# ELEC4620 Assignment 1

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## Question 1

The function for a rectangular pulse around t = 0, with amplitude A and width T, is:

$$h(t) = \begin{cases} A, & |t| < T/2 \\ 0, & |t| > T/2 \end{cases}$$

This is equivalently two step functions of equal magnitude and opposite sign at  $t = \pm T/2$ . Hence, the derivative of the rectangular pulse is composed of two impulses of equal magnitude and opposite sign, coinciding in time with the discontinuities in the pulse.

$$h'(t) = A\delta(t + \frac{T}{2}) - A\delta(t - \frac{T}{2})$$

Taking the Fourier transform of the derivative, which by definition is

$$\widehat{H'}(f) := \int_{-\infty}^{\infty} h'(t)e^{-j2\pi ft}dt$$

we aim to evaluate the following expression, split into two integrals for simplicity.

$$\widehat{H'}(f) = A \int_{-\infty}^{\infty} \delta(t + \frac{T}{2}) e^{-j2\pi f t} dt - A \int_{-\infty}^{\infty} \delta(t - \frac{T}{2}) e^{-j2\pi f t} dt$$

By definition of the Dirac delta,  $\delta(t-T)$ , for arbitrary T:

$$\delta(t-T) = \begin{cases} \infty, & t = T \\ 0, & t \neq T \end{cases} \quad \text{and} \quad \int_{-\infty}^{\infty} \delta(t-T)dt = 1$$

Therefore, the Fourier transform of the derivative simplifies to

$$\widehat{H'}(f) = Ae^{-j2\pi f(-T/2)} - Ae^{-j2\pi f(T/2)} = A\left[e^{j\pi fT} - e^{-j\pi fT}\right]$$

Finally, we can integrate in the time domain by dividing by  $j2\pi f$  in the frequency domain.

$$H(f) = \frac{A}{i2\pi f} \left[ e^{j\pi fT} - e^{-j\pi fT} \right]$$

Some re-arranging and substitutions can be performed to neaten the result, if desired:

$$H(f) = \frac{A}{\pi f} \sin(\pi T f) = AT \frac{\sin(\pi T f)}{\pi T f} = AT \operatorname{sinc}(T f)$$

Thus, we have derived the Fourier transform of a rectangular pulse.

We now repeat this procedure for a triangle function using a double derivative. The function for a triangular pulse around t = 0, with amplitude A and width T, is:

$$h(t) = \begin{cases} A(1-2|t|/T), & |t| \le T/2\\ 0, & |t| > T/2 \end{cases}$$

The first derivative produces a result composed of two rectangular pulses of equal magnitude and opposite sign, or equivalently three step functions.

$$h'(t) = \begin{cases} 2A/T, & -T/2 \le t \le 0\\ -2A/T, & 0 \le t \le T/2\\ 0, & |t| > T/2 \end{cases}$$

Hence, as before, the second derivative is composed of three impulses coinciding with the discontinuities in the first derivative.

$$h''(t) = \frac{2A}{T}\delta(t + \frac{T}{2}) - \frac{4A}{T}\delta(t) + \frac{2A}{T}\delta(t - \frac{T}{2})$$

The Fourier transform of the second derivative is therefore

$$\widehat{H''}(f) = \frac{2A}{T} \int_{-\infty}^{\infty} \delta(t + \frac{T}{2}) e^{-j2\pi f t} dt - \frac{4A}{T} \int_{-\infty}^{\infty} \delta(t) e^{-j2\pi f t} dt + \frac{2A}{T} \int_{-\infty}^{\infty} \delta(t - \frac{T}{2}) e^{-j2\pi f t} dt$$

Once again, using the definition of the Dirac delta, the Fourier transform simplifies to

$$\widehat{H''}(f) = \frac{2A}{T} \left[ e^{-j2\pi f(-T/2)} - 2e^{-j2\pi f(0)} + e^{-j2\pi f(T/2)} \right]$$

and further to

$$\widehat{H''}(f) = \frac{2A}{T} \left[ e^{j\pi fT} - 2 + e^{-j\pi fT} \right]$$

We can integrate twice in the time domain by dividing by  $(j2\pi f)^2$  in the frequency domain.

$$H(f) = \frac{2A}{(j2\pi f)^2 T} \left[ e^{j\pi fT} - 2 + e^{-j\pi fT} \right] = \frac{-A}{2\pi^2 f^2 T} \left[ e^{j\pi fT} - 2 + e^{-j\pi fT} \right]$$

Finally, as with the rectangular pulse, we can re-arrange this result into a more familiar form:

$$H(f) = \frac{A}{\pi^2 f^2 T} (1 - \cos(\pi T f))$$

Thus, we have derived the Fourier transform of a triangular pulse.

