

Using the section notation, this set can be compactly written as the inverse image of y through function f_{a_i} :

$$f_{a_i}^{-1}\left(y\right) := \left\{a_{-i} \in A_{-i} : f_{a_i}\left(a_{-i}\right) = y\right\} = \left\{a_{-i} \in A_{-i} : f\left(a_i, a_{-i}\right) = y\right\}.$$

Sections of sets and functions are related. First recall that the **graph** of a function $f: A \to Y$ is the set of pairs $(a, y) \in A \times Y$ such that f(a) = y, that is,

$$Gr(f) := \left\{ (a, y) \in A \times Y : f(a) = y \right\}.$$

Remark 5 The graph of the section of a function is the section of the graph of such function: $Gr(f_{a_J}) = (Gr(f))_{a_J}$.

Example 7 In Example 6 (Cobb-Douglas production function), Gr(f) is

$$\left\{(k,\ell,y)\in\mathbb{R}_+^{\{K,L,O\}}:y=\sqrt{k\ell}\right\},$$

where O is the index of output. Then $Gr(f_{k=1}) = (Gr(f))_{k=1}$ is the graph of function $\ell \mapsto \sqrt{\ell}$, that is,

$$\left\{ (\ell,y) \in \mathbb{R}_+^{\{L,O\}} : y = \sqrt{\ell} \right\}.$$

2 Games, sets, and functions

As an illustration, consider the mathematical description of the essential aspects of the rules of a game with simultaneous-moves.

Game forms A game form is a mathematical structure

$$\langle I, Y, (A_i)_{i \in I}, g \rangle$$

where

- I is the set of players,
- \bullet Y is a set **outcomes**, or consequences,
- A_i is the set of feasible actions of player i,
- $g: \times_{i \in I} A_i \to Y$ is the **outcome** (or consequence) **function**.

Structure $\langle I, Y, (A_i)_{i \in I}, g \rangle$ represents the rules of the game under the implicit assumption that players move simultaneously (if moves were not simultaneous, then the order of moves should appear in the mathematical representation). To avoid measure-theoretic technicalities, here we assume that the game form is *finite*, but most of the analysis below does not depend on this assumption.

Action profiles Let $\bar{A} = \bigcup_{i \in I} A_i$ denote the set of all actions. The Cartesian product $\times_{i \in I} A_i$ is the set of action profiles, that is, the set of all

$$\begin{array}{cccc} a: & I & \to & \bar{A} \\ & i & \mapsto & a_i \end{array}$$

such that $a_i \in A_i$ for each $i \in I$. The set of action profiles A is also the set of all selections from the feasible actions correspondence $i \mapsto A_i$.

Co-players From now on, we will take the perspective of a particular player $i \in I$. A_{-i} is the set of action profiles of the opponents of i (also called "co-players"). This is the set of functions $a_{-i}: I \setminus \{i\} \to \bar{A}$ such that $a_j \in A_j$ for each $j \in I \setminus \{i\}$. Then, it makes sense to write $a = (a_i, a_{-i})$, which means that action profile a is the function that associates i with a_i and j with a_j for each j different from i. Since we think of A as a set of functions rather than a set of ordered |I|-tuples, it also makes sense to write $A = A_i \times A_{-i}$. Thus, if we want to emphasize the perspective of player i, we can write the outcome function as follows:

$$g: A_i \times A_{-i} \to Y$$
.

2.1 Sections, beliefs, and preferences

functions

Here we use the mathematical language introduced so far to express some ideas from the theory of choice in connection with games.

Choice under certainty The section of the outcome function g at any particular a_{-i} , $g_{a_{-i}}$, shows how i affects the outcome when the actions of the other players are kept fixed at a_{-i} . For example, if i is certain that the opponents (or co-players) play a_{-i} , then his conjectured action-outcome map is $g_{a_{-i}}: A_i \to Y$. If i's preferences are represented by a utility function $v_i: Y \to \mathbb{R}$, then a rational i with such (deterministic) conjecture solves

$$\max_{a_i \in A_i} v_i \left(g_{a_{-i}} \left(a_i \right) \right),\,$$

a problem of choice under (subjective) certainty. The solution of a problem of choice under certainty is invariant to strictly increasing transformations of the utility function.

