

OTHER MODELS OF TURING MACHINES

Chap. 10

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Summary

- We essentially challenge Turing's thesis by examining a number of ways the Standard Turing Machine can be complicated to see if these complications increase its power.
- We look at a variety of *different storage devices* and even allow *nondeterminism*.
- *None* of these complications increases the essential power of the standard machine, which lends credibility to Turing's thesis.

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Learning Objectives

- The concept of *equivalence* between classes of *Automata*.
- Describe how a *TM* with a *stay-option* can be simulated by a standard-TM.
- Describe how a standard-TM can be simulated by a machine with a *semi-infinite tape*.
- Describe how *off-line and multidimensional TMs* can be simulated by standard-TMs.
- Construct *two-tape TMs* to accept simple languages.
- Describe the operation of *Nondeterministic TMs* and their relationship to deterministic TMs.
- Describe the components of a *Universal Turing Machine*
- Describe the operation of *Linear Bounded Automata* and their relationship to standard TM.

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Equivalence of Classes of Automata

- Definition 10.1: Two automata are *equivalent* if they accept the same language.
 Given two classes of automata C_1 and C_2 ,
 if for every automaton M_1 in C_1 , there is an equivalent automaton M_2 in C_2 s.t. $L(M_1)=L(M_2)$,
 then the class C_2 is *at least as powerful* as C_1 .
 If the class C_1 is at least as powerful as C_2 , and the converse also holds, then the classes C_1 and C_2 are *equivalent*.
- Equivalence can be established either through a constructive proof or by simulation.

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Turing Machines with a Stay-Option

- In a *Turing Machine with a Stay-Option*, the read-write head has the option to stay in place after rewriting the cell content: $\delta: Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R, S\}$
- Theorem 10.1: The class of TMs with a stay-option is equivalent to the class of Standard TMs.
- To show equivalence, we argue that any machine with a stay-option can be simulated by a standard TM, since the stay-option can be accomplished by
 - A rule that rewrites the symbol and moves Right, and
 - A rule that leaves the tape unchanged and moves Left.

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Turing Machines with a Stay-Option

- Theorem 10.1: The class of TMs with a stay-option is equivalent to the class of Standard TMs.

Proof) Since a TM with a stay-option is an extension of the standard model, any standard TM can be simulated by TM with a stay-option.

Let $M = (Q, \Sigma, \Gamma, \delta, q_0, \square, F)$ be a TM with a stay-option to be simulated by a standard TM $M' = (Q', \Sigma, \Gamma, \delta', q'_0, \square, F)$.

For each move of M ,

- If the move of M does not involve the stay-option, M' performs one move that is identical to M 's move.
- If the move of M involves S , then M' will make two moves:
 - The first *rewrites* the symbol and moves the head *right*;
 - the second moves the head *left*, leaving the tape contents unchanged.

M' can be constructed from M by defining δ' as follows:

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TMs with a Stay-Option (cont.)

- Theorem 10.1: The class of Turing Machines with a stay-option is equivalent to the class of Standard TMs.

Proof: cont.)

M' can be constructed from M by defining δ' as follows:

For each transition,

$$\delta(q_i, a) = (q_j, b, L/R) \Rightarrow \delta'(q'_i, a) = (q'_j, b, L/R)$$

For each S-transition,

$$\delta(q_i, a) = (q_j, b, S) \Rightarrow \begin{aligned} \delta'(q'_i, a) &= (q'_{js}, b, R) \\ \text{and } \delta'(q'_{is}, c) &= (q'_j, c, L) \quad \text{for all } c \in \Gamma. \end{aligned}$$

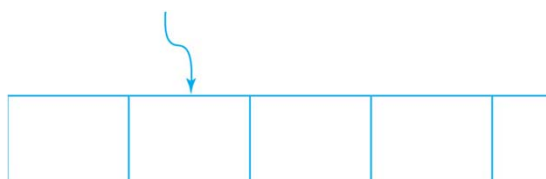
So, every computation of M has a corresponding computation of M' .

Thus, M' can simulate M .

