

The 2D Heat Equation

— Analysis and Numerical Approaches

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1 Formulation of Problem

The heat equation, as know as the diffusion equation,

Let $\Omega \subset \mathbb{R}^d$ be an open set with boundry $\Gamma := \partial\Omega$, set $\Omega_T = \Omega \times]0, T[$, $\Gamma_T := \Gamma \times]0, T[$, Γ_T is called the *lateral* boundary of the cylinder Ω_T .

Consider the heat equation with τ -periodic boundary condition:

$$\begin{cases} \partial_t u - \Delta_x u = f & \text{on } \Omega_T \\ u(x_i, t) = u(x_i + \tau, t) & \text{on } \Gamma_T \\ u(x, 0) = u_0(x) & \text{on } \Omega \times \{t = 0\} \end{cases} \quad (1.1)$$

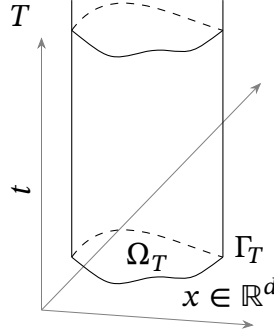


Figure 1: Region Ω_T

1.1 Fundamental Solution for Heat Equation

We note $|x| = \sqrt{\sum_1^d x_i^2}$.

✧ **Definition 1.1:** The function

$$\Phi(x, t) = \begin{cases} \frac{1}{(4\pi t)^{n/2}} e^{-\frac{|x|^2}{4t}} & x \in \mathbb{R}^d, t > 0 \\ 0 & x \in \mathbb{R}^d, t < 0 \end{cases} \quad (1.2)$$

is called the *fundamental solution of the heat equation*.

1.2 Spectrum Theory and Analysis

Given E, F two Banach spaces, an operator $T \in \mathcal{L}(E; F)$ is said to be compact if the image of unit ball in E under T , i.e. $T(B_E)$ is relatively compact in F .

Let $T \in \mathcal{L}(E)$, the resolvent set, denoted by $\rho(T)$ The spectrum, denoted by $\sigma(T)$ A real number λ is said to be an eigenvalue of T if $\text{Ker}(T - \lambda I) \neq \{0\}$

1.3 Maximum Principle

1.3.1 The strong maximum principle

2 Numerical Approaches - Case 1D

2.1 Discrete and Fast Fourier Transform (DFT & FFT)

[cf. [Sha03](#); [Sch01](#), ch.08]

$$\hat{f}(k) = \int_0^\tau f(x)e^{-2i\pi kx} dx \xrightarrow{\text{discretization}} U_k = \frac{1}{N} \sum_{j=0}^{N-1} f\left(\frac{j}{N}\right)e^{-2i\pi k \frac{j}{N}} \quad (2.1)$$

2.2 Finite Difference Method (FDM)

2.3 Finite Element Method (FEM) Approximation

3 Numerical Approaches - Case 2D

3.1 Discrete and Fast Fourier Transform (DFT & FFT)

3.2 Finite Difference Method (FDM)

3.3 Finite Element Method (FEM) Approximation

4 Analysis of Algorithms

4.1 Consistency

4.2 Stability

4.3 Order of Convergence

4.4 Possibility of Improvement

5 Application on Finance

5.1 The Black-Scholes PDE for the Pricing of Financial Derivatives

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