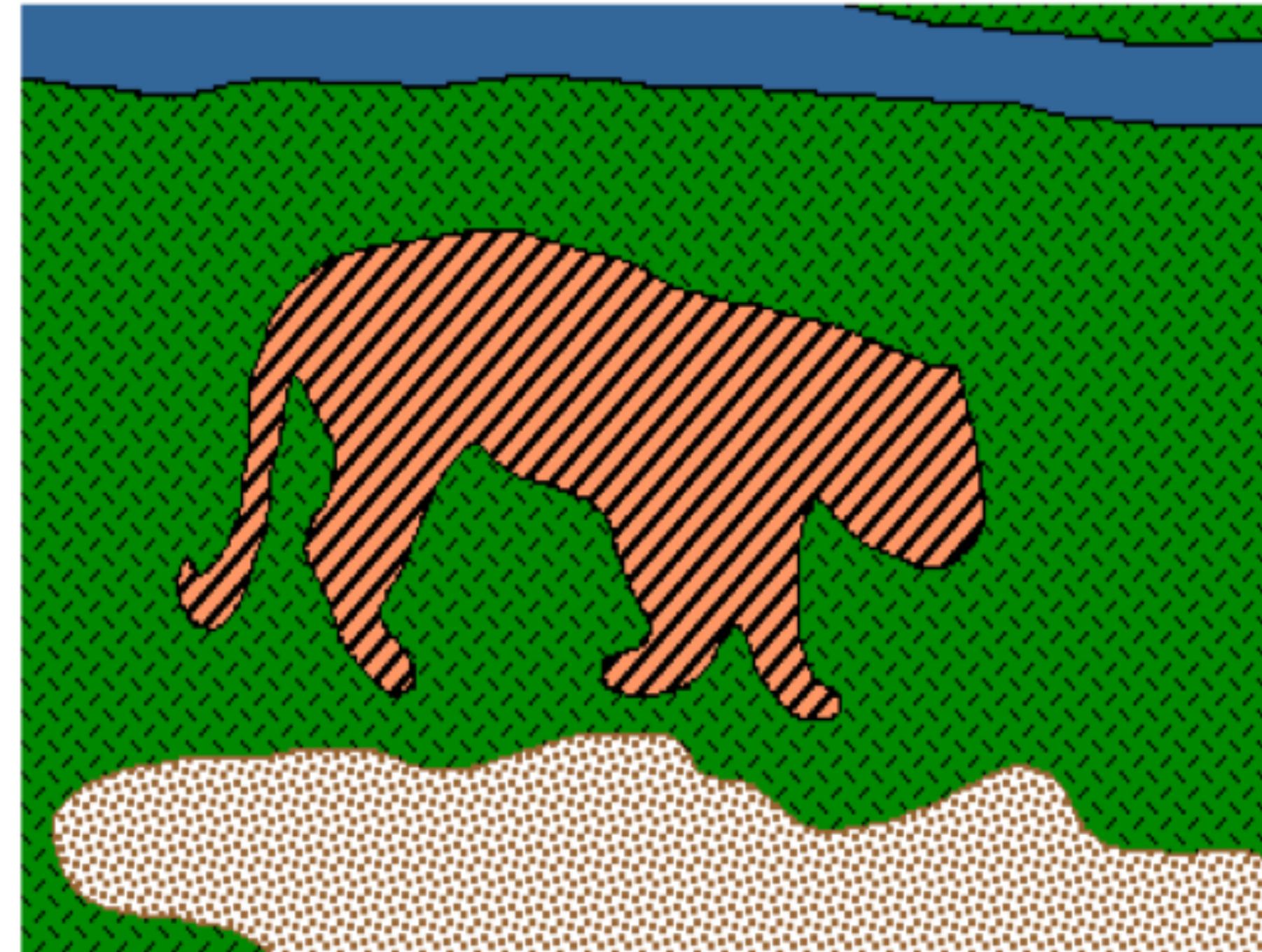


COMP0026: Image Processing

Image Segmentation



Lectures will be Recorded

Image Segmentation

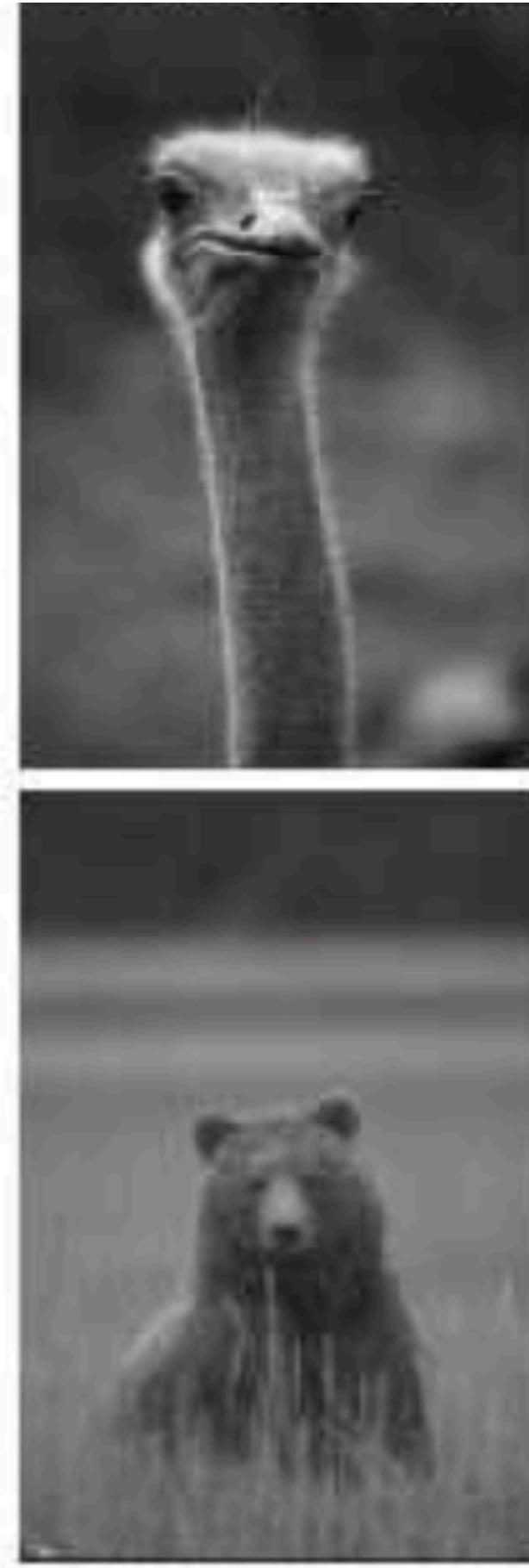


Image Segmentation



Overview

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What is image segmentation?

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Types of segmentation algorithms

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- 1. Thresholding, region labelling and growing algorithms**
 - (connected components, region growing, watershed)**

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- Segmentation partitions an image into **regions of interest** (ROI).
- The *first* stage in many automatic image analysis systems.
- A *complete segmentation* of an image I is a finite set of non-overlapping regions R_1, \dots, R_N , such that

$$I = \bigcup_{i=1}^N R_i \text{ and } R_i \cap R_j = \emptyset \quad \forall i \neq j.$$

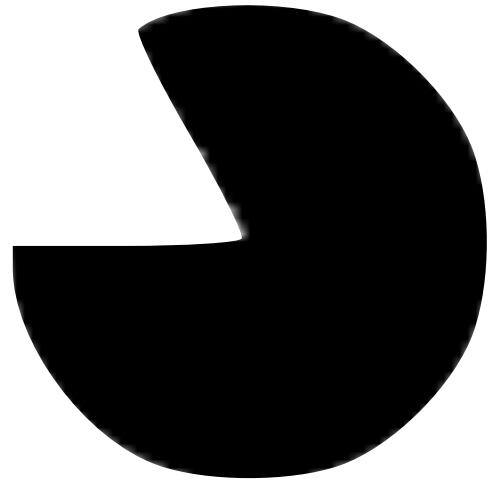
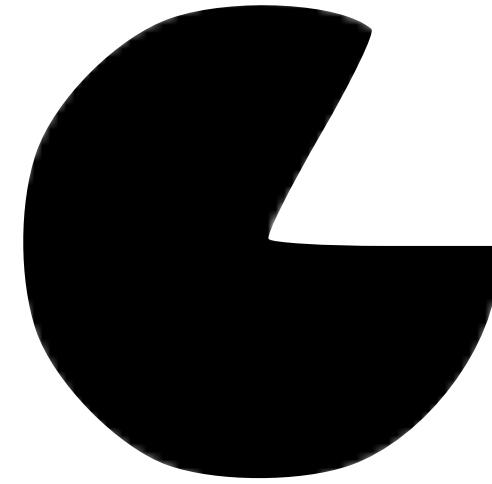
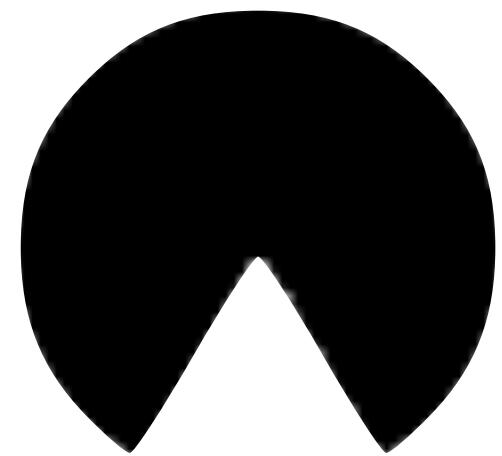


Where is the ...?



[Emerging Images, Mitra et al., Siggraph Asia, 2009]

Kanizsa Triangle

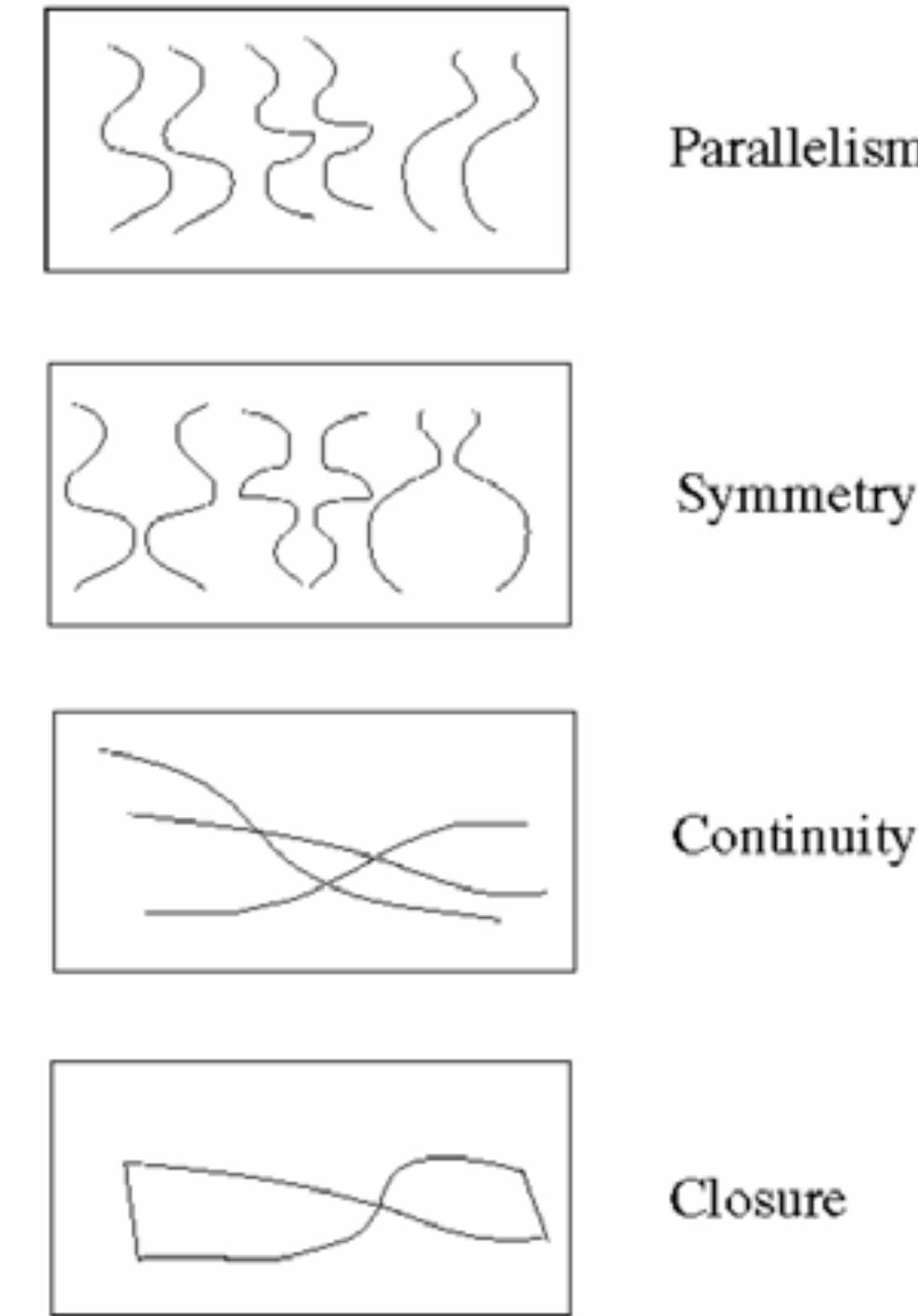
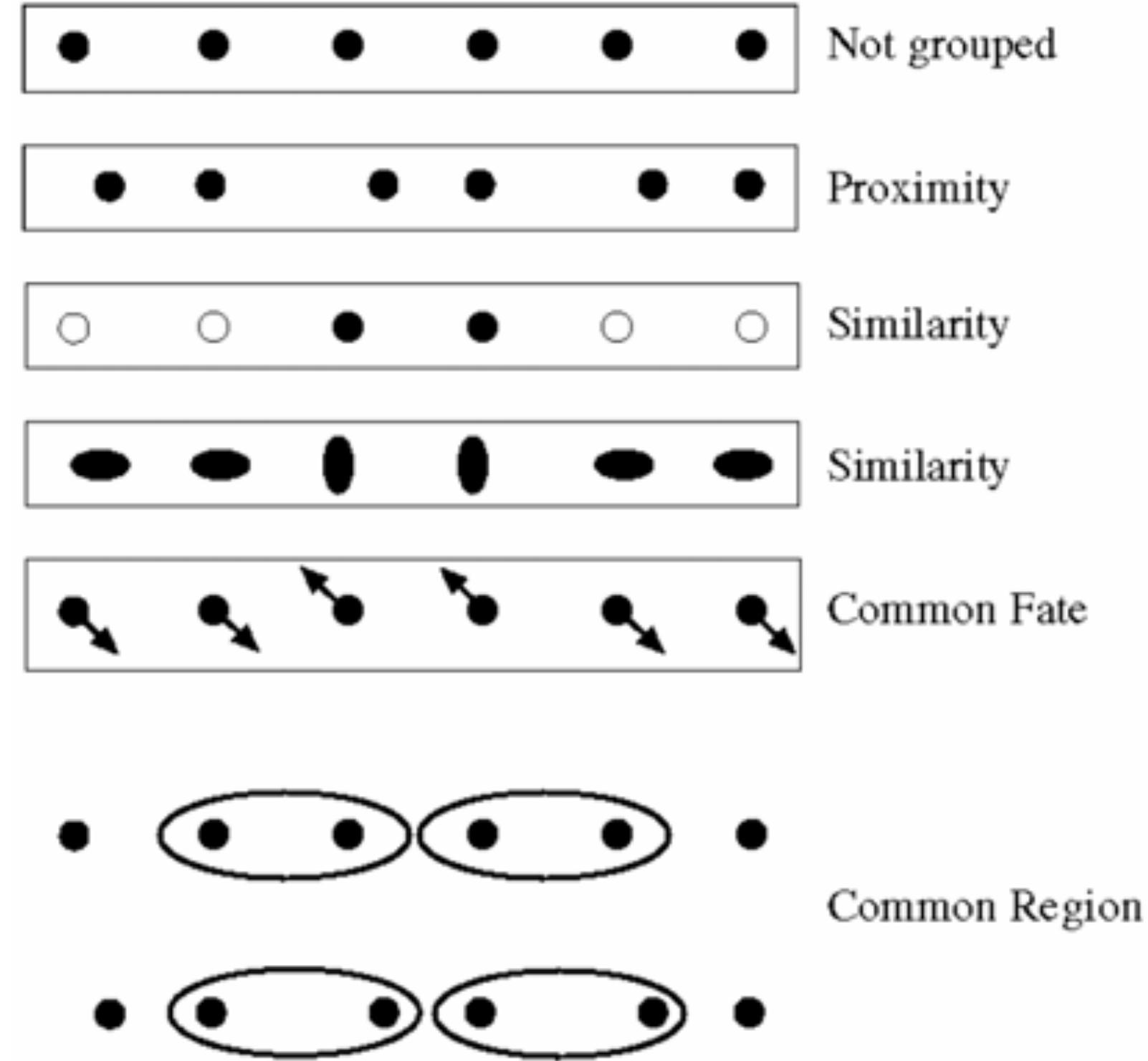


Illusory Contours: Kanizsa, G. (1955), Rivista di Psicologia 49(1): 7–30

The Cup?