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TMs with Semi-Infinite Tape

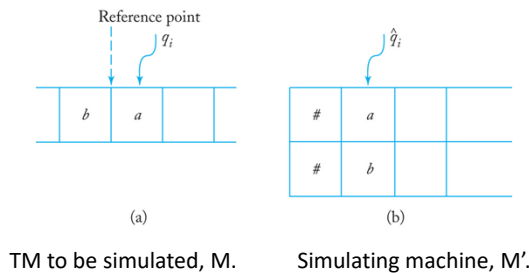
- As shown in Figure below, a common variation of the standard TM is one in which the tape is *unbounded only in one direction*.
- A *TM with semi-infinite tape* is otherwise identical to the standard model, except that *no left move* is possible when the read-write head is at the tape *boundary*.



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Equivalence of Standard TMs and Semi-Infinite Tape Machines

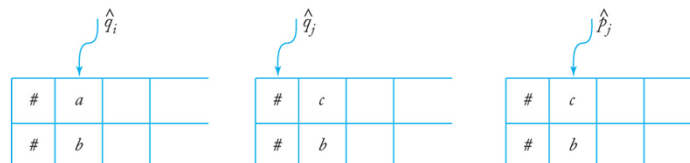
- The classes are equivalent because any standard TM, M , can be simulated by a TM with a semi-infinite tape, M' .
- The simulating machine, M' , has two tracks:
 - the *upper track* contains the symbols to the *right* of an arbitrary reference point, while
 - the *lower track* contains those to the *left* of the reference point in *reverse order*



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Cont.

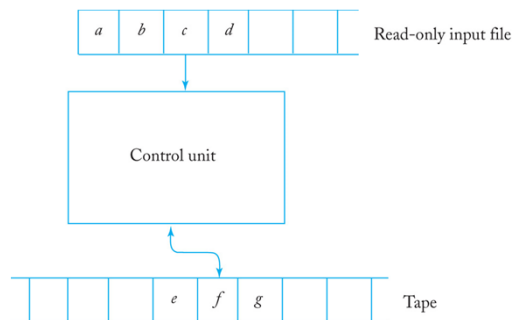
- M' uses information on the upper track only as long as a head of M is to the right of the reference point, and
 - M' works on the lower track as M moves into the left part of its tape.
 - $Q' = Q_U \cup Q_L$: the states working on the upper/lower tracks.
 - $\#$: the end marker on the left boundary of the tape, switching the track.
 - E.g.) $\delta(q_i, a) = (q_j, c, L)$ in $M \Rightarrow \delta'(q_i', (a, b)) = (q_j', (c, b), L)$ in M' , where $q_i' \in Q_U$.
- Then, $\delta'(q_j', (\#, \#)) = (p_j', (\#, \#), R)$ where $p_j' \in Q_L$.
- Now, M' works on the lower track.



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The Off-Line Turing Machine

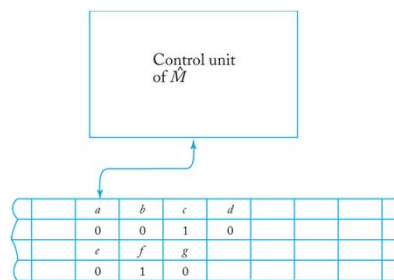
- An *Off-Line TM* has a **read-only input file** in addition to the read-write tape.
- Transitions are determined by both the current input symbol and the current tape symbol.



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Equivalence of Standard TMs and Off-Line TMs

- The classes are equivalent because a standard TM with four tracks can simulate the computation of an off-line machine.
- Two tracks are used to store the *input file contents* and *current position*, while the other two tracks store the *contents* and *current position of the read-write tape*.



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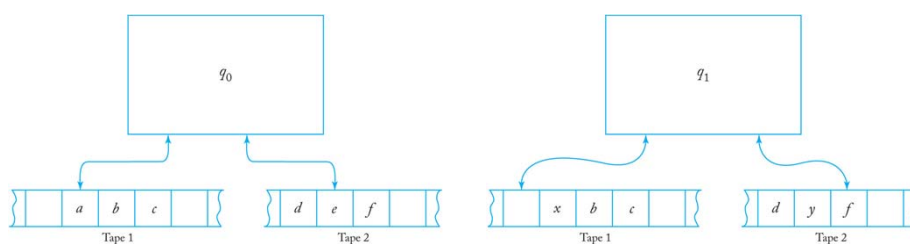
Multitape Turing Machines

- A **MultiTape Turing Machine** has several tapes, each with its own independent read-write head.

