

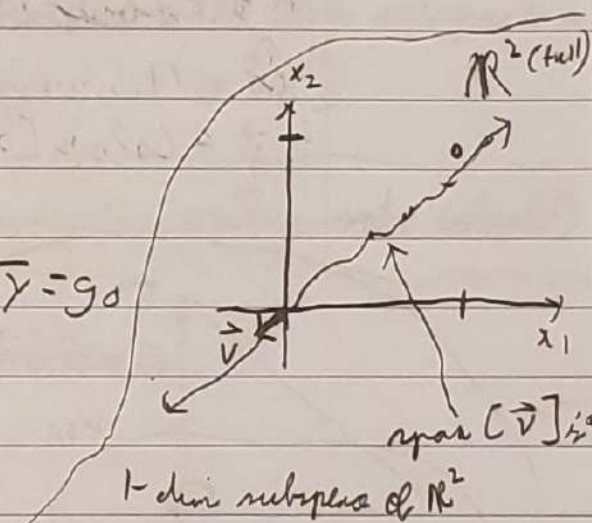
3/1/21

$$\vec{b} = (X^T X)^{-1} X^T \vec{y}, \text{ the OLS linear model, } \hat{\vec{y}} = X \vec{b}, g(\vec{x}_*) = \hat{y}_* = \vec{x}_*^T \vec{b}$$

What if we have no features? is the null model case.
Is there an OLS solution?

$$X = [\vec{1}_n] = \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix}$$

$$\vec{b} = b_0 = \underbrace{(X^T X)^{-1}}_{\frac{1}{n}} \underbrace{X^T}_{\sum y_i} \vec{y} = \frac{\sum y_i}{n} = \bar{y} = g_0$$



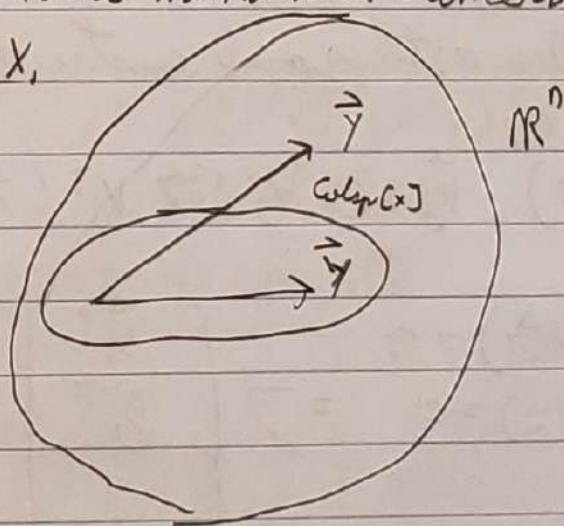
$p+1$ $\text{rank}[X] = \dim[\text{Colsp}[X]]$

$$\text{Colsp}[X] = \text{Span}[\vec{1}, \vec{x}_1, \dots, \vec{x}_p] = \left\{ w_0 \vec{1} + w_1 \vec{x}_1 + \dots + w_p \vec{x}_p : \underbrace{w_0, w_1, \dots, w_p}_{\vec{w} \in \mathbb{R}^{p+1}} \in \mathbb{R} \right\}$$

\nwarrow n -dim col. vector

$p+1$ -dimensional subspace of the entire
 n -dimensional "full space" (the number of dimensions of y which
is n , the number of rows of X).

$\vec{y} \in \text{Colsp}[X]$? yes



OLS sol.

$$H \in \mathbb{R}^{n \times n}$$

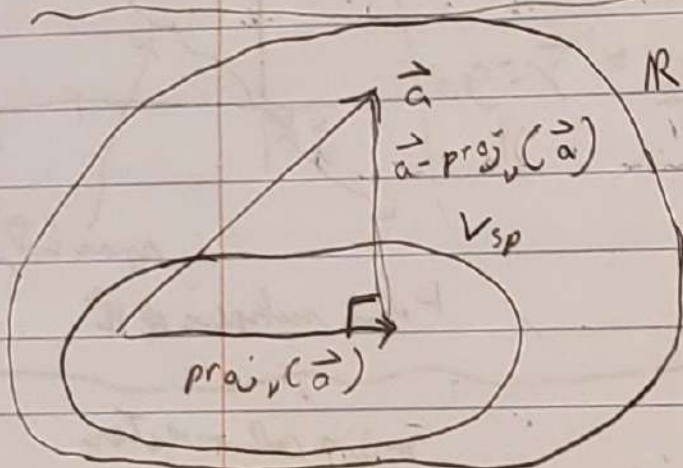
$$\hat{\vec{y}} = X\hat{\vec{b}} = X(X^T X)^{-1} X^T \vec{y} = H\vec{y}$$