Gestalt Factors



Intuitive sense, but difficult to realize algorithmically.

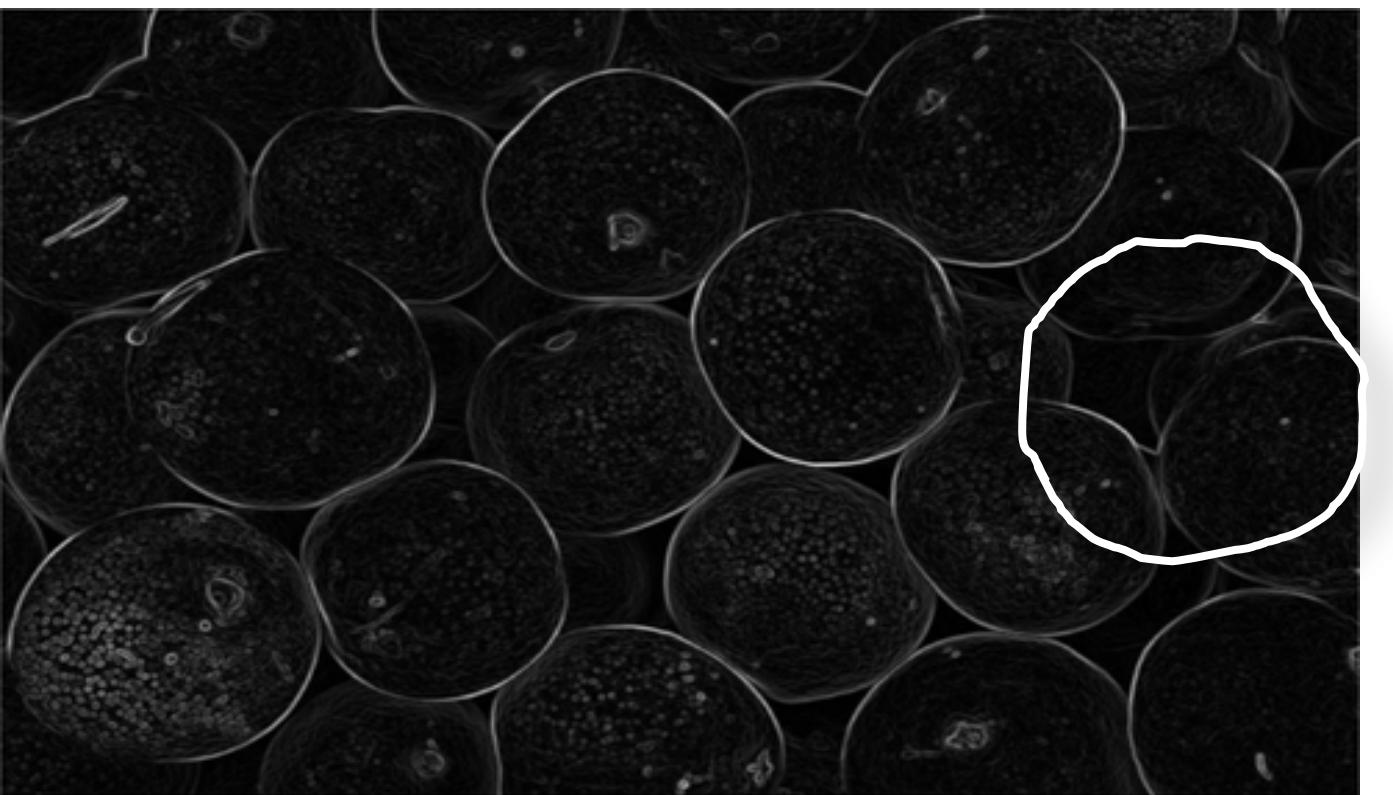
Slide from S.Lazebnik

Image Attributes

color



texture



gradient



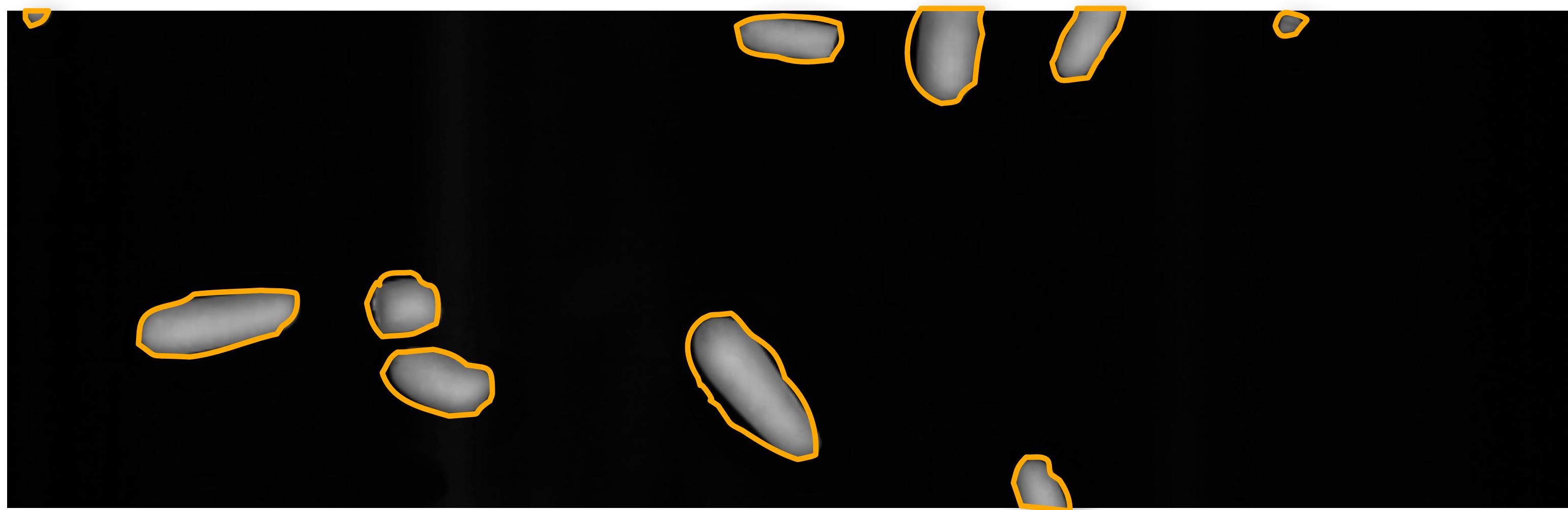
Combinations

<http://vision.ece.ucsb.edu/segmentation>

How to Segment?



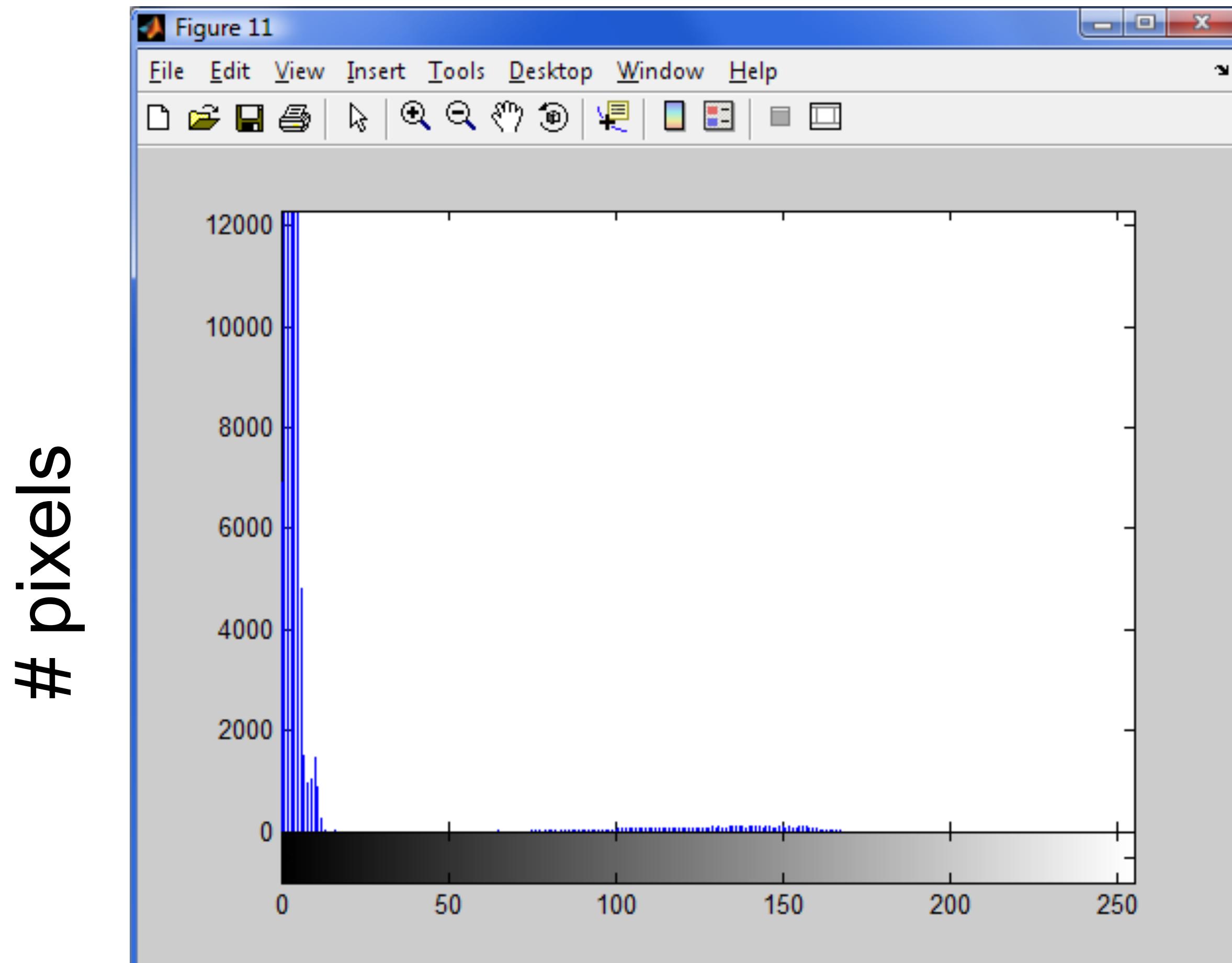
How to Segment?



Exclude Dark Pixels?

```
I = imread('BlobsIP.png');  
figure;  
imshow( I )  
size(I)          --> [ 244    767   3 ]  
figure;  
imhist( I(:,:,1) )  
figure;  
imshow( I(:,:,1) > 20 )
```

Histogram



gray-levels [0,255]

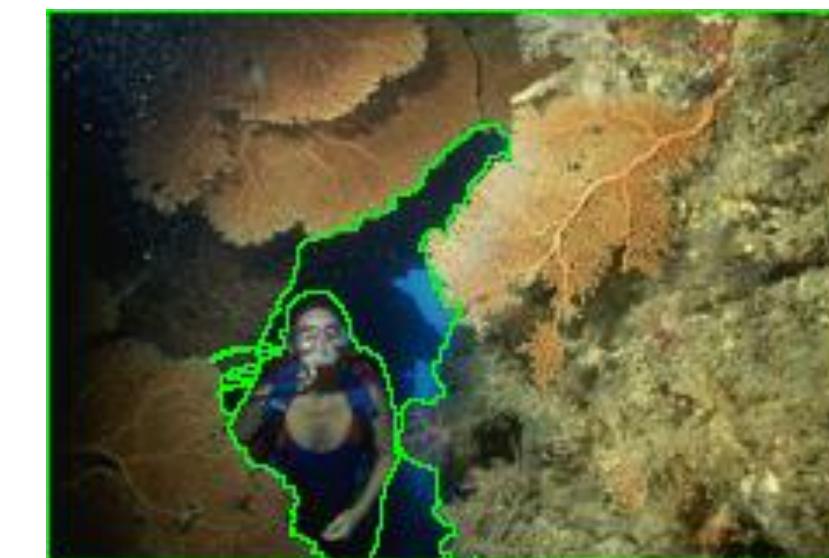
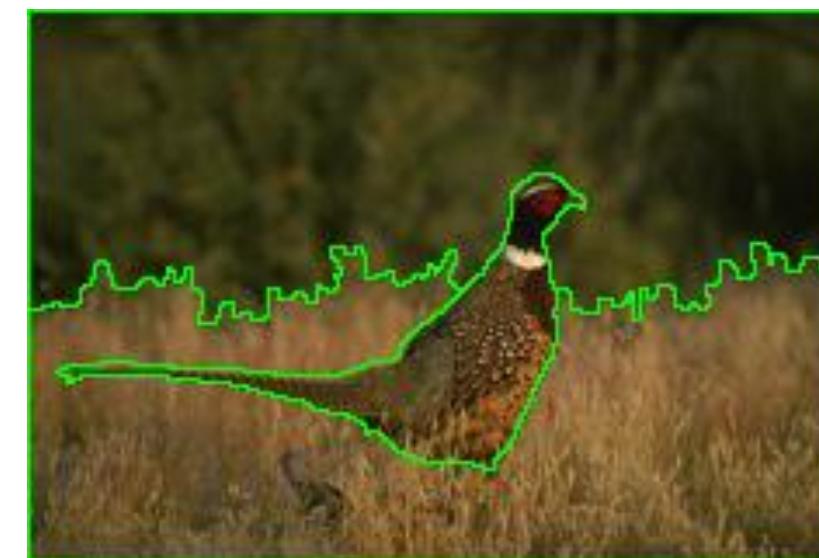
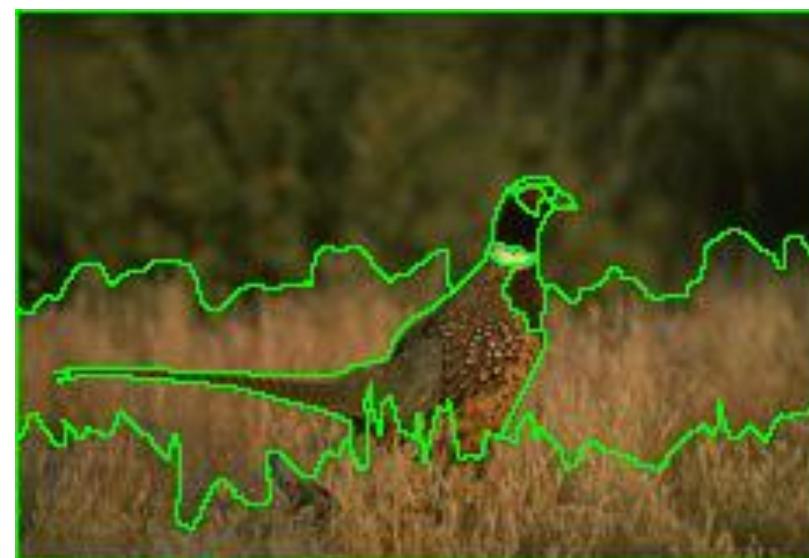
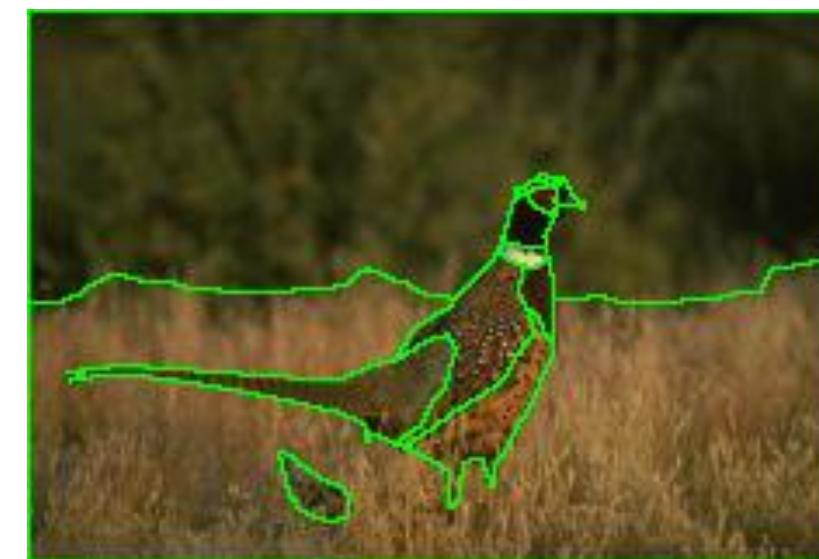
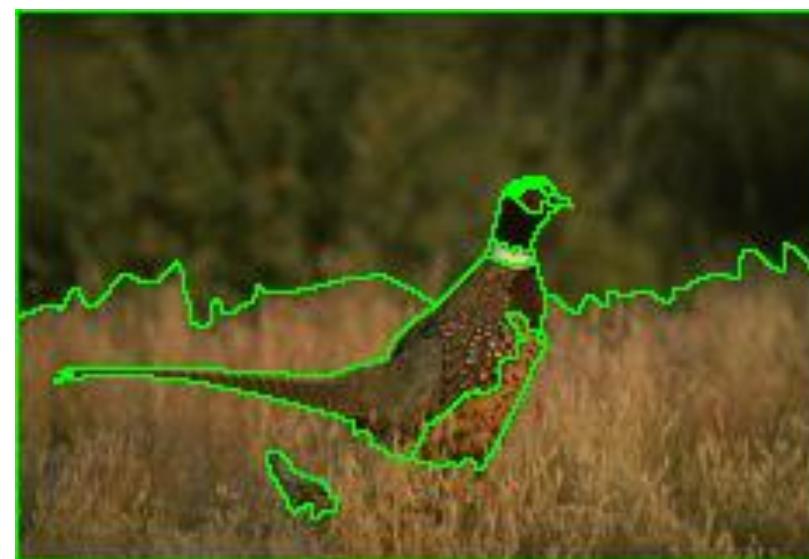
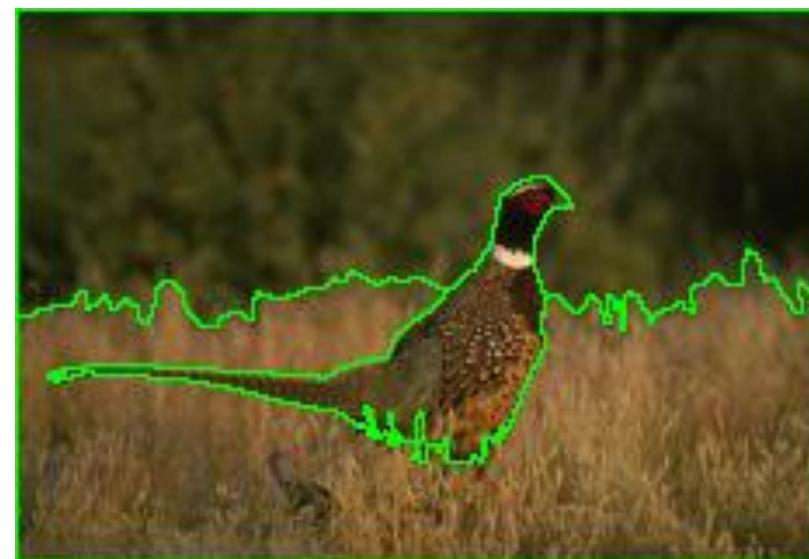
Harder Example