Remark 6 Let $f: v_i(\mathbb{R}) \to \mathbb{R}$ be strictly increasing. Then, for every outcome function $g: A \to Y$ and co-players' action profile $a_{-i} \in A_{-i}$,

$$\arg\max_{a_{i}\in A_{i}}v_{i}\left(g_{a_{-i}}\left(a_{i}\right)\right)=\arg\max_{a_{i}\in A_{i}}\left(f\circ v_{i}\right)\left(g_{a_{-i}}\left(a_{i}\right)\right).$$

Before we consider choice under risk and/or uncertainty, we recall some concepts from elementary probability theory.

Probability measures In probability theory, a probability space is a pair (Ω, μ) , where μ is a probability measure on Ω . When Ω is *finite*, μ can be equivalently represented either as a function $\mu: 2^{\Omega} \to [0, 1]$ such that (i) $\mu(\Omega) = 1$, and (ii) $\mu(E' \cup E'') = \mu(E'') + \mu(E'')$ if $E' \cap E'' = \emptyset$, or a (probability mass) function $\mu: \Omega \to \mathbb{R}_+$ such that $\sum_{\omega \in \Omega} \mu(\omega) = 1$, letting

$$\mu\left(E\right) = \sum_{\omega \in E} \mu\left(\omega\right).$$

(We ignore the complications related to infinite state spaces.) With this, we let

$$\Delta(\Omega) := \left\{ \mu \in [0,1]^{2^{\Omega}} : \mu(\Omega) = 1, \forall E', E'' \subseteq \Omega, E' \cap E'' = \emptyset \Rightarrow \mu(E' \cup E'') = \mu(E'') + \mu(E'') \right\}$$

$$\cong \left\{ \mu \in \mathbb{R}_{+}^{\Omega} : \sum_{\omega \in \Omega} \mu(\omega) = 1 \right\}$$

denote the set of all probability measures on Ω .

Expectation functionals Fix a (finite) probability space (Ω, μ) . A random variable (or random number) on (Ω, μ) is a real-valued function $v : \Omega \to \mathbb{R}$. The **expected value** of v (given μ) is the weighted average

$$\mathbb{E}_{\mu}(v) = \sum_{\omega \in \Omega} v(\omega) \mu(\omega).$$

We can interpret the $\mathbb{E}_{\mu}(\cdot)$ notation as a special case of our notation on functions and sections. For a fixed state space Ω , let us consider all the probability measures $\mu \in \Delta(\Omega)$ and variables/functions $v \in \mathbb{R}^{\Omega}$. We call "functional" a real-valued function whose domain is a set of functions, or—more generally—a set of n-tuple of functions. The **expectation functional**

$$\begin{array}{cccc} \mathbb{E}: & \mathbb{R}^{\Omega} \times \Delta\left(\Omega\right) & \to & \mathbb{R} \\ & \left(v, \mu\right) & \mapsto & \sum_{\omega \in \Omega} v\left(\omega\right) \mu\left(\omega\right) \end{array}$$

associates each pair (v, μ) with the expected value of v under probability measure μ . When we fix $\mu \in \Delta(\Omega)$, we obtain the section

$$\mathbb{E}_{\mu}: \mathbb{R}^{\Omega} \to \mathbb{R}$$

$$v \mapsto \sum_{\omega \in \Omega} v(\omega) \mu(\omega) ,$$

that is, the expectation functional defined of the set of random variables over probability space (Ω, μ) . (Of course, it also makes sense to define the "dual" functional $\mu \mapsto \sum_{\omega \in \Omega} v(\omega) \mu(\omega)$ for any fixed variable/function $v: \Omega \to \mathbb{R}$; but this is less important here.)