H for "hat matrix", the linear operator turning y -vec into \hat{y} -vec

$$X\hat{\vec{b}} \in \text{Colsp}[X]$$

\Leftrightarrow

$$H\vec{y} \in \text{Colsp}[X] \Rightarrow \text{rank}[H] = p+1 \Rightarrow H \text{ is not invertible}$$



V is a K -dim subspace of the n -dim full space

We want to "project" a -vec onto V such that the difference between a -vec and its projection is perpendicular. This is called an "orthogonal projection". We want a formula for this projection as a function of the space V .

$$V = \text{Span}\{\vec{v}_1, \dots, \vec{v}_K\}, K \leq n$$

$$\text{proj}_V(\vec{a}) \in \text{Span}\{\vec{v}_1, \dots, \vec{v}_K\} \Rightarrow \exists \vec{w}$$

$$\text{proj}_V(\vec{a}) = w_1 \vec{v}_1 + \dots + w_K \vec{v}_K = V\vec{w}$$

$$\text{st } V = [\vec{v}_1 | \dots | \vec{v}_K], \vec{w} \in \mathbb{R}^K$$

due to the orthogonal constraint, $\vec{a} - \text{proj}_V(\vec{a}) \perp \vec{v}_j \forall j$

$$\Rightarrow (\vec{a} - V\vec{w})^T \vec{v}_j = 0 \forall j \Leftrightarrow \vec{v}_j^T (\vec{a} - V\vec{w}) = 0 \forall j$$

$$\Rightarrow \vec{v}_1^T (\vec{a} - V\vec{w}) = 0$$

$$\vec{v}_2^T (\vec{a} - V\vec{w}) = 0$$

$$\vec{v}_K^T (\vec{a} - V\vec{w}) = 0$$

$$\begin{bmatrix} \vec{v}_1^T \\ \vec{v}_2^T \\ \vdots \\ \vec{v}_K^T \end{bmatrix}$$

$$(\vec{a} - V\vec{w}) = \vec{0}_K \Rightarrow V^T (\vec{a} - V\vec{w}) = \vec{0}_K$$

$$\Rightarrow V^T \vec{a} - V^T V \vec{w} = \vec{0}_k \Rightarrow V^T V \vec{w} = V^T \vec{a} \Rightarrow \vec{w} = (V^T V)^{-1} V^T \vec{a}$$

$\text{proj}_V(\vec{a}) = V \vec{w} = \underbrace{V(V^T V)^{-1} V^T}_{H} \vec{a} = H \vec{a}$ We call the $n \times n$ matrix H the orthogonal projection matrix onto the subspace $V_{sp} = \text{colsp}[V]$

$H = X(X^T X)^{-1} X^T$ is the orthogonal projection matrix onto $\text{colsp}[X]$

properties of orthogonal projection matrices, H

1) H is symmetric, $H^T = H$

$$H^T = (V(V^T V)^{-1} V^T)^T = V^T (V^T V)^{-1} V^T = V^T (V^T V)^{-1} V^T = V^T (V^T V)^{-1} V^T = H \checkmark$$

Let A be square, invertible and symmetric

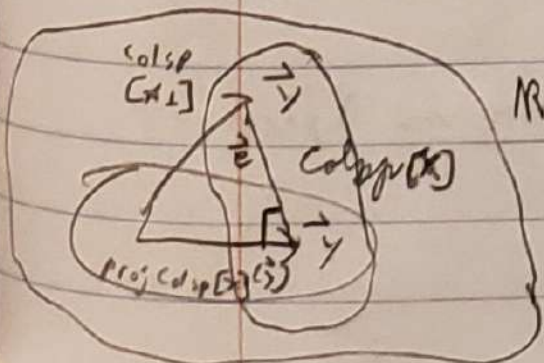
$$A^{-1} A = I = (A^{-1} A)^T = I^T = I \Rightarrow A^T (A^{-1})^T = I \Rightarrow (A^{-1})^T = (A^T)^{-1}$$

