1 Syntax

<i>9</i> ::=	\overline{S} $\overline{\mathcal{F}}$		Program					
${\mathcal F}$::=	$\mathtt{fn}\ f\langle\overline{\mathbf{k}:\kappa}\rangle\langle y:\varepsilon\rangle(\overline{e\ x:\delta})\overset{e}{\to}\delta,\ A\ \{\ t\ \}$	where γ Function	Definition					
S ::=	$struct \ s\langle \overline{\mathbf{k} : \kappa} \rangle \{ \ \overline{x : \delta} \ \}$ Struct Declaration							
			$\mid t ::=$	Term:				
t $:=$		Term:	for x in $\eta\eta$ $\{t\}$	for-loop				
	p	place expression	while $t \ \{ \ t \ \}$	$while ext{-}loop$				
	$\ominus t$	unary operation	if $t \mid t $	if- $else$				
	$t \; \oplus \; t$	binary operation	$\verb"unsafe" t$	unsafe				
	let $x{:}\delta = t$	definition						
	$\mathtt{let}(e) \; x : \delta$	declaration	p ::=	Place Expressions:				
	p = t	assigment	x	variable				
	$\&r \omega p$	(unique) borrow	$p.j \mid p.x$	projections				
	$[e]\{t\}^{\overline{r}}$	block	*p	dereference				
	$t \; ; \; t$	sequence	p[t]	index				
	(\overline{t})	tuple	p[e]	select				
	$s\langle \overline{\tau} \rangle \{ \ \overline{x:t} \ \}$	struct	p.v	view				
	$f :: \langle \overline{\tau} \rangle :: \langle e \rangle (\overline{p})$	function call						
	$f::\langle \overline{\tau}\rangle::\ll d, d \; ; \; \overline{r}, \; \overline{\delta} \gg (\overline{t})$	kernel call						
	$\mathtt{sched}(e_L.d)\ y\ \mathtt{in}\ e\ \{\ t\ \}$	schedule	$v ::= f_v :: \langle \overline{ au} \rangle(\overline{v})$	view expression				
	$\mathtt{split}(e_L.d)\ e\ \mathtt{at}\ \eta\ \{\ y\Rightarrow t,y\Rightarrow t\ \}$	$split\ exec$	$f_v \; ::= \;$					
	$\mathtt{sync}(e)$	barrier	to_view grp					
			$[\eta\eta] \mid { t reverse}$					
			transpose map					

Figure 1: Descend programs, terms and place expressions

$egin{array}{cccc} \kappa & ::= & & \ au & ::= & \ ext{k} & ::= & \ \end{array}$	$\begin{array}{c c} \mathtt{dty} \mid \mathtt{rgn} \mid \mathtt{mem} \mid \mathtt{nat} \\ \delta \mid \varrho \mid \mu \mid \eta \\ \alpha \mid \imath \mid m \mid n \end{array}$	Kinds Type-level terms Type-level identifier	μ	::=	cpu.mem gpu.global gpu.shared	Memory:
δ ::=	$\langle \overline{x:k} angle (\delta_1,\ldots,\delta_n) \xrightarrow{y:arepsilon} \delta$ where γ one and α bool $ $ int $ $ float $ $ AtomicU32	Function type Data Types: type variable base types	ρ	::=	m r	Lifetimes: abstract lifetime concrete lifetime
	$egin{array}{c} (\overline{\delta}) & & \\ s\{ \ \overline{x:\delta} \ \} & \\ [\delta;\eta] \mid \llbracket \delta;\eta rbracket & \\ \& ho \ \omega \ \mu \ \delta & \end{array}$	tuple type struct type array (view) type reference type	η	::=	$\eta\oplus\eta\mid n\mid 0\mid 1\mid\ldots$	Natural Numbers:
ω ::=	$\delta \ @ \ \mu$ shrd \mid uniq	boxed type Borrowing Mode	γ	::=	$\label{eq:true} \begin{array}{l} \texttt{true} \mid \eta = \eta \mid \eta < \eta \\ \gamma \text{ and } \gamma \mid \gamma \text{ or } \gamma \end{array}$	Nat Constraints:

