

# Homework 02

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- 3.1 Consider Fig 1. What is the representation of the vector  $x$  with respect to the basis  $[q_1, i_2]$ ? What is the representation of  $q_1$  with respect to the basis  $[i_2, q_2]$
- 3.2 What are the 1-norm, 2-norm, and infinite-norm of the vectors

$$x_1 = \begin{bmatrix} 2 \\ -3 \\ 1 \end{bmatrix} \quad x_2 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

- 3.3 Find two orthonormal vectors that span the same space as the two vectors in Problem 3.2.
- 3.4 Consider an  $n \times m$  matrix  $A$  with  $n \geq m$ . If all columns of  $A$  are orthonormal, then  $A'A = I_m$ . What can you say about  $AA'$ ?
- 3.5 Find the ranks and nullities of the following matrices:

$$A_1 = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad A_2 = \begin{bmatrix} 4 & 1 & -1 \\ 3 & 2 & 0 \\ 1 & 1 & 0 \end{bmatrix} \quad A_3 = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & -1 & -2 & 2 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

- 3.6 Find bases of the range spaces and null spaces of the matrices in Problem 3.5.
- 3.7 Consider the linear algebraic equation

Figure 1: Different representations of vector  $x$ .

$$\begin{bmatrix} 2 & -1 \\ -3 & 3 \\ -1 & 2 \end{bmatrix} x = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = y$$

It has three equations and two unknowns. Does a solution  $x$  exist in the equations? Is the solution unique? Does a solution exist if  $y = [111]'$ ?

3.8 Find the general solution of

$$\begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & -1 & -2 & 2 \\ 0 & 0 & 0 & 1 \end{bmatrix} x = \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix}$$

How many parameters do you have?

3.9 Find the solution in Example 3.3 that has the smallest Euclidean norm.

3.10 Find the solution in Problem 3.8 that has the smallest Euclidean norm.

3.11 Consider the equation

$$x[n] = A^n x[0] + A^{n-1} b u[0] + A^{n-2} b u[1] + \dots + A b u[n-2] + b u[n-1]$$

where  $A$  is an  $n \times n$  matrix and  $b$  is an  $n \times 1$  column vector. Under what conditions on  $A$  and  $b$  will there exist  $u[0], u[1], \dots, u[n-1]$  to meet the equation for any  $x[n]$  and  $x[0]$ ? *Hint:* Write the equation in the form

$$x[n] - A^n x[0] = [b A b \dots A^{n-1} b] \begin{bmatrix} u[n-1] \\ u[n-1] \\ \vdots \\ u[0] \end{bmatrix}$$

3.12 Given

$$A = \begin{bmatrix} 2 & 1 & 0 & 0 \\ 0 & 2 & 1 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \quad b = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \end{bmatrix} \quad \bar{b} = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 1 \end{bmatrix}$$

what are the representations of  $A$  with respect to the basis  $[b, Ab, A^2b, A^3b]$  and the basis  $[\bar{b}, A\bar{b}, A^2\bar{b}, A^3\bar{b}]$ , respectively? (Note that the representations are the same!)

3.13 Find Jordan-form representations of the following matrices:

$$\begin{aligned} A_1 &= \begin{bmatrix} 1 & 4 & 10 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix} & A_2 &= \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -2 & -4 & -3 \end{bmatrix} \\ A_3 &= \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix} & A_4 &= \begin{bmatrix} 0 & 4 & 3 \\ 0 & 20 & 16 \\ 0 & -25 & -20 \end{bmatrix} \end{aligned}$$

Note that all except  $A_4$  can be diagonalized.

3.14 Consider the companion-form matrix

$$A = \begin{bmatrix} -\alpha_1 & -\alpha_2 & -\alpha_3 & -\alpha_4 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

Show that its characteristic polynomial is given by

$$\Delta(\lambda) = \lambda^4 + \alpha_1\lambda^3 + \alpha_2\lambda^2 + \alpha_3\lambda + \alpha_4$$

Show also that if  $\lambda_i$  is an eigenvalue of  $A$  or a solution of  $\Delta(\lambda) = 0$ , then  $[\lambda_i^3 \lambda_i^2 \lambda_i 1]'$  is an eigenvector of  $A$  associated with  $\lambda_i$ .

3.15 Show that the Vandermonde determinant

$$\begin{bmatrix} \lambda_1^3 & \lambda_2^3 & \lambda_3^3 & \lambda_4^3 \\ \lambda_1^2 & \lambda_2^2 & \lambda_3^2 & \lambda_4^2 \\ \lambda_1 & \lambda_2 & \lambda_3 & \lambda_4 \\ 1 & 1 & 1 & 1 \end{bmatrix}$$

equals  $\prod_{1 \leq i < j \leq 4} (\lambda_j - \lambda_i)$ . Thus we conclude that the matrix is nonsingular or, equivalently, the eigenvectors are linearly independent if all eigenvalues are distinct.

