

## 1.6. Elementary Matrices:

Defn: If a matrix  $E$  is obtained from the identity matrix  $I_{nxn}$  by a single elementary row operation is called an elementary matrix.

Type I -

$$cR_i + R_j \rightsquigarrow \begin{bmatrix} 1 & & & \\ & \ddots & & \\ & & 1 & \\ & & c & \ddots \\ & & & 1 \end{bmatrix}_{nxn} \xrightarrow{\text{i-th row}} \begin{bmatrix} 1 & & & \\ & \ddots & & c \\ & & 1 & \\ & & & 1 \end{bmatrix}_{nxn} \xrightarrow{\text{j-th row}} \begin{bmatrix} 1 & & & \\ & \ddots & & \\ & & 1 & \\ & & & 1 \end{bmatrix}_{nxn}$$

exp:  $n=3$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{2R_2+R_1} \begin{bmatrix} 1 & 2 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\text{or } \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{2R_2+R_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 2 & 1 \end{bmatrix}$$

are elementary matrices of Type I.

Type II -

$$R_i \leftrightarrow R_j$$

$$\rightsquigarrow \begin{bmatrix} 1 & & & \\ & \ddots & & \\ & & 0 & \dots & 1 \\ & & & \ddots & 0 \\ & & & & 1 \end{bmatrix}$$

exp:  $n=3$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{R_2 \leftrightarrow R_1} \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

elementary matrix of Type II.

Type III -

$$cR_i$$

$$\rightsquigarrow \begin{bmatrix} 1 & & & \\ & \ddots & & c \\ & & 1 & \\ & & & 1 \end{bmatrix}_{nxn} \xrightarrow{\text{i-th row}} \begin{bmatrix} 1 & & & \\ & \ddots & & \\ & & 1 & \\ & & & 1 \end{bmatrix}_{nxn}$$

exp:  $n=3$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{3R_3} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & ? \end{bmatrix}$$

elementary matrix of -

$$\underline{\text{exp:}} \quad n=3 \quad \begin{vmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{vmatrix} \xrightarrow{3R_3} \begin{vmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 3 \end{vmatrix} \quad \text{Elementary matrix of Type III}$$

Lemma: For any matrix  $A_{m \times n}$  and elementary row operation  $E$   $E(A) = E(I_m) \cdot A$  where  $I_{m \times m}$

Proof: consider  $E$  as type I elementary row operation

$$A = \begin{bmatrix} R_1 \\ R_2 \\ \vdots \\ R_m \end{bmatrix} \xrightarrow[E: cR_i + R_j]{(i < j)} \begin{bmatrix} R_1 \\ R_i \\ \vdots \\ cR_i + R_j \\ \vdots \\ R_m \end{bmatrix} = E(A)$$

$$E(I_m) \cdot A = \begin{bmatrix} e_1 \\ e_2 \\ \vdots \\ ce_i + e_j \\ \vdots \\ e_m \end{bmatrix} \cdot \begin{bmatrix} R_1 \\ R_i \\ \vdots \\ R_j \\ \vdots \\ R_m \end{bmatrix} = \begin{bmatrix} R_1 \\ R_i \\ \vdots \\ cR_i + R_j \\ \vdots \\ R_m \end{bmatrix}$$

where  $e_i = (0, \dots, 0, \underset{i\text{-th}}{1}, 0, \dots, 0)$   
 $\quad \quad \quad (0, \dots, 0, c, 0, \dots, 1, \dots, 0)$

$$\underline{\text{exp:}} \quad A = \begin{bmatrix} 1 & 2 & 0 & 1 \\ 0 & 1 & 3 & 2 \\ 2 & 0 & 1 & 0 \end{bmatrix}_{3 \times 4} \xrightarrow{E: 2R_3 + R_1} \begin{bmatrix} 5 & 2 & 2 & 1 \\ 0 & 1 & 3 & 2 \\ 2 & 0 & 1 & 0 \end{bmatrix}$$

$$I = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{2R_3 + R_1} \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = E(I)$$

$$E(I) \cdot A =$$

Consider  $E^{-1}: -2R_3 + R_1$

$\mathcal{E}^{-1}(\mathcal{E}(A)) = A$  by Lemma we have

$$A = \mathcal{E}^{-1}(\mathcal{E}(A)) = \underbrace{\mathcal{E}^{-1}(\mathcal{E}(I))}_{I} \mathcal{E}(A)$$

Notation: Elementary matrices are represented by  $E_i$ .