Figure 2: Formal syntax of kinds and types in *Descend*.

```
\bullet \ | \ \Delta, \alpha : \mathtt{dty} \ | \ \Delta, \imath : \mathtt{rgn} \ | \ \Delta, m : \mathtt{mem} \ | \ \Delta, n : \mathtt{nat}
                                                                                                                                                           Kinding Environemnt
                         ullet \mid \Gamma, (\mathcal{F})
                                                                                                                                                                 Stack\ Environment
Γ
                         \bullet \mid \mathcal{F}, x : \stackrel{\circ}{e} \tilde{\delta} \mid \mathcal{F}, \underline{\quad} : e \; \delta \mid \mathcal{F}, r \mapsto \{ \; \overline{\ell} \; \}
\frac{\mathcal{F}}{\tilde{\delta}}
                                                                                                                                                                                 Stack Frame
                         \delta \mid \lfloor \delta \rfloor \mid (	ilde{\delta}, \ldots, 	ilde{\delta})
                                                                                                                                                                                Partial\ Types
\ell
                         \omega_p
                                                                                                                                                                                                  Loans
                         \bullet \mid A, \ell
                                                                                                                                                              Access Environment
A
```

Figure 3: Environments and other syntax relevant for typing

```
\operatorname{grid}\langle d, d \rangle.\operatorname{blocks}[e_{\mathsf{R}}] \dots [e_{\mathsf{R}}].threads[e_{\mathsf{R}}] \dots [e_{\mathsf{R}}]
                     \texttt{grid} \langle \ell, \ell \rangle. \texttt{blocks}[e_{\mathsf{R}}] \dots [e_{\mathsf{R}}]. \texttt{warps}[e_{\mathsf{R}}]. \texttt{lanes}[e_{\mathsf{R}}]
                     y \mid e[..\eta]_{e_L.d} \mid e[\eta..]_{e_L.d}
                     blocks | warps | threads | lanes
e_L
                     n \mid \eta..\eta
e_{\mathsf{R}}
                     cond | all
                                                                                                                                       Conditional Select
          ::=
c
d
                                                                                                                                                  Dimensions:
          ::=
                     xyz\langle \eta, \eta, \eta \rangle
                                                                                                                                                               3-dim
                     \mathtt{xy}\langle \eta, \eta 
angle \mid \mathtt{xz}\langle \eta, \eta 
angle \mid \mathtt{yz}\langle \eta, \eta 
angle
                                                                                                                                                               2-dim
                     x\langle \eta \rangle \mid y\langle \eta \rangle \mid z\langle \eta \rangle
                                                                                                                                                               1-dim
d
                     x \mid y \mid z
                                                                                                                                                 Dim-selector
                                                                                                                                                   Exec Types:
\varepsilon
                     \operatorname{gpu.grid}\langle d, d \rangle.\operatorname{blocks}[n]_0..[n]_{d-1}.\operatorname{threads}[n]_0..[n]_{d-1}
                     \mathtt{gpu.grid}\langle d, d \rangle.\mathtt{blocks}[n]_0..[n]_{d-1}.\mathtt{warps}[n].\mathtt{lanes}[n]
                      cpu.Thread
                      gpu.Grid d d
                      gpu.Block ℓ
                     gpu.Thread
                      gpu.Warp
                     gpu.BlockGrp & &
                     gpu.ThreadGrp d
                     {\tt gpu.WarpGrp}~\eta
                     gpu.GlobalThreads d \varepsilon
                     Any
```

Figure 4: Execution Resources

2 Well-formedness Judgements

 $\vdash \mathcal{P}$: Program Typing

$$\frac{\forall \mathcal{F} \in \mathcal{P}.\ \mathcal{P} \vdash \mathcal{F}}{\vdash \mathcal{P}}$$

 $\mathcal{P} \vdash \mathcal{F}$: Check types and well-formedness of function definitions.