$$\delta: Q \times \Gamma^n \rightarrow Q \times \Gamma^n \times \{L, R\}^n$$

- A sample transition rule for a two-tape machine must consider the current symbols on both tapes:

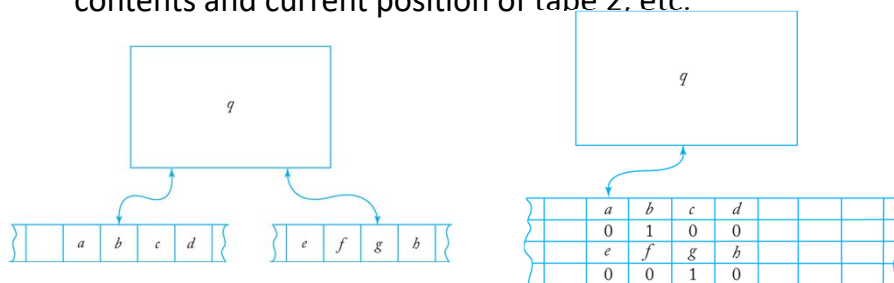
$$\delta(q_0, (a, e)) = (q_1, (x, y), (L, R))$$



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Equivalence of Standard TMs and MultiTape TMs

- The classes are equivalent because a standard TM with multi tracks can simulate the computation of a multitape machine.
- Two tracks are used to store the contents and current position of tape 1, while the other two tracks store the contents and current position of tape 2, etc.



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Equivalence of Standard TMs and MultiTape TMs

Example 10.1: $L = \{a^n b^n\}$.

TM with one tape to accept L in Example 9.7.

A two-tape machine to accept L ? -- easier.

Assume that an initial string $a^n b^n$ is written on tape 1 at the beginning of the computation.

Then, we read all the a 's, copying them onto tape 2.

When we reach the end of the a 's, we match the b 's on tape 1 against the copied a 's on tape 2.

By this way, we can determine whether there are an equal number of a 's and b 's without repeated back-and-forth movement of the read-write head.

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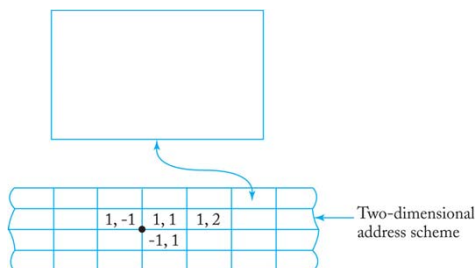
Multidimensional Turing Machines

- A *Multidimensional Turing Machine* has a tape that can extend infinitely in more than one dimension.
- In the case of a two-dimensional machine, the transition function must specify movement along both dimensions:

$$\delta: Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R, U, D\} \text{ where}$$

L, R, U, D specify movement of the head

Left, Right, Up or Down, respectively.



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Equivalence of Standard TMs and Multidimensional TMs

- The classes are equivalent because a standard TM with two tracks can simulate the computation of a two-dimensional machine.
- In the simulating machine, one track is used to store the cell contents and the other one to keep the associated address.
- The configuration in which cell $(1, 2)$ contains a and cell $(10, -3)$ contains b is shown below.
- The address track uses a variable field-size arrangement, using a special symbol to delimit the field.

	a				b						
	1	#	2	#	1	0	#	-	3	#	

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Equivalence of Standard TMs and Multidimensional TMs

- Let's simulate multi(2)-dim TM M in the standard TM M' .
- Assume that, at the start of the simulation of each move, the RW-head of the 2-dim machine M and the RW-head of the simulating machine M' are always on corresponding cells.

To simulate a move, the simulating machine M' first computes the address of the cell to which M is to move.

Once the address is computed, M' finds the cell with this address on track 2 and then changes the cell contents to account for the move of M . In such a way, M can be simulated in M' .

Thus, a multi-dim. TM is equivalent to a standard TM.

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Nondeterministic Turing Machines (NTM)

- A *Nondeterministic Turing Machine* is one with potentially many transition choices for a given (state, symbol) combination.

$$\delta: Q \times \Gamma \rightarrow 2^{Q \times \Gamma \times \{L, R\}}$$

- Example 10.2: A transition rule for Nondeterministic TM:

$$\delta(q_0, a) = \{(q_1, b, R), (q_2, c, L)\}$$

Both $q_0aaa \vdash bq_1aa$ and $q_0aaa \vdash cq_2caa$ are possible.