Having derived the Fourier transforms of the two functions, we are interested in comparing the rates at which their magnitudes decrease as frequency increases. We note the only term contributing to a change in magnitude with frequency is the 1/f term for the rectangular pulse, and the  $1/f^2$  term for the triangular pulse.

Indeed, in general, if a function has discontinuities in the  $n^{\rm th}$  derivative, the sidelobes of its Fourier transform will fall off as  $1/f^{n+1}$ . Intuitively, this is because the function must be derived n+1 times to obtain a number of impulses which can be Fourier transformed without yielding any frequency-dependent coefficients. The transform of the derivative is then integrated n+1 times by dividing by  $(j2\pi f)^{n+1}$ ; hence, the term  $1/f^{n+1}$  is produced.

Figure 1.1 presents the Fourier transforms of the rectangular and triangular pulses, enabling a visual comparison of the rates at which their sidelobes fall off.

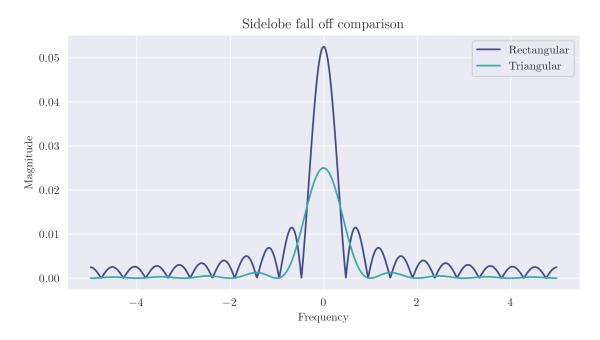


Figure 1.1: Fourier transform sidelobe fall off comparison: rectangular and triangular pulses.

Denote the given polynomials in z by X(z) and Y(z), as follows:

$$X(z) = 1 + 2z^{-1} + 6z^{-2} + 11z^{-3} + 15z^{-4} + 12z^{-5}$$
$$Y(z) = 1 - 3z^{-1} - 3z^{-2} + 7z^{-3} - 7z^{-4} + 3z^{-5}$$

Their corresponding vectors are constructed from their respective coefficients:

$$v_X = [1, 2, 6, 11, 15, 12]$$
 and  $v_Y = [1, -3, -3, 7, -7, 3]$ 

The result of multiplying X(z) and Y(z) can be obtained by convolving their respective vectors and interpreting the outcome as the coefficients of the polynomial product. That is,

$$v_X * v_Y = [1, -1, -3, -6, -29, -35, -40, 10, 12, -39, 36]$$

This can be calculated using the convolve function from the Python scipy.signal library:

which calculates the full discrete linear convolution, automatically zero-padding the vectors as necessary, using traditional convolution (i.e. multiplying and summing, as opposed to the FFT).

Hence, we can interpret the convolution result as the polynomial product of X(z) and Y(z) as

$$1 - z^{-1} - 3z^{-2} - 6z^{-3} - 29z^{-4} - 35z^{-5} - 40z^{-6} + 10z^{-7} + 12z^{-8} - 39z^{-9} + 36z^{-10}$$

Since convolution is equivalent to multiplication in the Fourier domain, we could equivalently Fourier transform both vectors, multiply in the Fourier domain, then perform an inverse Fourier transform to obtain the same vector of coefficients derived above.

When doing this in Python, we must manually zero-pad the vectors before performing the FFT.

Here, the Python numpy package is used to zero-pad both vectors on the right side only to the appropriate length. Then, fft and ifft from scipy.fft can be applied:

This calculates the following vector, which we can observe is identical to the vector determined through direct convolution:

Hence, the same polynomial product can be constructed from either convolving the vector representations of the polynomials, or multiplying the Fourier transforms of the vectors, then taking the inverse Fourier transform.

