Optimizing NOMA Pairing with Semantic Awareness: A Reinforcement Learning Approach

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Abstract

Non Orthogonal Multiple Access (NOMA) systems allow for simultaneous communication throughout users, even with varying channel conditions, which maximizes 2 spectral efficiency using power domain multiplexing. Traditional user pairing 3 methods, like greedy, optimize this based on distance and fading, but doesn't generalize beyond predefined heuristics. In this abstract, we introduce a reinforcement learning based framework for semantic aware NOMA user pairing, where the agent learns to form pairs that maximize total semantic utility $\sum w_i R_i$. We simulate environments with 10 users, each with random channel conditions and semantic 8 weight. Per step, the Q learning agent selects a pair from remaining users, then 9 recieves a reward depending on semantic utility, and updating accordingly. Over 10 1000+ episodes, the agent will learn to approximate, or even outperform, greedy 11 strategies. The preliminary results reveals that it manages to capture pairing pat-12 terns similar to greedy baselines, while improving adaptability. Such an approach 13 reflects the advantages of leveraging maching learning for dynamic and utility 14 aware NOMA resource allocation. 15

1 Introduction

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- 17 NOMA allows multiple users to share time frequency resources user varying power levels, which
- boosts spectral efficiency. User grouping traditional relies on channel aware heuristics, such as greedy
- distance based pairing. Such methods are effective, but lack the flexibility and scalability, especially
- 20 in dynamic scenarios.
- 21 In order to bridge the gap, we aim to approach this with reinforcement learning (RL) with Q learning
- 22 to train for optimal user pairings in NOMA systems. The objective then is to maximize semantic
- 23 utility of user pairs, considering both physical (channel) and application level (semantic) features.
- 24 This framework, powered by ML, allows for adaptive decision making, beyond fixed heuristics.

25 2 Method

- We first simulate a NOMA environment with a set of n=10 users, each assigned a 3D position to
- 27 calculate distance, a Rayleigh fading coefficient, and a semantic weight $w_i \sim \mathcal{U}(0,1)$. Utility U_{sem} is
- calculated based on achievable rates R_1, R_2 and weights w_1, w_2 .
- The achievable R_1 and R_2 are calculated using standard NOMA decoding schemes, where R_1 (the
- weak user) considers interference from the strong user, while R_2 (strong user) assumes perfect
- 31 successive interference cancellation (SIC).
- The Q learning is designed where the agent is trained to form user pairings, maximizing U_{sem} through
- 33 trial and error over multiple episodes.

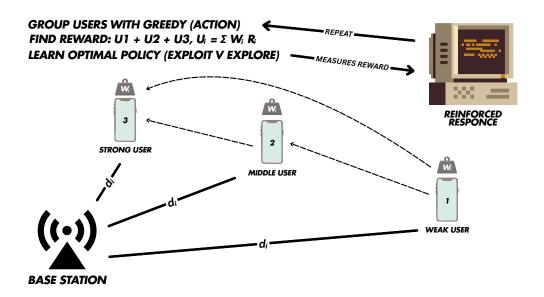


Figure 1: Greedy and Q learning

4 Q Learning Framework, Environment, and Setup

- **Initial State:** All 10 users are unpaired.
 - Action: Select a pair (user i, user j) from the unpaired set.
 - **Reward:** Compute semantic utility $w_i R_i + w_i R_j$ for the selected pair.
 - Transition: Remove the selected pair from the user set and proceed to next decision.
 - Episode End: When all users have been grouped.
- 40 Training episodes are run where the agent explores different pairing combinations, stores the rewards,
- and learns optimal policies via exploitation strategies over time.
- The state is encoded as the current set of unpaired users. Q values are stored and is trained for 1000+
- 43 episodes.

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44 3 Preliminary Results

- The simulation compares Q learned pairings, base lining greedy algorithms. Early results may suggest:
 - Q learning converges to high utility pairings within 1000 episodes.
 - Learned pairings match or exceed greedy baseline performance.
 - Semantic weights influence pairing strategy and model adaptability.
 - Variance in performance decreases over time due to stability in training policies.
 - Q learning matches best case utility found by greedy baselines, occasionally it slightly outperforms.
 - Q agent learns to favor pairings with large channel gain gaps and complementary semantic weights.

4 Conclusion and Future Work

- our work will present a reinforcement learning approach to user pairing in NOMA systems, which
- integrates semantic awareness. This prioritizes users not only by channel gain, but also utility weights

- se reflecting application relevance. Modeling pairing processes as a sequential decision making problem,
- 59 the O learning agent is then able to iteratively improve its policy, match, and exceed traditional greedy
- 60 algorithms in terms of total semantic utility.
- 61 As mentioned in the preliminary results, they demonstrate the agent's ability to generalize beyond
- 62 fixed policies, and adapting to random user deployments all while capturing meaningful pairing
- strategies. The learned policy is able to offer comparable utility, with the added advantage of being
- extensible to various pairing objectives and dynamic environments.
- 65 We can also incorporate triplet based grouping, introducing higher order complexity. Another route
- would be to incorporate and adapt to dynamic user arrivals and time varying channels in real world
- 67 deployments. This framework opens up promising directions for intelligent and context aware
- resource allocations for next generation wireless networks.

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