view_frames Result Recorded at time: 1954.746 map Broadcaster: /amcl Average rate: 39.934 Hz Most recent transform: 1954.755 (-0.009 sec old) Buffer length: 4.257 sec odom Broadcaster: /gazebo Average rate: 10.238 Hz Most recent transform: 1954.676 (0.070 sec old) Buffer length: 4.200 sec robot_footprint Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1954.746 sec old) Buffer length: 0.000 sec chassis Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10.225 Hz Average rate: 10.225 Hz Average rate: 10000.000 Hz Most recent transform: 1954.711 (0.035 sec old) Most recent transform: 1954.711 (0.035 sec old) Buffer length: 0.000 sec Buffer length: 4.303 sec Buffer length: 4.303 sec hokuyo left_wheel

Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1954.746 sec old) Buffer length: 0.000 sec camera

Most recent transform: 0.000 (1954.746 sec old)

right_wheel