Probability functionals The simplest random variables on probability spaces (Ω, μ) are the indicator functions of events

$$\mathbf{1}_E:\Omega\to\{0,1\}\quad (E\subseteq\Omega).$$

The expected value of $\mathbf{1}_E$ given μ is the probability of E given μ . This gives the **probability functional**

$$\mathbb{P}: \quad 2^{\Omega} \times \Delta(\Omega) \quad \to \quad \mathbb{R}$$

$$(E, \mu) \quad \mapsto \quad \mathbb{E}(\mathbf{1}_{E}, \mu) = \sum_{\omega \in E} \mu(\omega) \quad .$$

When we fix $\mu \in \Delta(\Omega)$, we obtain the section

$$\mathbb{P}_{\mu}: \quad 2^{\Omega} \quad \to \quad \mathbb{R}$$

$$E \quad \mapsto \quad \sum_{\omega \in E} \mu(\omega) \quad .$$

Savage acts, choice under uncertainty If we consider the section of outcome function g at any action $a_i \in A_i$, we obtain functions $g_{a_i} : A_{-i} \to Y$ $(a_i \in A_i)$. This shows that an action can always be interpreted as a function from what the decision maker i does not control (in this case, the actions of other players a_{-i}) to the outcomes, or consequences. In decision theory, such functions are called acts in the sense of Savage, or Savage acts. According to the subjective expected utility (SEU) theory of Savage (1954), i has a preference relation $\succeq_i \subseteq Y^{A_{-i}} \times Y^{A_{-i}}$ over the set $Y^{A_{-i}}$ of all conceivable acts, i which contains the set

$$\left\{ f \in Y^{A_{-i}} : \exists a_i \in A_i, f = g_{a_i} \right\}$$

⁸Recall, a **binary relation** over a set X is a subset $R \subseteq X \times X$. We write x'Rx'' if $(x', x'') \in R$.

of all feasible acts. If \succeq_i satisfies the axioms of SEU theory, there exists a utility function $v_i: Y \to \mathbb{R}$ (unique up to positive affine transformations) and a probability measure $\mu^i \in \Delta(A_{-i})$ such that, for all acts $f', f'' \in Y^{A_{-i}}$, 10

$$f' \succsim_{i} f'' \Leftrightarrow \mathbb{E}_{\mu^{i}} (v_{i} \circ f') \geq \mathbb{E}_{\mu^{i}} (v_{i} \circ f'')$$
.

Thus, a rational player i with (probabilistic) conjecture μ^i chooses one of the actions in the set

$$\arg\max_{a_{i}\in A_{i}}\mathbb{E}_{\mu^{i}}\left(v_{i}\circ g_{a_{i}}\right):=\left\{a_{i}^{*}\in A_{i}:\forall a_{i}\in A_{i},\mathbb{E}_{\mu^{i}}\left(v_{i}\circ g_{a_{i}^{*}}\right)\geq \mathbb{E}_{\mu^{i}}\left(v_{i}\circ g_{a_{i}}\right)\right\}.$$

For each pair of constants k and m, we denote by $(mv_i + k)$ the following affine transformation

$$(mv_i + k): Y \rightarrow \mathbb{R}$$

 $y \mapsto mv_i(y) + k$

Uniqueness up to positive affine transformations implies the following.

Remark 7 For all $(k, m) \in \mathbb{R}^2$ with m > 0, $g \in Y^A$, and $\mu^i \in \Delta(A_{-i})$,

$$\arg\max_{a_{i}\in A_{i}}\mathbb{E}_{\mu^{i}}\left(v_{i}\circ g_{a_{i}}\right)=\arg\max_{a_{i}\in A_{i}}\mathbb{E}_{\mu^{i}}\left(\left(mv_{i}+k\right)\circ g_{a_{i}}\right).$$

Stochastic outcomes Some games have rules that make the outcome depend on actions only stochastically. This can be represented in two ways:

• There is a "chance" player that chooses a deterministic outcome function $g \in Y^A$ at random according to some objective probability measure $\gamma \in \Delta(Y^A)$. Then, in the finite case, for all $a \in A$ and $y \in Y$, the probability of outcome y given action profile a is the sum of the probabilities of all the outcome functions g such that g(a) = y:

$$\hat{g}(y|a) = \sum_{g \in Y^A: g(a) = y} \gamma(g).$$

⁹What we say about acts and subjective expected utility is "in the same spirit" as Savage (1954). But he considers an uncountable A_{-i} ; therefore, his theory does not exactly apply here.

