

# Multi-output linear regression

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## 1 Abstract

The maths behind multi-output linear regression.

## 2 Problem statement

We have  $N$  input-output pairs  $\{(\mathbf{x}_n, \mathbf{y}_n)\}_{n=1}^N$  where  $\mathbf{y}_n \in \mathbb{R}^K$ . We propose the model

$$y_{n,i} = \boldsymbol{\theta}_i^T \boldsymbol{\phi}(\mathbf{x}_n) \quad (1)$$

where  $\boldsymbol{\phi}$  is a  $D$ -dimensional basis function. In general, we are therefore proposing that

$$\begin{pmatrix} y_{n,1} \\ \vdots \\ y_{n,K} \end{pmatrix} = \begin{bmatrix} \boldsymbol{\theta}_1^T \\ \vdots \\ \boldsymbol{\theta}_K^T \end{bmatrix} \boldsymbol{\phi}(\mathbf{x}_n) \quad (2)$$

which we write as

$$\mathbf{y}_n = \boldsymbol{\Theta}^T \boldsymbol{\phi}(\mathbf{x}_n) \quad (3)$$

## 3 Least-squares solution

Objective function:

$$J = \frac{1}{2} \sum_{n=1}^N \sum_{i=1}^K (y_{n,i} - \boldsymbol{\theta}_i^T \boldsymbol{\phi}_n)^2 \quad (4)$$

$$= \frac{1}{2} \sum_n \sum_i (-2y_{n,i} \boldsymbol{\theta}_i^T \boldsymbol{\phi}_n + \boldsymbol{\theta}_i^T \boldsymbol{\phi}_n \boldsymbol{\phi}_n^T \boldsymbol{\theta}_i) + \text{const.} \quad (5)$$

where we have adopted the notation  $\boldsymbol{\phi}_n \equiv \boldsymbol{\phi}(\mathbf{x}_n)$ . Through standard vector calculus we can show that

$$\frac{\partial J}{\partial \boldsymbol{\theta}_j} = - \sum_n y_{n,j} \boldsymbol{\phi}_n + \left[ \sum_n \boldsymbol{\phi}_n \boldsymbol{\phi}_n^T \right] \boldsymbol{\theta}_j \quad (6)$$

With the aim of evaluating

$$\frac{\partial J}{\partial \boldsymbol{\Theta}} = \begin{bmatrix} \frac{\partial J}{\partial \boldsymbol{\theta}_1} & \frac{\partial J}{\partial \boldsymbol{\theta}_2} & \dots \end{bmatrix} \quad (7)$$

we can now write that

$$\frac{\partial J}{\partial \Theta} = \begin{bmatrix} -\sum_n y_{n,1} \phi_n + [\sum_n \phi_n \phi_n^T] \theta_1 & -\sum_n y_{n,2} \phi_n + [\sum_n \phi_n \phi_n^T] \theta_2 & \dots \end{bmatrix} \quad (8)$$

$$= -\sum_n \begin{bmatrix} y_{n,1} \phi_n & y_{n,2} \phi_n & \dots \end{bmatrix} + \left[ \sum_n \phi_n \phi_n^T \right] \underbrace{\begin{bmatrix} \theta_1 & \theta_2 & \dots \end{bmatrix}}_{\Theta} \quad (9)$$

Consequently, defining

$$\mathbf{Y} = \begin{bmatrix} \mathbf{y}_1^T \\ \vdots \\ \mathbf{y}_N^T \end{bmatrix} \quad \mathbf{\Phi} = \begin{bmatrix} \phi_1^T \\ \vdots \\ \phi_N^T \end{bmatrix} \quad (10)$$

we can write that

$$\frac{\partial J}{\partial \Theta} = -\mathbf{\Phi}^T \mathbf{Y} + \mathbf{\Phi}^T \mathbf{\Phi} \Theta \quad (11)$$

Setting the above expression equal to zero and solving for the optimal parameter matrix we obtain

$$\Theta^* = [\mathbf{\Phi}^T \mathbf{\Phi}]^{-1} \mathbf{\Phi}^T \mathbf{Y} \quad (12)$$

## 4 Regularised least-squares solution

If we use the classic regularisation term that is employed in ridge-regression then the objective function is

$$J = \frac{1}{2} \sum_{n=1}^N \sum_{i=1}^K (y_{n,i} - \theta_i^T \phi_n)^2 + \frac{\lambda}{2} \sum_{i=1}^K \theta_i^T \theta_i \quad (13)$$

then, following a procedure similar to the previous section, we can show that

$$\frac{\partial J}{\partial \theta_j} = -\sum_n y_{n,j} \phi_n + \left( \left[ \sum_n \phi_n \phi_n^T \right] + \mathbf{I} \lambda \right) \theta_j \quad (14)$$

and so

$$\frac{\partial J}{\partial \Theta} = -\mathbf{\Phi}^T \mathbf{Y} + [\mathbf{\Phi}^T \mathbf{\Phi} + \mathbf{I} \lambda]^{-1} \Theta \quad (15)$$

which implies that our optimal parameters are given by

$$\Theta^* = [\mathbf{\Phi}^T \mathbf{\Phi} + \mathbf{I} \lambda]^{-1} \mathbf{\Phi}^T \mathbf{Y} \quad (16)$$