Given the following numbers in base 10, we seek to apply similar methods to Question 2 to multiply the numbers, first using convolution, then using Fourier transform techniques.

$$x = 8755790$$
 and  $y = 1367267$ 

First, however, we can perform regular multiplication to determine the correct answer that we should get from the convolution and Fourier transform methods:

$$8755790 \times 1367267 = 11971502725930$$

Next, the numbers are constructed digit-wise into vectors:

$$v_x = [8, 7, 5, 5, 7, 9, 0]$$
 and  $v_y = [1, 3, 6, 7, 2, 6, 7]$ 

As before, the result of multiplying x and y can be obtained by convolving their respective vectors. However, the "carry" step must then be performed to produce a number in base 10.

Once again, using convolve from scipy.signal with the same keyword arguments:

$$v_x * v_y = [8, 31, 74, 118, 117, 157, 212, 192, 142, 95, 103, 63, 0]$$

Now, however, unlike with the polynomial multiplication, we cannot expect to arrive at the correct value by simply stringing together all of these digits. Instead, starting from the right, each value must be taken modulo 10, and the remainder added to the value immediately to the left. This yields the following vector, which now can be concatenated into the result of  $x \times y$ :

$$[1,1,9,7,1,5,0,2,7,2,5,9,3,0] \longrightarrow 11971502725930$$

Naturally, the same outcome can be achieved by Fourier transforming the vectors, multiplying in the Fourier domain, then inverse Fourier transforming the result. Again, in Python, the vectors must be zero-padded before performing the FFT.

Then, using the same Python function calls as from Question 2:

```
ifft(fft(vx) * fft(vy)) = [8. 31. 74. 118. 117. 157. 212. 192. 142. 95. 103. 63. 0.]
```

The result is identical to the vector produced by convolution. Therefore, applying the same "carrying" process will yield the same number result.

Hence, integer multiplication also can be accomplished by either convolving the vector representations of the numbers and converting to base 10, or multiplying the Fourier transforms of the vectors, then taking the inverse Fourier transform and converting to base 10.

a) First, we individually transform the sequences using the fft function from scipy.fft:

$$\begin{split} \mathtt{fft(x)} &= [34, \ -1.879 + j6.536, \ -5 + j7, \ -6.121 + j0.536, \\ 0, \ -6.121 - j0.536, \ -5 - j7, \ -1.879 - j6.536] \\ \mathtt{fft(y)} &= [28, \ 2.243 + j4.243, \ -2 - j2, \ -6.243 + j4.243, \\ -8, \ -6.243 - j4.243, \ -2 + j2, \ 2.243 - j4.243] \end{split}$$

Now, we combine x and y element-wise into a single complex vector:

$$z = \begin{bmatrix} 1+j & 2+j5 & 4+j3 & 4+j & 5+j3 & 3+j5 & 7+j3 & 8+j7 \end{bmatrix}$$

and Fourier transform this to obtain:

$$\begin{aligned} \mathtt{fft(z)} &= [34 + j28, \ -6.121 + j8.778, \ -3 + j5, \ -10.364 - j5.707, \\ &- j8, \ -1.879 - j6.778, \ -7 - j9, \ 2.364 - j4.293] \end{aligned}$$

The Fourier transforms of x and y can be determined from the Fourier transform of z as

$$X = \text{Ev}(\text{Re}(Z)) + j\text{Od}(\text{Im}(Z))$$
$$Y = \text{Ev}(\text{Im}(Z)) - j\text{Od}(\text{Re}(Z))$$

where Z is the Fourier transform of z. Since x is purely real and y purely imaginary, the Fourier transform of x has a purely even real component and purely odd imaginary component, and vice versa for the Fourier transform of y. Even and odd components are orthogonal; hence, X and Y can be independently reconstructed.