¹⁰Note that, for every $f: A_{-i} \to Y$ and $\mu^i \in \Delta(A_{-i}), v_i \circ f: A_{-i} \to \mathbb{R}$ is a random variable on the probability space (A_{-i}, μ^i) .

• There is a "chance" player that, for each $a \in A$, selects the outcome at random according to an objective probability measure $\bar{g}(a) \in \Delta(Y)$. This yields a stochastic outcome function

$$\begin{array}{cccc} \bar{g}: & A & \to & \Delta(Y) \\ & a & \mapsto & \bar{g}(a) \end{array}.$$

The connection between \bar{g} and \hat{g} is the following:

$$\forall a \in A, \forall y \in Y, \ \bar{g}(a)(y) = \hat{g}(y|a).$$

Choice under risk Suppose that the game form is stochastic and player i is certain of a particular action profile a_{-i} . How is i supposed to rank his actions and choose? In this case each action a_i induces an objective probability measure over outcomes, or lottery, $\bar{g}_{a_{-i}}(a_i) \in \Delta(Y)$. According to the objective expected utility theory of von Neumann and Morgenstern (1947), i's preference relation $\succeq_i \subseteq \Delta(Y) \times \Delta(Y)$ over the whole set of conceivable lotteries is such that there is a utility function $v_i : Y \to \mathbb{R}$ (unique up to positive affine transformations) such that, for all $\lambda', \lambda'' \in \Delta(Y)$,

$$\lambda' \succsim_{i} \lambda'' \Leftrightarrow \mathbb{E}_{\lambda'}(v_{i}) \geq \mathbb{E}_{\lambda''}(v_{i}).$$

Note that, if i is certain of a_{-i} , then he thinks that the set of feasible lotteries is

$$\left\{\lambda \in \Delta\left(Y\right) : \exists a_i \in A_i, \bar{g}_{a_{-i}}\left(a_i\right) = \lambda\right\}.$$

Thus, given conjecture a_{-i} , a rational player i chooses one of the actions in the set

$$\arg\max_{a_{i}\in A_{i}}\mathbb{E}_{\bar{g}_{a_{-i}}\left(a_{i}\right)}\left(v_{i}\right).$$

Choice under risk and uncertainty What if i is not certain about a_{-i} ? In this case, each action a_i induces a function $\bar{g}_{a_i}: A_{-i} \to \Delta(Y)$ that associates each a_{-i} with an objective probability measure on Y. Such functions (the elements of $\Delta(Y)^{A_{-i}}$) are called "Anscombe-Aumann acts," or Adacts. According to the subjective expected utility theory of Anscombe and Aumann (1963), agent i has a preference relation $\succsim_i \subseteq \Delta(Y)^{A_{-i}} \times \Delta(Y)^{A_{-i}}$ over the set of all conceivable AA-acts, where \succsim_i has the property that there exist a utility function $v_i: Y \to \mathbb{R}$ (unique up to positive affine transformations) and a subjective probability measure $\mu^i \in \Delta(A_{-i})$ such that, for all $f', f'' \in \Delta(Y)^{A_{-i}}$,

$$f' \succsim_{i} f'' \Leftrightarrow \sum_{a_{-i} \in A_{-i}} \mu^{i}(a_{-i}) \mathbb{E}_{f'(a_{-i})}(v_{i}) \geq \sum_{a_{-i} \in A_{-i}} \mu^{i}(a_{-i}) \mathbb{E}_{f''(a_{-i})}(v_{i}).$$

