Environment Mapping

Computer Graphics
CSE 167
Lecture 13

CSE 167: Computer graphics

- Environment mapping
 - An image-based lighting method
 - Approximates the appearance of a surface using a precomputed texture image (or images)
 - In general, the fastest method of rendering a surface

More realistic illumination

- In the real world, at each point in a scene, light arrives from all directions (not just from a few point light sources)
 - Global illumination is a solution, but is computationally expensive
 - An alternative to global illumination is an environment map
 - Store "omni-directional" illumination as images
 - Each pixel corresponds to light from a certain direction
 - Sky boxes make for great environment maps



Dror, Willsky, & Adelson 2004]

Reflection mapping

- Early (earliest?) non-decal use of textures
- Appearance of shiny objects
 - Phong highlights produce blurry highlights for glossy surfaces

A polished (shiny) object reflects a sharp image of its

environment

 The whole key to a shiny-looking material is providing something for it to reflect





Figure 2. (a). A shiny sphere rendered under photographically acquired real-world illumination. (b). The same sphere rendered under illumination by a point light source.

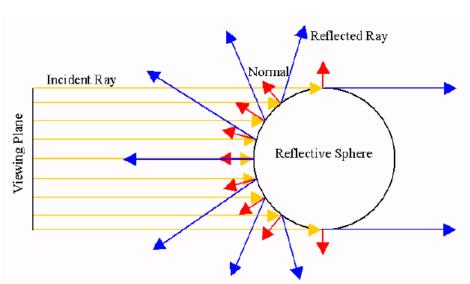
 A function from the sphere to colors, stored as a texture

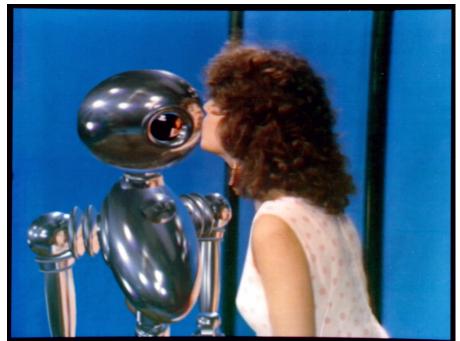




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Interface (Lance Williams, 1985)





Video

Flight of the Navigator (1986)









• Terminator 2 (1991)



• Star Wars: Episode I *The Phantom Menace* (1999)



Creating environment maps

- An environment map is a spherical panoramic image
- Capturing a spherical panoramic image
 - Use a 360 degree camera
 - Take a picture of a mirrored ball (called a light probe)









Light Probes by Paul Debevec http://www.debevec.org/Probes/

Environment maps as light sources

- Key assumption: light captured by an environment map is emitted from infinitely far away
- As such, an environment map consists of directional light sources
 - An environment map value is defined for each direction, independent of position in scene
 - The same environment map is used at each point in the scene

Environment maps



Global illumination with pre-computed radiance transfer [Sloan et al. 2002]



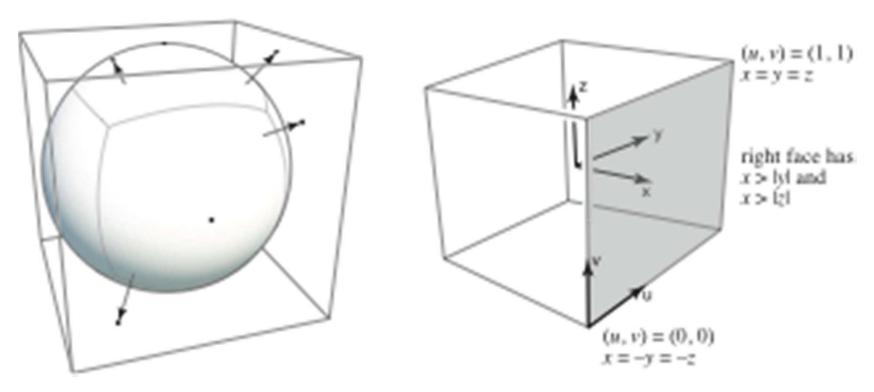
Reflection mapping [Georg-Simon Ohm University of Applied Sciences]