Harder Example

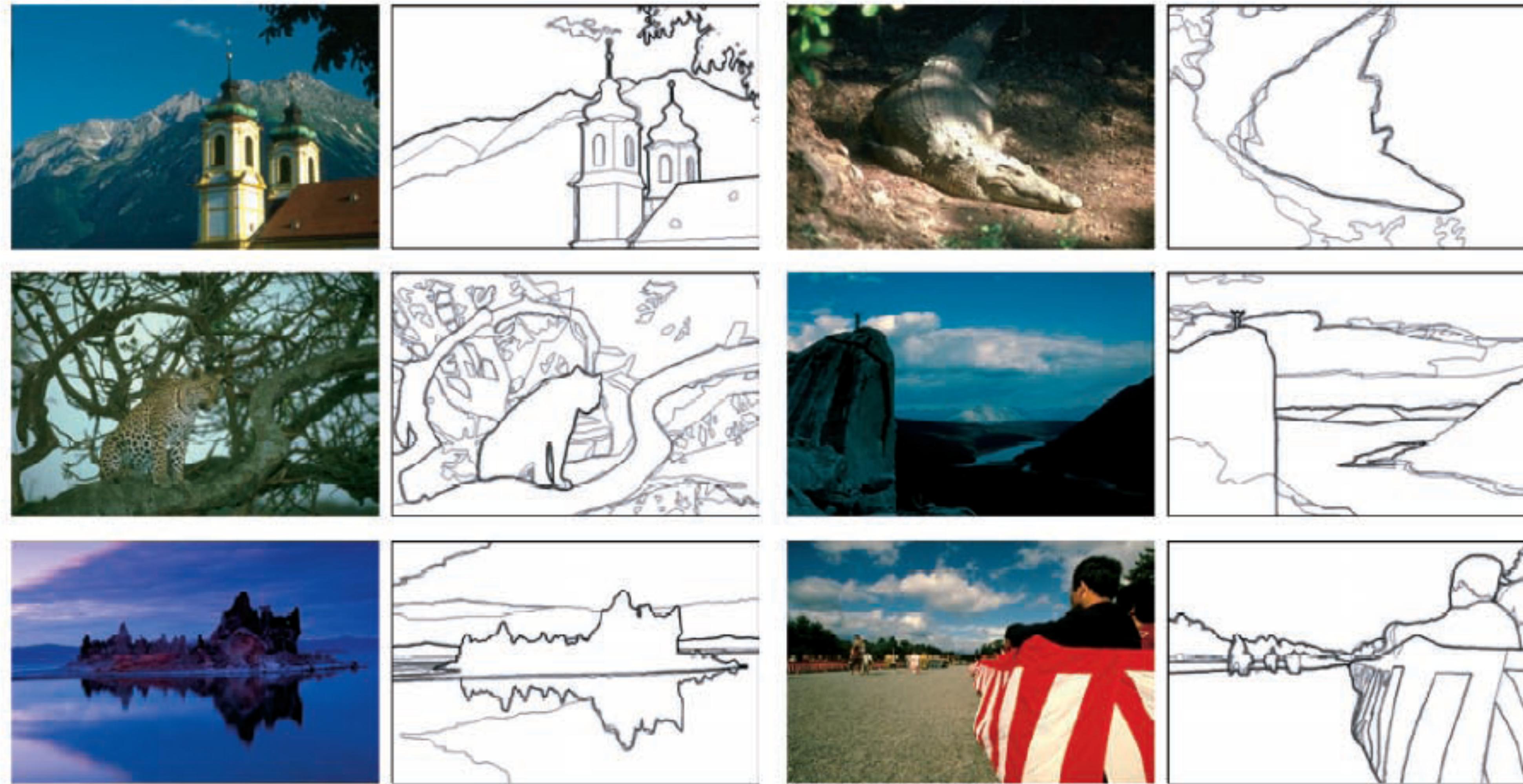


Berkeley Segmentation Database and Benchmark



<http://www.eecs.berkeley.edu/Research/Projects/CS/vision/grouping/segbench/>

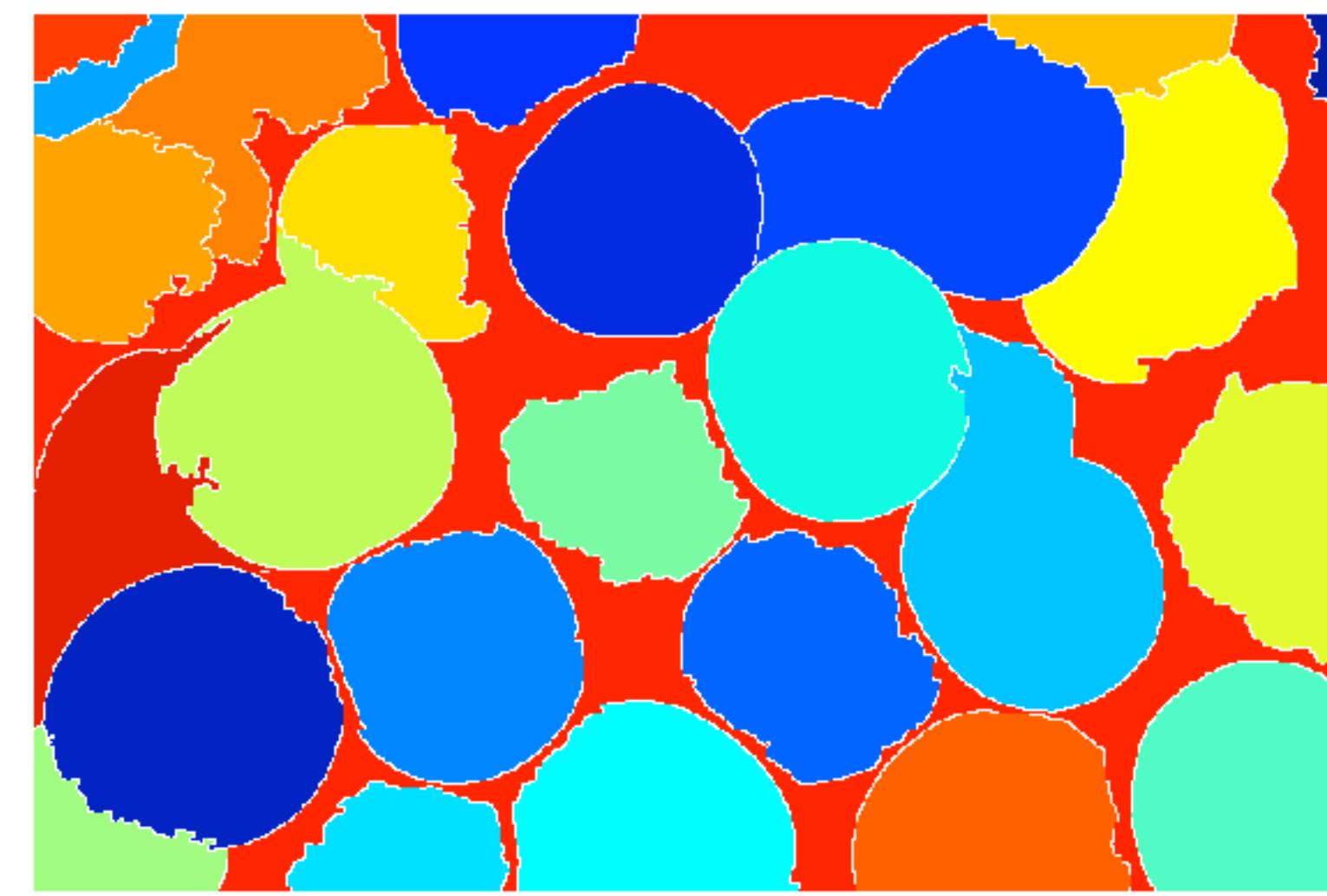
Berkeley Segmentation Database and Benchmark



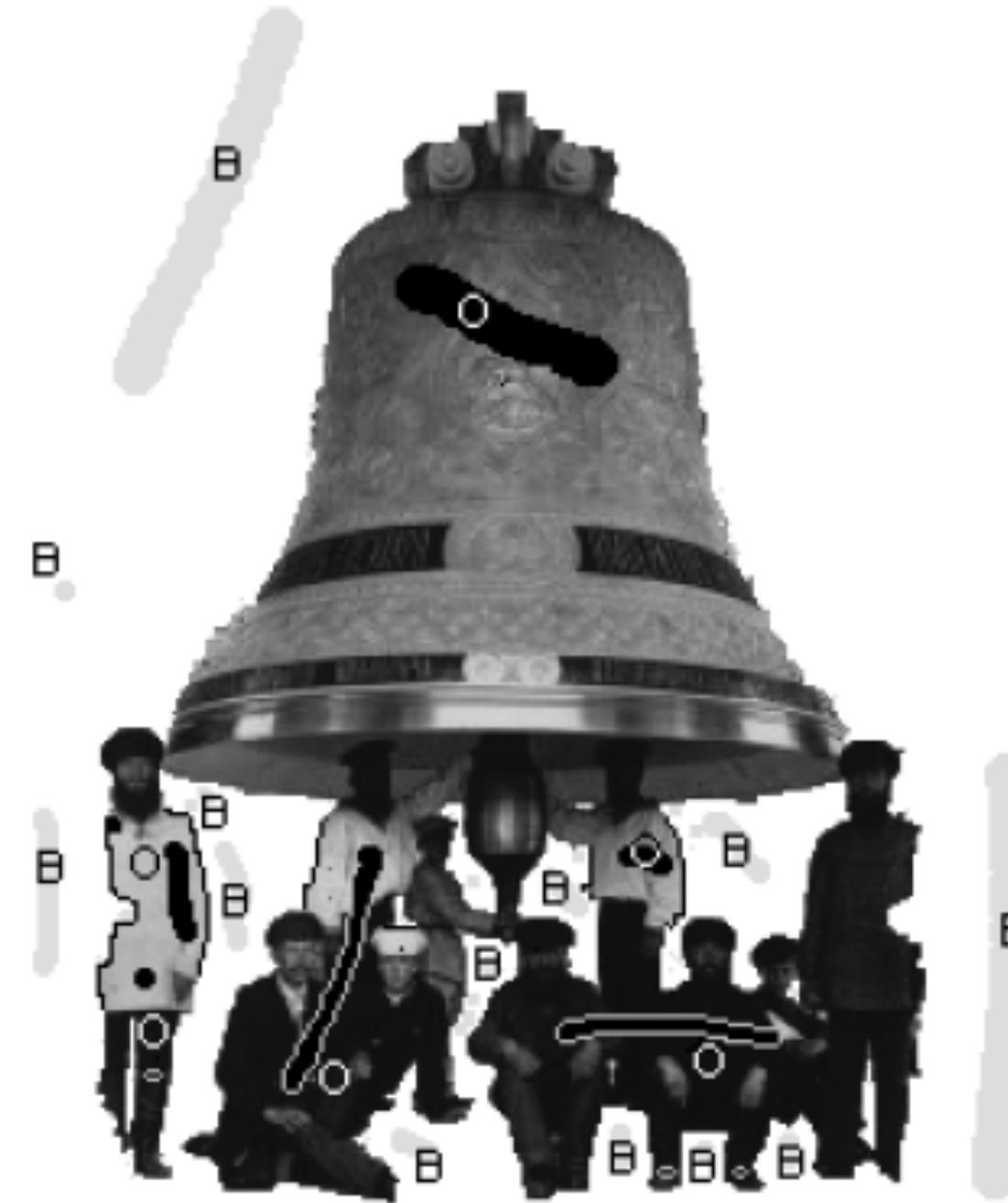
Martin et al. PAMI 2004

Segmentation Philosophies

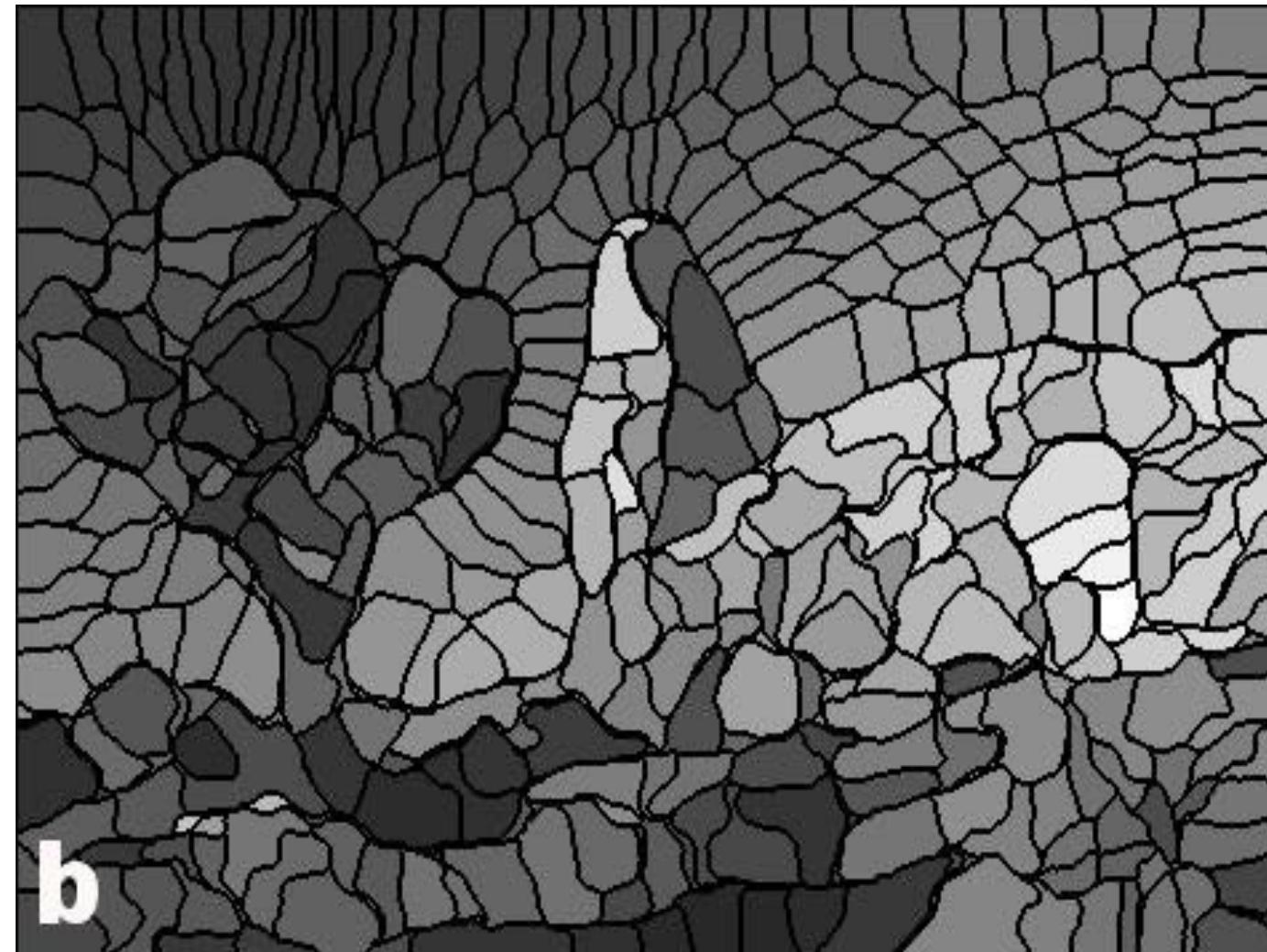
Binary vs. Multi-label



Supervised vs. Unsupervised



Exact- vs. Over-segmentation



Top-down or Bottom-up



... they lie on the same object ... they are locally coherent

Overview

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Types of segmentation algorithms

