

GIVEN: POINT SETS

$$P = \{p_i\}_{i=1:n}$$

$$Q = \{q_i\}_{i=1:n}$$

+ CORRESPONDENCE, i.e., $p_i \leftrightarrow q_i \quad \forall i$

GOAL. FIND RIGID TRANSFORM (R, t) SUCH THAT

$$E(R, t) = \sum \|p_i - Rq_i - t\|^2 \quad \text{IS MINIMIZED, i.e.,}$$

BEST ALIGNING ^{RIGID} TRANSFORM FOR THE
GIVEN CORRESPONDENCE.

$$E(R, t) = \sum_{i=1}^n \|p_i - Rq_i - t\|^2 \quad (1) \quad \text{SUCH THAT} \quad \left\{ \begin{array}{l} RR^T = I \quad (2) \\ \text{RIGID TRANSFORM} \\ \det(R) = 1 \quad (3) \end{array} \right.$$

$$\min_{R, t} E(R, t) \Rightarrow \left. \begin{array}{l} \frac{\partial E}{\partial R} = 0 \\ \frac{\partial E}{\partial t} = 0 \end{array} \right\} \begin{array}{l} 4a \\ 4b \end{array}$$

FROM (4b)

$$\frac{\partial E}{\partial t} = \sum_i 2(p_i - Rq_i - t) = 0$$

$$\Rightarrow \frac{\sum p_i}{n} - \frac{\sum Rq_i}{n} - \frac{\sum t}{n} = 0$$

$$\Rightarrow \boxed{\bar{p} = R\bar{q} + t} \quad (5)$$

$$\left. \begin{array}{l} \bar{p} = \frac{\sum p_i}{n} \\ \bar{q} = \frac{\sum q_i}{n} \end{array} \right\} \begin{array}{l} \text{MEAN OF} \\ \text{POINT} \\ \text{SETS} \end{array}$$

USING (5) IN (1) WE GET,

$$E(R, t) = \sum_{i=1}^n \|p_i - Rq_i + R\bar{q} - \bar{p}\|^2$$

$$= \sum_{i=1}^n \|(p_i - \bar{p}) - R(q_i - \bar{q})\|^2$$

WHERE

$$= \sum_i \|\tilde{p}_i - R\tilde{q}_i\|^2 \quad \left\{ \begin{array}{l} \tilde{p}_i = p_i - \bar{p} \\ \tilde{q}_i = q_i - \bar{q} \end{array} \right. \quad \forall i$$

$$= E(R) \quad \left\{ \begin{array}{l} \text{ONLY} \\ \text{DEPENDS} \\ \text{ON } R \end{array} \right.$$

EQUATION (1) REDUCES TO,

$$E(R) = \sum_i \|\tilde{p}_i - R\tilde{q}_i\|^2$$

$$\boxed{\begin{array}{ll} \min_R E(R) & \text{s.t. } RR^T = I \\ & \det R = 1 \end{array}} \quad (6)$$

$$E(R) = \sum_i (\tilde{p}_i - R\tilde{q}_i)^T (\tilde{p}_i - R\tilde{q}_i)$$

$$= \sum_i \tilde{p}_i^T \tilde{p}_i - \sum_i \tilde{p}_i^T R\tilde{q}_i - \sum_i \tilde{q}_i^T R^T \tilde{p}_i + \sum_i \tilde{q}_i^T R^T R \tilde{q}_i$$

IDENTITY USING (2)

RECALL

$$\|x\|^2 = x^T x$$

when x is a COLUMN VECTOR

IF $x^T \cdot y$ IS A SCALAR THEN,

$$x^T y = y^T x$$

$$\begin{aligned} \tilde{q}_i^T R^T \tilde{p}_i &= (R\tilde{q}_i)^T \tilde{p}_i \\ &= \tilde{p}_i^T R \tilde{q}_i \end{aligned}$$

$$= \underbrace{\sum_i \tilde{p}_i^T \tilde{p}_i + \sum_i \tilde{q}_i^T \tilde{q}_i}_{\text{INDEPENDENT OF } R} - 2 \sum_i \tilde{p}_i^T R \tilde{q}_i$$

INDEPENDENT OF R

$$\Rightarrow \min_R E(R) \stackrel{\substack{\uparrow \\ \text{EQUIVALENT TO}}}{=} \min - 2 \sum_i \tilde{p}_i^T R \tilde{q}_i = \max_R \sum_i \tilde{p}_i^T R \tilde{q}_i$$

SO, EQUATION (6) REDUCES TO

$$\boxed{\begin{array}{ll} \max \sum_i \tilde{p}_i^T R \tilde{q}_i & \text{s.t. } RR^T = I \\ & \det R = 1 \end{array}} \quad (7)$$

$$\sum_i \tilde{p}_i^T R \tilde{q}_i = \text{TRACE} \left\{ \underbrace{\begin{bmatrix} -\tilde{p}_1^T - \\ -\tilde{p}_2^T - \\ \vdots - \\ -\tilde{p}_n^T - \end{bmatrix}}_{\tilde{P}^T \quad n \times 3} \underbrace{\begin{bmatrix} R \end{bmatrix}}_{3 \times 3} \underbrace{\begin{bmatrix} \tilde{q}_1 & \tilde{q}_2 & \dots & \tilde{q}_n \end{bmatrix}}_{\tilde{Q} \quad 3 \times n} \right\}$$