$$\begin{array}{c} \Delta = \overline{k : \kappa} \\ \Delta \vdash \varepsilon & \overline{y : \varepsilon \vdash e' : \varepsilon'} \quad y : \varepsilon \vdash e : \varepsilon'' \\ \overline{\Delta}; \bullet \vdash \delta : \mathsf{dty} \end{array}$$

$$\Delta ; \bullet, \ (\overline{e' \ x : \delta}) \ \mid \ y : \varepsilon ; e \ \mid \bullet \ \vdash \boxed{t : \delta'} \ \dashv \ \Gamma' \ \mid \ \mathsf{A}$$

$$\begin{array}{c} \Delta ; \bullet \vdash \bullet \quad \delta' \leadsto \delta \dashv \bullet \\ \overline{\mathscr{P}; \ \Delta; \ \Gamma \mid y : \varepsilon ; e \vdash \mathsf{A}} \end{array}$$

$$\overline{\mathscr{P} \vdash \mathsf{fn} \ f \langle \overline{k : \kappa} \rangle \langle y : \varepsilon \rangle (\overline{e' \ x : \delta}) \xrightarrow{e} \delta, \ \mathsf{A} \ \{ \ t \ \} \ \mathsf{where} \ \gamma}$$

 $\Delta; \ y : \varepsilon; \ e \vdash \Gamma$: Check that the Stack Environment is well-formed.

$$\begin{array}{c} \Delta; \ y:\varepsilon; \ e \vdash \Gamma \\ \forall x:e' \ \delta \in \mathcal{F}. \ \Delta; \ \Gamma, (\mathcal{F}) \vdash \delta: \mathtt{dty} \\ \forall x:e' \ \delta \in \mathcal{F}. \ y:\varepsilon \vdash e':\varepsilon' \\ \hline \Delta; \ y:\varepsilon; \ e \vdash \bullet \\ \hline \\ \Delta; \ y:\varepsilon; \ e \vdash \Gamma, (\mathcal{F}) \end{array}$$

 Γ_g ; Δ ; $\Gamma \mid y : \varepsilon ; e \vdash A$: Check that the Access Environment is well-formed.

$$\frac{\forall^{\omega} p \in A. \ \Delta; \ \Gamma \mid \ y : \varepsilon; \ e \ \vdash^{\omega}_{\mathtt{p1}} p \ : \delta'}{\Gamma_{q}; \ \Delta; \ \Gamma \mid y : \varepsilon; e \vdash A}$$

 $\overline{\Delta} \vdash^n e_{\mathsf{R}}$

$$\frac{\text{WF-Range}}{n \le s} \frac{0 < n - m}{\Delta \vdash^{s} m..n}$$

$$\frac{\text{WF-RangeVar}}{\Delta(x) = m..n} \frac{n \le s}{\Delta \vdash^{s} x} 0 < n - m$$

 $\Delta \vdash e : \varepsilon$: Well-formedness of execution resource types.

 $\Delta \vdash \texttt{cpu.thread} : \texttt{cpu.Thread}$

T-Base

$$\forall 0 \leq i < d. \ \Delta \vdash^{\ell_{g_i}} e_{\mathsf{R}_i} \wedge \Delta \vdash^{\ell_{b_i}} e_{\mathsf{R}_i}$$

 $\Delta \vdash \texttt{gpu.grid} \langle d_q, d_b \rangle. \texttt{blocks}[e_{\texttt{Rblocks}0}]_0 \dots [e_{\texttt{Rblocks}d-1}]_{d-1}. \texttt{threads}[e_{\texttt{Rthreads}0}] \dots [e_{\texttt{Rthreads}d-1}] :$ $\mathtt{gpu.grid}\langle \ell_q, \ell_b \rangle.\mathtt{blocks}[m_0]_0..[m_{d-1}]_{d-1}.\mathtt{threads}[n_0]_0..[n_{d-1}]_{d-1}$

