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```
function dx = linearizedTwoPendulumTwoCart(t,x,A,B)
```

```
    u = 0;
```

```
    dx = A * x + B * u;
```

```
end
```

```
Not enough input arguments.
```

```
Error in linearizedTwoPendulumTwoCart (line 5)
```

```
    dx = A * x + B * u;  
        ^
```

*Published with MATLAB® R2024b*