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Thresholding

- Thresholding is a simple segmentation process.
- Thresholding produces a binary image B .
- It labels each pixel in or out of the region of interest by comparison of the greylevel with a threshold T :

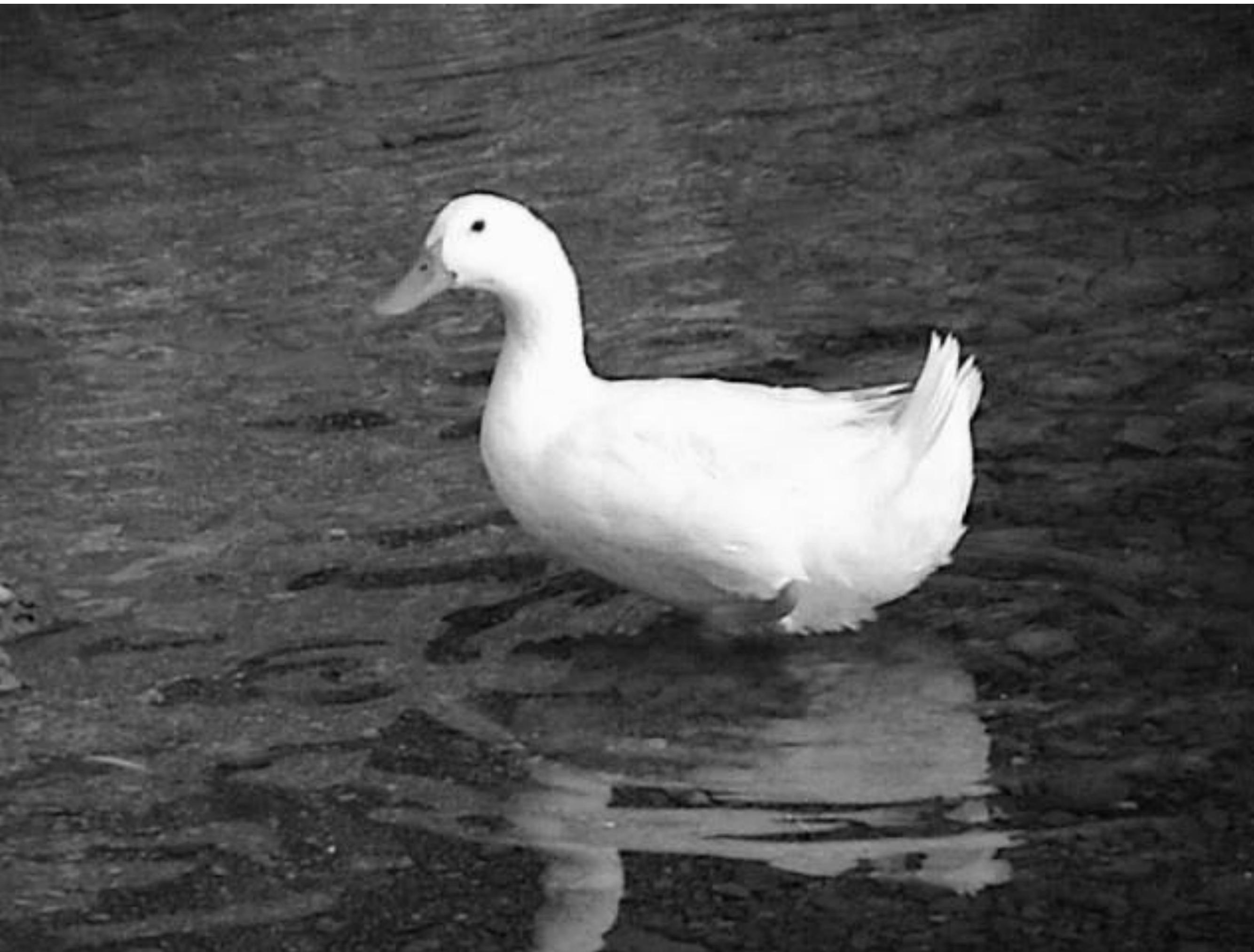
$$B(x, y) = \begin{cases} 1 & \text{if } I(x, y) \geq T \\ 0 & \text{if } I(x, y) < T. \end{cases}$$

Intensity

Basic Thresholding Algorithm

```
for x=1:X  
    for y=1:Y  
        B(x,y) = (I(x,y) >= T);  
    end  
end
```