T-BaseWarps

$$\forall 0 \leq i < d. \ m_{2i} \leq \ell_{g_i} \land m_i = m_{2i} - m_{1i} \land m_i > 0 \qquad o_2 \leq \mathsf{WarpSize}$$

$$o = o_2 - o_1 \qquad o > 0$$

$$\begin{array}{c} \text{T-BASEWARPS} \\ \forall 0 \leq i < d. \ m_{2i} \leq \ell_{g_i} \land m_i = m_{2i} - m_{1i} \land m_i > 0 \quad o_2 \leq \mathsf{WarpSize} \quad o = o_2 - o_1 \quad o > 0 \\ \\ n_b = \sum_{i=0}^{d-1} \ell_{b_i} \quad n_w = \frac{n_b}{\mathsf{WarpSize}} \quad n_2 \leq n_w \quad n_b \; \mathsf{mod} \; \mathsf{WarpSize} = 0 \quad n = n_2 - n_1 \quad n > 0 \\ \\ \hline \Delta \vdash \mathsf{gpu.grid} \langle \ell_g, \ell_b \rangle. \mathsf{blocks}[m_{10}..m_{20}] \ldots [m_{1d-1}..m_{2d-1}]. \mathsf{warps}[n_1..n_2]. \mathsf{lanes}[o_1..o_2] : \\ \\ \mathsf{gpu} \; \mathsf{Grid} \langle \ell_g, \ell_b \rangle. \mathsf{blocks}[m_{20}] \ldots [m_{1d-1}..m_{2d-1}]. \mathsf{varps}[n] \; \mathsf{lanes}[o] : \\ \\ \mathsf{gpu} \; \mathsf{Grid} \langle \ell_g, \ell_b \rangle. \mathsf{blocks}[m_{20}] \ldots [m_{1d-1}..m_{2d-1}]. \mathsf{varps}[n] \; \mathsf{lanes}[o] : \\ \\ \mathsf{gpu} \; \mathsf{Grid} \langle \ell_g, \ell_b \rangle. \mathsf{blocks}[m_{20}] \ldots [m_{2d-1}..m_{2d-1}]. \mathsf{varps}[n] \; \mathsf{lanes}[o] : \\ \\ \mathsf{gpu} \; \mathsf{Grid} \langle \ell_g, \ell_b \rangle. \mathsf{blocks}[m_{20}] \ldots [m_{2d-1}..m_{2d-1}]. \mathsf{varps}[n] \; \mathsf{lanes}[o] : \\ \\ \mathsf{gpu} \; \mathsf{Grid} \langle \ell_g, \ell_b \rangle. \mathsf{blocks}[m_{20}] \ldots [m_{2d-1}..m_{2d-1}]. \mathsf{varps}[n] \; \mathsf{lanes}[o] : \\ \\ \mathsf{gpu} \; \mathsf{Grid} \langle \ell_g, \ell_b \rangle. \mathsf{blocks}[m_{20}] \ldots [m_{2d-1}..m_{2d-1}]. \mathsf{varps}[n] \; \mathsf{lanes}[o] : \\ \\ \mathsf{gpu} \; \mathsf{Grid} \langle \ell_g, \ell_b \rangle. \mathsf{blocks}[m_{20}] \ldots [m_{2d-1}..m_{2d-1}]. \mathsf{varps}[n] \; \mathsf{lanes}[o] : \\ \\ \mathsf{gpu} \; \mathsf{grid} \langle \ell_g, \ell_b \rangle. \mathsf{blocks}[m_{20}] \ldots [m_{2d-1}..m_{2d-1}]. \mathsf{varps}[n] \; \mathsf{lanes}[o] : \\ \\ \mathsf{gpu} \; \mathsf{grid} \langle \ell_g, \ell_b \rangle. \mathsf{blocks}[m_{2d-1}..m_{2d-1}]. \mathsf{varps}[n] \; \mathsf{lanes}[o] : \\ \\ \mathsf{gpu} \; \mathsf{grid} \; \; \mathsf$$

gpu.Grid $\langle d_q, d_b \rangle$.blocks $[m_0]_0..[m_{d-1}]_{d-1}$.warps[n].lanes[o]

