Design Task	Objectives	Constraints	Iterations	Simulations	Time(m)
Flipper	$\theta_c^2$		5	44	242
Catapult	Xc - Xtarget		5	39	350
Jump Onto	$\theta_c^2$	$x_{wall}-x_c \le 0$ , $y_{wall}-y_c \le 0$	5	47	376
Jump Over	$\theta_c^2$	$X_{wall}-X_{c}\leq 0,$ $Y_{wall}-Y_{highest}\leq 0$	7	56	415