

$\sin^{-1} \arcsin(x)$

domain $[-1, 1]$
step: 0.1
20 values to calculate
 $k=0 = k=1$

$$\arcsin(x) = \sum_{k=0}^{\infty} \left(\frac{(2k)!}{2^{2k} (k!)^2} \right) \frac{x^{2k+1}}{2k+1}, |x| \leq 1$$

$$\arcsin(x) = x + \left(\frac{1}{2}\right) \frac{x^3}{3} + \left(\frac{1}{2} \cdot \frac{3}{4}\right) \frac{x^5}{5} + \left(\frac{1}{2} \cdot \frac{3}{4} \cdot \frac{5}{6}\right) \frac{x^7}{7}$$

~~$$\left(\frac{(2k)!}{2^{2k} (k!)^2}\right) \frac{x^{2k+1}}{2k+1}$$~~

.2

$$\frac{1}{2} \cdot \frac{3}{4} \cdot \frac{5}{6} \cdot \frac{7}{8} \cdot \frac{9}{10} \left(\frac{x}{9}\right)$$

$\cos^{-1} \arccos(x)$

domain $[-1, 1]$
step: 0.1
20 values to calculate

$$\arccos(x) = \frac{\pi}{2} - \arcsin(x)$$

or

$$\frac{\pi}{2} - \sum_{k=0}^{\infty} \frac{(2k)!}{2^{2k} (k!)^2} \frac{x^{2k+1}}{2k+1}$$

$\tan^{-1} \arctan(x)$

domain $[-1, 10]$
step: 0.1
100 values to calculate

$$\arctan(x) = \arcsin\left(\frac{x}{\sqrt{x^2+1}}\right) = \arccos\left(\frac{1}{\sqrt{x^2+1}}\right), x > 0$$

or

$$\sum_{k=0}^{\infty} \frac{2^k (k!)^2}{(2k+1)!} \frac{x^{2k+1}}{(1+x^2)^{k+1}}$$

$\log(x)$

domain $[1, 10]$
step: 0.1

$$x_{k+1} = x_k + \frac{y - e^{x_k}}{e^{x_k}}$$

y is user input, ie: $\log(5)$, $y=5$

x_k start with 1, end at

$\sin^{-1} \arcsin(x)$

Test values from -1 to 1 , with Step 0.1

$$\sin^{-1}(x) = \sum_{k=0}^{\infty} \frac{(2k)!}{2^{2k}(k!)^2} \frac{x^{2k+1}}{2k+1}, |x| \leq 1$$

WHERE AS...

$$\sin^{-1}(x) = x + \left(\frac{1}{2}\right) \frac{x^3}{3} + \left(\frac{1}{2} \cdot \frac{3}{4}\right) \frac{x^5}{5} \dots$$

LEFT RIGHT

If the code uses this style of Taylor series, you would need to calculate the factorials from the ground up after each iteration. (INEFFICIENT)

This simplified version clearly shows a repeating pattern.

The left side's new value's numerator is the num current iteration number, and denominator is ~~the~~ 2x the previous denominator OR 2x the iteration #.

The right side's numerator grows by "x*x" after each iteration.

The denominator is plus 2 from previous denominator.

VS

With each iteration, the code needs to recompute all the values such as $(2k)!$ and (2^k)

With each iteration, values do not need to be calculated from the ground up. Meaning, more efficient.

Using this simplified version of arcsin is significantly faster.

(I tried the other method, and)
NO GOOD

~~arc~~ PsuedoCode

arcSin: Declare the changing variables after each iteration

Declare finalans, Declare numerator & denominator for **left**, and for **Right**

Declare counter to keep track of iteration,

Declare **testans** to remember answer from previous iteration,

and Multiply x by $x \cdot x$ because the loop starts from 1.