Note that the set of feasible AA-acts is

$$\left\{ f \in \Delta \left(Y \right)^{A_{-i}} : \exists a_i \in A_i, f = \bar{g}_{a_i} \right\}.$$

Therefore, a rational player i with (probabilistic) conjecture μ^i chooses one of the actions in the set

$$\arg \max_{a_{i} \in A_{i}} \sum_{a_{-i} \in A_{-i}} \mu^{i}(a_{-i}) \mathbb{E}_{\bar{g}_{a_{i}}(a_{-i})}(v_{i})$$

$$= \arg \max_{a_{i} \in A_{i}} \sum_{a_{-i} \in A_{-i}} \mu^{i}(a_{-i}) \sum_{y \in Y} \bar{g}_{a_{i}}(a_{-i})(y) v_{i}(y),$$

where $\bar{g}_{a_i}(a_{-i}) \in \Delta(Y)$ is the lottery induced by action a_i when the coplayers choose a_{-i} . Uniqueness up to positive affine transformation implies the following.

Remark 8 For all $(k, m) \in \mathbb{R}^2$ with m > 0, $\bar{g} \in \Delta(Y)^A$, and $\mu^i \in \Delta(A_{-i})$,

$$\arg \max_{a_{i} \in A_{i}} \sum_{a_{-i} \in A_{-i}} \mu^{i}(a_{-i}) \mathbb{E}_{\bar{g}_{a_{i}}(a_{-i})}(v_{i})$$

$$= \arg \max_{a_{i} \in A_{i}} \sum_{a_{-i} \in A_{-i}} \mu^{i}(a_{-i}) \mathbb{E}_{\bar{g}_{a_{i}}(a_{-i})}(mv_{i} + k).$$

Mixed actions There is another way to obtain AA-acts and it works even if the outcome function g is deterministic: Player i can delegate the choice of his action a_i to a randomization device with distribution $\alpha_i \in \Delta(A_i)$. By choosing such device, i induces a **mixed action** α_i . Since the induced mixed action is all that matters, we can think of a set of *conceivable* choices $\Delta(A_i)$ whereas the set of *feasible choices* includes A_i (which we identify with the set of Dirac measures on A_i) and all the non-Dirac measures α_i that are induced by some feasible randomization device.

Each mixed action α_i induces a corresponding AA-act:

$$\alpha_i \mapsto (\hat{g}_{a_{-i}}(\alpha_i))_{a_{-i} \in A_{-i}} \in \Delta(Y)^{A_{-i}},$$

where

$$\begin{array}{cccc}
\hat{g}_{a_{-i}} : & \Delta(A_i) & \to & \Delta(Y) \\
& \alpha_i & \mapsto & \alpha_i \circ g_{a_{-i}}^{-1}
\end{array}$$

is the **pushforward** function such that

$$\hat{g}_{a_{-i}}\left(\alpha_{i}\right)\left(E\right) = \alpha_{i}\left(g_{a_{-i}}^{-1}\left(E\right)\right) = \alpha_{i}\left(\left\{a_{i} \in A_{i} : g_{a_{-i}}\left(a_{i}\right) \in E\right\}\right)$$

for each outcome-event $E \subseteq Y$.

Example 8 Consider the outcome function

g	ℓ	r
t	G	B
m	M	M
d	B	G

and let $A_i = \{t, m, d\}$ (hence, $A_{-i} = \{\ell, r\}$). Then, the mixed action $\alpha_i = \frac{1}{2}\delta_t + \frac{1}{2}\delta_m$ that randomizes $\frac{1}{2}: \frac{1}{2}$ on t and m yields the following AA-act f

f	B	M	G
$\hat{g}_{\ell}\left(\frac{1}{2}\delta_{t}+\frac{1}{2}\delta_{m}\right)$	0	$\frac{1}{2}$	$\frac{1}{2}$
$\hat{g}_r \left(\frac{1}{2} \delta_t + \frac{1}{2} \delta_m \right)$	$\frac{1}{2}$	$\frac{1}{2}$	0

