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Section 3.2

Ving Matrices to solve systems of equations.

(any number of equations, any number of unknowns.)

Recall: As linear equation in 2 variables can be written

ax+by=c -> is a line

Lets generalize to linear equations in more than 2 unknowns ex/3x + 4y - 5z = 2

sometime instead of x, y, z we might write X, Xz, X3, X4, ..., Xn

Recall: We can we write systems of equations as matrix multiplication equations

 $\begin{cases} 4x + 2y - 8z = 9 \\ -x - y - z = -1 \\ 4x + y - z = 5 \end{cases} = \begin{cases} 4 & 2 & -8 \\ -1 & -1 & -1 \\ 4 & 1 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 9 \\ -1 \\ 5 \end{bmatrix}$

these are two different ways of representing the same system.

In 4.3 we talked about solving systems of equising matrix inverses & matrix multiplication.

$$\begin{bmatrix} 4 & 2 & -8 \\ -1 & -1 & -1 \end{bmatrix} \begin{bmatrix} 1 & 2 & -8 \\ -1 & -1 & -1 \end{bmatrix} \begin{bmatrix} 1 & 2 & -8 \\ -1 & -1 & -1 \end{bmatrix} \begin{bmatrix} 1 & 2 & -8 \\ 2 & 2 & -1 \end{bmatrix} \begin{bmatrix} 1 & 2 & -1 \\ 2 & 2 & -1 \end{bmatrix} \begin{bmatrix} 1 & 2 & -1 \\ 2 & 2 & -1 \end{bmatrix} \begin{bmatrix} 1 & 2 & -1 \\ 2 & 2 & -1 \end{bmatrix} \begin{bmatrix} 1 & 2 & -1 \\ 2 & 2 & -1 \end{bmatrix} \begin{bmatrix} 1 & 2 & -1 \\ 2 & 2 & -1 \end{bmatrix} \begin{bmatrix} 1 & 2 & -1 \\ 2 & 2 & -1 \end{bmatrix} \begin{bmatrix} 1 & 2 & -1 \\ 2 & 2 & -1 \end{bmatrix} \begin{bmatrix} 1 & 2 & -1 \\ 2 & 2 & -1 \end{bmatrix} \begin{bmatrix} 1 & 2 & -1 \\ 2 & 2 & -1 \end{bmatrix} \begin{bmatrix} 1 & 2 & -1 \\ 2 & 2 & -1 \end{bmatrix} \begin{bmatrix} 1 & 2 & -1 \\ 2 & 2 & -1 \end{bmatrix} \begin{bmatrix} 1 & 2 & -1 \\ 2 & 2 &$$

Great! We can use matrix inverses to solvea systems,

What are some limitations:

- what if our matrix is singular? - singular matrices don't have an inverse.

· What if it's not a square matrix?

So this method only works when we have the same # of unknowns and equations, and if that matrix even has an inverse.

New method: By Use the Augmented matrix and Elementary Row operations

what is the Augmented matrix?

 $\begin{cases} 2x + 3y = 4 \\ -x + 3y = 2 \end{cases}$ $\Rightarrow \begin{bmatrix} z & 3 \\ -1 & 3 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 4 \\ z \end{bmatrix}$

Il to write as Augmented matrix

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We will use Ron operations to simplify this matrix:

Row operations are d'things we can do to the augmented "operations" matrix that does not change the system it represents.

12 A Type I - we can replace a row by a multiple of itself RimaRi ato

 $ex\left(\begin{bmatrix} 2 & 3 & 4 \\ -1 & 3 & 2 \end{bmatrix}\right) \leftarrow 2x + 3y = 4$ -x + 3y = 2

Replace R, with ZR,

add a multiple of a row to a different row $R_i \rightarrow R_i \pm aR_i$

$$\begin{cases} 2x+3y=4\\ -x+3y=2 \end{cases}$$

and to the first raws add the second row x 2 to the first row

$$\begin{bmatrix} 2 + (-2) & 3 + (6) & 4 + (4) \\ -1 & 3 & 2 \end{bmatrix}$$

$$R_{1} \rightarrow R_{1} + 2R_{2}$$

$$\left[2 + (-2) \quad 3 + (6) \quad 4 + (4)\right]$$

$$\left[-1 \quad 3\right]$$

$$\left[-1 \quad 3$$

$$\begin{bmatrix} 0 & 9 & 8 \\ -1 & 3 & z \end{bmatrix} \qquad \begin{cases} 4y = 8 \\ -x + 3y = 2 \end{cases}$$

$$\begin{cases} 4y = 8 \\ -x + 3y = 2 \end{cases}$$

Type 3! We can switch the order of rows

 $\begin{cases} 2 & 3 & 4 \\ -1 & 3 & 2 \end{cases} \iff \begin{cases} 2x + 3y = 4 \\ -x + 3y = 2 \end{cases}$

$$\begin{cases} 2x + 3y = 4 \\ -x + 3y = 2 \end{cases}$$

 $\begin{bmatrix} -1 & 3 & 2 \\ 2 & 3 & 4 \end{bmatrix} \quad \text{(a)} \quad \begin{cases} -x + 3y = 2 \\ 2x + 3y = 4 \end{cases}$

Lets use these to solve a system of equations

 $\begin{cases} -2\frac{1}{3} + \frac{1}{2} = -3 \\ \frac{1}{4} - \frac{1}{4} = \frac{1}{4} \end{cases} \iff \begin{cases} -\frac{2}{3} & \frac{1}{2} & -\frac{3}{3} \\ \frac{1}{4} & -1 & \frac{1}{4} \end{cases}$

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and the second row by 4
\begin{bmatrix} -4 \\ 3 \\ -4 \\ 11 \end{bmatrix} \qquad (a) \qquad \begin{cases} -4x + 3y = -18 \\ x - 4y = 11 \end{cases}
   of Idea is to use the first non-zero # in the
       first row and klear out everything else in
        its column.
   Use -4 to clear out the 1
   use the 2nd type of row aperation
           Rz -> Rz + 4R,
         of we can also mattply the secon
                       Rz - URz - URz + R,
But lets switch the rong first
   \begin{bmatrix} 1 & -1 & 11 \\ -4 & 3 & -18 \end{bmatrix} \quad \text{(a)} \quad \begin{cases} x - 4y = 11 \\ -4x + 3y = -18 \end{cases}
                Rz > Rz + UR,
   \begin{cases} 1 & -4 & 11 \\ 0 & -13 & 26 \end{cases} \iff \begin{cases} x - 4y = 11 \\ -13y = 26 \end{cases}
               Lets see how much we can simplify this
      Lets take Rz > 12 Rz
    \begin{cases} 1 - 4 & 11 \\ 0 & 1 - 2 \end{cases} = \begin{cases} x - 4y = 11 \\ y = -2 \end{cases}
       Now lets use the 1 to clear out the -4 above it
               R_1 \rightarrow R_1 + 4R_2
   \begin{bmatrix} 1 & 0 & 3 \\ 0 & 1 & -2 \end{bmatrix} \quad \text{(a)} \quad \begin{cases} x & = 3 \\ y & = -2 \end{cases}
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Multiply the first row by 6

why is this better?

one reason is on it helps us organize the syste.

But the real reason is that we can write this us an algorithm that a computer can use to solve systems quickly

- . This process has a comple names
 - · boussian Elimination
 - Row reduction
 - Gaussi Jordan reduction

From now on will be using technology to do this row reduction for us.