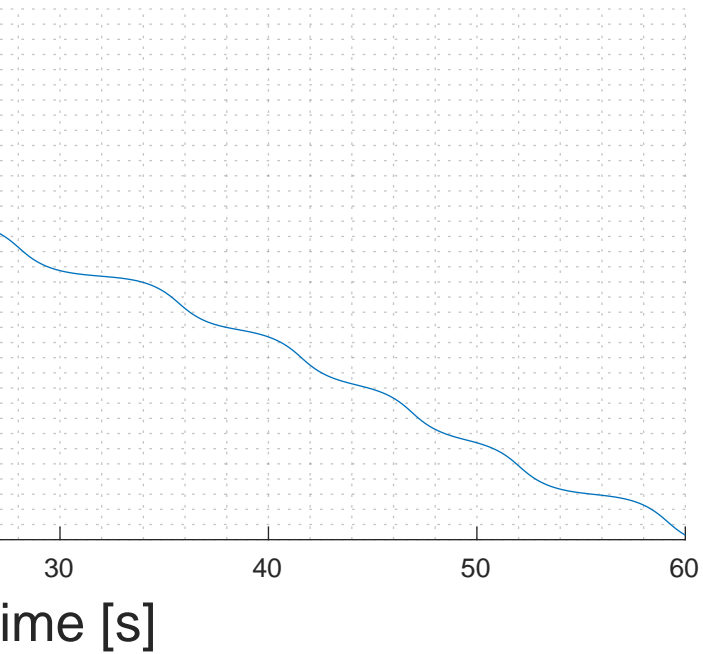
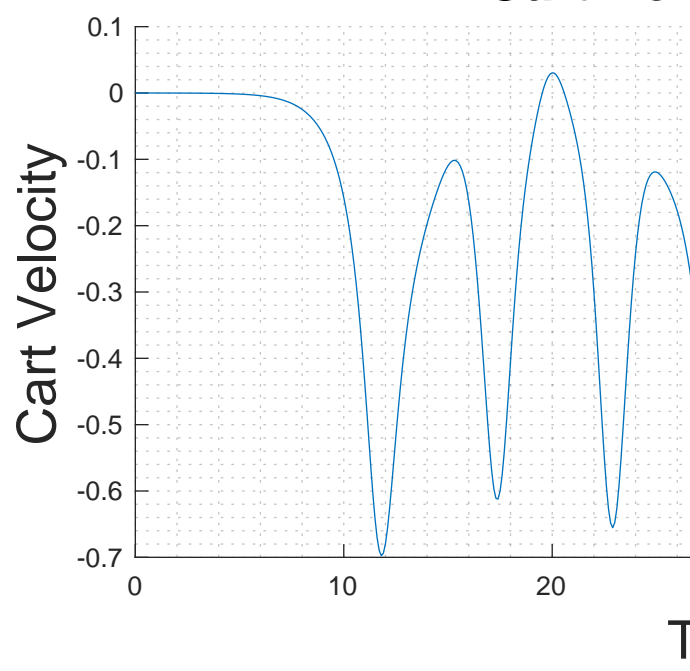
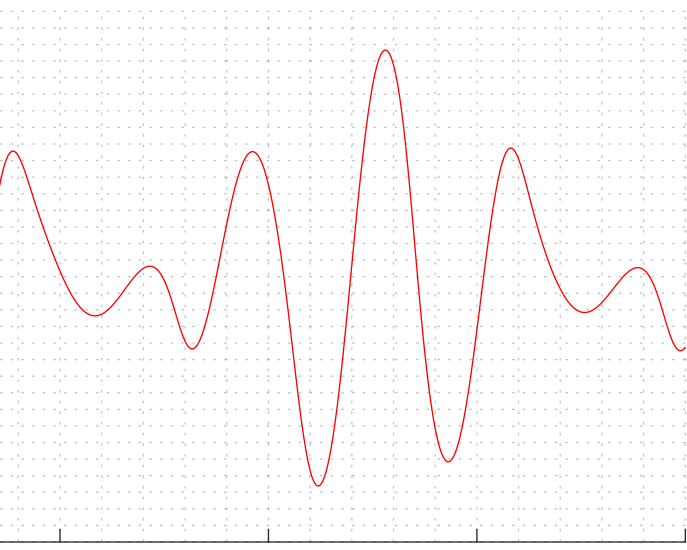


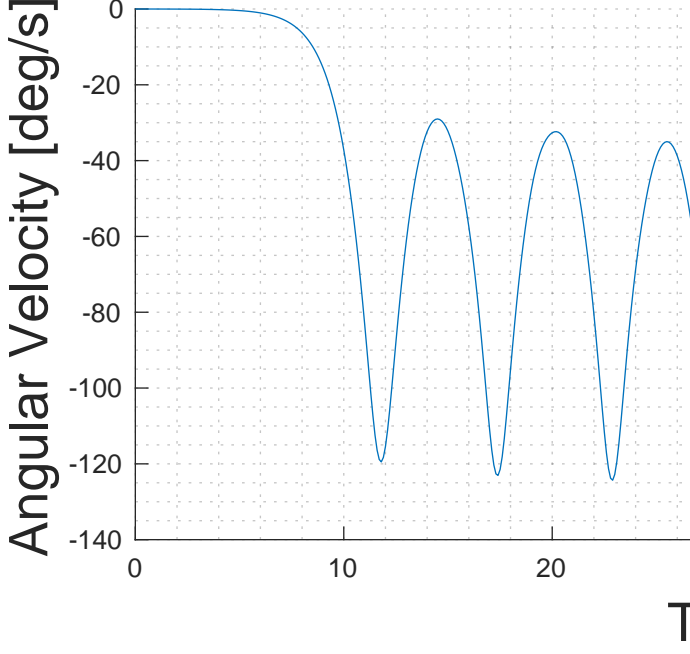
Position vs. Time



Position vs. Time



θ_1 Angular



θ_2 Angular