The even and odd components of a sequence H(n) are determined as:

$$Ev(n) = \frac{H(n) + H(-n)}{2}$$
  $Od(n) = \frac{H(n) - H(-n)}{2}$ 

where H(-n) is the vector H with all elements after the first in reversed order. Hence,

$$\begin{aligned} & \text{Ev}(\text{Re}(Z)) = [34, \ -1.879, \ -5, \ -6.121, \ 0, \ -6.121, \ -5, \ -1.879] \\ & \text{Od}(\text{Im}(Z)) = [0, \ 6.536, \ 7, \ 0.536, \ 0, \ -0.536, \ -7, \ -6.535] \\ & \text{Ev}(\text{Im}(Z)) = [28, \ 2.243, \ -2, \ -6.243, \ -8, \ -6.243, \ -2, \ 2.243] \\ & \text{Od}(\text{Re}(Z)) = [0, \ -4, \ 243, \ 2, \ -4, 243, \ 0, \ 4.243, \ -2, \ 4.243] \end{aligned}$$

wherein from the second element of each vector onward, the even and odd symmetries can be observed. Finally, we can reconstruct the individual Fourier transforms of x and y:

$$\begin{split} X &= [34, \ -1.879 + j6.536, \ -5 + j7, \ -6.121 + j0.536, \\ 0, \ -6.121 - j0.536, \ -5 - j7, \ -1.879 - j6.536] \\ Y &= [28, \ 2.243 + j4.243, \ -2 - j2, \ -6.243 + j4.243, \\ -8, \ -6.243 - j4.243, \ -2 + j2, \ 2.243 - j4.243] \end{split}$$

Comparing these vectors to those determined individually at the start, we can see they are identical. Therefore, we have shown that the double transform algorithm gives the same answer as directly transforming the sequences.

b) In the previous part, the double transform algorithm was applied to sequences of equal length. However, it is also applicable to sequences of unequal length by right-padding the shorter sequence with zero. For example,

$$x = [1 \ 2 \ 4 \ 4 \ 5 \ 3 \ 7 \ 8]$$
  $y = [1 \ 5 \ 3 \ 1 \ 3 \ 5 \ 3 \ 0]$ 

The individual Fourier transforms of x and y are:

$$\begin{split} \texttt{fft(x)} &= [34, \ -1.879 + j6.536, \ -5 + j7, \ -6.121 + j0.536 \\ &\quad 0, \ -6.121 - j0.536, \ -5 - j7, \ -1.879 - j6.536] \\ \texttt{fft(y)} &= [21, \ -2.707 - j0.707, \ -2 - j9, \ -1.293 - j0.707 \\ &\quad -1, \ -1.293 + j0.707, \ -2 + j9, \ -2.707 + j0.707] \end{split}$$

As before, we combine x and y element-wise into a single complex vector, but this time we must right-pad y with zero such that the vectors are equal length.

$$z = [1+j \ 2+j5 \ 4+j3 \ 4+j \ 5+j3 \ 3+j5 \ 7+j3 \ 8+j0]$$

The Fourier transform of z is

fft(z) = 
$$[34 + j21, -1.172 + j3.828, 4 + j5, -5.414 - j0.757, -j, -6.828 - j1.828, -14 - j9, -2.586 - j9.243]$$

Again, the Fourier transforms of x and y can individually be determined from Z using the even and odd components of the real and imaginary parts of Z, per part (a). Hence,

$$\begin{aligned} & \text{Ev}(\text{Re}(Z)) = [34, \ -1.879, \ -5, \ -6.121, \ 0, \ -6.121, \ -5, \ -1.879] \\ & \text{Od}(\text{Im}(Z)) = [0, \ 6.536, \ 7, \ 0.536, \ 0, \ -0.536, \ -7, \ -6.536] \\ & \text{Ev}(\text{Im}(Z)) = [0, \ 0.707, \ 9, \ 0.707, \ 0, \ -0.707, \ -9, \ -0.707] \\ & \text{Od}(\text{Re}(Z)) = [21, \ -2.707, \ -2, \ -1.293, \ -1, \ -1.293, \ -2, \ -2.707] \end{aligned}$$

Part part (a), we can reconstruct the individual Fourier transforms of x and y:

$$X = \begin{bmatrix} 34, & -1.879 + j6.536, & -5 + j7, & -6.121 + j0.536 \\ & 0, & -6.121 - j0.536, & -5 - j7, & -1.879 - j6.536 \end{bmatrix}$$

$$Y = \begin{bmatrix} 21, & -2.707 - j0.707, & -2 - j9, & -1.293 - j0.707 \\ & -1, & -1.293 + j0.707, & -2 + j9, & -2.707 + j0.707 \end{bmatrix}$$