Battigalli et al. (2017) show that it is not necessary to consider the whole set $\Delta(Y)^{A_{-i}}$ of conceivable AA-acts to develop an axiomatic theory of choice under uncertainty with a subjective EU representation, because the subset

$$\left\{ f \in \Delta \left(Y \right)^{A_{-i}} : \exists \alpha_i \in \Delta \left(A_i \right) : f = \left(\hat{g}_{a_{-i}} \left(\alpha_i \right) \right)_{a_{-i} \in A_{-i}} \right\}$$

of AA-acts induced by mixed actions is "sufficiently rich." That is, one can provide an axiomatic theory of choice under uncertainty looking at preferences over mixed actions, $\succsim_i \subseteq \Delta(A_i) \times \Delta(A_i)$.

3 Predicates, sets, and games

Predicate calculus is a branch of mathematical logic that analyzes sentences about the properties of individual objects and relationships between objects. A predicate is a statement that some property or relationship holds for an object, or a tuple of objects. Here we are only interested in the formal representation of such sentences, how they are used to represent sets, and some simple rules. We illustrate with examples from the theory of games.

Games A simultaneous-move game is given by a game form

$$\langle I, Y, (A_i)_{i \in I}, g \rangle$$

and a profile of utility functions

$$(v_i:Y\to\mathbb{R})_{i\in I}$$
.

For each player $i \in I$, let

$$u_i = v_i \circ g : A \to \mathbb{R}$$

denote the so called "**payoff function**" of i. Then, we can consider the "reduced form"

$$G = \langle I, (A_i, u_i)_{i \in I} \rangle$$

of the game. The basic set of objects under consideration is the set of mixed actions $\Delta(A_i)$ of a given player i. As usual, we regard A_i as a subset of $\Delta(A_i)$: $A_i \subseteq \Delta(A_i)$. We also consider the set $\Delta(A_{-i})$ of conjectures about the action profiles of the co-players; again, $A_{-i} \subseteq \Delta(A_{-i})$.

Justifiability and dominance Here are two examples of (informally stated) sentences in predicate calculus:

- "action a_i is justifiable" and
- "action a_i is dominated."

Both examples involve the "for all" quantifier \forall and the "there exists" quantifier \exists . Specifically, by definition,

- a_i is **justifiable** iff (if and only if) there exists a conjecture $\mu^i \in \Delta(A_{-i})$ such that $\mathbb{E}_{\mu^i}(u_{i,a_i}) \geq \mathbb{E}_{\mu^i}(u_{i,b_i})$ for all $b_i \in A_i$, ¹²
- a_i is **dominated** iff there exists a mixed action α_i such that $\mathbb{E}_{\alpha_i}(u_{i,a_{-i}}) > u_{i,a_i}(a_{-i})$ for all $a_{-i} \in A_{-i}$.

When we state such sentences with logical quantifiers in the natural language, we sometimes put the "for all" quantification at the end of the sentence, as in the examples above. Sometimes we put the "there exists" quantification at the end of the sentence, but with different words, such as "for some ..." or "for at least one ...". As long as the meaning is clear, this is fine.

¹¹ It is somewhat confusing to call "payoff function" the map that associates each action profile with a player's utility of the induced outcome. This has a historical origin. The early work on game theory assumed that outcomes are profiles $y = (y_i)_{i \in I} \in \mathbb{R}^I$ of monetary payoffs and that players are risk neutral, hence they just want to maximize their own expected monetary payoff. In this case $v_i(y) = y_i$, and $u_i(a) = g_i(a)$, where $g_i(a)$ is i's "gain" given action profile a.

¹²Here we take for granted without proof that, for every conjecture, the subjective expected utility of a mixed action cannot be higher than the largest subjective expected utility of pure actions. Hence, justifiability can be expressed with reference to pure actions.