- Since multiple transitions may be applied at each step, the machine may have multiple active simultaneous threads, any of which may accept the input string when the thread halts.
- For every Nondeterministic TM, there is an equivalent deterministic TM that can simulate its operation.
(+: separator of IDs, x: to delimit the area of interest)

□	×	a	q ₀	a	a	+	b	b	q ₁	a	×	□
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Equivalence of NTM and DTM

- Theorem 10.2: The class of Deterministic TM and Nondeterministic TM are equivalent.

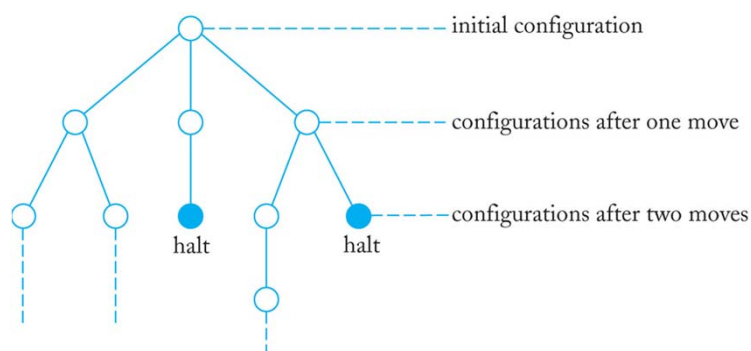
Proof) Construct D-TM to simulate N-TM.

- Since multiple transitions may be applied at each step, the machine may have multiple active simultaneous threads, any of which may accept the input string when the thread halts.
- Keep all possible Instantaneous Descriptions(IDs) of NTM on its tape, separated by some convention (e.g. +): E.g.) aq_0aa, bbq_1a
- For every NTM, there is an equivalent DTM that can simulate its operation. (+: separator of IDs, x: delimiter)
- The simulating machine looks at all active configurations and updates them according to the program of the NTM. New configuration or expanding IDs involve moving 'x' marker.

□	×	a	q ₀	a	a	+	b	b	q ₁	a	×	□
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Configuration Tree of NTM



The width depends on the # of options available on each move.

If $k = \text{max. branching}$, $M = k^n$ is the max # of configurations after n moves.

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Equivalence of NTM and DTM

- Definition 10.3:

A Nondeterministic TM M is said to **accept** a language L

if $\forall w \in L$, *at least one of the possible configurations accepts w :*

$$q_0 w \vdash^* x_1 q_f x_2 \text{ where } q_f \in F, x_1, x_2 \in \Gamma^*$$

i.e. $L = \{ w \mid \exists q_0 w \vdash^* x_1 q_f x_2 \text{ where } q_f \in F, x_1, x_2 \in \Gamma^* \}$.

There may be branches that lead to *nonaccepting configurations*, while some may put the machine into an *infinite loop*.

But these are irrelevant for acceptance.

- A Nondeterministic TM M is said to **decide** a language L

if, for all $w \in \Sigma^*$, there is a *path* that leads

either *to accept w* or *to reject w*
then, *halt*.

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Decidable vs. Acceptable Language: i.e. Recursive vs. Recursively Enumerable Language

- A language is *recursively enumerable (r.e.)* if it is the set of strings *accepted* by some TM, i.e. Turing acceptable language.
- A language is *recursive (rec.)* if it is the set of strings *accepted* by some TM that *halts on every input*.
- For example, any regular language is recursive.

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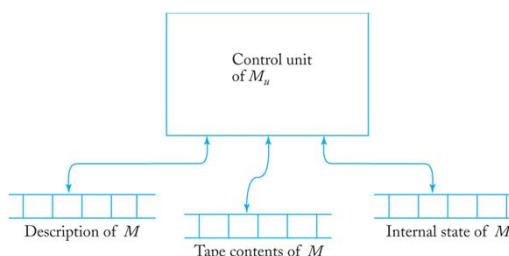
A Universal Turing Machine

- A standard TM is a special purpose computer:
Once δ is defined, TM is restricted to carry out one particular type of computation.
- Digital computer is more general-purpose machine that can be programmed to do different jobs at different times
→ need a TM more in the general purpose machine?
- A *Universal Turing Machine* is a reprogrammable TM which, given as input the description of a TM M and a string w , can simulate the computation of M on w .
- A Universal TM has the structure of a multitape machine.