Comparing these vectors to those determined individually at the start, we can see they are identical. We can additionally check that the shorter sequence can be recovered using the inverse Fourier transform:

$$ifft(Y) = [1. 5. 3. 1. 3. 5. 3. -0.]$$

Hence, given we know how many zeros were padded onto the end of the shorter sequence, it can indeed be recovered. Therefore, the double transform algorithm can be applied even if the sequences differ in length.

a) Given the polynomial

$$F(z) = 1 + 5z^{-1} + 3z^{-2} + 4z^{-3} + 4z^{-4} + 2z^{-5} + z^{-6}$$

the absence of a denominator indicates an all-zero model. The positions of the zeros in the complex plane are the roots of F(z), which can be found using numpy.polynomial:

This finds the following six roots:

$$z = -1.332, -0.628 \pm j1.565, -0.223, 0.405 \pm j1.011$$

Figure 5.1 plots these on the complex plane, with the unit circle for reference.

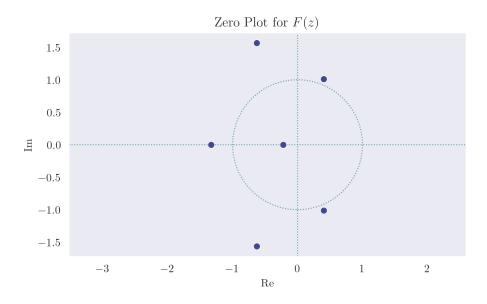


Figure 5.1: Zero plot for F(z); no poles are present.

b) The sinusoidal steady-state response of the system can be modelled by evaluating the magnitude of F(z) around the unit circle. This is effectively what is done by the DFT. That is,

$$F(z)|_{z=e^{-j\frac{2\pi}{N}k}, k=0,...,N-1}$$

Figure 5.2 compares scipy.fft and a self-implemented DFT function for N = 128.

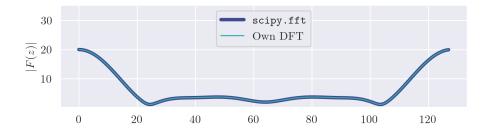


Figure 5.2: |F(z)| evaluated at 128 points around the unit circle.

# **Appendix**

### A sidelobes.py

```
1
2
   Script associated with Q1.
3
   Plots Fourier transform of rectangular and triangular pulse functions, enabling
4
5
   comparison of rates at which sidelobes fall off.
6
7
8
   from pathlib import Path
9
10
   import matplotlib.pyplot as plt
11
   import numpy as np
   import seaborn as sns
12
13
14 from scipy.fft import fft, fftfreq
15
16 from config import Al_ROOT, SAVEFIG_CONFIG
17
19
20
   def rectangular_pulse(_t: np.array, A: float = 1, T: float = 1) -> np.array:
21
22
       Constructs a rectangular pulse of amplitude 'A' and width 'T', centred about
23
       t=0 on '-t'. Returns array of y-values corresponding to '-t'.
24
25
       \mathbf{return}\ A\ *\ (\operatorname{np.abs}(\ \_t\ )\ <=\ T)
26
   def triangular_pulse(_t: np.array, A: float = 1, T: float = 1) -> np.array:
27
28
29
       Constructs a triangular pulse of maximum amplitude 'A' and width 'T',
       centred\ about\ t=0\ on\ `\_t\ `.\ Returns\ array\ of\ y-values\ corresponding\ to\ `\_t\ `.
30
31
       return A * (1 - np.abs(_t) / T) * (np.abs(_t) \ll T)
32
33
34
   35
36
   def main():
37
                   # Number of sample points
38
39
       T\,=\,1\,e{-}1
                   # Sample spacing
40
       _{t} = \text{np.linspace}(-N*T/2, N*T/2, N, endpoint=False)
41
42
       _{f} = fftfreq(N, T)
43
       _y1 = rectangular_pulse(_t)
44
       _{-H1} = 2 / N * np.abs(fft(_y1))
45
46
47
       _y2 = triangular_pulse(_t)
       _{-}H2 = 2 / N * np.abs(fft(_{-}y2))
48
49
50
       fig, ax = plt.subplots(figsize = (8, 4))
51
52
       sns.lineplot(x=_f, y=_H1, ax=ax, label="Rectangular")
       sns.lineplot(x=_f, y=_H2, ax=ax, label="Triangular")
53
54
       ax.set_title("Sidelobe_fall_off_comparison")
55
       ax.set_xlabel("Frequency")
56
       ax.set_ylabel("Magnitude")
57
58
```