Example

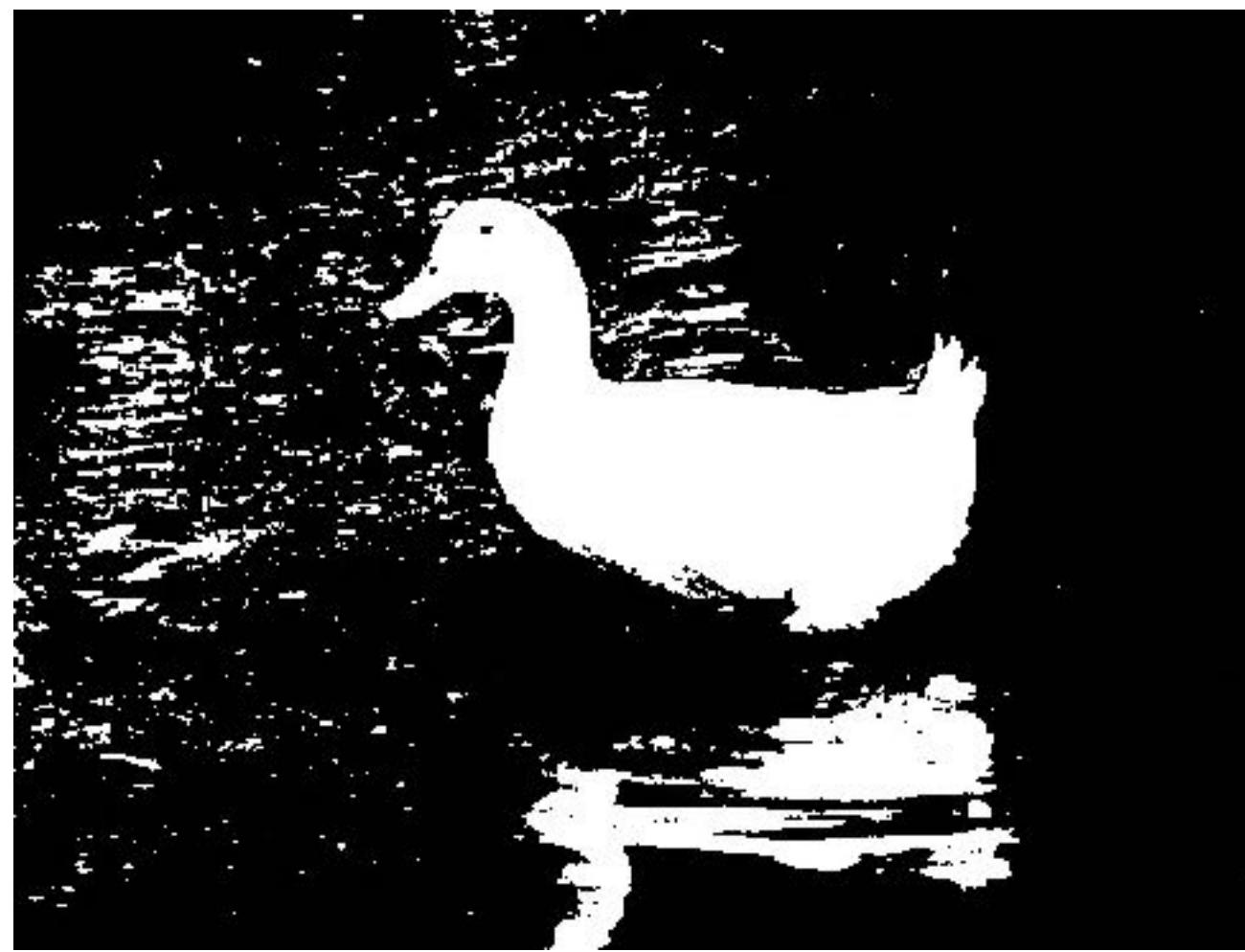


Different Choices for T

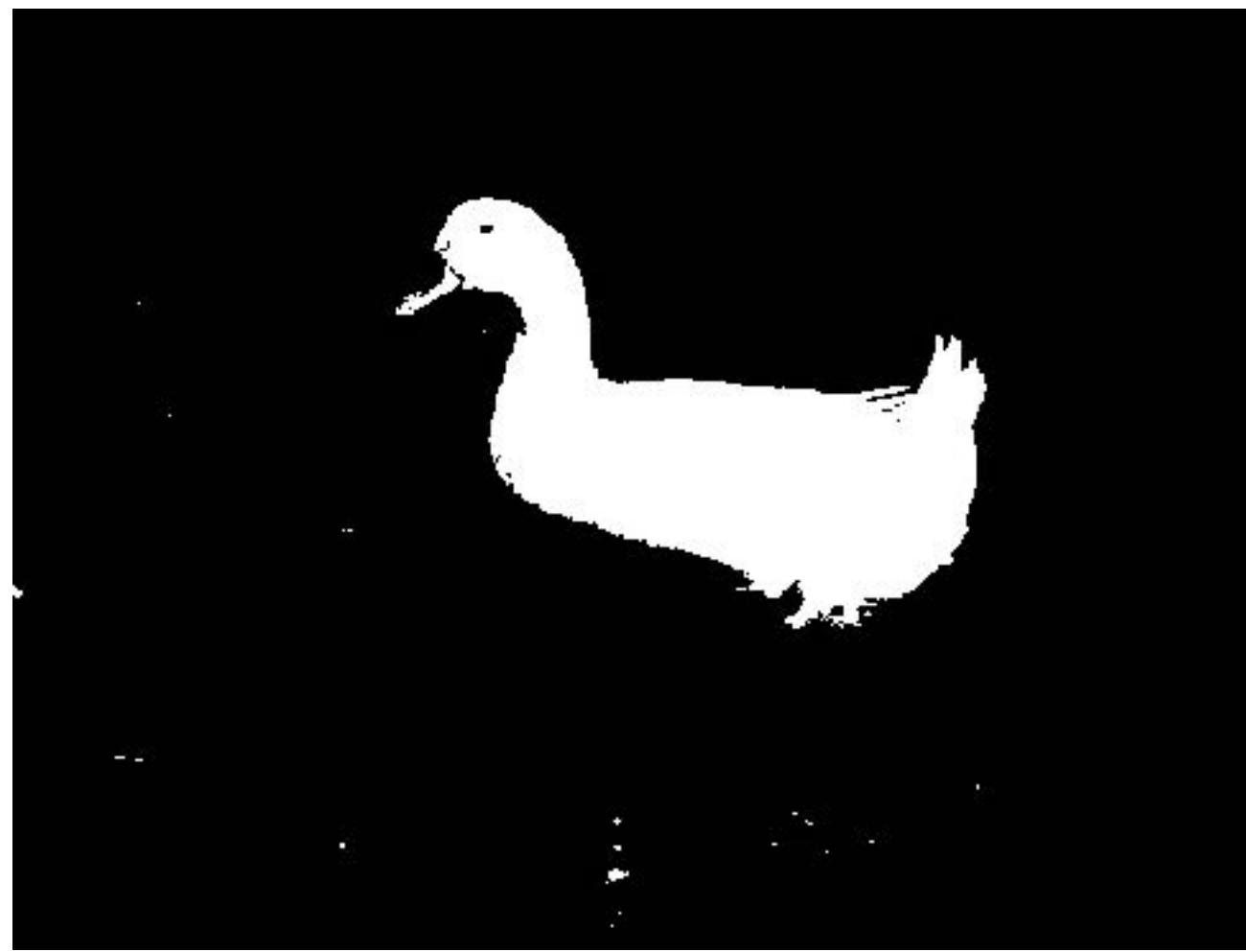
$T=50$



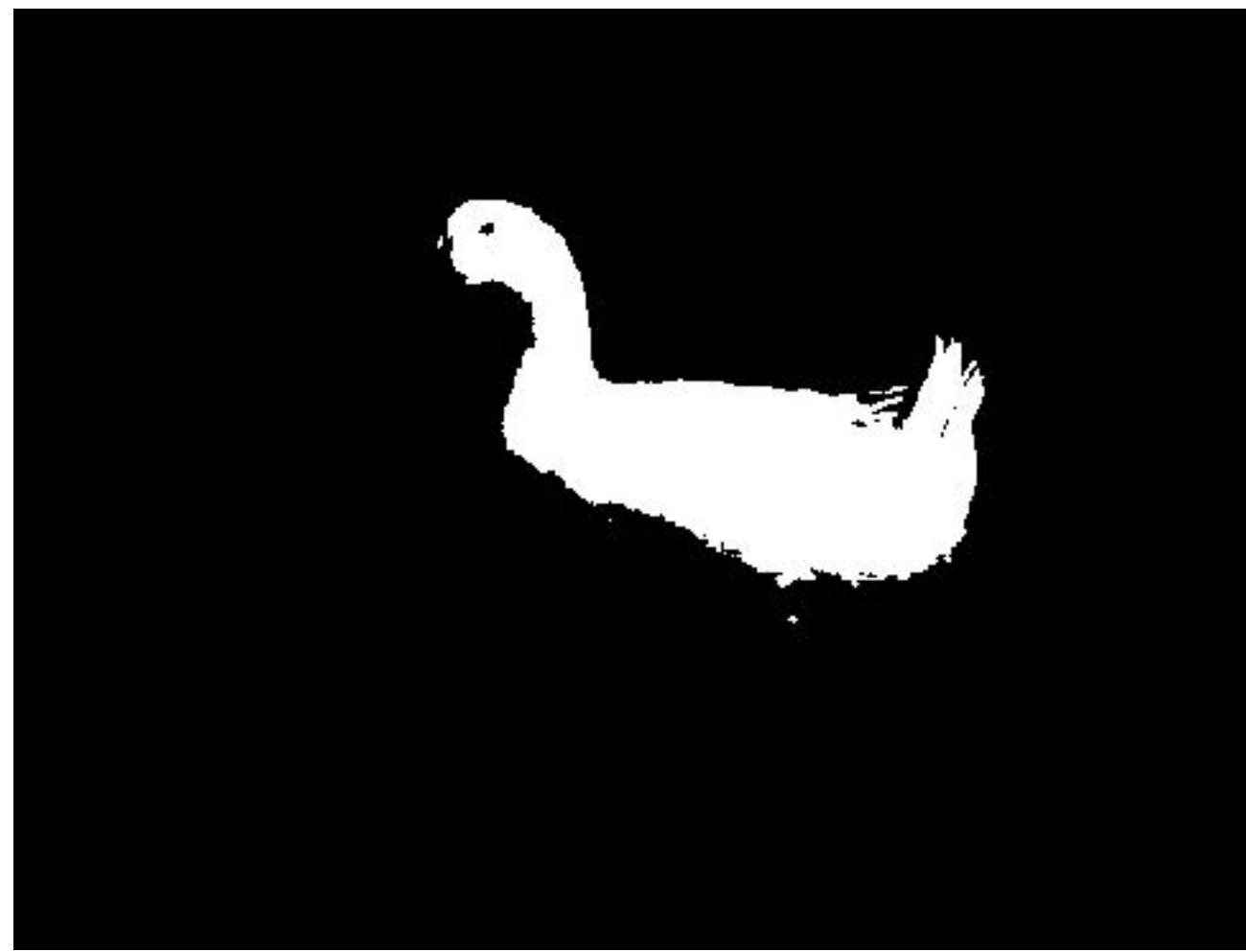
$T=100$



$T=150$



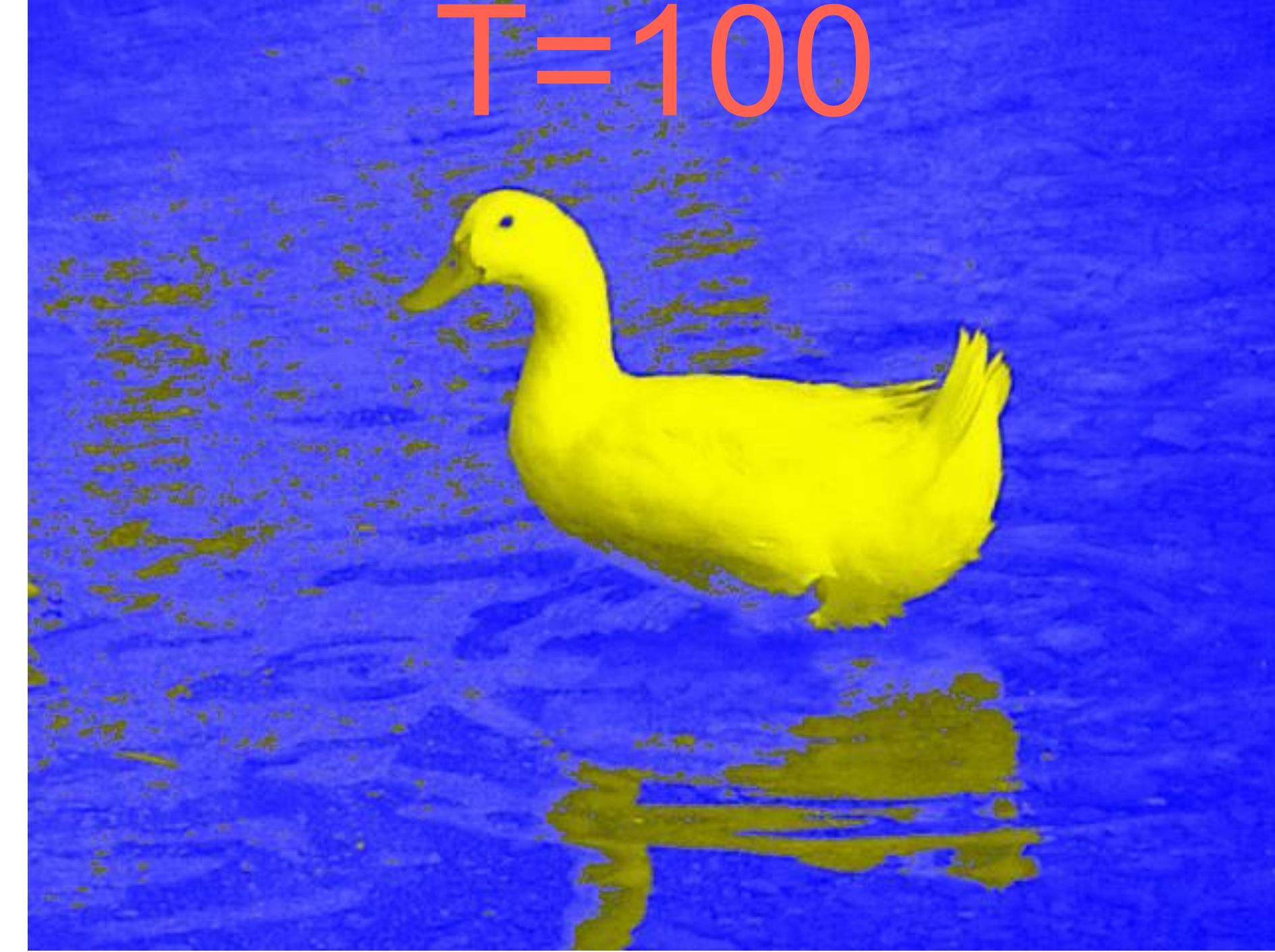
$T=200$



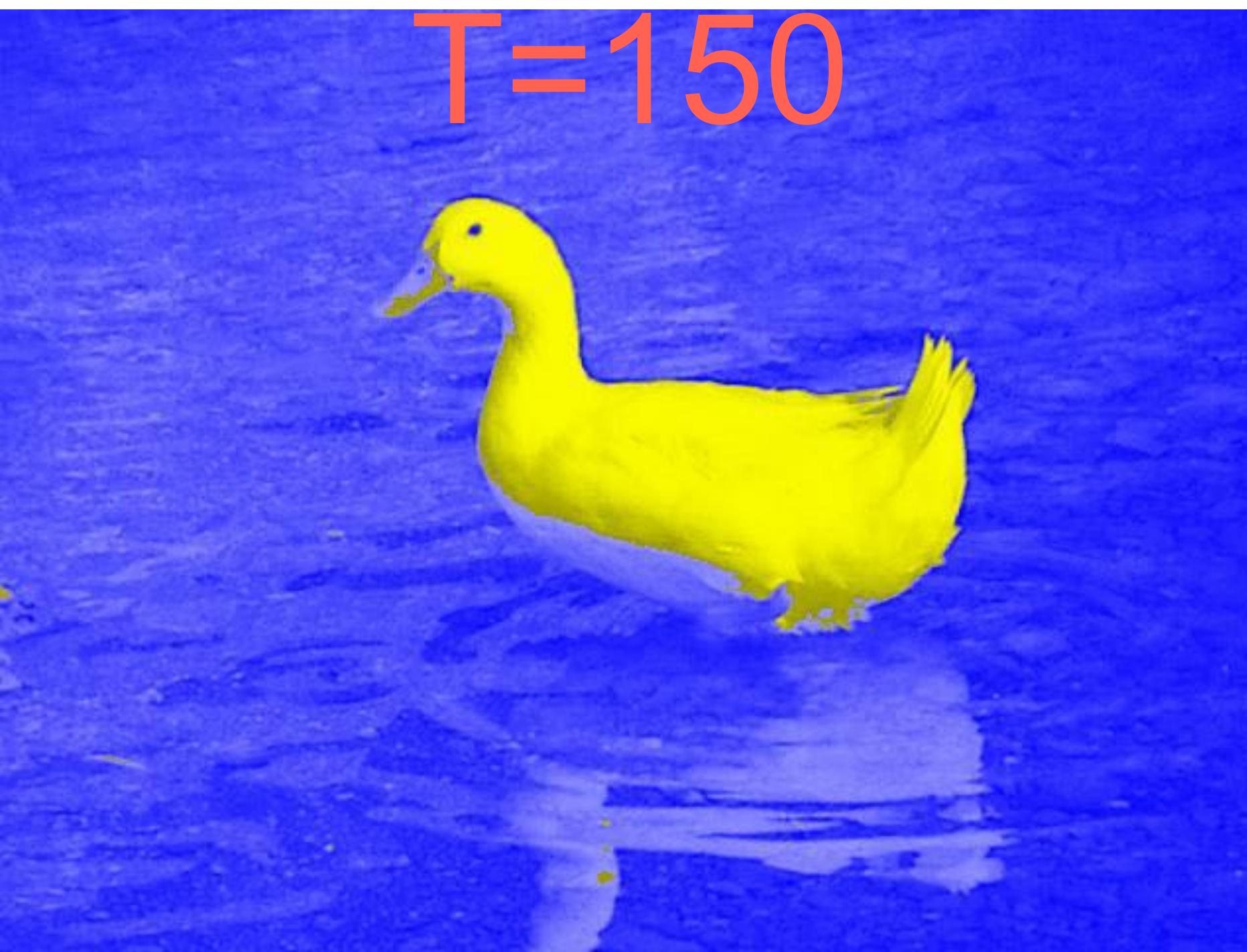
$T=50$



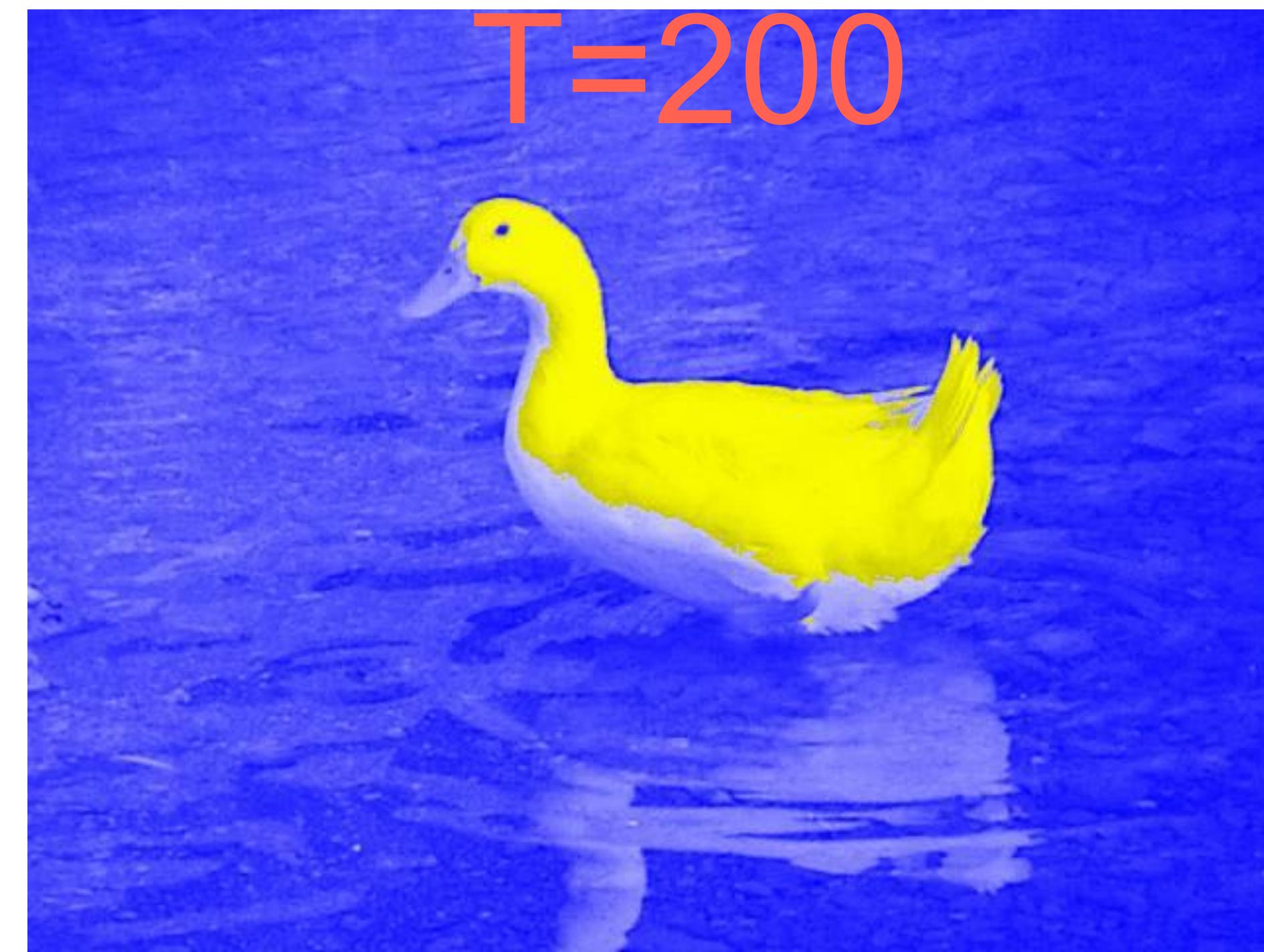
$T=100$



$T=150$

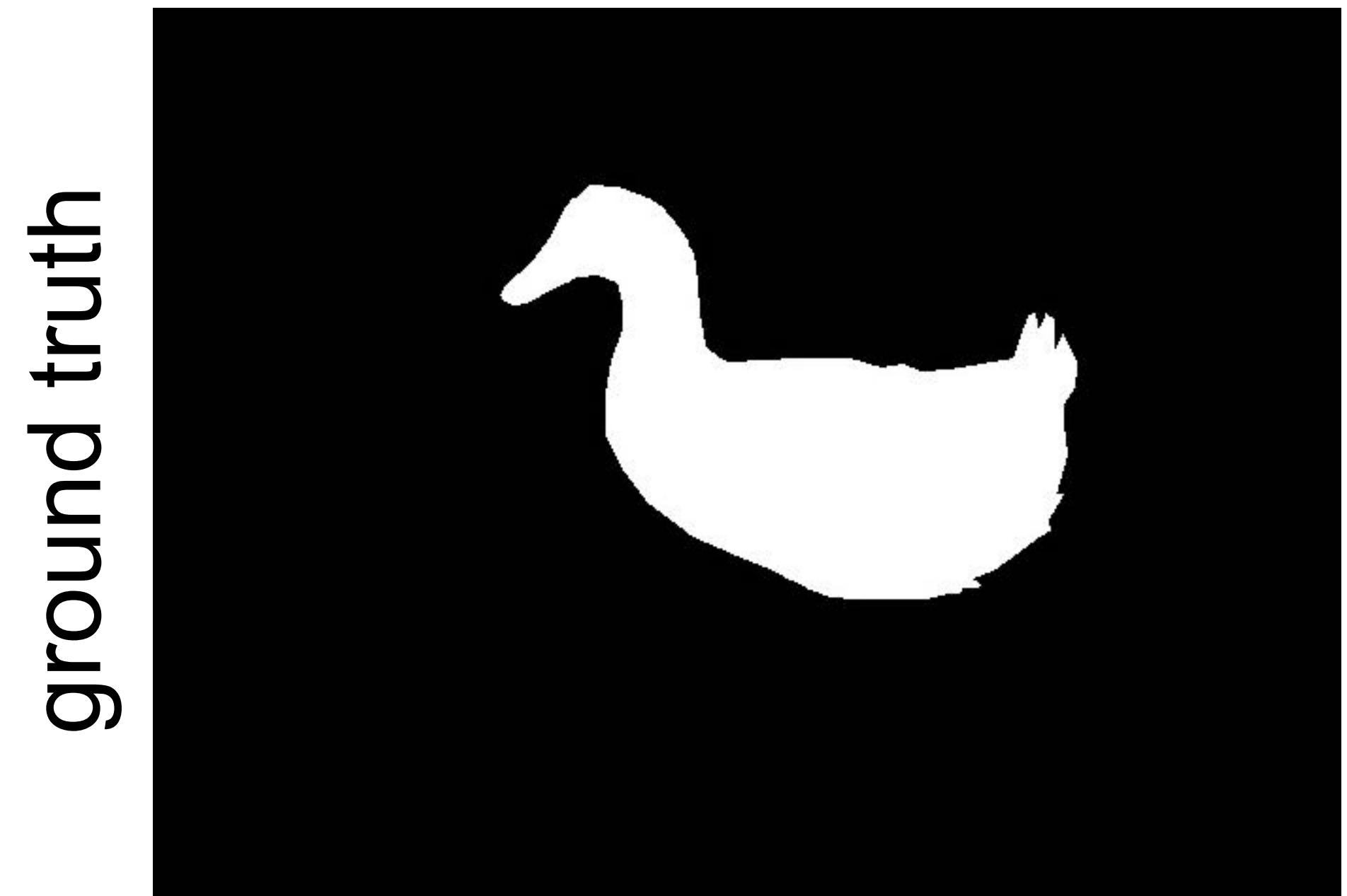


$T=200$



Segmentation Performance

- To analyze performance, we need to know the true classification of each test.
- We need to do the segmentation by hand on some example images.



