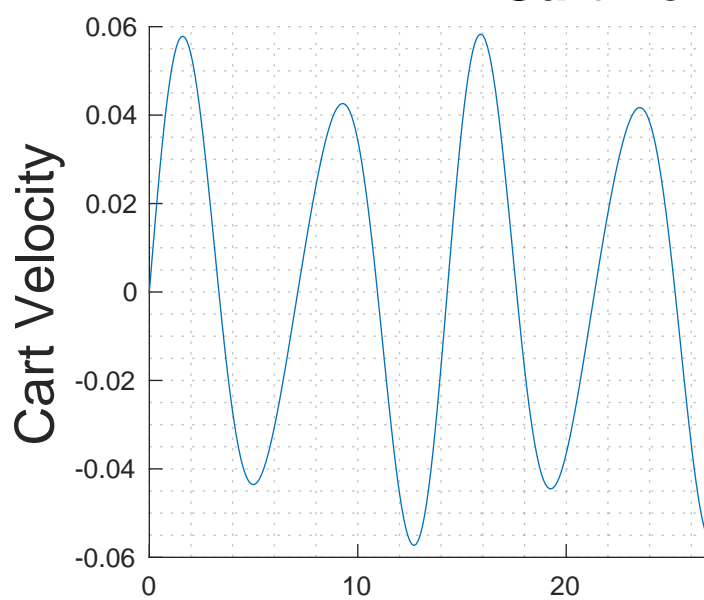


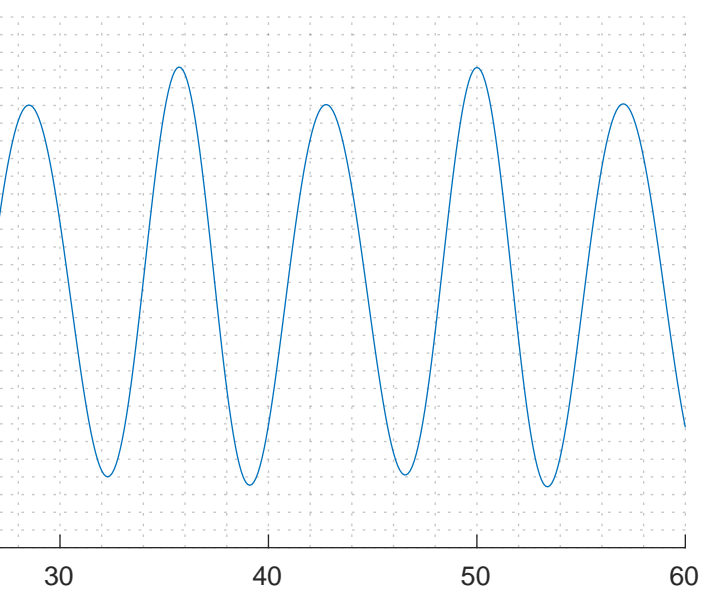
Time [s]

**Position vs. Time**



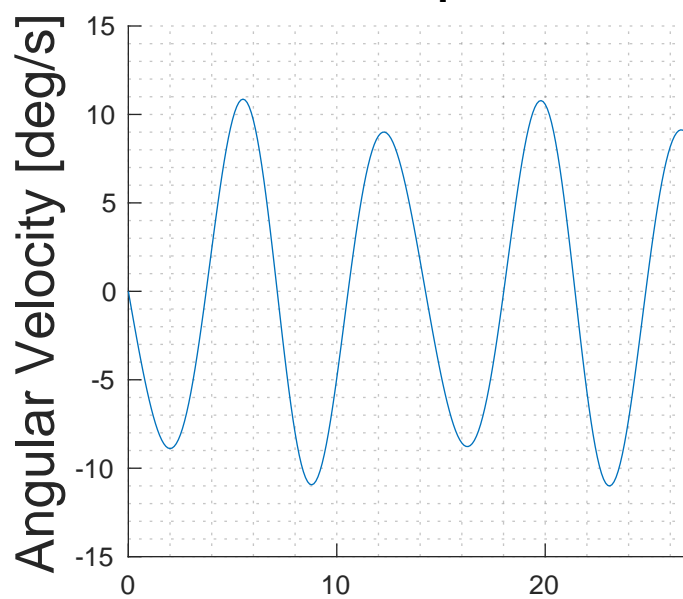
Time [s]

**$\theta_1$  Angular**



Time [s]

**Position vs. Time**



Time [s]

**$\theta_2$  Angular**