## B multiplying.py

```
1
2
   Script associated with Q2 and 3.
3
4
   Multiplies polynomials/numbers in vector representation using convolution and
5
   Fourier transform methods.
6
7
8
   import numpy as np
9
10 from scipy.signal import convolve
   from scipy.fft import fft, ifft
11
12
13
  14
15
   def multiply_carry(z: np.array) -> np.array:
16
17
       Perform the "carry" steps of the multiplication process. Starting from the
       right end of 'z', each digit is taken modulo 10 and the remainder is added
18
19
       to the value immediately to the left. Returns an array of single digits,
20
       possibly except the first value (though the answer will still be correct).
21
       r = 0; ret = []
22
23
       for n in z[::-1]:
24
           n += r
25
           ret.append(n % 10)
26
           r = n // 10
27
       ret.append(r)
28
       return np. array (ret[::-1])
29
30
   31
32
   def multiply_conv(x: np.array, y: np.array, carry: bool = False) -> np.array:
33
34
       Convolve arrays 'x' and 'y' using direct convolution. If 'carry' is True,
       the output array is modified to be equivalent to the vectorised integer
35
36
       product of vectorised integers 'x' and 'y'. Otherwise, the convolution
37
       result is returned "as-is".
38
39
       z = convolve(x, y, mode="full", method="direct")
40
       if carry:
41
           z = multiply\_carry(z)
42
       return z
43
44
   def multiply_fft(x: np.array, y: np.array, carry: bool = False) -> np.array:
45
       Convolve \ arrays \ `x` \ and \ `y` \ by \ performing \ the \ FFT \ on \ `x` \ and \ `y`, \\ multiplying \ the \ results \ , \ then \ performing \ the \ inverse \ FFT. \ If \ `carry` \ is
46
47
       True, the output array is modified to be equivalent to the vectorised
48
       integer product of vectorised integers 'x' and 'y'. Otherwise, the
49
50
       convolution\ result\ is\ returned\ "as-is".
51
52
       xpad = np.pad(x, (0, len(y) - 1))
53
       ypad = np.pad(y, (0, len(x) - 1))
54
       z = ifft(fft(xpad) * fft(ypad)).real
55
       if carry:
56
           z = multiply\_carry(z)
57
       return z
58
59
   60
61
   def main():
```

```
62
63
             ### QUESTION 2 ###
64
65
             vx \, = \, np.\,array\, (\, [\, 1 \; , \; \, 2 \, , \; \, 6 \, , \; \, 11 \, , \; \, 15 \, , \; \, 12 \, ]\,)
66
             vy = np.array([1, -3, -3, 7, -7, 3])
67
             \begin{array}{l} \textbf{print} (\ "Q2\_by\_convolution: \ \ "\ , \ \ multiply\_conv (vx\,, \ vy\,)) \\ \textbf{print} (\ "Q2\_by\_FFT\_and\_IFFT: \ \ "\ , \ \ multiply\_fft (vx\,, \ vy\,)) \end{array}
68
69
70
             ### QUESTION 3 ###
71
72
73
             vx = np.array([8, 7, 5, 5, 7, 9, 0])
74
             vy = np.array([1, 3, 6, 7, 2, 6, 7])
75
76
             \mathbf{print} \, (\, "Q3\_by\_multiplication:" \, , \ 8755790 \ * \ 1367267)
             print("Q3_by_convolution:", multiply_conv(vx, vy, carry=True))
print("Q3_by_FFT_and_IFFT:", multiply_fft(vx, vy, carry=True))
77
78
79
80
81
      if __name__ == "__main__":
82
             main()
```