T-Selectrange

$$\Delta \vdash^{n_k} m_1..m_2$$

$$\frac{\Delta \vdash e : \mathtt{gpu.Grid} \langle \mathscr{d}_g, \mathscr{d}_b \rangle. e_{L0}[n_{0,0}]..[n_{0,d-1}] \dots e_L[n_0]..[n_k]..[n_{d-1}] \dots e_{Lo}[n_{n,0}]..[n_{n,d-1}]}{\Delta \vdash e[m_1..m_2]_{e_L.k} : \mathtt{gpu.grid} \langle \mathscr{d}, \mathscr{d} \rangle. e_{L0}[n_{0,0}]..[n_{0,d-1}] \dots e_L[n_0]..[m_2 - m_1]..[n_{d-1}] \dots e_{Lo}[n_{n,0}]..[n_{n,d-1}]}$$

FOWARPS
$$n_b = \sum_{i=0}^{d-1} d_{bi}$$
 $n_w = \frac{n_b}{\mathsf{WarpSize}}$ $n_b \bmod \mathsf{WarpSize} = 0$ $\Delta \vdash e : \mathsf{gpu.Grid} \langle d_g, d_b \rangle.\mathsf{blocks}[m_0]..[m_{d-1}]$

$$\overset{-\circ}{\Delta} dash e : exttt{gpu.Grid} \langle {d_g}, {d_b}
angle. exttt{blocks}[m_0]..[m_{d-1}]$$

 $\overline{\Delta \vdash e.\mathtt{to}_\mathtt{warps}: \mathtt{gpu.Grid}\langle \ell_q, \ell_b
angle}.\mathtt{blocks}[m_0]..[m_{d-1}].\mathtt{warps}[n_w]$

 $\Delta; \Gamma \vdash \tau : \kappa$

 Δ ; $\Gamma \vdash \rho$: rgn

$$\frac{r \in \mathrm{dom}(\Gamma)}{\Delta; \ \Gamma \vdash r : \mathtt{rgn}}$$

$$\Delta(r) = rgn$$

$$\overline{\Delta; \ \Gamma \vdash \iota : \mathtt{rgn}}$$

 Δ ; $\Gamma \vdash \mu : \mathtt{mem}$

$$\underline{\mu \in \{ \text{ cpu.mem}, \text{gpu.global}, \text{gpu.shared} \ \}}$$

$$\Delta; \ \Gamma \vdash \mu : \mathtt{mem}$$

$$\Delta(m) = \text{mem}$$

$$\Delta$$
; $\Gamma \vdash m : \text{mem}$

 Δ ; $\Gamma \vdash \delta$: dty

$$WF\text{-}BaseType$$

$$\frac{\text{WF-TVar}}{\Delta(\alpha) = \texttt{dty}}$$

$$\frac{\Delta; \ \Gamma \vdash \rho : \mathtt{rgn} \qquad \Delta; \ \Gamma \vdash \mu : \mathtt{mem} \qquad \Delta; \ \Gamma \vdash \delta : \mathtt{dty}}{\Delta; \ \Gamma \vdash \& \rho \ \omega \ \mu \ \delta : \mathtt{dty}}$$

$$\Delta;\ \Gamma dash \delta: \mathtt{dty}$$

$$\begin{array}{c} \text{WF-Array} \\ \Delta; \ \Gamma \vdash \delta : \texttt{dty} \end{array}$$

 Δ ; $\Gamma \vdash [\delta; \eta] : dty$

 $\overline{\Delta}; \ \Gamma \vdash \mathtt{int} : \mathtt{dty}$

$$\frac{\Delta(\alpha)}{\Delta; \ \Gamma \vdash \alpha : \mathtt{dty}}$$

$$\Lambda \colon \Gamma \vdash \mu \colon \mathsf{mem}$$

$$\frac{\text{WF-Tuple}}{\forall \delta \in \overline{\delta}. \ \Delta; \ \Gamma \vdash \delta : \text{dty}}{\Delta : \ \Gamma \vdash (\overline{\delta}) : \text{dty}}$$

