Question 5

This script designs a Blackman-windowed differentiator filter and explores some of its properties.

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In [ ]: from pathlib import Path
        import matplotlib.pyplot as plt
        import numpy as np
        import seaborn as sns
        from a2 config import A2 ROOT, SAVEFIG CONFIG
In [ ]: # Define filter specifications
        N_TAPS = 25  # number of filter taps
F_SAMP = 50  # sampling frequency, kHz
        F_BAND = [0, 20] # operating frequency range, kHz
In [ ]: import scipy.signal as signal
        def plot_impz(t, coeffs, fname=None):
            fig, ax = plt.subplots(figsize=(6, 2))
            fig.tight_layout()
            plt.stem(t, coeffs, linefmt="C0", basefmt="C0")
            # Axis Labels
            ax.set_xlabel("Time (ms)")
            ax.set_ylabel("Response")
            # Save or just short
            if fname:
                 fig.savefig(Path(A2_ROOT, "output", fname), **SAVEFIG_CONFIG)
            plt.show()
        # Define differentiator filter
        taps = signal.remez(N TAPS, F BAND, [1], type="differentiator", fs=F SAMP)
        t = np.arange(0, N_TAPS/F_SAMP, 1/F_SAMP)
        plot_impz(t, taps, fname="q5_diff_impz.png")
In [ ]: from scipy.fft import fft, ifft
        from scipy.signal.windows import blackman
        # Helper function for converting frequency response to dB scale
        dB = lambda x: 20 * np.log10(x)
        def plot_freqz(w, h, fname=None):
             """Plot frequency response and overlay filter requirements."""
            fig, axs = plt.subplots(3, sharex=True, figsize=(6, 4))
            fig.tight layout()
             sns.lineplot(x=w, y=np.abs(h), ax=axs[0], label="Realistic")
             sns.lineplot(x=w, y=0.02 * w, ax=axs[0], ls=":", label="Ideal")
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sns.lineplot(x=w, y=dB(np.abs(h)), ax=axs[1])
            sns.lineplot(x=w, y=np.angle(h), ax=axs[2])
            # Axis labels
            axs[0].set_ylabel("Gain")
            axs[0].legend(framealpha=1)
            axs[1].set ylabel("Gain (dB)")
            axs[2].set xlabel("Frequency (kHz)")
            axs[2].set_ylabel("Phase (rad)")
            axs[2].set yticks([-np.pi, 0, np.pi])
            axs[2].set_yticklabels(["$-\pi$", "0", "$\pi$"])
            # Save or just show
            if fname:
                fig.savefig(Path(A2_ROOT, "output", fname), **SAVEFIG_CONFIG)
            plt.show()
        # Apply Blackman window
        h_blackman = taps * blackman(N_TAPS)
        f, H blackman = signal.freqz(h blackman, [1], fs=F SAMP)
        plot_freqz(f, H_blackman, fname="q5_diff_freqz.png")
In [ ]: # Generate sample "continuous" functions to test the differentiator filter
        t = np.linspace(0, 1, 512, endpoint=False)
        t_tri = signal.sawtooth(2 * np.pi * 5 * t)
        t sqr = signal.square(2 * np.pi * 5 * t)
        t \sin = np.sin(2 * np.pi * 5 * t)
        # Apply the differentiator filter
        filt_tri = ifft(fft(t_tri) * H_blackman)
        filt sqr = ifft(fft(t sqr) * H blackman)
        filt_sin = ifft(fft(t_sin) * H_blackman)
        # Plot unfiltered and filtered comparison
        normalise = lambda arr: arr.real / max(np.abs(arr.real))
        fig, axs = plt.subplots(3, sharex=True, figsize=(6, 4))
        fig.tight layout()
        axs[0].plot(t, t_tri, label="Triangle Wave")
        axs[0].plot(t, normalise(filt_tri), label="Norm. Deriv.")
        axs[1].plot(t, t_sqr, label="Square Wave")
        axs[1].plot(t, normalise(filt_sqr), label="Norm. Deriv.")
        axs[2].plot(t, t_sin, label="Sine Wave")
        axs[2].plot(t, normalise(filt sin), label="Norm. Deriv.")
        # Axis labels
        axs[2].set_xlabel("Time (ms)")
        axs[1].set ylabel("Normalised Response")
        axs[0].legend(loc="upper right", framealpha=1)
        axs[1].legend(loc="upper right", framealpha=1)
        axs[2].legend(loc="upper right", framealpha=1)
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fname = Path(A2_ROOT, "output", "q5_diff_applied.png")

fig.savefig(fname, **SAVEFIG_CONFIG)