Parallel Computing with GPUs

CUDA Streams Part 1 - Synchronous and Asynchronous Execution



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This Lecture (learning objectives)

- ☐ Synchronous and Asynchronous Execution
 - □Classify synchronous and asynchronous execution
 - ☐ Demonstrate examples of synchronous execution with CUDA
 - ☐ Demonstrate examples of asynchronous execution with CUDA



Blocking and Non-Blocking Functions

□ Synchronous vs Asynchronous □Synchronous: ☐Blocking call ☐ Executed sequentially □ Asynchronous: □Non-Blocking call □ Control returns to host thread ☐ Asynchronous Advantages □Overlap execution and data movement on different devices ☐ Not just GPU and CPU □ Also consider disk or network (low latency)



Asynchronous Behaviour so far...

□CPU pipeline ☐ Programmer writes code considering it to be synchronous operations ☐ Compiler generates overlapping instructions to maximise pipe utilisation ☐ Same end result as non overlapping instructions (hopefully) □ CPU threading ☐ Similar threads execute asynchronously on different multiprocessors ☐ Requires careful consideration of race conditions OpenMP gives us critical sections etc. to help with this □CUDA Warp execution ☐ Threads in the same warp execute instructions synchronously ☐ Warps on a SMP are interleaved and executed asynchronously

□ Careful use of syncthreads () to ensure no race conditions



CUDA Host and Device

☐ Most CUDA Host functions are synchronous (blocking)

- ☐ Exceptions (synchronous with the host)
 - ☐ Kernel calls
 - ☐ cudaMemcpy within a device (cudaMemcpyDeviceToDevice)
 - ☐ cudaMemcpy host to device of less than 64kB
 - □ Asynchronous memory copies and streams... (this lecture)
- ☐ Asynchronous functions will block when
 - ☐ deviceSynchronize() is called
 - ☐A new kernel must be launched (implicit synchronisation)
 - ☐ Memory must be copied to or from the device (implicit synchronisation)



```
//copy data to device
cudaMemcpy(d_a, a, size * sizeof(int), cudaMemcpyHostToDevice);
cudaMemcpy(d_b, b, size * sizeof(int), cudaMemcpyHostToDevice);

//execute kernels on device
kernelA<<<blocks, threads>>>(d_a, d_b);
kernelB<<<blocks, threads>>>(d_b, d_c);

//copy back result data
cudaMemcpy(c, d_c, size * sizeof(int), cudaMemcpyDeviceToHost);
```

Is there any Asynchronous Execution?



```
//copy data to device
cudaMemcpy(d_a, a, size * sizeof(int), cudaMemcpyHostToDevice);
cudaMemcpy(d_b, b, size * sizeof(int), cudaMemcpyHostToDevice);

//execute kernels on device
kernelA<<<blooks, threads>>>(d_a, d_b);
kernelB<<<blooks, threads>>>(d_b, d_c);

//copy back result data
cudaMemcpy(c, d_c, size * sizeof(int), cudaMemcpyDeviceToHost);
```



Completely Synchronous

time

cudaMemcpy(H2D) cudaMemcpy(H2D) kernelA kernelB cudaMemcpy(D2H)



```
//copy data to device
cudaMemcpy(dev_a, a, size * sizeof(int), cudaMemcpyHostToDevice);
cudaMemcpy(dev_b, b, size * sizeof(int), cudaMemcpyHostToDevice);

//execute kernel on device
addKernel<<<br/>blocks, threads>>>(dev_c, dev_a, dev_b);

//host execution
myCPUFunction();

//copy back result data
cudaMemcpy(c, dev_c, size * sizeof(int), cudaMemcpyDeviceToHost);
```

Is there any Asynchronous Execution?



```
//copy data to device
cudaMemcpy(dev_a, a, size * sizeof(int), cudaMemcpyHostToDevice);
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addKernel<<<br/>blocks, threads>>>(dev_c, dev_a, dev_b);

//host execution
myCPUFunction();

//copy back result data
cudaMemcpy(c, dev_c, size * sizeof(int), cudaMemcpyDeviceToHost);
```



Asynchronous GPU and CPU Execution

time

cudaMemcpy(H2D) cudaMemcpy(H2D)

addKernel

myCPUFunction

cudaMemcpy(D2H)

Asynchronous Execution



Summary

- ☐ Synchronous and Asynchronous Execution
 - □Classify synchronous and asynchronous execution
 - ☐ Demonstrate examples of synchronous execution with CUDA
 - ☐ Demonstrate examples of asynchronous execution with CUDA

■ Next Lecture: CUDA Streams