Loop^s

$$\text{Leftside} = \text{Leftside} * \left(\frac{\text{Left}}{\frac{\text{num}}{\text{denom}}} \right)$$

$$\text{Finalans} = \text{Finalans} + (\text{left} * (x / \text{denominator}))$$

$$\text{Counter } t = 1$$

$$x = x \cdot x \cdot x$$

$$\text{Left}^{t+2} \text{ num and Left}^{t+2} \text{ denom}$$

~~Right~~

Test for exit: $\text{Finalans} - \text{testans}$ is less than epsilon:

return Finalans

$\cos^{-1} \text{arcCos}(x)$ Test Values from $[-1, 1]$, step: 0.1

$$\text{arcCos}(x) = \frac{\pi}{2} - \text{arcSin}(x)$$

In this function, $\text{arcCos}(x)$ would pass x to $\text{arcSin}(\cdot)$.

Then return $\left(\frac{\pi}{2} - \text{arcSin}(x) \right);$

NOTE

π will be defined wrong <Math.h>

arcCos Pseudo Code

As explained above, $M_{\text{PI}} = \pi$ is defined. So....

return $\left(\frac{\pi}{2} - \text{arcSin}(x) \right);$

$\tan^{-1} \arctan(x)$

Test Values from 1 to 10, step 0.1

$$\arctan() = \arcsin\left(\frac{x}{\sqrt{x^2+1}}\right) \text{ OR } \arccos\left(\frac{1}{\sqrt{x^2+1}}\right)$$

Because \arccos calls \arcsin .

I will be using $\arcsin\left(\frac{x}{\sqrt{x^2+1}}\right)$ for this function.

Step 1. Pass $\left(\frac{x}{\sqrt{x^2+1}}\right)$ to \arcsin . Pseudo

└ Compute Square Roots.

Square roots computed through Newton's method.

Loop { //Remember the previous values

 test = finalans

$$\text{finalans} = \left(\text{test} + \frac{(\text{base})}{\text{test}} \right) \frac{1}{2}$$

 test: The previous answer
 for the loop

 finalans: The current answer
 for the loop

Then if ~~the~~ the difference

from finalans and test is less than epsilon,
~~return~~ The square root is computed.

Step 2. Return the value from Step 1.

Log()

Test values from 1 to 10, step 0.1

$$x_{k+1} = x_k + \frac{y - e^{x_k}}{e^{x_k}}$$

The $\exp()$ function is provided to us. This function finds answers of (e^x) .

y = Value to compute log for

x_k = The previous answer from previous iteration. $(x_k + \frac{y - e^{x_k}}{e^{x_k}})$

Log(x) { Pseudocode

declare "pass" for the " x_k "
declare "epow" for ~~the~~ " e^{x_k} "

Loop {

$epow = \exp(\text{pass})$ // Pass is used here because pass is " x_k "

$\text{pass} = x_k + \frac{y - e^{x_k}}{e^{x_k}}$ // pass + $\frac{x - \text{epow}}{\text{epow}}$

 Test if the difference ~~between~~ between epow and pass is $< \epsilon$.
 If so, return pass.

Test harness

- This function ~~acts as a test harness for mathlib.c~~ acts as a test harness for mathlib.c

- a: to run all test
- S: to run arcsin test
- c: to run arcCos test
- t: to run arcTan test
- l: to run log test.

If arguments are incorrect,
Print program usage.
Print arguments in order.
-a, -S should only run -a

Pseudo code

// argc will hold # of inputs
// argv is the array of inputs

int main(int argc, char *argv[])

Declare a T/F flag for every test option, set to False

Choices of the possible inputs

while ((choice = getopt(argc, argv, "ascfl")) != -1) {

switch(choice)

~~Consider~~ for every choice, if that choice is chosen, set the respective flag to True.

case "?":
print program usage

}

argv is the array, and optarg is the pointer so, if the pointer points to the array as NULL, Print Program Usage.

Finally, make 4 if statements. Each if statement checks if the flag for "every test" = True OR the respective test = True.

If so, print the respective X value, respective test, Test from <math.h>, an the difference