DERECK LAM HON WAH

3rd Year BSc. Computer Science (System Engineering)

Student from Middlesex University Mauritius

linkedin.com/in/dereck-lam-hon-wah-315039227 https://github.com/derecklhw



UNDERSTANDING THE BOOT PROCESS

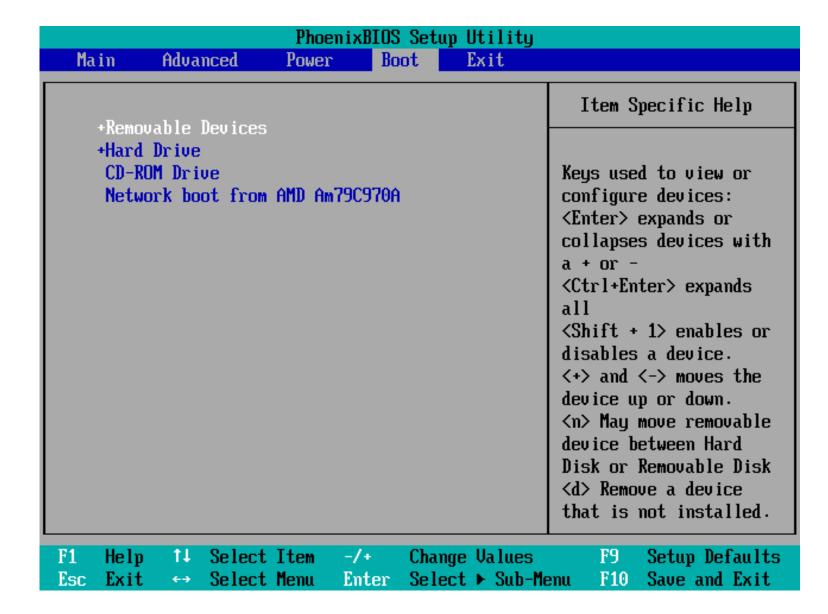
OVERVIEW OF THE BOOT PROCESS

BIOS MBR GRUB KERNEL SYSTEMD RUNLEVEL

BIOS

BASIC INPUT OUTPUT SYSTEM

- Perform the **POST** (Power-on self-test) which run some system integrity checks of hardware and peripherals.
- Searches, loads, and executes the boot loader program, which can be found in the MBR.
- Once the boot loader program is detected and loaded into the memory, BIOS gives the control to it.



MBR

MASTER BOOT RECORD

- Responsible for loading and executing the GRUB boot loader.
- Located in the first sector of a hard disk or a removable drive.
- Contains details about the partitions and their locations.