\tilde{Q}
↑
matrix

$$= \text{TRACE} (\tilde{P}^T R \tilde{Q})$$

TRACE OF A MATRIX
= SUM OF DIAGONALS

SO, EQUATION (7) REDUCES TO

$$\boxed{\begin{array}{l} \max_{\substack{R \\ \det(R) = 1}} \text{TRACE}(\tilde{P}^T R \tilde{Q}) \end{array} \quad \begin{array}{l} \text{s.t. } R R^T = I \\ \det(R) = 1 \end{array}} \quad (8)$$

$$\text{TRACE}(AB) = \text{trace}(BA) \quad - (9)$$

$$\Rightarrow \text{trace}(\tilde{P}^T R \tilde{Q}) = \text{trace} \tilde{R} \tilde{Q} \tilde{P}^T$$

$$\text{LET } \tilde{Q} \tilde{P}^T = U \Sigma V^T$$

SINGULAR
VALUE
DECOMPOSITION

$$\left\{ \begin{array}{l} \text{SVD}(\tilde{Q} \tilde{P}^T) = U \Sigma V^T \\ \uparrow \\ \text{SVD}(\sum_i \tilde{q}_i \tilde{p}_i^T) \end{array} \right.$$

$$\begin{aligned} \Rightarrow \text{trace}(\tilde{P}^T R \tilde{Q}) &= \text{trace}(R U \Sigma V^T) \\ &= \text{trace}(\Sigma \underbrace{V^T R U}_{\substack{\uparrow \\ \text{ORTHONORMAL} \\ \text{SINCE}}}) \end{aligned} \quad \left\{ \begin{array}{l} \text{USING (9)} \end{array} \right.$$

$$V^T V = U^T U = R^T R = I$$

$$\begin{aligned} \text{SAY } M &= V^T R U = \begin{bmatrix} m_{11} & m_{12} & m_{13} \\ m_{21} & m_{22} & m_{23} \\ m_{31} & m_{32} & m_{33} \end{bmatrix} \\ \text{SINCE } M^T M &= I \Rightarrow 1 = m_{i1}^T m_{i1} = \sum_{j=1}^3 m_{ij}^2 \Rightarrow |m_{ij}| \leq 1 \end{aligned} \quad (10)$$

$$\begin{aligned} \max_R \text{trace}(\Sigma M) &= \max_R \text{trace} \begin{bmatrix} \sigma_1 & 0 & 0 \\ 0 & \sigma_2 & 0 \\ 0 & 0 & \sigma_3 \end{bmatrix} \begin{bmatrix} m_{11} & m_{12} & m_{13} \\ m_{21} & m_{22} & m_{23} \\ m_{31} & m_{32} & m_{33} \end{bmatrix} \\ &= \sum_{i=1}^3 \sigma_i m_{ii} \\ &\leq \sum_{i=1}^3 \sigma_i \end{aligned} \quad \left\{ \begin{array}{l} \text{USING (10)} \\ \text{AND } \sigma_i \geq 0 \end{array} \right. \quad (11)$$

$$\begin{aligned} \text{SO } \max_R \text{tr}(\Sigma M) &\leq \sum_i \sigma_i \\ \& \text{ EQUALITY HOLDS WHEN } m_{ii} &= 1 \end{aligned} \quad \left\{ \begin{array}{l} \text{FOLLOWS} \\ \text{FROM (10) \& (11)} \end{array} \right.$$

so

$$\max_R \text{tr}(\tilde{P}^T R \tilde{Q}) \Rightarrow m_{ii} = 1 \quad i = 1:3$$

$$\Rightarrow M = I$$

$$\Rightarrow V^T R U = I$$

$$\Rightarrow V V^T R U U^T = V U^T \quad \left| \begin{array}{l} V V^T = I \\ U U^T = I \end{array} \right.$$

$$\Rightarrow \boxed{R = V U^T}$$

IF $\det(V U^T) = 1$, THEN

$$\boxed{\begin{array}{l} R = V U^T \\ t = \bar{p} - R \bar{q} \end{array}} \quad (\text{using } \textcircled{5})$$

IF $\det(V U^T) = -1$, THEN

$$\boxed{\begin{array}{l} R = V \begin{bmatrix} 1 & & \\ & 1 & \\ & & -1 \end{bmatrix} U^T \\ t = \bar{p} - R \bar{q} \end{array}}$$

FINAL SOLUTION.

$$\rightarrow \begin{cases} \bar{p} = \frac{\sum p_i}{n} \\ \bar{q} = \frac{\sum q_i}{n} \end{cases}$$

$$\rightarrow \text{SVD} \left(\sum_i \tilde{q}_i \tilde{p}_i^T \right) = \text{SVD}(\tilde{Q} \tilde{P}^T) = U \Sigma V^T$$

$$\rightarrow \boxed{\begin{array}{l} R = V \begin{bmatrix} 1 & & \\ & 1 & \\ & & \det(V U^T) \end{bmatrix} U^T \\ t = \bar{p} - R \bar{q} \end{array}}$$