ROC (Receiver operating characteristic) Analysis

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- An ROC (receiver operating characteristic) curve characterizes the performance of a binary classifier.

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- An ROC (receiver operating characteristic) curve characterizes the performance of a binary classifier.
- A binary classifier distinguishes between two different types of thing, e.g.,
 - Healthy/afflicted patients – cancer screening
 - Pregnancy tests
 - Foreground/background image pixels
 - Object detection

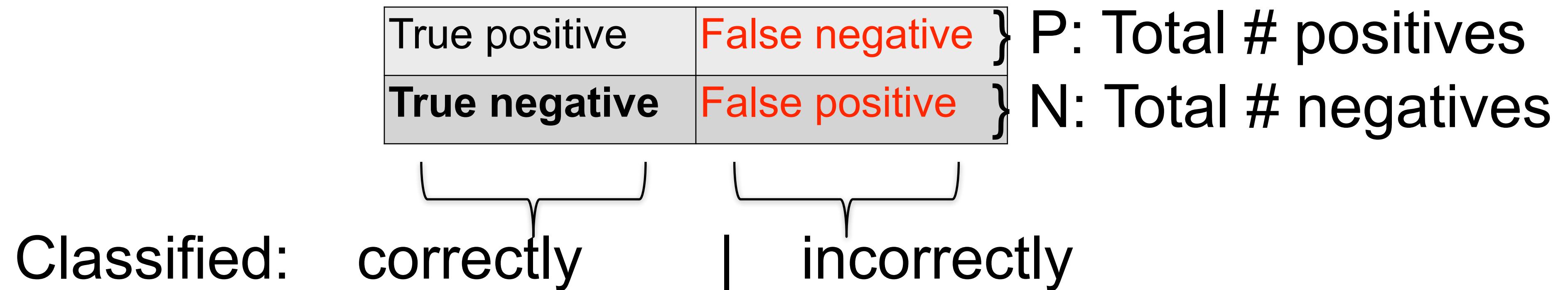
Classification Error

- Binary classifiers make errors.
- Two types of input to a binary classifier:
 - Positives
 - Negatives
- Four possible outcomes in any test:

True positive	False negative
True negative	False positive

P: Total # positives N: Total # negatives

Classified: correctly | incorrectly



ROC Explained

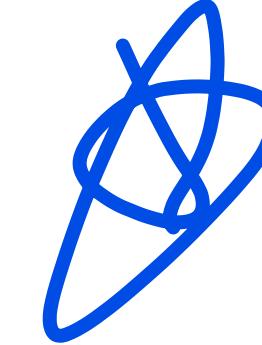
		ground truth	
		P	N
predicted	P'	TP	FP
	N'	FN	TN

ROC Explained

		ground truth	
		P	N
predicted	P'	TP	FP
	N'	FN	TN

$$\text{TPR} = \text{TP}/\text{P} = \text{TP}/(\text{TP}+\text{FN})$$

ROC Explained



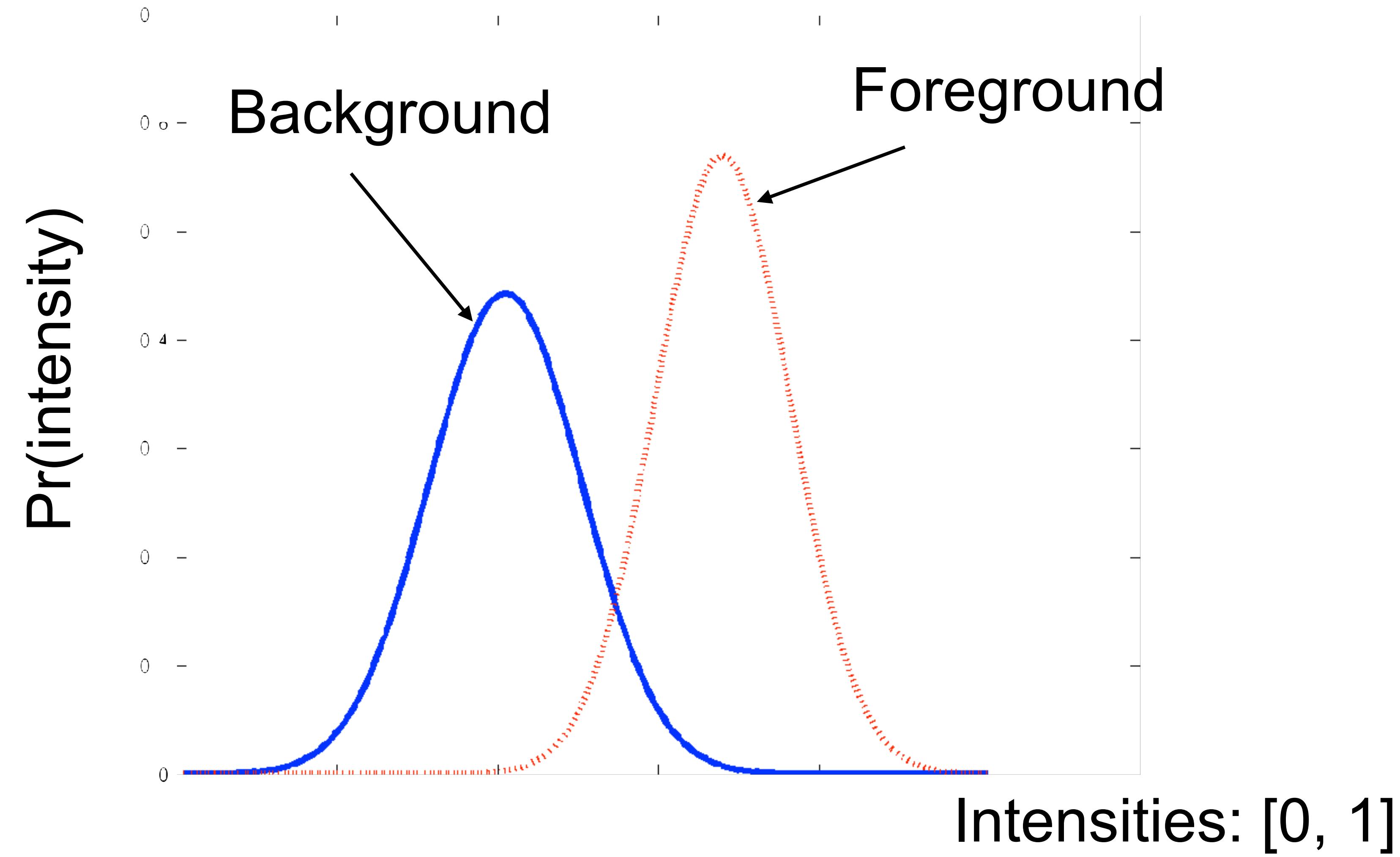
ground truth

		P	N
predicted	P'	TP	FP
	N'	FN	TN

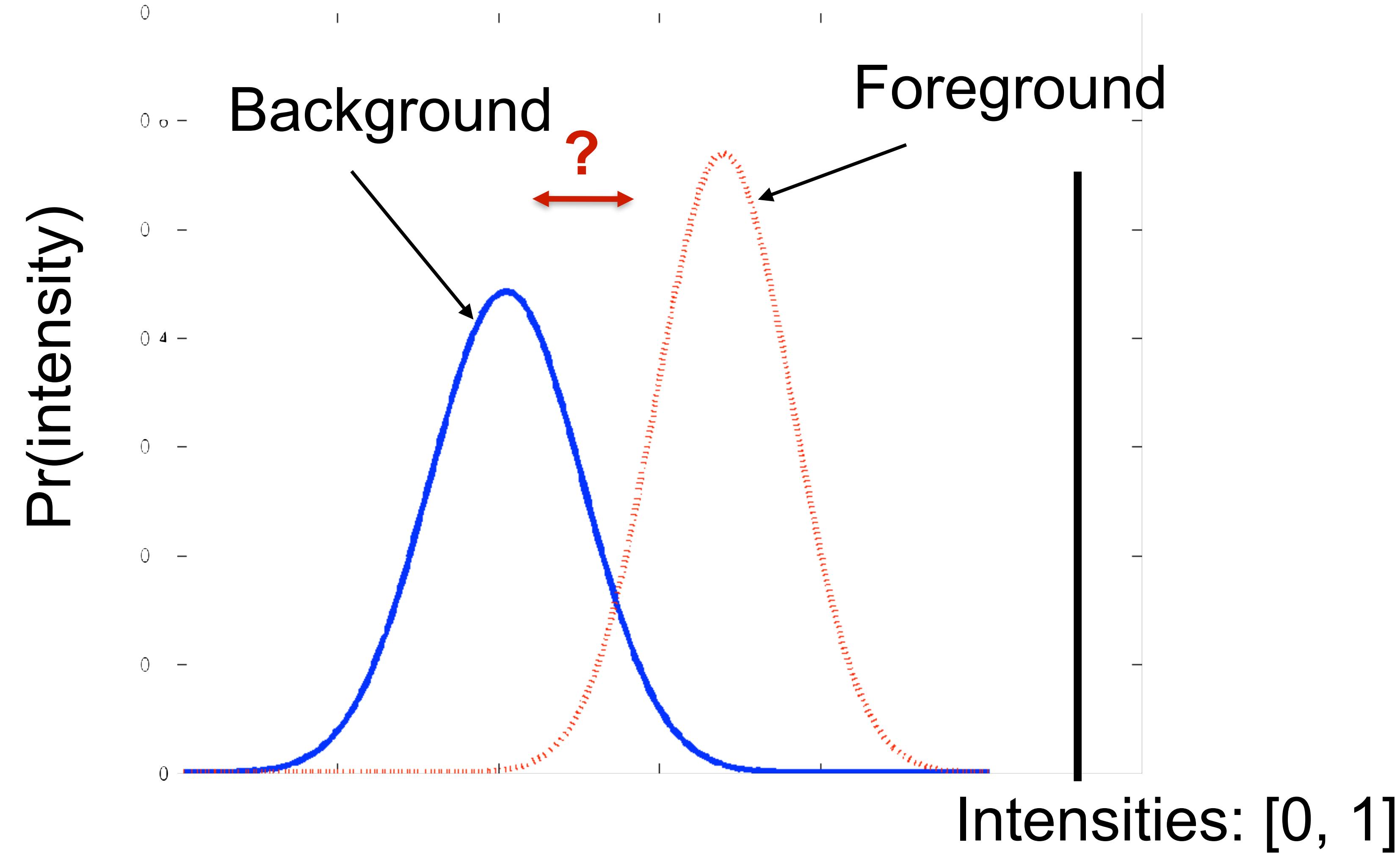
$$\text{TPR} = \text{TP}/\text{P} = \text{TP}/(\text{TP}+\text{FN})$$