WF-VIEW $\frac{\Delta; \ \Gamma \vdash \delta : \mathtt{dty}}{\Delta; \ \Gamma \vdash \llbracket \delta; \ \eta \rrbracket : \mathtt{dty}}$

$$\frac{\Delta; \ \Gamma \vdash \delta : \mathtt{dty} \qquad \Delta; \ \Gamma \vdash \mu : \mathtt{mem}}{\Delta; \ \Gamma \vdash \delta@\mu : \mathtt{dty}}$$

$$-\delta@\mu: \mathtt{dty}$$

3 Typing Rules

 Δ ; $\Gamma \mid e$; $A \mid t \vdash | \delta : \Gamma' | \dashv A' |$

T-Write-Local is Place(p)
$$\Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [t : \delta] + \Gamma' \mid A' \\ \Gamma'(p) = (\beta_0, \alpha_1) = e = e_0 \\ \Delta; \Gamma' \mid y : \varepsilon; e \mid A \vdash [t : \delta] + \Gamma' \mid A' \\ \Gamma'(p) = (\beta_0, \alpha_1) = e = e_0 \\ \Delta; \Gamma' \mid y : \varepsilon; e \mid A \vdash [p = t : unit] + \Gamma'[p \mapsto \delta_t] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [p = t : unit] + \Gamma'[p \mapsto \delta_t] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [p = t : unit] + \Gamma'[p \mapsto \delta_t] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [p = t : unit] + \Gamma'[p \mapsto \delta_t] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [p = t : unit] + \Gamma'[p \mapsto \delta_t] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [p = t : unit] + \Gamma'[p \mapsto \delta_t] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [p = t : unit] + \Gamma''[p \mapsto \delta_t] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [p = t : unit] + \Gamma'[p \mapsto \delta_t] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [p = t : unit] + \Gamma'[p \mapsto \delta_t] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [p = t : unit] + \Gamma''[p \mapsto \delta_t] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [p = t : unit] + \Gamma''[p \mapsto \delta_t] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [p = t : unit] + \Gamma''[p \mapsto \delta_t] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [p = t : unit] + \Gamma''[p \mapsto \delta_t] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [p = t : unit] + \Gamma''[p \mapsto \delta_t] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [p = t : unit] + \Gamma''[p \mapsto \delta_t] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [p = t : unit] + \Gamma''[p \mapsto \delta_t] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [p = t : unit] + \Gamma''[p \mapsto \delta_t] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [p = t : unit] + \Gamma''[p \mapsto \delta_t] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [p = t : unit] + \Gamma''[p \mapsto \delta_t] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [p = t : unit] + \Gamma''[p \mapsto \delta_t] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [p = t : unit] + \Gamma''[p \mapsto \delta_t] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [p = t : unit] + \Gamma''[p \mapsto \delta_t] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [p = t : unit] + \Gamma''[p \mapsto \delta_t] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [p = t : unit] + \Gamma''[p \mapsto \delta_t] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [p \mapsto \delta] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [p \mapsto \delta] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [p \mapsto \delta] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [p \mapsto \delta] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [p \mapsto \delta] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [p \mapsto \delta] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [p \mapsto \delta] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [p \mapsto \delta] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [p \mapsto \delta] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [p \mapsto \delta] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [p \mapsto \delta] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash [p \mapsto \delta] \mid A' \\ \Delta; \Gamma \mid y : \varepsilon; e \mid$$

Figure 5: Memory operations (Read, Write, Borrow)

T-FUNCTION CALL

$$\begin{split} \mathscr{P}(f) &= \operatorname{fn} \ f \langle \overline{\mathbf{k}} : \kappa \rangle \langle y' \underline{: \varepsilon' \rangle (\overline{e_2 \ x : \delta'})} \overset{e_1}{\longrightarrow} \delta'_r, \ \mathbf{A} \ \{ \ t \ \} \ \text{where} \ \gamma \\ \overline{\Delta}; \ \Gamma \vdash \tau : \kappa \quad \overline{\delta} &= \delta' \overline{[\mathbf{k} : = \tau]} \quad \delta_r = \delta'_r \overline{[\mathbf{k} : = \tau]} \\ y : \varepsilon \vdash e_f : \varepsilon' \quad e = e_1 [y' := e_f] \\ \forall i \in \{ \ 1 \dots n \ \}. \ \Delta; \ \Gamma_{i-1} \ \mid \ y : \varepsilon; \ e_{2i} [y' := e_f] \ \mid \ \mathbf{A}_{i-1} \ \vdash \overline{[p_i : \delta_i]} \ \dashv \ \Gamma_i \ \mid \ \mathbf{A}_i \\ \overline{\Delta}; \ \Gamma_0 \ \mid \ y : \varepsilon; \ e \ \mid \ \mathbf{A}_0 \ \vdash \overline{[f :: \langle \overline{\tau} \rangle :: \langle e_f \rangle (\overline{p})} \ : \delta_r \ \mid \ \Gamma_n \ \mid \ \mathbf{A}_n \ \uplus \ \mathbf{A}_{\overline{[\mathbf{k} : = \tau]}} [y' := e_f] \overline{[x : = p]} \end{split}$$