Predicates about justifiability and dominance However, it is often convenient to express such sentences with formulas containing \forall and/or \exists . Such predicate formulas must be written with all the quantifiers at the beginning and in the correct order. With this, there are simple rules to manipulate such formulas according to logical calculus that help us in our reasoning. Here we focus on the rule to obtain the negation of a sentence in predicate calculus.

The formula for " a_i is justifiable" is

$$\exists \mu^{i} \in \Delta \left(A_{-i} \right), \forall b_{i} \in A_{i}, \mathbb{E}_{\mu^{i}} \left(u_{i,a_{i}} \right) \geq \mathbb{E}_{\mu^{i}} \left(u_{i,b_{i}} \right).$$

The formula for " a_i is dominated" is

$$\exists \alpha_i \in \Delta\left(A_i\right), \forall a_{-i} \in A_{-i}, \mathbb{E}_{\alpha_i}\left(u_{i,a_{-i}}\right) > u_{i,a_i}\left(a_{-i}\right).$$

Note that the order of quantifiers is crucial, as illustrated by the following example.

Example 9 (Justifiability and order of quantifiers) Consider the following payoff function u_i :

$$\begin{array}{c|cccc} u_i : & \ell & r \\ \hline t & 0 & 1 \\ \hline m & \frac{1}{3} & \frac{1}{3} \\ d & 1 & 0 \\ \hline \end{array}$$

where $A_i = \{t, m, d\}$ (u_i is obtained by appending utility function $v_i(G) = 1$, $v_i(M) = 1/3$, $v_i(B) = 0$ to the game form of Example 8) It can be checked that action m is not justifiable: indeed, the special case for this payoff function and action m of the justifiability formula written above can be re-written as follows

$$\exists \mu^{i} \in \Delta\left(\left\{\ell, r\right\}\right), \left(\frac{1}{3} \ge \mu^{i}\left(r\right)\right) \wedge \left(\frac{1}{3} \ge \mu^{i}\left(\ell\right)\right),$$

(where \land means "and"), which is false because either $\mu^i(r) \ge \frac{1}{2}$ or $\mu^i(\ell) \ge \frac{1}{2}$. Yet, inverting the order of quantifiers in the justifiability formula, we obtain

$$\forall b_{i} \in \left\{t, m, d\right\}, \exists \mu^{i} \in \Delta\left(\left\{\ell, r\right\}\right), \mathbb{E}_{\mu^{i}}\left(u_{i, m}\right) \geq \mathbb{E}_{\mu^{i}}\left(u_{i, b_{i}}\right),$$

which is true, because
$$\mathbb{E}_{\mu^i}(u_{i,m}) \geq \mathbb{E}_{\mu^i}(u_{i,t})$$
 if $\mu^i(r) \leq \frac{1}{3}$, and $\mathbb{E}_{\mu^i}(u_{i,m}) \geq \mathbb{E}_{\mu^i}(u_{i,d})$ if $\mu^i(\ell) \leq \frac{1}{3}$. A similar example applies to dominance.¹³

Predicate formulas with quantifiers can be used to express sets. For example, the set of justifiable actions is

$$J_i := \left\{ a_i \in A_i : \exists \mu^i \in \Delta \left(A_{-i} \right), \forall b_i \in A_i, \mathbb{E}_{\mu^i} \left(u_{i,a_i} \right) \ge \mathbb{E}_{\mu^i} \left(u_{i,b_i} \right) \right\},\,$$

and the set of dominated actions is

$$D_{i} := \left\{ a_{i} \in A_{i} : \exists \alpha_{i} \in \Delta (A_{i}), \forall a_{-i} \in A_{-i}, \mathbb{E}_{\alpha_{i}} (u_{i,a_{-i}}) > u_{i,a_{i}} (a_{-i}) \right\}.$$

Predicates and negation Is there a relatively simple and explicit way to write the sets of unjustifiable and undominated actions? Yes, it is enough to apply the following rule:

• To obtain the negation of a predicate formula with quantifiers, replace each ∀ with ∃, replace each ∃ with ∀, and replace the predicate in the formula with its negation (e.g., replace < with ≥).