## C double\_transform.py

```
1
2
   Script associated with Q4.
3
4
   Implementation of the double transform algorithm to Fourier transform two real
   {\it N-point sequences using one commplex N-point transform.}
5
6
7
8
   import numpy as np
9
10 from scipy.fft import fft, ifft
11
   12
13
   def ev(H: np.array) -> np.array:
14
15
       Returns the even component of the given sequence 'H'.
16
17
       H_{\text{minus}} = \text{np.concatenate}([H[:1], H[-1:0:-1]])
18
19
       return 0.5 * (H + H_{-minus})
20
21
   def od(H: np.array) -> np.array:
22
       Returns the odd component of the given sequence 'H'.
23
24
25
       H_{\text{minus}} = \text{np.concatenate}([H[:1], H[-1:0:-1]])
       return 0.5 * (H - H_minus)
26
27
28
   29
30
   def main():
31
32
       x = np.array([1, 2, 4, 4, 5, 3, 7, 8])
       \# y = np.array([1, 5, 3, 1, 3, 5, 3, 7]) \# PART A: comment out for the other
33
       y = np.array([1, 5, 3, 1, 3, 5, 3, 0]) # PART B: comment out for the other
34
35
36
       Z = fft(np.array([a+b*1j for a, b in zip(x, y)]))
37
       X = ev(np.real(Z)) + 1j * od(np.imag(Z))
38
       Y = ev(np.imag(Z)) - 1j * od(np.real(Z))
39
40
       print (f" { fft (x) = _}")
41
       print(f"{fft(y) = }")
42
       print (f" {Z=_}}")
43
44
45
       print (f" {ev (np. real (Z)) = }")
       print(f"{od(np.imag(Z)) == }")
print(f"{od(np.real(Z)) == }")
46
47
       print (f" {ev (np.imag(Z)) = }")
48
49
50
       print (f" {X=_}}")
       print ( f" {Y = _ }")
51
52
53
       \mathbf{print}(f" ifft(Y) = \{np.round(ifft(Y).real, =3)\}")
54
55
56
   if _-name_- = "_-main_-":
57
       main()
```

