

15 - higher order linear ode's / converting them into a first order system

n th order derivative = $y^{(n)} = \frac{d^n y}{dt^n}$

solutions intervals

singular points = the points which coefficients are undefined (when $y^{(n)}$ coefficient is 1)
 \rightarrow ex: $t y'' + 3y' = 1 \rightarrow y'' + \frac{3}{t}y' = \frac{1}{t} \rightarrow (-\infty, 0) \text{ or } (0, \infty)$ $t=0$ singular point

converting a higher order ode into a first order system

$y^{(n)} + a_1(t)y^{(n-1)} + a_2(t)y^{(n-2)} + \dots + a_{n-1}(t)y' + a_n(t)y = b(t) \rightarrow$ by $(n \times n)$ system

$x_1 = y$
 $x_2 = y' = x_1'$
 $x_3 = y^{(2)} = x_2'$
 \vdots
 $x_n = y^{(n-1)} = x_{n-1}'$
 $x_{n+1} = y^{(n)} = x_n' = -a_n(t)y - a_{n-1}(t)y' - \dots - a_2(t)y^{(n-2)} - a_1(t)y^{(n-1)} + b(t)$

x_1 x_2 x_{n-1} x_n

$$\begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_{n-1} \\ x_n \end{bmatrix}' = \begin{bmatrix} 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & 0 & 1 \\ -a_n(t) & -a_{n-1}(t) & \dots & -a_2(t) & -a_1(t) \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_{n-1} \\ x_n \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \\ b(t) \end{bmatrix}$$

ex:

$y''' + 3y'' - ty' + 2y = \cos(t)$

$\Rightarrow \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}' = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -2 & t & -3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ \cos(t) \end{bmatrix}$

Structure of the solution set

- solution of the system is n linearly independent vectors $y^{(n)} \rightarrow y_1, y_2, y_3$
- the combination of these vectors with some constants are solutions $y(t) = c_1 y_1 + c_2 y_2 + c_3 y_3$

ex: check if $y_i = t^i$ are the solution of the system when $t > 0$.

$$\begin{pmatrix} y_1 \\ y_2 \\ y_3 = \frac{1}{t} \end{pmatrix}$$

$$t^3 y''' + t^2 y'' - 2t y' + 2y = 0$$

$$\rightarrow \textcircled{t} \rightarrow 0 + 0 - 2t \cdot 1 + 2t = 0 \checkmark$$

$$\textcircled{t^2} \rightarrow 0 + t^2 \cdot 2 - 2t \cdot 2t + 2t^2 = 0 \checkmark$$

$$\textcircled{\frac{1}{t}} \rightarrow t^3 \cdot (-\frac{1}{t^2}) + t^2 \cdot 2 \cdot \frac{1}{t^3} - 2t \cdot (-\frac{1}{t^2}) + 2 \cdot \frac{1}{t} = \frac{-6}{t} + \frac{2}{t} + \frac{2}{t} + \frac{2}{t} = 0 \checkmark$$

check for independence

$$W(y_1, y_2, y_3) = \begin{vmatrix} t & t^2 & \frac{1}{t} \\ 1 & 2t & -\frac{1}{t^2} \\ 0 & 2 & \frac{2}{t^3} \end{vmatrix} = \frac{6}{t} \neq 0$$

$$\hookrightarrow y(t) = c_1 t + c_2 t^2 + \frac{c_3}{t}$$