$$\text{FPR} = \text{FP}/\text{N} = \text{FP}/(\text{FP}+\text{TN})$$

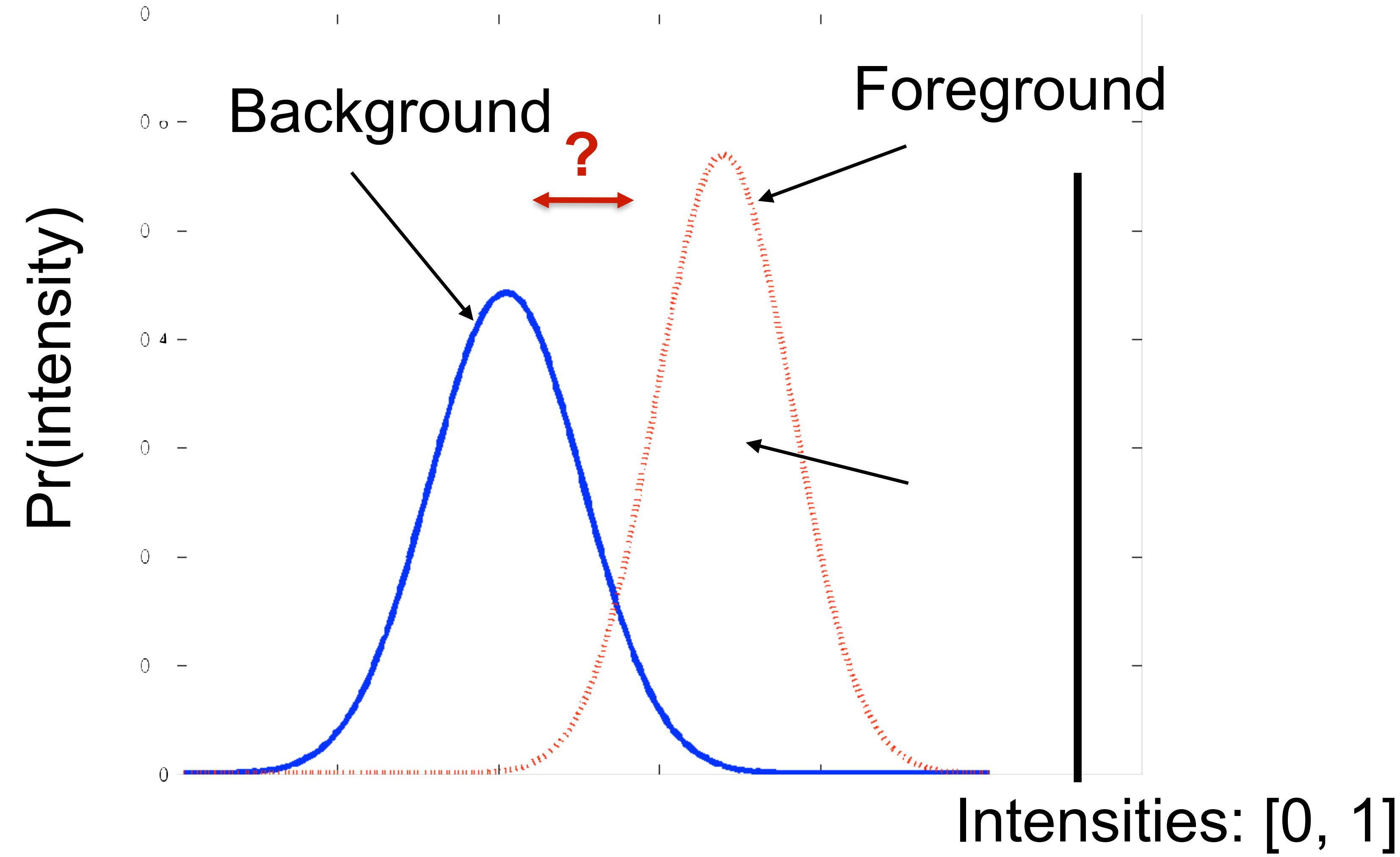
Real Measurement Distributions



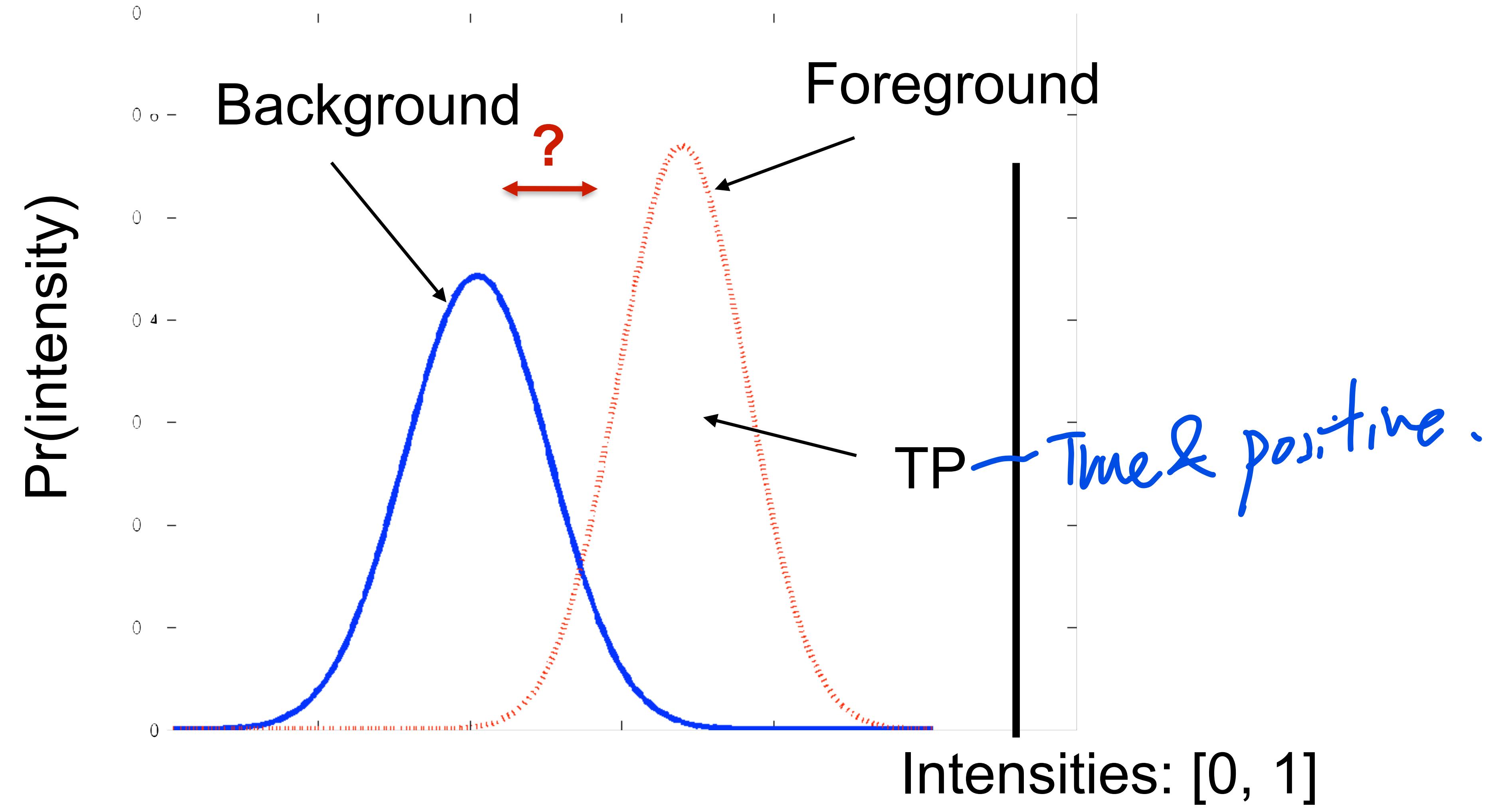
Real Measurement Distributions



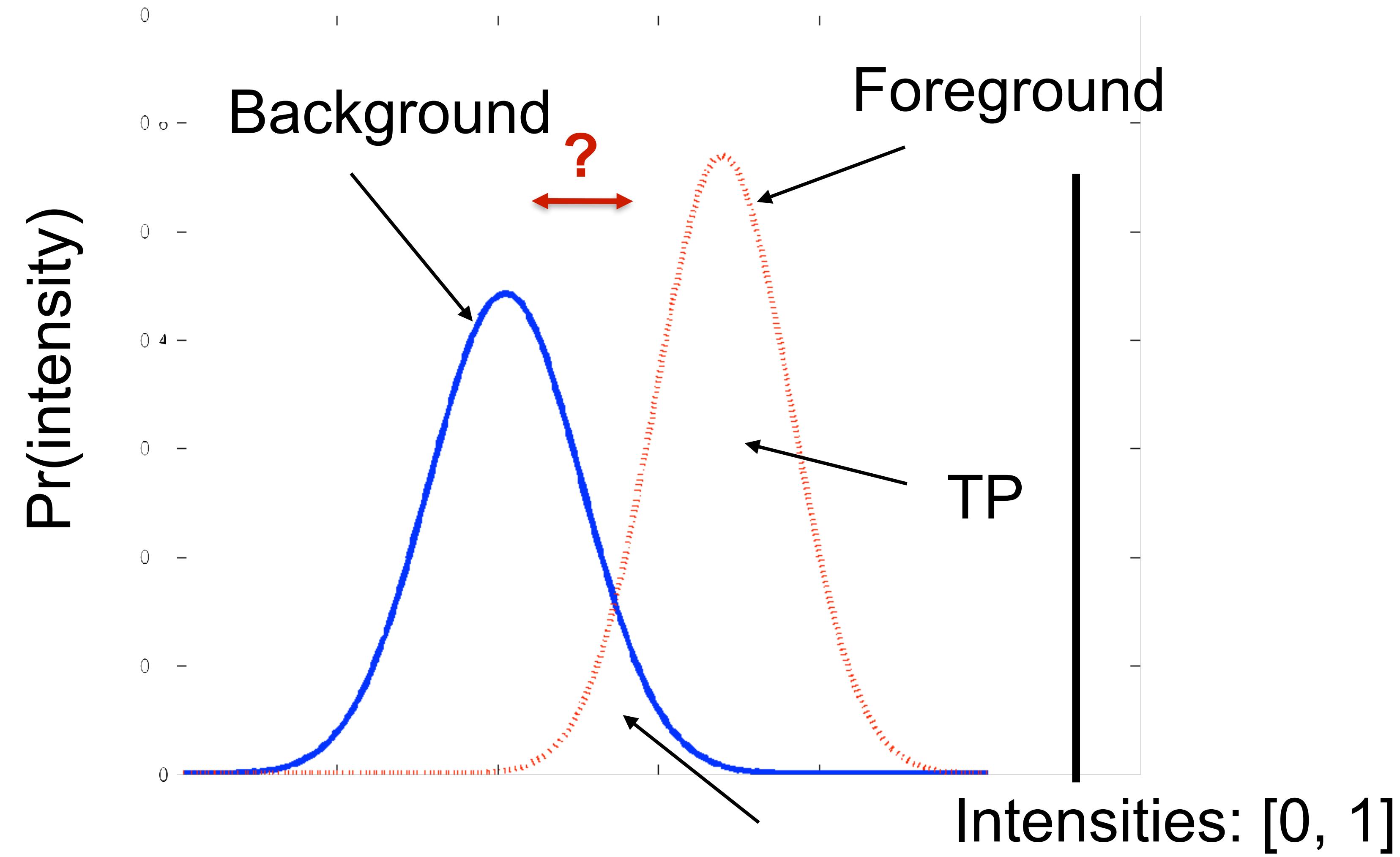
Real Measurement Distributions



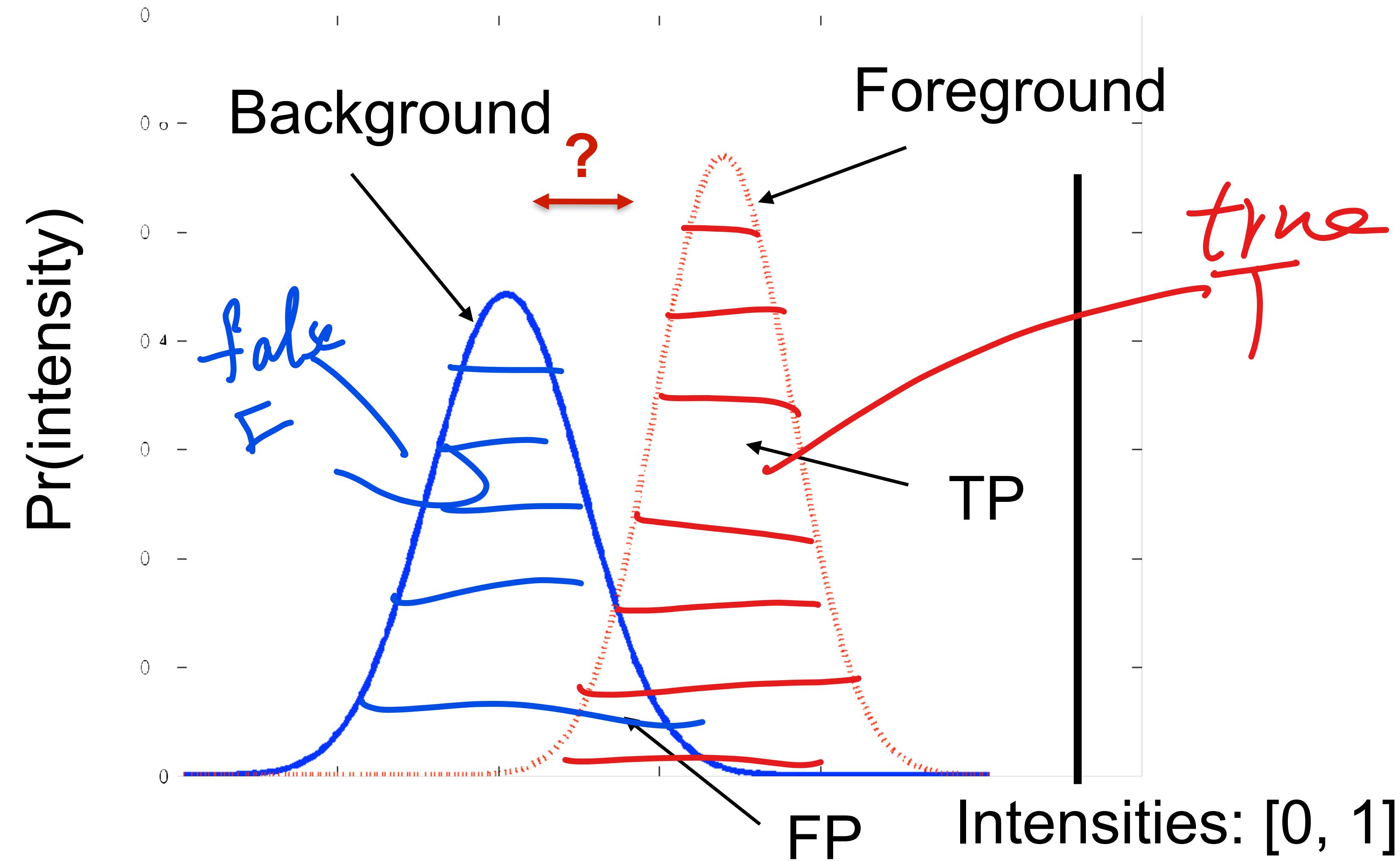
Real Measurement Distributions (*left by foreground*)



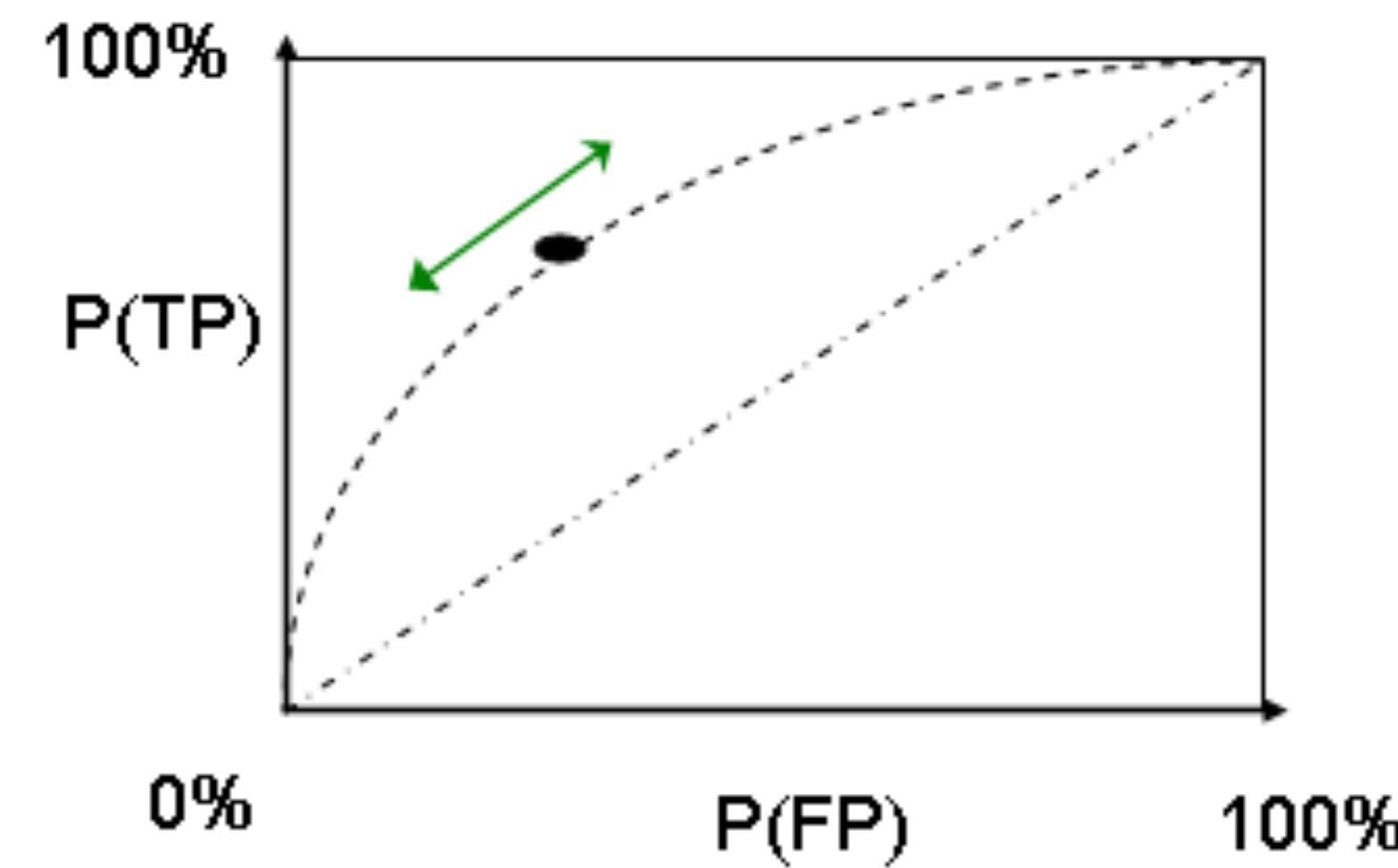
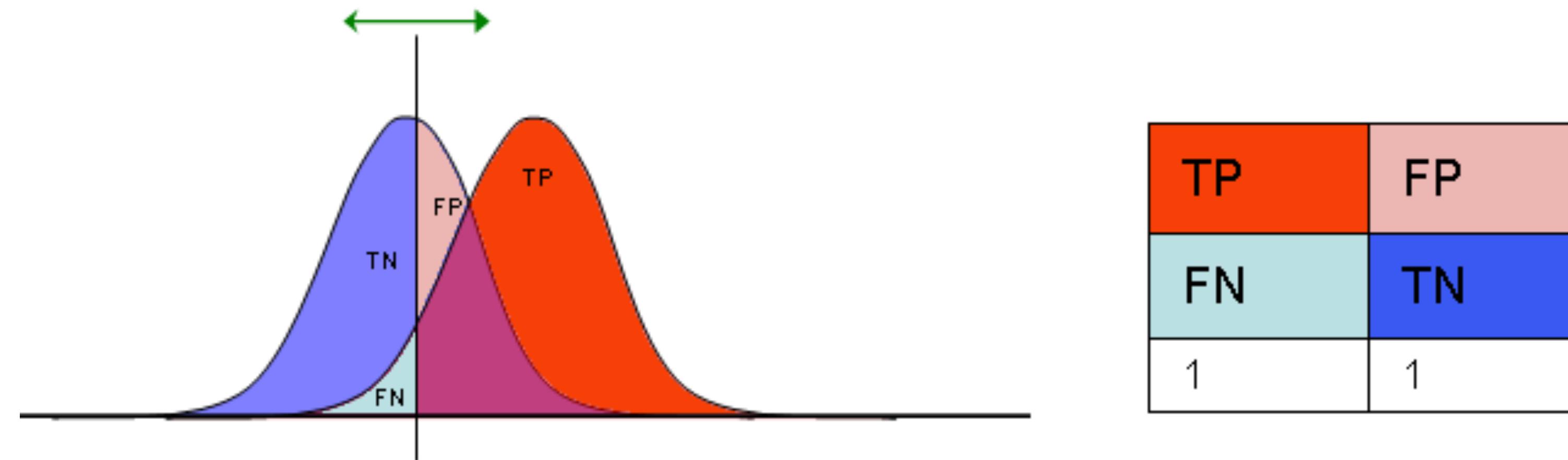
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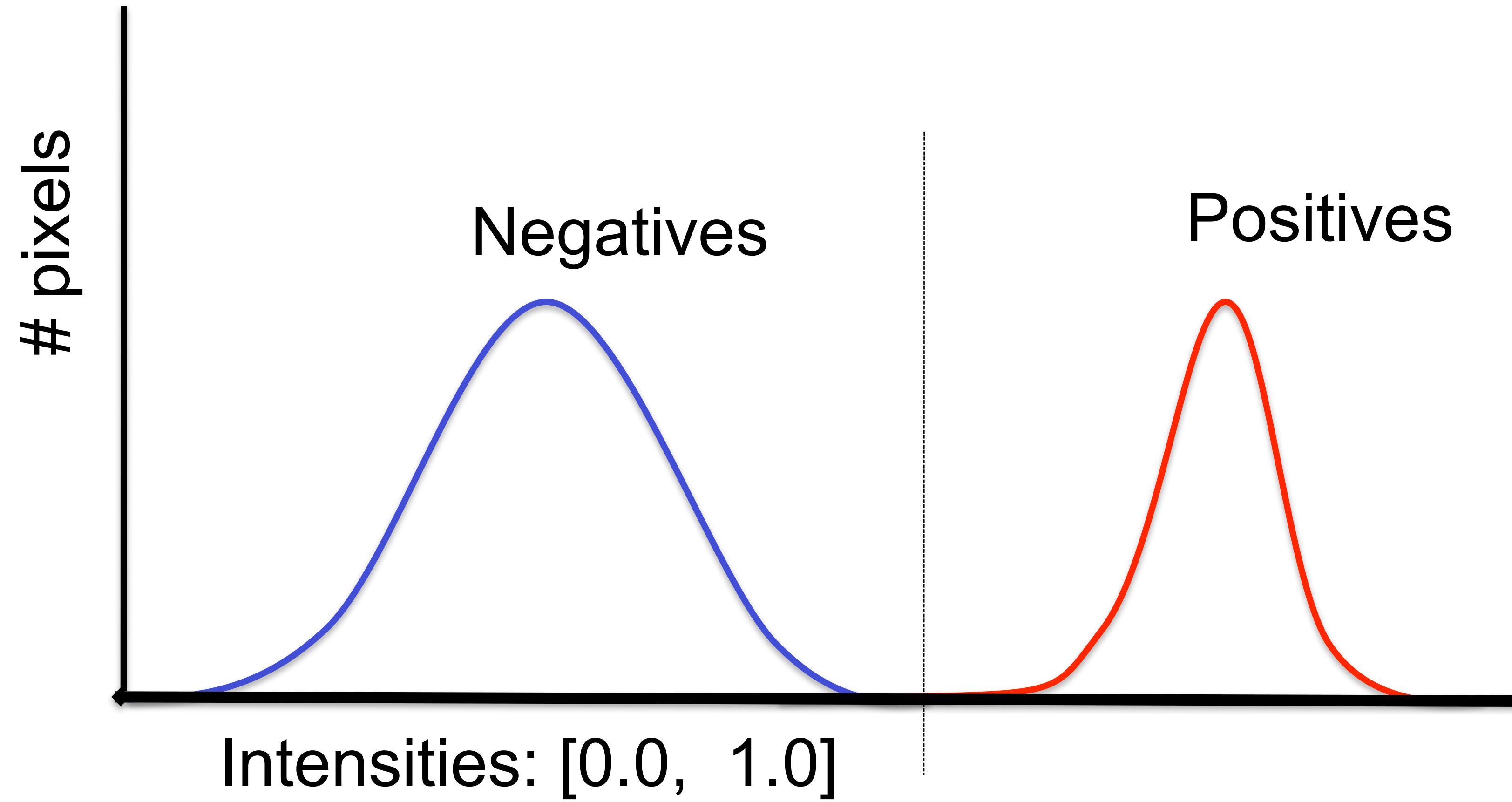