2) H is idempotent, i.e. $HH = H$

$$HH = V(V^T V)^{-1} V^T (V(V^T V)^{-1} V^T) = V \cancel{(V^T V)^{-1} (V^T V)} (V^T V)^{-1} V^T = V(V^T V)^{-1} V^T = H$$

$$\text{proj}_V(\text{proj}_V \vec{a}) = \text{proj}_V(H \vec{a}) = HH \vec{a} = H \vec{a} = \text{proj}_V(\vec{a})$$

$$\hat{\vec{y}} = H \vec{y} = \text{proj}_{\text{colsp}[X]}(\vec{y})$$



$$\vec{y} = \hat{\vec{y}} + \vec{e}, \quad \hat{\vec{y}} \cdot \vec{e} = 0$$

$$\vec{e} = \vec{y} - \hat{\vec{y}} = \vec{y} - H \vec{y} = (I - H) \vec{y} = (I - H) \vec{y}$$

$$\hat{\vec{y}} \cdot \vec{e} = (H \vec{y})^T (I - H) \vec{y} = \vec{y}^T H^T (I - H) \vec{y} = \vec{y}^T H (I - H) \vec{y} = 0$$

$$= \vec{y}^T H (I \vec{y} - H \vec{y}) = \vec{y}^T H I \vec{y} - \vec{y}^T H H \vec{y}$$

$$= \vec{y}^T H \vec{y} - \vec{y}^T H \vec{y} = 0$$

Let's verify $I-H$ is a projection matrix by demonstrating that it is (1) symmetric and (2) idempotent

$$(I-H)^T = I^T - H^T = I - H \checkmark$$

$$(I-H)(I-H) = II - IH - HI + HH = I - H - H + H = I - H$$

$$(I-H)\vec{e} = \vec{e}$$

$$H\vec{e} = \vec{0}_n$$

$$(I-H)\hat{\vec{y}} = \vec{0}_n$$

$$H\hat{\vec{y}} = \hat{\vec{y}}$$

$$\text{Colsp}[X] \oplus \text{Colsp}[X_\perp] = \mathbb{R}^n$$

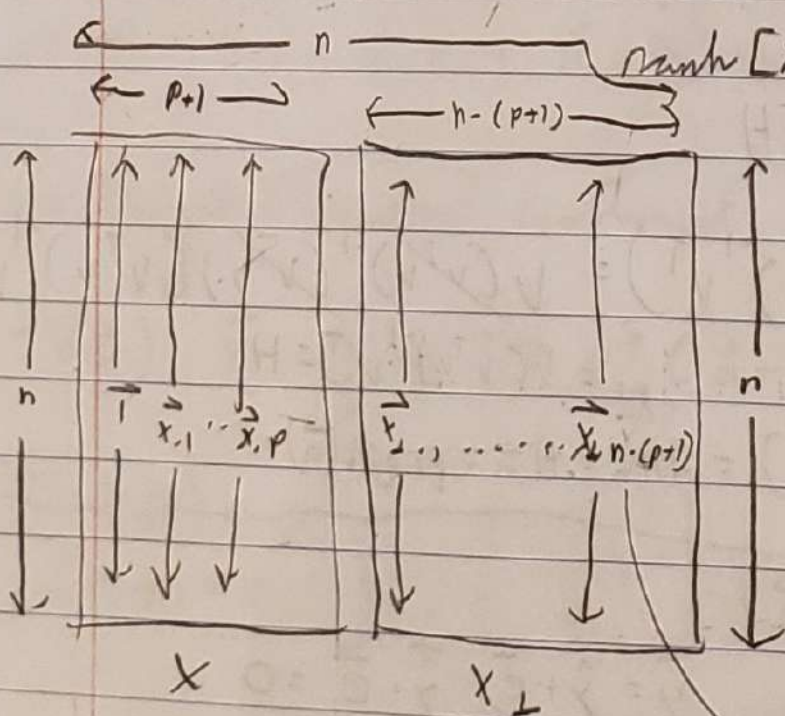
the "residual space" since
it's the space the residuals
 \vec{e} live inside

$$\text{rank}[X] = p+1, \text{rank}[X_\perp] = n - (p+1)$$

$$\text{rank}[X] + \text{rank}[X_\perp] = n$$

degrees of freedom of

the residuals



The column vectors in X_\perp are vectors that span the "rest of the space". They're not known, and you can construct them computationally.

the last column in X_\perp