e.g.  $A \xrightarrow{E_1} - \xrightarrow{E_2} - \xrightarrow{E_3} B \quad B = E_3(E_2(E_1(A)))$

or  $B = E_3(I) \cdot E_2(I) \cdot E_1(I) \cdot A = E_3 \cdot E_2 \cdot E_1 \cdot A$

exp:  $\begin{bmatrix} 1 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$  not elementary matrix

for example

$$\begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 & 2 & 0 & 1 \\ 0 & 1 & 3 & 2 \\ 2 & 0 & 1 & 0 \end{bmatrix} = \begin{bmatrix} 5 & 2 & 2 & 1 \\ 0 & 1 & 3 & 2 \\ 2 & 0 & 1 & 0 \end{bmatrix}$$

$$\underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}}_{E_2} \underbrace{\begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}}_{E_1} \underbrace{\begin{bmatrix} 1 & 2 & 0 & 1 \\ 0 & 1 & 3 & 2 \\ 2 & 0 & 1 & 0 \end{bmatrix}}_{R_2 \leftrightarrow R_3} = \begin{bmatrix} 5 & 2 & 2 & 1 \\ 2 & 0 & 1 & 0 \\ 0 & 1 & 3 & 2 \end{bmatrix} = B$$

$$B = E_2(E_1(A)) = E_2(I) \cdot E_1(I) \cdot A = \underbrace{E_2 \cdot E_1 \cdot A}$$

Thm: If  $A_{m \times n}$  is row equivalent to  $B$  then there is a matrix  $P_{m \times m}$  such that  $B = P \cdot A$ .

$$A \sim B \Leftrightarrow B = P \cdot A$$

$$B \sim A \Leftrightarrow A = Q \cdot B$$

Proof:  $A \sim B$  then  $B = E_k(\dots(E_1(A))) =$

$$\underbrace{E_k(I) \cdot E_{k-1}(I) \cdots E_1(I)} \cdot A = \underbrace{E_k \cdot E_{k-1} \cdots E_1}_{P} \cdot A$$

$$B \sim A \Rightarrow A = \underbrace{\tilde{E}_1^{-1} \cdots (\tilde{E}_{k-1}^{-1}(\tilde{E}_k^{-1}(B)))}_{Q} =$$

$$\begin{aligned} & \tilde{E}_1^{-1}(I) \cdot \tilde{E}_2^{-1}(I) \cdots \tilde{E}_{k-1}^{-1}(I) \cdot \tilde{E}_k^{-1}(I) \cdot B \\ &= \underbrace{\tilde{E}_1^{-1} \cdot \tilde{E}_2^{-1} \cdots \tilde{E}_k^{-1}}_Q \cdot B \end{aligned}$$

RMK: How to find  $P$  if  $B = P \cdot A$ ?

$$[A \mid I] \longrightarrow \dots \longrightarrow [B \mid P]$$

$$E_2(I)E_1(I) = E_2(E_1(I))$$

exp: Find row reduced echelon matrix  $R$  &  $P$  such that  $R = P \cdot A$ .

$$\left[ \begin{array}{cccc|ccc} -1 & 1 & 2 & -1 & 1 & 0 & 0 \\ 1 & -1 & 1 & 3 & 0 & 1 & 0 \\ 1 & -1 & 4 & 5 & 0 & 0 & 1 \end{array} \right] \xrightarrow{\begin{array}{l} R_1 + R_2 \\ R_1 + R_3 \end{array}} \left[ \begin{array}{cccc|ccc} -1 & 1 & 2 & -1 & 1 & 0 & 0 \\ 0 & 0 & 3 & 2 & 1 & 1 & 0 \\ 0 & 0 & 6 & 4 & 1 & 0 & 1 \end{array} \right]$$

$$\xrightarrow{-2R_2 + R_3} \left[ \begin{array}{cccc|ccc} -1 & 1 & 2 & -1 & 1 & 0 & 0 \\ 0 & 0 & 3 & 2 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & -1 & -2 & 1 \end{array} \right] \xrightarrow{\begin{array}{l} \frac{1}{3}R_2 \\ -R_1 \end{array}} \left[ \begin{array}{cccc|ccc} \frac{1}{3} & -1 & -2 & 1 & -1 & 0 & 0 \\ 0 & 0 & \frac{1}{3} & \frac{2}{3} & \frac{1}{3} & \frac{1}{3} & 0 \\ 0 & 0 & 0 & 0 & -1 & -2 & 1 \end{array} \right]$$

$$\xrightarrow{2R_2 + R_1} \left[ \begin{array}{cccc|ccc} 1 & -1 & 0 & \frac{2}{3} & -\frac{1}{3} & \frac{2}{3} & 0 \\ 0 & 0 & 1 & \frac{2}{3} & \frac{1}{3} & \frac{1}{3} & 0 \\ 0 & 0 & 0 & 0 & -1 & -2 & 1 \end{array} \right]$$

$\underbrace{R}_{\text{row reduced echelon}} = \underbrace{P}_{\text{}}$

$$\underbrace{\begin{bmatrix} -\frac{1}{3} & \frac{2}{3} & 0 \\ \frac{1}{3} & \frac{1}{3} & 0 \\ -1 & -2 & 1 \end{bmatrix}}_P \underbrace{\begin{bmatrix} -1 & 1 & 2 & -1 \\ 1 & -1 & 1 & 3 \\ 1 & -1 & 4 & 5 \end{bmatrix}}_A = R$$

## CHAPTER 2 - Systems of Linear Eqns.

2.1 . Defn: A system of  $m$  linear equations in  $n$  unknowns is called a system of linear eqns.