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A Universal Turing Machine

- A **Universal TM (M_u)** is a reprogrammable TM which, given as input the description/encoding of a TM M ($\langle M \rangle$), and a string w ($\langle w \rangle$), can simulate the computation of M on w .
- A Universal TM has the structure of a multitape machine:
 - Tape 1: Description of M
 - Tape 2: Tape Contents of M
 - Tape 3: Internal state of M



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A Universal Turing Machine

- A universal-TM M_u is an automaton that, given as input the *description of any TM M* and a *string w* , can simulate the computation of M on w .
- To construct such an M_u , we first choose a standard way of describing Turing Machines: i.e. encoding of TM M , $\langle M \rangle$

Encoding of the states Q and the tape symbols Γ :

Assume that $Q = \{q_1, q_2, \dots, q_n\}$, $\Gamma = \{a_1, a_2, \dots, a_m\}$, with q_1 the **initial state**, q_2 the **single final state**, and where a_1 represents the **blank**. We then select an encoding in which q_1 is represented by 1, q_2 is represented by 11, and so on. Similarly, a_1 is encoded as 1, a_2 as 11, etc.

The symbol 0 will be used as a separator between the 1's.

With the initial and final state and the blank defined by this convention, any TM can be described completely with δ only.

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A Universal Turing Machine

Encoding of the transition function δ :

- The transition function is encoded according to this scheme, with the arguments and result in some prescribed sequence.
- For example, $\delta(q_1, a_2) = (q_2, a_3, L)$ might appear as
 $\dots 10110110111010\dots$
- So, any TM has a *finite encoding as a string on $\{0, 1\}^+$* and that, given any encoding of M ($\langle M \rangle$), we can decode it uniquely.

Some strings will not represent any TM (e.g., the string 00011).

- A universal-TM, M_u , then has an input alphabet including $\{0, 1\}$ and the structure of a multitape machine.
- M_u looks at the contents of tapes 2 (input symbol) and tape 3 (current state) to determine the configuration of M .
 - Then, M_u consults tape 1 for a transition δ of M in this configuration.
 - Finally, tapes 2 and 3 will be modified to reflect the result of the transition.

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Cantor and Infinity (from Goddard's: chap. 14)

Equal-Size Sets:

- If two *finite sets* are the equal size, one can pair the sets off: e.g.) 10 apples with 10 oranges. This is called a *1–1 correspondence*: every apple and every orange is used up.
- So, we say
two infinite sets, A and B are the equal size ($|A| = |B|$) if there exists a 1–1 correspondence.
 In mathematics, *there exists a bijective function f*
(both injection (=into) and surjection (=onto))
 $f: A \rightarrow B$.

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Cantor and Infinity (from Goddard's: chap. 14)

Countable Sets:

- Define \mathbb{N} to be the set of all positive integers: $\{1, 2, 3, \dots\}$.
- The set of the positive *even numbers* are the equal size as \mathbb{N} :
 - $\exists f: i \rightarrow 2i \quad \forall i \in \mathbb{N}$
 - one can pair 1 with 2, 2 with 4, 3 with 6, and so on.

Note that the even numbers are used up: $1 - 2, 2 - 4, 3 - 6, \dots$

- A set is *countably infinite* if the equal size as \mathbb{N} : $|A| = |\mathbb{N}|$
- A set is *countable* if *finite or countably infinite*.
i.e. there is a numbered *enumeration* of all elements.
- E.g.) The rational numbers are countable.
- But, there are sets that are *NOT countable*:
uncountably infinite or uncountable: e.g.) The real numbers.

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Cantor and Infinity (from Goddard's: chap. 14 & chap.10 of Lintz)

- Example: The rational numbers (\mathbb{Q}) are countable.

Enumeration procedure: How to enumerate the set of rational numbers?

A rational number is a quotient of the form p/q where $p, q \in \mathbb{N}$.

$1/1, 1/2, 1/3, 1/4, \dots$

$2/1, 2/2, 2/3, 2/4, \dots$

$3/1, 3/2, 3/3, 3/4, \dots$

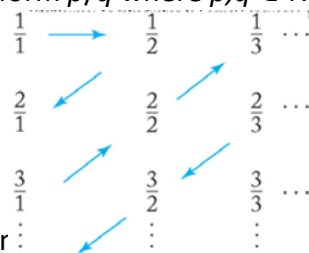
.....