T-KernelCall

$$y: \varepsilon \vdash e: \mathtt{cpu.Thread}$$

$$e_g = \mathtt{gpu.grid} \langle d_g, d_b \rangle \qquad e_s = e_g.\mathtt{blocks}[n_1] \dots [n_k]$$

$$\mathcal{P}(f) = \mathtt{fn} \ f \langle \overline{\mathtt{k} : \kappa} \rangle \langle y' : \varepsilon' \rangle (e_g \ x : \delta', e_s \ \underline{x_s : \& \varepsilon \ uniq \ gpu.shared} \ \overline{\delta_s}) \xrightarrow{e_g} \mathtt{unit}, \ A \ \{ \ t \ \} \ \mathtt{where} \ \gamma$$

$$\overline{\Delta}; \ \Gamma_0 \vdash \overline{\tau} : \kappa \qquad \overline{\delta} = \delta'[\overline{\mathtt{k} := \tau}] \qquad \delta_r = \delta'_r[\overline{\mathtt{k} := \tau}]$$

$$\forall i \in \{ \ 1 \dots n \ \}. \ \Delta; \ \Gamma_{i-1} \ | \ y : \varepsilon; e \ | \ A_{i-1} \ \vdash [\overline{p_i : \delta_i}] \ \dashv \ \Gamma_i \ | \ A_i$$

$$\overline{\Delta}; \ \Gamma_0 \ | \ y : \varepsilon; e \ | \ A \ \vdash [f::\langle \overline{\tau} \rangle :: \ll d_g, d_b \ ; \ \overline{r, \delta_s} \ggg (\overline{p}) : \mathtt{unit}] \ \dashv \ \Gamma_n \ | \ A_n$$

$$\overline{\Delta}; \ \Gamma_0 \ | \ y : \varepsilon; e \ | \ A_0 \ \vdash [\mathtt{for} \ n \ \mathtt{in} \ \eta_1...\eta_2 \ \{ \ t \ \} : \mathtt{unit}] \ \dashv \ \Gamma_n \ | \ A_n}$$

T-IFELSE

T-Let-Uninit

$$\frac{y:\varepsilon \vdash e':\varepsilon' \quad \forall r \in \text{free-regions}(\delta). \ \Gamma \vdash r \ \text{rnrb}}{\Delta; \ \Gamma \ | \ y:\varepsilon; \ e \ | \ A \ \vdash \boxed{\texttt{let}(e') \ x:\delta : \texttt{unit}} \ \dashv \ \Gamma, \ x:e'\delta^\dagger \ | \ A}$$

T-SEQ

$$\frac{\Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash \boxed{t_1 : \delta_1} \dashv \Gamma' \mid A'}{\Delta; \text{ gc-loans}(\Gamma') \mid y : \varepsilon; e \mid A \vdash \boxed{t_2 : \delta_2} \dashv \Gamma'' \mid A''}$$

$$\frac{\Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash \boxed{t_1; t_2 : \delta_2} \dashv \Gamma'' \mid A''}{\Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash \boxed{t_1; t_2 : \delta_2} \dashv \Gamma'' \mid A''}$$