- 3.16 Show that the companion-form matrix in Problem 3.14 is nonsingular if and only if  $\alpha_4 \neq 0$ . Under this assumption, show that its inverse equals

$$A^{-1} = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -1/\alpha_4 & -\alpha_1/\alpha_4 & -\alpha_2/\alpha_4 & -\alpha_3/\alpha_4 \end{bmatrix}$$

- 3.17 Consider

$$A = \begin{bmatrix} \lambda & \lambda T & \lambda T^2/2 \\ 0 & \lambda & \lambda T \\ 0 & 0 & \lambda \end{bmatrix}$$

with  $\lambda \neq 0$  and  $T > 0$ . Show that  $[001]'$  is a generalized eigenvector of grade 3 and the three columns of

$$Q = \begin{bmatrix} \lambda^2 T^2 & \lambda T^2 & 0 \\ 0 & \lambda T & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

constitute a chain of generalized eigenvectors of length 3. Verify

$$Q^{-1}AQ = \begin{bmatrix} \lambda & 1 & 0 \\ 0 & \lambda & 1 \\ 0 & 0 & \lambda \end{bmatrix}$$

- 3.18 Find the characteristic polynomials and the minimal polynomials of the following matrices:

$$\begin{bmatrix} \lambda_1 & 1 & 0 & 0 \\ 0 & \lambda_1 & 1 & 0 \\ 0 & 0 & \lambda_1 & 0 \\ 0 & 0 & 0 & \lambda_2 \end{bmatrix} \quad \begin{bmatrix} \lambda_1 & 1 & 0 & 0 \\ 0 & \lambda_1 & 1 & 0 \\ 0 & 0 & \lambda_1 & 0 \\ 0 & 0 & 0 & \lambda_1 \end{bmatrix}$$

$$\begin{bmatrix} \lambda_1 & 1 & 0 & 0 \\ 0 & \lambda_1 & 0 & 0 \\ 0 & 0 & \lambda_1 & 0 \\ 0 & 0 & 0 & \lambda_1 \end{bmatrix} \quad \begin{bmatrix} \lambda_1 & 0 & 0 & 0 \\ 0 & \lambda_1 & 0 & 0 \\ 0 & 0 & \lambda_1 & 0 \\ 0 & 0 & 0 & \lambda_1 \end{bmatrix}$$

- 3.19 Show that if  $\lambda$  is an eigenvalue of  $A$  with eigenvector  $x$ , then  $f(\lambda)$  is an eigenvalue of  $f(A)$  with the same eigenvector  $x$ .

3.20 Show that an  $n \times n$  matrix has the property  $A^k = 0$  for  $k \geq m$  if and only if  $A$  has eigenvalues 0 with multiplicity  $n$  and index  $m$  or less. Such a matrix is a *nilpotent* matrix.

3.21 Given

$$A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

find  $A^{10}$ ,  $A^{103}$ , and  $e^{At}$ .

3.22 Use two different methods to compute  $e^{At}$  for  $A_1$  and  $A_4$  in Problem 3.13.

3.23 Show that functions of the same matrix commute; that is,

$$f(A)g(A) = g(A)f(A)$$

Consequently we have  $Ae^{At} = e^{At}A$ .

3.24 Let

$$C = \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix}$$

Find a matrix  $B$  such that  $e^B = C$ . Show that if  $\lambda_i = 0$  for some  $i$ , then  $B$  does not exist. Let

$$C = \begin{bmatrix} \lambda & 1 & 0 \\ 0 & \lambda & 0 \\ 0 & 0 & \lambda \end{bmatrix}$$

Find a  $B$  such that  $e^B = C$ . Is it true that, for any nonsingular  $C$ , there exists a matrix  $B$  such that  $e^B = C$ ?

- Obtain eigenvectors of the following matrix:

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{bmatrix}$$

- Obtain a transformation matrix  $P$  such that  $P^{-1}AP$  is diagonal.  $A$  is given by

$$\begin{bmatrix} 0 & 1 & 0 \\ 3 & 0 & 2 \\ -12 & -7 & -6 \end{bmatrix}$$

- Find a transformation matrix  $S$  such that

$$S^{-1}AS = J$$

where

$$A = \begin{bmatrix} 4 & 1 & -2 \\ 1 & 0 & 2 \\ 1 & -1 & 3 \end{bmatrix}, \quad J = \begin{bmatrix} 3 & 1 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

- Find the Jordan-canonical-form representations of the following matrices:

$$\begin{aligned} A_1 &= \begin{bmatrix} 1 & 4 & 10 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix} & A_2 &= \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -2 & -4 & -3 \end{bmatrix} \\ A_3 &= \begin{bmatrix} 0 & 4 & 3 \\ 0 & -150 & -120 \\ 0 & 200 & 160 \end{bmatrix} & A_4 &= \begin{bmatrix} 0 & 4 & 3 \\ 0 & 20 & 16 \\ 0 & -25 & -20 \end{bmatrix} \\ A_5 &= \begin{bmatrix} 7/2 & 21/2 & 14 \\ -1/2 & -3/2 & -2 \\ -1/2 & -3/2 & -2 \end{bmatrix} & A_6 &= \begin{bmatrix} 0 & 1 & 1 & 1 & 1 \\ 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \end{aligned}$$

- Find the Jordan-canonical-form representations of the following matrices:

$$A_1 = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 2 & 1 & -2 \end{bmatrix} \quad A_2 = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -8 & -12 & -6 \end{bmatrix} \quad A_3 = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 4 & -4 & -3 & 4 \end{bmatrix}$$