Count (or list, enumerate) them diagonally:

i.e. list p/q in the non-decreasing order of $(p+q)$,

$1/1, (2/2, 3/1), (4/1, 5/2, 6/3), (7/3, 8/2, 9/1), (10/5, 11/4, 12/3, 13/2, 14/1), \dots$

So, there exists a function $f: \mathbb{N} \rightarrow \mathbb{Q}$. Therefore, \mathbb{Q} is countable.



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Cantor's Diagonalization (from Goddard's)

- Given a list of words, one can construct a word not on the list:
Start with the diagonal as a word, and then
replace each letter by the next letter in the alphabet.

- Example:

1.	Q	U	I	E	T
2.	S	T	O	N	E
3.	O	F	F	E	R
4.	C	L	E	A	R
5.	P	H	L	O	X

Here diagonalization produces **RUGBY**. This is not on the list.

- Diagonalization Always Gives New Word:

The new word cannot be on the list:

it is different from 1st word in 1st letter,

different from 2nd word in 2nd letter, etc.

- Cantor's insight was that same idea works with infinite lists...

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Cantor's Theorem (Goddard's and Th^m 11.1@Linz)

- Theorem 11.1: Let S be an countably infinite set.
Then, its powerset 2^S (or $\wp(S)$) is not countable.
- Cantor's Theorem: The powerset $\wp(N)$ is *not countable*.

Proof by Contradiction)

Suppose $\wp(N)$ is countable. It means we can write down
a enumeration of all the subsets of N .

Maybe the list starts: 1 – N , 2 – $\{4, 7\}$, 3 – $\{2, 4, 6, 8\}$, 4 – \emptyset , ...

i.e. We have a function $f: N \rightarrow \wp(N)$ that maps numbers to
subsets s.t. every subset appears in the list.

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Cantor's Theorem (cont.)

- Cantor's Theorem: The powerset $\wp(N)$ is not countable.

Proof by Contradiction: cont.)

Now, define a subset T on N :

For each number $i \in N$, look up $f(i)$ and add i to T if $i \notin f(i)$.

But: T is not on list. Why?

- $T \neq f(1)$, because T and $f(1)$ differ on 1.
(by definition $1 \in T \Leftrightarrow 1 \notin f(1)$).
- $T \neq f(2)$, because T and $f(2)$ differ on 2. (by def., $2 \in T \Leftrightarrow 2 \notin f(2)$)
- and so on.

Contradiction!! i.e. f is a lie; it doesn't use up the sets in $\wp(N)$.

It means: such an enumeration doesn't exist.

i.e. There doesn't exist such a 1 – 1 function $f: N \rightarrow \wp(N)$.

Therefore, $\wp(N)$ is not countable. Q.E.D.

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Cantor's Theorem (cont.)

Immediate Implication of Cantor's Theorem:

- 1) For any alphabet, the set of TMs is countable.
 - 2) For any alphabet, the set of languages is uncountable.
- The set of TMs is countable
because each TM can be represented by a *binary number* in its encoding $\langle M \rangle$, hence as an *integer*.
 - However, the subsets of the integers are not countable and hence the number of languages is uncountable.
 - Therefore, there exists the languages that are not accepted by any TM, i.e. not recursively enumerable.

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Enumeration Procedure

- Definition 10.4: Let S be a set of strings on some alphabet Σ . Then, an *enumeration procedure* for S is a TM that can carry out the sequence of steps

$$q_0 \vdash^* q_s x_1 \# s_1 \vdash^* q_s x_2 \# s_2 \dots,$$

with $x_i \in \Gamma^* - \{\#\}$, $s_i \in S$, in such a way that any $s \in S$ is produced in a finite number of steps.

The state q_s is a state signifying membership in S ; i.e., whenever q_s is entered, the string following $\#$ must be in S .

- Note: Not every set is countable, i.e. there are some uncountable sets.
- Any set for which an enumeration procedure exists is countable.
- Since S is infinite, an enumeration procedure can't be called an algorithm as it won't terminate.

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Countability of TM

- Theorem 10.3: The set of all TMs is countable, although infinite.

Proof) Encode each TM using 0 and 1.

With this encoding, construct the following enumeration procedure.