ROC Curve

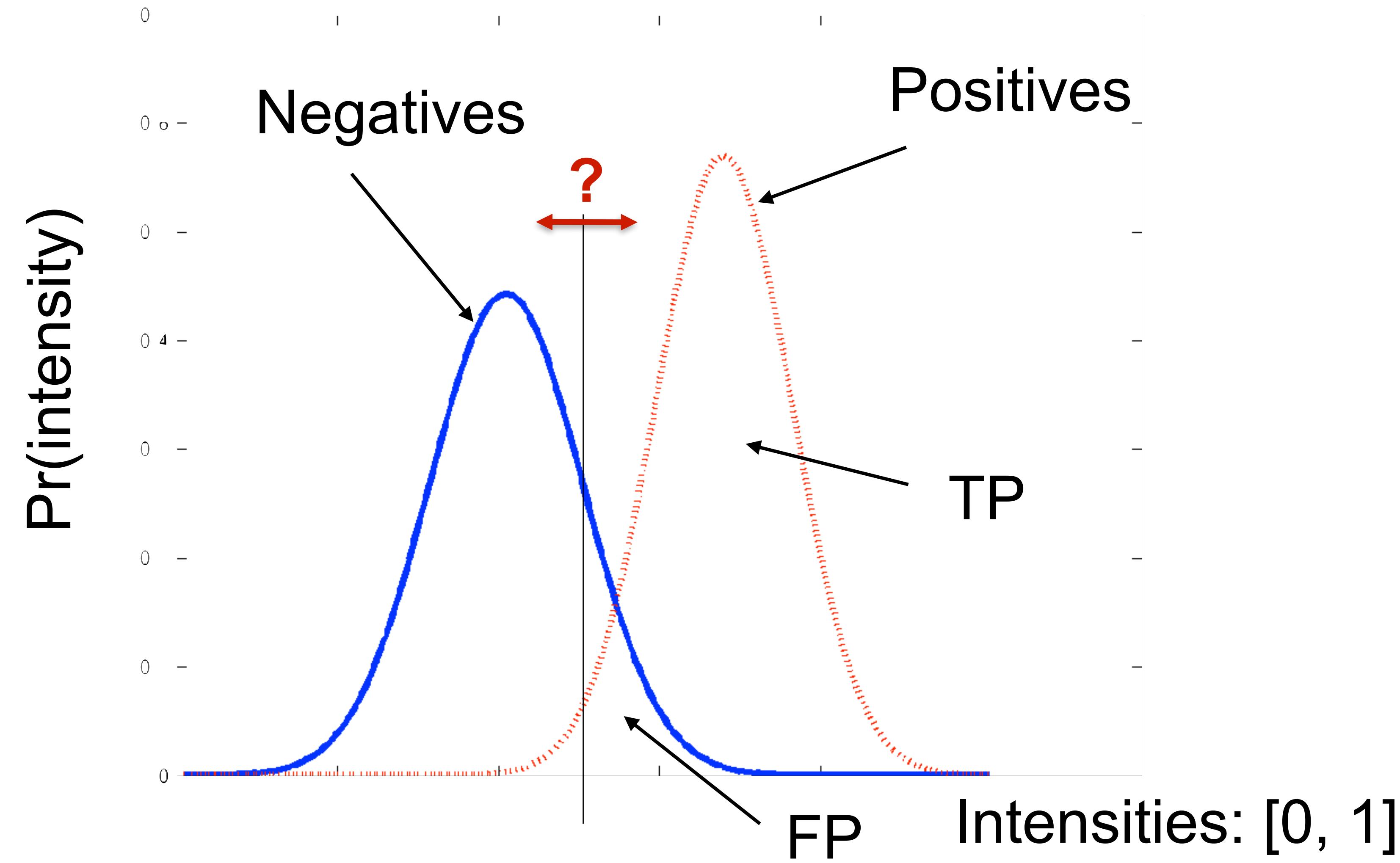


[wikipedia]

Wouldn't it be nice...



Real Measurement Distributions



Classification Outcomes

- As we change the threshold, FP and TP change.
- Notice that:
 - $FP + TN = N$ (the total number of negatives)
 - $TP + FN = P$ (total positives)
- How to evaluate performance?

positive 相当于对结果的
negative { false 是 GT ground truth
the

The ROC Curve

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- **Characterizes the error trade-off in binary classification tasks.**

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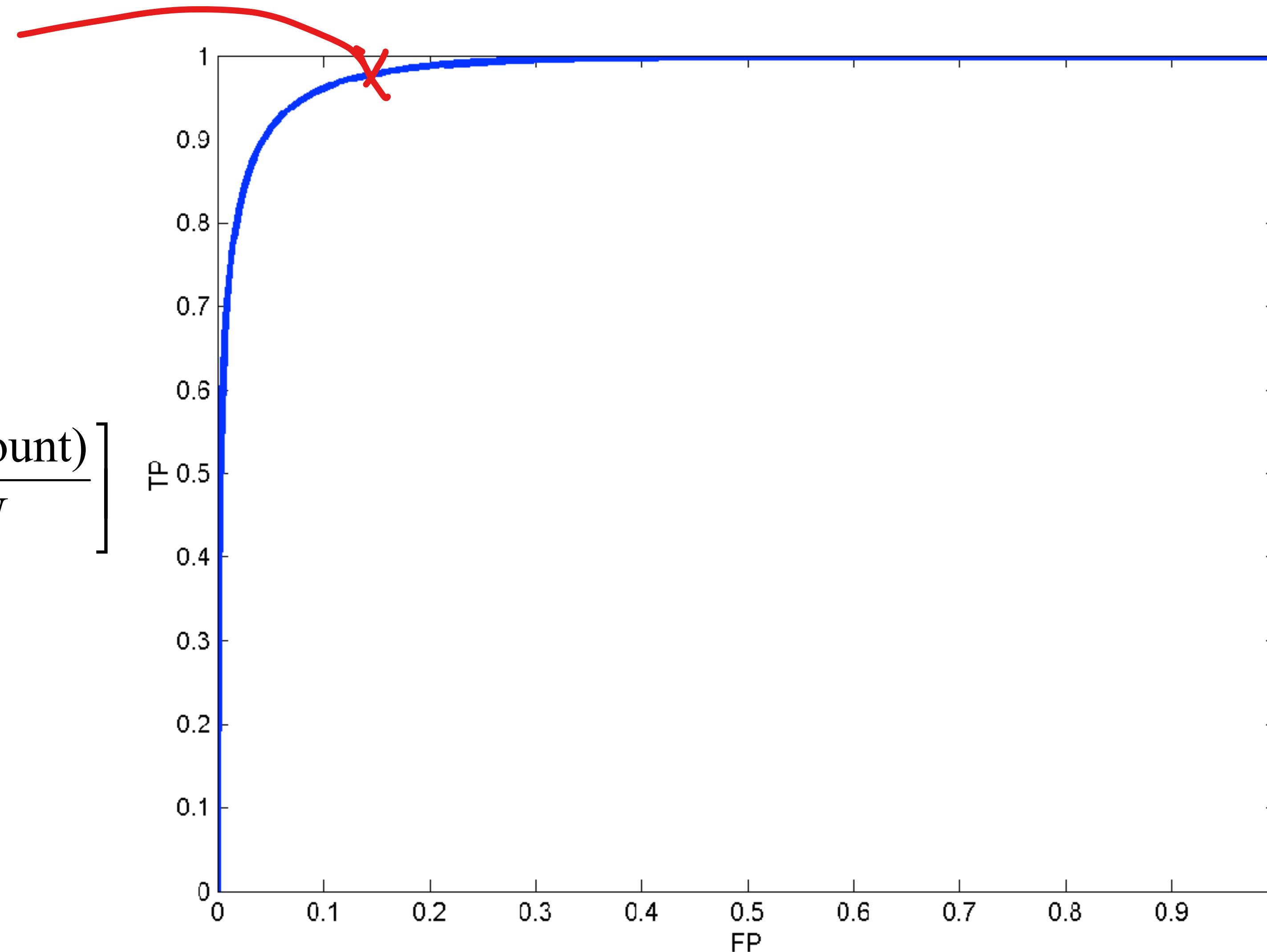
$$\frac{\text{True positive count}}{P}$$

The ROC Curve

- **Characterizes the error trade-off in binary classification tasks.**
- **It plots the TP fraction against FP fraction.**
- **TP fraction (sensitivity) is**
$$\frac{\text{True positive count}}{P}$$
- **FP fraction (1-specificity) is**
$$\frac{\text{False positive count}}{N}$$

each point
threshold

$$\left[\frac{(\text{True positive count})}{P = TP + FN} \right]$$



$$\left[\frac{(\text{False positive count})}{N = FP+TN} \right]$$

Properties of ROC curves

- An ROC curve always passes through (0,0) and (1,1).
- What is the ROC curve of a perfect system?
- What if the ROC curve is a straight line from (0,0) to (1,1)?

Area under the ROC curve

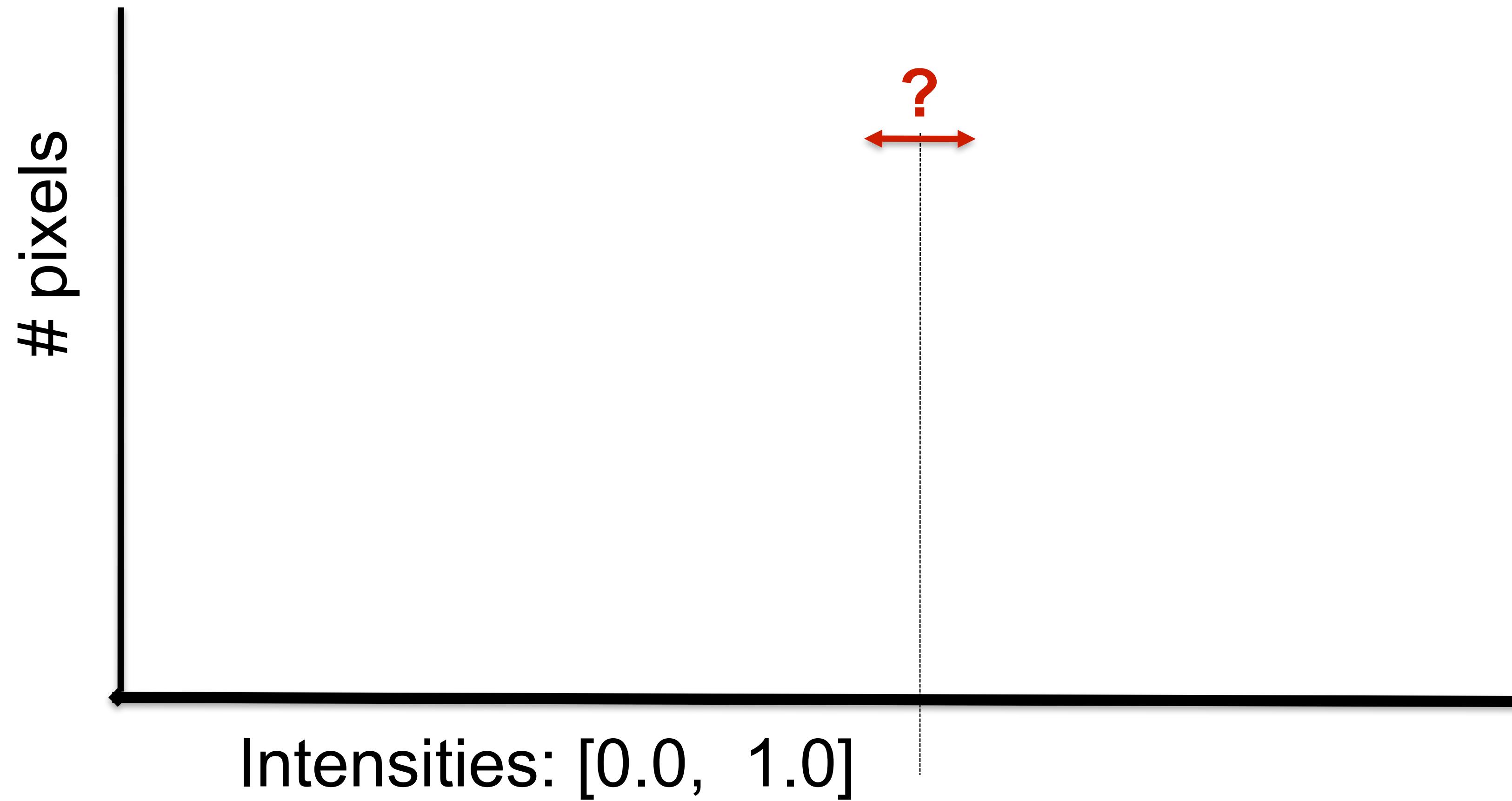
- The area **A** under the curve measures overall classification performance.
- If the distributions of measurements on positive and negative cases can be modeled as Normal distributions (**Gaussians**) **N** with $N(\mu_P, \sigma_P)$ and $N(\mu_N, \sigma_N)$, respectively, then

$$A = Z\left(\frac{|\mu_P - \mu_N|}{(\sigma_P^2 + \sigma_N^2)^{1/2}} \right)$$

- **Z** is the cumulative normal distribution function

$$Z(x) = \int_{-\infty}^x z(t)dt$$

How to select a Threshold?



Operating points

- Choose an operating point by assigning relative costs and values to each outcome:
 - V_{TN} – value of true negative
 - V_{TP} – value of true positive
 - C_{FN} – cost of false negative
 - C_{FP} – cost of false positive
- Choose the point on the ROC curve with gradient
$$\beta = \frac{N V_{TN} + C_{FP}}{P V_{TP} + C_{FN}}$$
- For simplicity, we often set $V_{TN} = V_{TP} = 0$.

Classification outcomes