For example, the negation of the false formula

$$\forall n \in \mathbb{N}, \exists m \in \mathbb{N}, m < n$$

is the true formula

$$\exists n \in \mathbb{N}, \forall m \in \mathbb{N}, m > n.$$

To check that the first formula is false and the second (its negation) is true, just consider the smallest natural number n = 1.14

We can use this simple rule to express the sets of unjustifiable and undominated actions as follows:

$$A_{i}\backslash J_{i}=\left\{a_{i}\in A_{i}:\forall\mu^{i}\in\Delta\left(A_{-i}\right),\exists b_{i}\in A_{i},\mathbb{E}_{\mu^{i}}\left(u_{i,a_{i}}\right)<\mathbb{E}_{\mu^{i}}\left(u_{i,b_{i}}\right)\right\}$$

and

$$A_{i} \backslash D_{i} = \left\{ a_{i} \in A_{i} : \forall \alpha_{i} \in \Delta \left(A_{i} \right), \exists a_{-i} \in A_{-i}, \mathbb{E}_{\alpha_{i}} \left(u_{i, a_{-i}} \right) \leq u_{i, a_{i}} \left(a_{-i} \right) \right\}.$$

¹³ The crucial importance of the order of quantifiers explains why predicate formulas must list quantifiers on the left, so that their order reflects the reading order from left to right. Some mathematicians and theorists, casually write the universal quantifier \forall on the right in formulas that do not contain quantifier \exists . In particular, this is very common among decision theorists.

¹⁴We use \mathbb{N} to denote the set of *strictly positive* integers. We denote the set of nonnegative integers by \mathbb{N}_0 .

Predicates and optimization We can also relate predicate formulas involving inequalities with the sup and inf operations, which become max and min operations when we can take for granted that the sup and inf are always attained. For example, given the assumption that the game is finite, we can express justifiability as follows: a_i is justifiable iff, for some conjecture μ^i , there is a non-positive incentive to deviate from a_i to any action b_i , that is,

$$\exists \mu^{i} \in \Delta \left(A_{-i} \right), \forall b_{i} \in A_{i}, \mathbb{E}_{\mu^{i}} \left(u_{i,b_{i}} \right) - \mathbb{E}_{\mu^{i}} \left(u_{i,a_{i}} \right) \leq 0,$$

which is equivalent to

$$\min_{\mu^{i} \in \Delta(A_{-i})} \max_{b_{i} \in A_{i}} \left(\mathbb{E}_{\mu^{i}} \left(u_{i,b_{i}} \right) - \mathbb{E}_{\mu^{i}} \left(u_{i,a_{i}} \right) \right) \leq 0.$$

To see this, note that—for every given μ^{i} — $\mathbb{E}_{\mu^{i}}(u_{i,b_{i}}) - \mathbb{E}_{\mu^{i}}(u_{i,a_{i}}) \leq 0$ for all b_{i} in the finite set A_{i} iff

$$\max_{b_i \in A_i} \left(\mathbb{E}_{\mu^i} \left(u_{i,b_i} \right) - \mathbb{E}_{\mu^i} \left(u_{i,a_i} \right) \right) \le 0.$$

Let $H(\mu^i)$ denote the above maximum. Then a_i is justifiable iff $H(\mu^i) \leq 0$ for some μ^i . By standard arguments, H is a continuous function over the compact domain $\Delta(A_i)$, therefore $\min_{\mu^i \in \Delta(A_{-i})} H(\mu^i)$ is well defined and $H(\mu^i) \leq 0$ for some μ^i iff $\min_{\mu^i \in \Delta(A_{-i})} H(\mu^i) \leq 0$.

Using arguments of this kind and the celebrated Maxmin Theorem of von Neumann, one can prove the lemma of Wald and Pearce: $J_i = A_i \setminus D_i$ (see the Appendix of Chapter 3 of Game Theory: Analysis of Strategic Thinking).

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