Environment maps

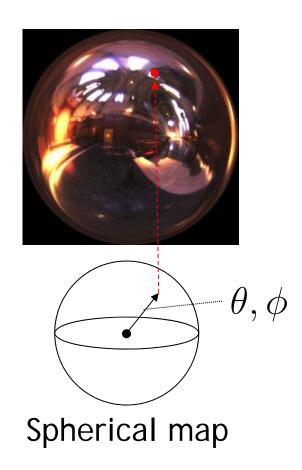


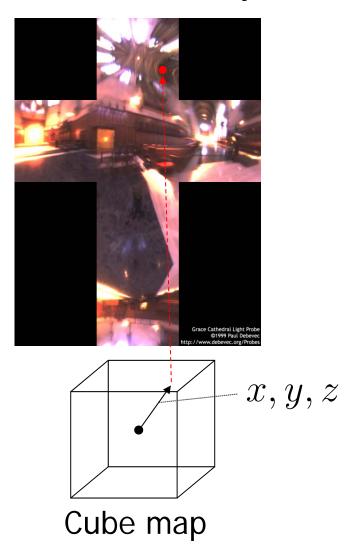
Cube environment map

Store incident light on six faces of a cube instead of on sphere



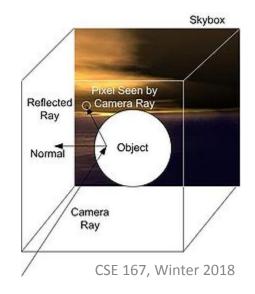
Cube environment map





Cube vs. spherical maps

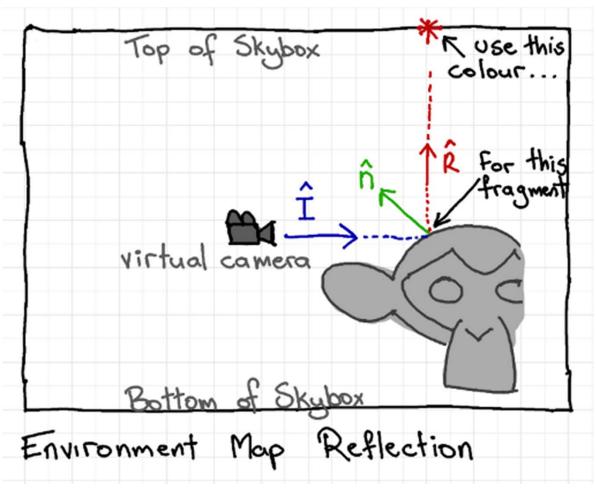
- Advantages of cube maps
 - More even texel sample density causes less distortion, allowing for lower resolution maps
 - Easier to dynamically generate cube maps for realtime simulated reflections



Cube environment map

- Cube map look-up
 - Given light direction (x,y,z)
 - Largest coordinate component determines cube map face
 - Dividing by magnitude of largest component yields coordinates within face
 - In GLSL:
 - Use (x,y,z) direction as texture coordinates to samplerCube

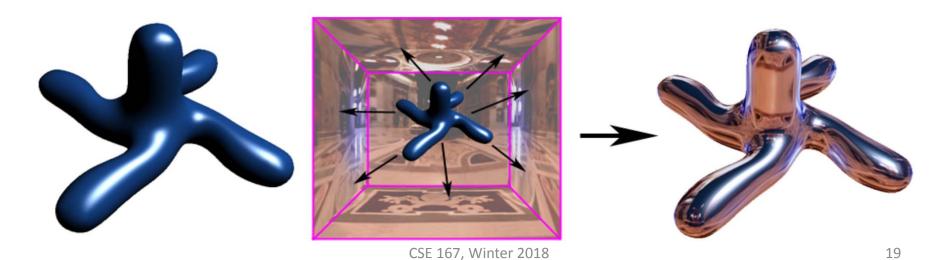
Environment mapping



Source: http://antongerdelan.net/opengl/cubemaps.html

Reflection maps

- Simulates mirror reflection
- Computes reflection vector at each pixel
- Use reflection vector to look up cube map
- Rendering cube map itself is optional (application dependent)



Reflection maps





Images from *Illumination and Reflection Maps:*Simulated Objects in Simulated and Real Environments
Gene Miller and C. Robert Hoffman
SIGGRAPH 1984 "Advanced Computer Graphics Animation" Course Notes

Reflection mapping in GLSL

- Application setup
 - Load and bind a cube environment map

```
glBindTexture(GL_TEXTURE_CUBE_MAP, ...);
glTexImage2D(GL_TEXTURE_CUBE_MAP_POSITIVE_X,...);
glTexImage2D(GL_TEXTURE_CUBE_MAP_NEGATIVE_X,...);
glTexImage2D(GL_TEXTURE_CUBE_MAP_POSITIVE_Y,...);
...
glEnable(GL_TEXTURE_CUBE_MAP);
```

Environment mapping: vertex shader

```
#version 400
in vec3 vp; // positions from mesh
in vec3 vn; // normals from mesh
uniform mat4 P, V, M; // proj, view, model matrices
out vec3 pos eye;
out vec3 n eye;
void main()
  pos_eye = vec3(V * M * vec4(vp, 1.0));
  n_{eye} = vec3(V * M * vec4(vn, 0.0));
 gl Position = P * V * M * vec4(vp, 1.0);
```

Environment mapping: fragment shader

```
#version 400
in vec3 pos eye;
in vec3 n eye;
uniform samplerCube cube_texture;
uniform mat4 V; // view matrix
out vec4 frag colour;
void main()
  // reflect ray around normal from eye to surface
  vec3 incident_eye = normalize(pos_eye);
  vec3 normal = normalize(n_eye);
  vec3 reflected = reflect(incident eye, normal);
  // convert from eye to world space
  reflected = vec3(inverse(V) * vec4(reflected, 0.0));
  frag colour = texture(cube texture, reflected);
```

Diffuse irradiance environment map

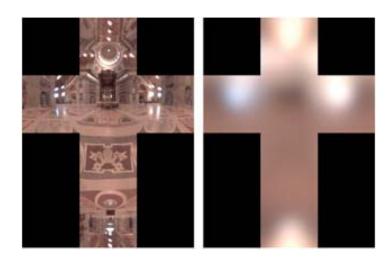
- Given a scene with k directional lights, light directions $d_1, ..., d_k$, and intensities $i_1, ..., i_k$ illuminating a diffuse surface with normal n and color c
- Pixel intensity *B* is computed as $B = c \sum_{j=1..k} \max(0, d_j \cdot n) i_j$
- The cost of computing B is proportional to the number of texels in environment map
- Observations
 - All surfaces with normal direction n will return the same value for the sum
 - The sum is dependent on just the lights in the scene and the surface normal

Diffuse irradiance environment map

- Precompute diffuse reflections
 - Precompute sum for any normal n and store result in a second environment map, indexed by surface normal
- Second environment map is called diffuse irradiance environment map
- Allows to illuminate objects with arbitrarily complex lighting environments with single texture lookup

Diffuse irradiance environment map

- Two cubic environment maps
 - Reflection map
 - Diffuse map



Diffuse shading vs. shading with diffuse map





Image source: http://http.developer.nvidia.com/GPUGems2/gpugems2 chapter10.html

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Environment mapping

Rendering with Natural Light (Paul Debevec,

1998)



Video