## Introduction to NonParametric Statistics

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## Linear Models in general

- Have several model assumptions
  - Independence of error terms
  - Constant variance of error terms
  - Normally distributed error terms
- "All models are wrong, but some are useful" George Box
- Model assumptions must be approximately met for the results to be useful.
- Often use transformations on y-variable to address variance and normality violations.
  - $-\log(Y)$
  - $-\sqrt{(Y)}$
  - rank transformation
  - sign transformation

#### **Rank Transformation**

- Sort all of the data, smallest-to-largest, and call the order number the rank.
- Smallest value has rank 1, second smallest has rank 2, etc, until the largest value has rank n.
- If there are ties, give an average rank.

### Wilcoxen Rank Sum

- Let
  - $n_i$  be the number of observations in group i
  - $-R_{ij}$  the the rank of the jth observation in group i
  - $-n = \sum n_i$
- For each group, calculate the sum of the ranks

$$R_i = \sum_{j=1}^{n_i} R_{ij}$$

- Note, for two groups:  $R_1 + R_2 = n(n+1)/2$
- Under the null hypotheses,

$$R_1 \approx R_2 \approx \frac{n(n+1)}{4}$$

• Let  $W = R_1 - R_2$ 

## Simulating the Sampling Distribution under $H_0$

```
SamplingDist <- mosaic::do(10000) *
Tents %>%
  mutate( Rank.Sim = mosaic::shuffle(Rank) ) %>%
  group_by(Type) %>%
  summarise( R = sum( Rank.Sim ) ) %>%
  summarise( W=diff(R) )
```

### Conclusions

- Nonpparametric tests are more widely applicable than a standard t-test.
- By using rank or sign transformed responses, we cannot make confidence intervals on the scale that is scientifically useful.
- If the usual requirements are met for a t-test, then the standard approach is more powerful and should preferentially be used.