We can represent any system of linear eqns. by matrices. as follows:

$$\left. \begin{array}{l} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1 \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2 \\ \vdots \quad \vdots \quad \vdots \quad \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m \end{array} \right\} \quad \begin{array}{l} x_1, \dots, x_n \text{ are unknowns} \\ a_{ij} \text{ are coefficients.} \end{array}$$

(\*)

$$\underbrace{\begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}}_A \cdot \underbrace{\begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}}_{n \times 1} = \underbrace{\begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}}_{m \times 1} \Rightarrow \underline{A \cdot X = B}$$

We will represent this by a matrix so called "augmented matrix"

$$\Rightarrow \underbrace{\begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} & | & b_1 \\ a_{21} & a_{22} & \dots & a_{2n} & | & b_2 \\ \vdots & \vdots & & \vdots & | & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} & | & b_m \end{bmatrix}}_A \quad \begin{array}{l} \text{"Augmented matrix" of the} \\ \text{system (*)} \end{array}$$

$\nearrow$  1 matrix

A

B

↗  
coefficient matrix

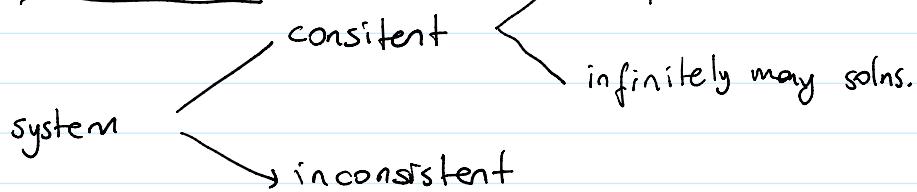
By a solution of a system we mean a set  $S$  such that

$$A \cdot S = B \text{ where } S_{n \times 1}$$

e.g.

$\begin{array}{l} x+y=1 \\ -x-y=2 \\ \hline 0+0=3 \end{array}$	$\rightsquigarrow \left[ \begin{array}{cc c} 1 & 1 & 1 \\ -1 & -1 & 2 \end{array} \right] \xrightarrow{R_1+R_2} \left[ \begin{array}{cc c} 1 & 1 & 1 \\ 0 & 0 & 3 \end{array} \right]$
--	--

Defn: When the system has at least one soln. then it is called "consistent" otherwise it is called "inconsistent".

e.g.,

$\begin{array}{l} x+y=1 \\ 2x+2y=2 \\ \hline x+y=1 \end{array}$	$\rightsquigarrow \left[ \begin{array}{cc c} 1 & 1 & 1 \\ 2 & 2 & 2 \end{array} \right] \xrightarrow{-2R_1+R_2} \left[ \begin{array}{cc c} 1 & 1 & 1 \\ 0 & 0 & 0 \end{array} \right]$
---	--

e.g.

$\begin{array}{l} x+y=1 \\ x-y=0 \\ \hline x=\frac{1}{2}, y=\frac{1}{2} \end{array}$	$\rightsquigarrow \left[ \begin{array}{cc c} 1 & 1 & 1 \\ 1 & -1 & 0 \end{array} \right] \xrightarrow{-R_1+R_2} \left[ \begin{array}{cc c} 1 & 1 & 1 \\ 0 & -2 & -1 \end{array} \right]$
--	--

$\left[ \begin{array}{cc} 1 & 1 \\ 0 & -2 \end{array} \right] \left[ \begin{array}{c} x \\ y \end{array} \right] = \left[ \begin{array}{c} 1 \\ -1 \end{array} \right] \Rightarrow \boxed{\begin{array}{l} x+y=1 \\ -2y=-1 \end{array}} \quad \begin{array}{l} x=\frac{1}{2} \\ y=\frac{1}{2} \end{array}$

Defn: Two systems  $A_1 X = B_1$  &  $A_2 X = B_2$  are said to be equivalent systems if  $[A_1 | B_1] \sim [A_2 | B_2]$  are row equivalent.

Thm : Equivalent systems have the same solutions.

Rmk! The converse of above thm is not true!  
Just consider two systems with no solution.

Proof: If two systems are equivalent then  $[A_1 | B_1] \sim [A_2 | B_2]$   
 $\Rightarrow$  there are  $P, Q$  product of elementary matrices such that

$$[A_2 | B_2] = P \cdot [A_1 | B_1] \quad \& \quad [A_1 | B_1] = Q \cdot [A_2 | B_2] \Rightarrow$$

$$\Rightarrow A_2 = PA_1 \quad \& \quad B_2 = PB_1, \quad A_1 = QA_2 \quad \& \quad B_1 = QB_2$$

$$\text{If } A_1 \cdot S = B_1 \Rightarrow \underbrace{PA_1}_{} \cdot S = \underbrace{PB_1}_{} \quad \text{if } A_2 \cdot S = B_2 \Rightarrow \underbrace{QA_2}_{} \cdot S = \underbrace{QB_2}_{} \\ A_2 \cdot S = B_2 \quad A_1 \cdot S = B_1$$

Hence equivalent systems has same solutions.  $\blacksquare$