## D polezero\_dft.py

```
1
2
   Script associated with Q5.
3
4
   Determines the roots of a certain polynomials and produces a pole-zero plot.
5
   Evaluates the magnitude of the polynomial around the unit circle using the DFT.
6
7
   import matplotlib.pyplot as plt
8
   import numpy as np
10 import seaborn as sns
11
12 from pathlib import Path
13
14 from matplotlib.axes._axes import Axes
   from matplotlib.lines import Line2D
16
   from matplotlib.patches import Circle
17
   from numpy.polynomial.polynomial import Polynomial, polyval
18
   from scipy.fft import fft
19
   from config import Al_ROOT, PLT_CONFIG, SAVEFIG_CONFIG
20
21
   22
23
24
   def zdft(poly_coef: np.array, N: int) -> np.array:
25
26
       Computes the 1D 'n'-point discrete Fourier transform of some sequence from
27
       its \ Z \ transform \ , \ given \ by \ `poly `.
28
29
       return np.array([polyval(np.exp(-1j*2*np.pi*k/N), poly_coef) for k in range(N)])
30
31
   32
33
   def plot_poles_or_zeros(F: Polynomial, type: str, ax: Axes) -> Axes:
34
35
       Plots the roots of the polynomial in the complex plane on the given axes.
36
37
       roots = F.roots()
38
39
       marker = {"poles": "X", "zeros": "o"}[type]
40
       sns.scatterplot(x=np.real(roots), y=np.imag(roots), ax=ax, marker=marker)
41
42
       ax.set_xlabel("Re")
43
       ax.set_ylabel("Im")
44
45
       return ax
46
   def axes_ratio_scale(ax: Axes, ratio: float, padto: str = None) -> Axes:
47
48
49
       Sets axes aspect as equal and autoscales the axes. If the axes limits ratio
       does not match the given aspect ratio (i.e. the ratio height / width), the
50
51
       x- or y-axis is lengthened to the desired ratio. Returns the modified axes.
52
53
       if padto and padto not in ("upper", "lower", "left", "right", "center"):
54
           raise ValueError ("invalid _ 'padto '_specified")
55
       padto = padto or "center"
56
       ax.set_aspect("equal")
57
58
       ax.autoscale()
59
60
       xlim, ylim = ax.get_xlim(), ax.get_ylim()
61
       \operatorname{xrng}, \operatorname{yrng} = \operatorname{xlim}[1] - \operatorname{xlim}[0], \operatorname{ylim}[1] - \operatorname{ylim}[0]
```

```
62
         curr_ratio = yrng / xrng
63
64
         if curr_ratio > ratio: # i.e. the current ratio is too tall and narrow
             add\_xlim = (yrng / ratio - xrng) * 0.5
if padto == "right":
65
66
                 new\_xlim = (xlim[0], xlim[1] + 2 * add\_xlim)
67
68
             elif padto == "left":
69
                 \text{new\_xlim} = (\text{xlim} [0] - 2 * \text{add\_xlim}, \text{xlim} [1])
70
             else:
                 new_x lim = (xlim[0] - add_x lim, xlim[1] + add_x lim)
71
72
             ax.set_xlim(new_xlim)
73
         if curr_ratio < ratio: # i.e. the current ratio is too short and wide
74
75
             add_ylim = (xrng * ratio - yrng) * 0.5
             if padto == "upper":
76
77
                 new_ylim = (ylim[0], ylim[1] + 2 * add_ylim)
78
             elif padto == "lower":
                 new_y lim = (y lim [0] - 2 * add_y lim, y lim [1])
79
80
81
                 new_y lim = (y lim [0] - add_y lim, y lim [1] + add_y lim)
82
             ax.set_ylim(new_ylim)
83
84
        return ax
85
86
    def draw_unit_circle(ax: Axes) -> Axes:
87
88
         Draws dotted axes and unit circle on the given axes, similar in style to
89
        MATLAB's zplane function.
90
         style_config = {"ls": "dotted", "lw": 0.9, "color": "cadetblue", "zorder": 0}
91
92
93
         u\_circ = Circle(xy=(0, 0), radius=1, fill=False, **style\_config)
94
        ax.add_patch(u_circ)
95
96
         \texttt{x\_axis} = \texttt{Line2D}(\texttt{xdata} = \texttt{ax.get\_xlim}(), \ \texttt{ydata} = (0, \ 0), \ **style\_config) 
97
        y_axis = Line2D(xdata=(0, 0), ydata=ax.get_ylim(), **style_config)
98
        ax.add_line(x_axis)
99
        ax.add_line(y_axis)
100
        ax.set_aspect("equal")
101
102
        return ax
103
104
    105
106
    def run_part_a(F: Polynomial) -> None:
107
         Plots the roots of the polynomial with given coefficients on the complex
108
109
         plane, with a unit circle underlay.
110
111
         print(f"{F.roots() = }")
112
        # Override default style to hide grid
113
        sns.set_style("dark")
114
115
        \# Re-set the plot text customisation, which gets overriden by set_style
116
        plt.rcParams.update(PLT_CONFIG)
117
118
119
         fig, ax = plt.subplots()
120
121
        ax = plot_poles_or_zeros(F, "zeros", ax)
122
        ax = axes_ratio_scale(ax, ratio=9/16, padto="center")
123
        ax = draw_unit_circle(ax)
        ax.set_title("Zero_Plot_for_$F(z)$")
124
```

```
125
126
        fname = Path(A1\_ROOT, "output", "q5a\_polezero.png")
        \label{eq:fig_savefig}  \mbox{fig.savefig} \ (\mbox{fname} \ , \ \ **SAVEFIG\_CONFIG) 
127
128
129
    def run_part_b(poly: Polynomial) -> None:
130
131
        Plots the magnitude of the polynomial with the given coefficients at 128
132
        uniformly spaced points around the unit circle using the DFT.
133
        y_ffft = np.abs(fft(poly.coef, n=128))
134
        y_dft = np.abs(zdft(poly.coef, N=128))
135
136
137
        fig, ax = plt.subplots()
138
        sns.lineplot(x=np.arange(128), y=y\_fft, ax=ax, lw=3, label=r"\$\backslash texttt\{scipy.fft\}\$")
139
140
        sns.lineplot(x=np.arange(128), y=y_dft, ax=ax, lw=1, label=r"Own_DFT")
141
        ax = axes_ratio_scale(ax, ratio=1/4, padto="upper")
142
143
        ax.set_title("")
144
        ax. set_xlabel("")
145
        ax.set_ylabel("$|F(z)|$")
146
147
148
        ax.legend(loc="upper_center")
149
150
        fname = Path(A1_ROOT, "output", "q5b_dftsample.png")
151
        fig.savefig(fname, **SAVEFIG_CONFIG)
152
153
    154
155
    def main():
156
157
        poly = Polynomial([1, 5, 3, 4, 4, 2, 1])
158
        \# run_part_a(poly)
159
        run_part_b (poly)
160
161
162
    if __name__ == "__main__":
163
        main()
```