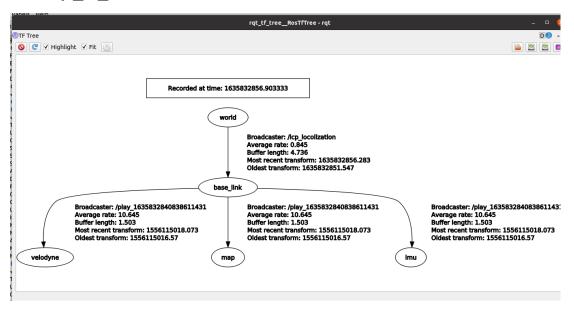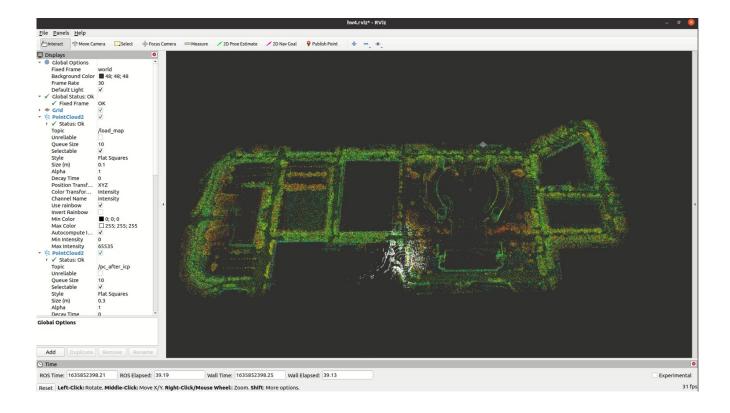# ICP Localization

- **Rqt_tf_tree**

- **Map point cloud**

- **Result of ICP Localization**

Red Arrows: ground truth odometry
Blue Arrows: your result
Cyan Dots: GPS measurements
White Points: point cloud from LiDAR
Colorful Points: point cloud map