Partition Table

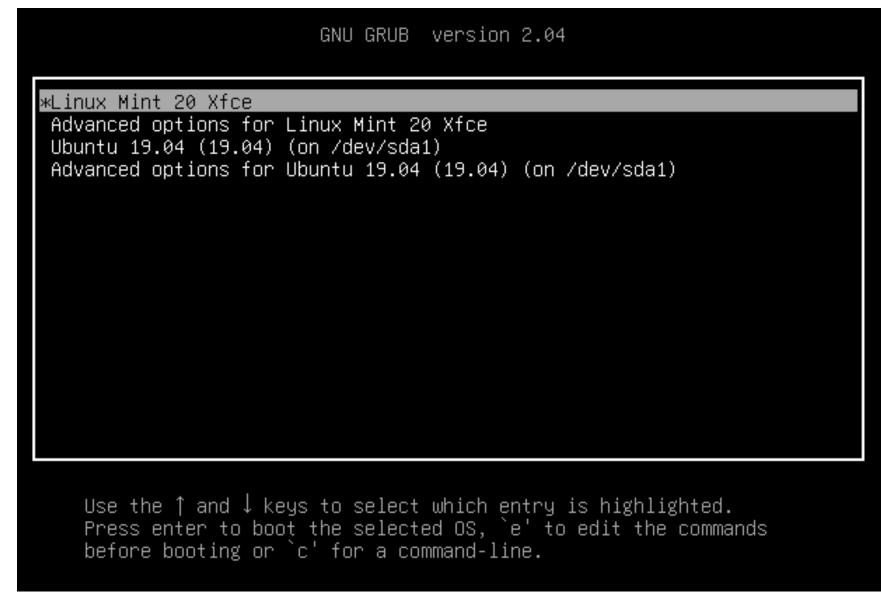
Bootstrap code

1 2 3 4

GRUB

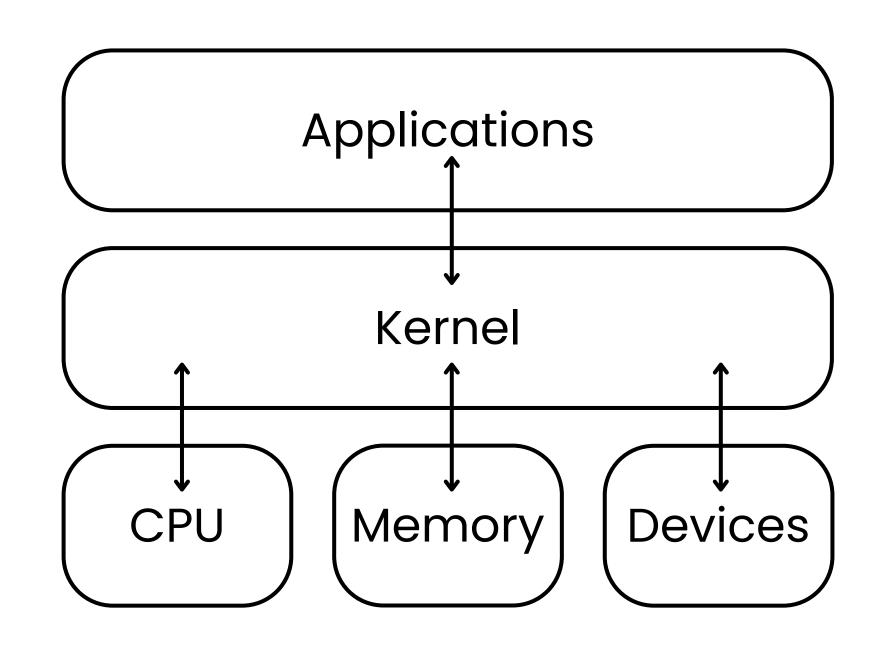
GNU GRAND UNIFIED BOOTLOADER

- LILO (Linux Loader) in very old system.
- If you have multiple kernel images installed on your system, you can choose which one to be executed.
- GRUB configuration file is:
 - /boot/grub/grub.conf
 - /etc/grub.conf
- Insert kernel into memory and turns control of the system over to the kernel.



KERNEL

- Core of any operating system and has complete control over everything in your system.
- Follows a predefined procedure:
 - decompress itself in place (vmlinuz vs vmlinux)
 - perform hardware checks
 - gain access to vital peripheral hardware
 - o run the init process



SYSTEMD

- The parent process when the kernel initiates the init process.
- Replaces the old **SysVinit** process.
- Performs a range of tasks:
 - probe all remaining hardware
 - mount filesystems
 - initiate and terminate services
 - manage essential system processes like user login
 - o run a desktop environment

RUNLEVEL

- Stands for the current state of the operating system, defining which system services are running.
- Previously, SysVinit identified run levels by number. However, .target files now replace run levels in Systemd.

Let's check our default target:

\$ sudo systemctl get-default

To change boot target:

\$ sudo systemctl set-default <target>

RUNLEVEL

• You can change the target (run level) while the system runs.

For example, to switch to run level 3 from run level 5, we can run the following command:

\$ sudo systemctl isolate multi-user.target

Then, to take the system to run level 5, let's run the command:

\$ sudo systemctl isolate graphical.target

poweroff.target	run level 0	turn off (shut down) the computer
rescue.target	run level 1	initiate a rescue shell process
multi-user.target	run level 3	configure the system as a non- graphical (console) multi-user environment
graphical.target	run level 5	establish a graphical multi-user interface with network services
reboot.target	run level 6	restart the machine