1. Generate the next string in $\{0, 1\}^+$ in proper order.
2. Check the generated string to see if it defines a TM.
If so, write it on the tape in the form required by Def. 10.4.
If not, ignore the string.
3. Return to Step 1.

Since every TM has a finite description, any specific machine will eventually be generated by this process.

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Linear Bounded Automata (LBA)

- The power of a standard TM can be restricted by limiting the area of the tape that can be used.
- E.g.) A PDA may be a N-TM with a tape that is restricted to being used like a stack.
- A *Linear Bounded Automaton (LBA)* is a TM that restricts the usable part of the tape to exactly the cells used by the input.
i.e. $|\text{work space}| = |\text{input size}|$
- Input can be considered as bracketed by two special symbols or markers which can be neither overwritten nor skipped by the read-write head: e.g.) $[w]$
- LBAs are assumed to be *Nondeterministic-TM* and accept languages in the same manner as other TM accepters.

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Linear Bounded Automata (LBA)

- Definition 10.5: A *Linear Bounded Automaton* is a Nondeterministic TM $M = (Q, \Sigma, \Gamma, \delta, q_0, \square, F)$, subject to the restriction that Σ must contain two special symbols $[$ and $]$, such that
 $\delta(q_i, [)$ can contain only elements of the form $(q_j, [, R)$, and
 $\delta(q_i,])$ can contain only elements of the form $(q_j,], L)$.

- Definition 10.6: A string w is *accepted* by a LBA if there is a possible sequence of moves

$$q_0[w] \vdash^* [x_1 q_f x_2] \quad \text{for some } q_f \in F, x_1, x_2 \in \Gamma^*.$$

The language accepted by the LBA is the set of all such accepted strings.

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Languages Accepted by Linear Bounded Automata

- It can be shown that any Context-Free Language can be accepted by a Linear Bounded Automaton.
- In addition, LBA can be designed to accept languages which are *not* context-free, such as

$$L = \{ a^n b^n c^n \mid n \geq 1 \}$$

- Example 9.8: TM for L didn't require space outside the original input w , so it can be carried out by a LBA.
- LBA are *not as powerful as* standard Turing machines, while it is difficult to come up with a concrete and explicitly defined language to use as an example.

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Languages Accepted by LBA (Cont.)

- Example 10.5: Find a LBA that accepts

$$L = \{ a^{n!} \mid n \geq 1 \}$$

Divide the number of a 's successively by 2, 3, 4, ..., until we can either accept or reject the string.

If the input is in L , eventually there will be a single a left;

if not, at some point a nonzero remainder will arise.

In a multitrack LBA, use the extra tracks as works pace. Let's use 2-track tape.

1st track: contains the number of a 's left during the process of division,

2nd track: contains the current divisor.

Using the divisor on the 2nd track, we divide the number of a 's on the 1st track, by removing all symbols except those at multiples of the divisor.

After this, we increment the divisor by one, and continue until we either find a nonzero remainder ($w \notin L$) or are left with a single a ($w \in L$).

	[a	a	a	a	a	a]	a 's to be examined
	[a	a	a]	Current divisor

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Languages Accepted by LBA (Cont.)

- Example 10.5: Find a LBA that accepts

$$L = \{ a^{n!} \mid n \geq 1 \}$$

Divide the number of a 's successively by 2, 3, 4, ..., until we can either accept or reject the string. In 2-track tape LBA,

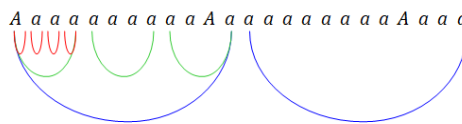
1st track: contains the number of a 's left during the process of division,

2nd track: contains the current divisor.

Using the divisor on the 2nd track, we divide the number of a 's on the 1st track, by removing all symbols except those at multiples of the divisor.

After this, we increment the divisor by one, and continue until we either find a nonzero remainder or are left with a single a .

Example: $a^{4!} = a^{24}$



For a divided subsubstring, divide it by 4,

.....
until there is a single symbol a
or a nonzero remainder

For a divided substring, divide it by 3

Divide a string by 2

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Languages Accepted by LBA (Cont.)

- So, LBA is more powerful than PDA in the Examples where neither of the languages is CFL.
- There exists CFL that can be accepted by an LBA not by a PDA.
- The class of LBA is less powerful than the class of unrestricted TMs.

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