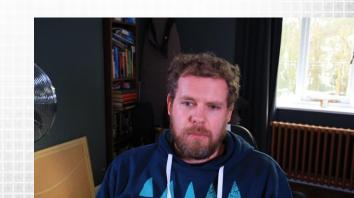
Parallel Computing with GPUs

CUDA Memory
Part 2 - Global and Constant
Memory



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This Lecture (learning objectives)

- ☐Global and Constant Memory
 - □ Compare and contrast manual memory movement with Unified Memory
 - ☐ Identify the use cases for constant memory
 - ☐ Demonstrate an appropriate use of constant memory

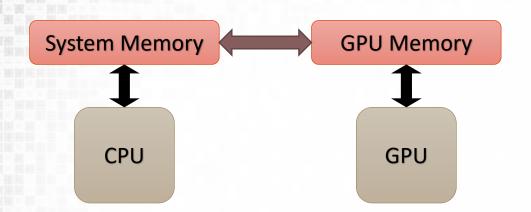


Dynamic vs Static Global Memory

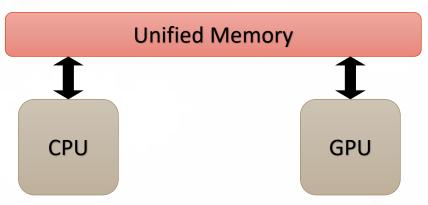
☐ In the previous lab we dynamically defined GPU memory ☐ Using cudaMalloc() ☐ You can also statically define (and allocate) GPU global memory □Using device qualifier □ Requires memory copies are performed using cudaMemcpyToSymbol or cudaMemcpyFromSymbol ☐ See example from last weeks lecture ☐ This is the equivalent of the following in C (host code) \square int my static array[1024]; \square int *my dynamic array = (int*) malloc(1024*sizeof(int));



Unified Memory



CUDA 6.0+ Kepler+



- ☐So far the developer view is that GPU and CPU have separate memory
 - ☐ Memory must be explicitly copied
 - Deep copies required for complex data structures
- ☐ Unified Memory changes that view



Unified Memory Example

C Code

```
void sortfile(FILE *fp, int N) {
  char *data;
 data = (char *) malloc(N);
  fread(data, 1, N, fp);
 qsort(data, N, 1, compare);
  use data(data);
  free (data);
```

CUDA (6.0+) Code

```
void sortfile(FILE *fp, int N) {
  char *data;
  cudaMallocManaged(&data, N);
  fread(data, 1, N, fp);
  gpu qsort(data, N, 1, compare);
  cudaDeviceSynchronize();
  use data(data);
  cudaFree (data);
```

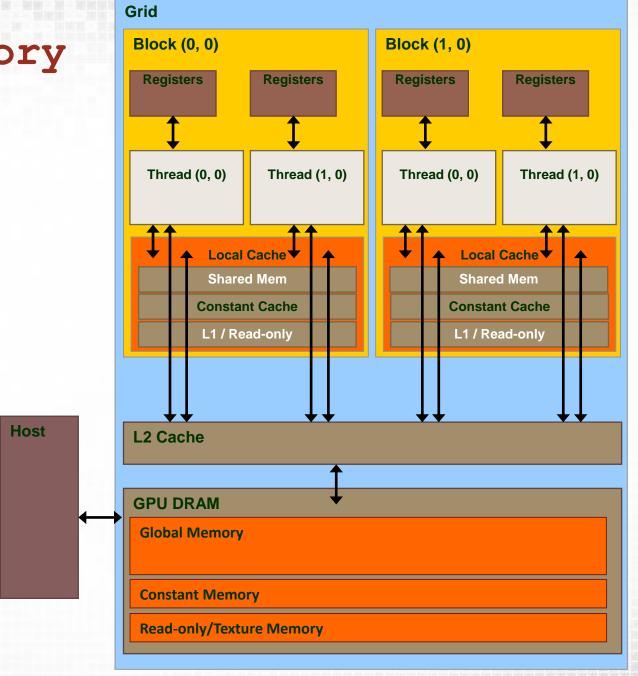
Implications of CUDA Unified Managed Memory

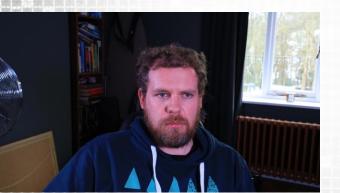
- ☐ Simpler porting of code
- ☐ Memory is only *virtually* unified
 - ☐GPU still has discrete memory
 - ☐ It still has to be transferred via PCIe (or NVLINK)
- ☐ Easier management of data to and from the device
 - ☐ Explicit memory movement is not required
 - ☐ Similar to the way the OS handles virtual memory
- **□**Issues
 - Requires look ahead and paging to ensure memory is in the correct place (and synchronised)
 - □ It is not as fast as hand tuned code which has finer explicit control over transfers
- ☐ We will manage memory movement ourselves!





Constant Memory







Constant Memory

☐ Constant Memory	
☐Stored in the devices global memory	
☐ Read through the per SM constant cache	
☐Set at runtime	
lue When using correctly only 1/16 of the traffic compared to global loa	ds
☐When to use it?	
☐When small amounts of data are read only	
☐When values are broadcast to threads in a half warp (of 16 threads)	
□Very fast when cache hit	
□Very slow when no cache hit	
☐ How to use	
☐ Must be statically (compile-time) defined as a symbol usingcorqualifier	ß
☐Value(s) must be copied using cudaMemcpytoSymbol .	4

Constant Memory Broadcast

☐.... When values are **broadcast** to threads in a half warp (groups of 16 threads)

```
__constant__ int my_const[16];
__global__ void vectorAdd() {
int i = blockIdx.x;

int value = my_const[i % 16];
}
```

```
__constant__ int my_const[16];

__global__ void vectorAdd() {
  int i = blockIdx.x * blockDim.x + threadIdx.x;

int value = my_const[i % 16];
}
```

Which is good use of constant memory?



Constant Memory Broadcast



```
__constant__ int my_const[16];

__global__ void constant_test() {
int i = blockIdx.x;

int value = my_const[i % 16];
}
```

```
__constant__ int my_const[16];

__global__ void constant_test() {
int i = blockIdx.x * blockDim.x + threadIdx.x;

int value = my_const[i % 16];
}
```

Which is good use of constant memory?

■Best possible use of constant memory
■Every thread in half warp reads the same
■ Index based on blockIdx
■No serialisation
■ 1 read request for every thread!
■Other threads in the block will also hit cache

□ Worst possible use of constant memory
 □ Every thread in half warp reads different value
 □ Index based on threadIdx
 □ Each access will be serialised
 □ 16 different read requests!
 □ Other threads in the block will likely miss the cache

Constant Memory

- ☐ Question: Should I convert #define to constants?
 - ☐ E.g. #define MY CONST 1234
- ☐Answer: No
 - ☐ Leave alone
 - #defines are embed in the code by pre-processors
 - ☐ They don't take up registers as they are embed within the instruction space
 - ☐ i.e. are replaced with literals by the pre-processor
- □Only replace constants that may change at runtime (but not during the GPU programs)

Summary

- ☐Global and Constant Memory
 - □Compare and contrast manual memory movement with Unified Memory
 - □ Identify the use cases for constant memory
 - ☐ Demonstrate an appropriate use of constant memory

☐ Next Lecture: Read Only and Texture Memory