T-Block

$$\frac{\Delta\,;\,\Gamma,(r\mapsto\{\ \})\ |\ y:\varepsilon\,;\,e\ |\ \mathbf{A}\ \vdash \boxed{t\::\delta}\ \dashv\ \Gamma',(\mathcal{F})\ |\ \mathbf{A}'}{\Delta\,;\,\Gamma\ |\ y:\varepsilon\,;\,e\ |\ \mathbf{A}\ \vdash \boxed{[e]\{\ t\ \}^{\overline{r}}\::\delta}\ \dashv\ \Gamma'\ |\ \mathrm{remove\text{-}plexpr}_{\Gamma'}(\mathbf{A}')}$$

T-Tuple

$$\frac{\forall i \in \{\ 1 \dots n\ \}.\ \Delta\,;\ \Gamma_{i-1},\underline{\ }:\delta_{i-1}\ \mid\ y:\varepsilon\,;\ e\ \mid\ \mathbf{A}_{i-1}\ \vdash \boxed{t_i\ :\delta_i}\ \dashv\ \Gamma_i\ \mid\ \mathbf{A}_i}{\Delta\,;\ \Gamma_0\ \mid\ y:\varepsilon\,;\ e\ \mid\ \mathbf{A}_0\ \vdash \boxed{(\overline{t})\ :(\overline{\delta})}\ \dashv\ \mathrm{remove\text{-}anon}(\Gamma_n)\ \mid\ \mathbf{A}_n}$$

T-Struct

$$\begin{split} \mathscr{P}(s) &= \mathtt{struct} \ s \langle \overline{\mathtt{k} : \kappa} \rangle \{ \ \overline{x : \delta} \ \} \quad \overline{\Delta}; \ \Gamma_0 \vdash \tau : \kappa \quad \overline{\delta' = \delta[\mathtt{k} := \tau]} \\ &\forall i \in \{ \ 1 \ldots n \ \}. \ \Delta; \ \Gamma_{i-1}, \underline{\quad} : \delta'_{i-1} \ \mid \ y : \varepsilon; \ e \ \mid \ A_{i-1} \ \vdash \boxed{t_i : \delta'_i} \ \dashv \ \Gamma_i \ \mid \ A_i \\ \hline &\Delta; \ \Gamma_0 \ \mid \ y : \varepsilon; \ e \ \mid \ A_0 \ \vdash \boxed{s \langle \overline{\tau} \rangle \{ \ \overline{x : t} \ \}} \ : s \{ \ \overline{x : \delta'} \ \} \ \dashv \ \mathrm{remove-anon}(\Gamma_n) \ \mid \ A_n \end{split}$$

T-BINOP

T-LITERAL

$$\overline{\Delta; \Gamma \mid y : \varepsilon; e \mid A \vdash \underline{\underline{l} : b} \dashv \Gamma \mid A}$$

$$\Delta\,;\,\Gamma \mid y:\varepsilon\,;\,e \vdash^{\omega}_{\mathtt{pl}} p\,:\delta$$

$$\frac{\Gamma\text{-PL-VAR}}{\Gamma(x) = \delta} \\ \frac{\Gamma(x) = \delta}{\Delta; \Gamma \mid y : \varepsilon; e \vdash_{\mathtt{pl}}^{\omega} x : \delta} \\ \frac{\Delta; \Gamma \mid y : \varepsilon; e \vdash_{\mathtt{pl}}^{\omega} p : (\delta_{1}, \ldots, \delta_{i}, \ldots, \delta_{n-1})}{\Delta; \Gamma \mid y : \varepsilon; e \vdash_{\mathtt{pl}}^{\omega} p : (\delta_{1}, \ldots, \delta_{i}, \ldots, \delta_{n-1})} \\ \frac{\Gamma\text{-PL-DEREF}}{\Delta; \Gamma \mid y : \varepsilon; e \vdash_{\mathtt{pl}}^{\omega} p : \& \rho \; \omega' \; \mu \; \delta} \\ \frac{\Delta; \Gamma \mid y : \varepsilon; e \vdash_{\mathtt{pl}}^{\omega} p : \& \rho \; \omega' \; \mu \; \delta}{\Delta; \Gamma \mid y : \varepsilon; e \vdash_{\mathtt{pl}}^{\omega} p : \delta} \\ \frac{\Delta; \Gamma \mid y : \varepsilon; e \vdash_{\mathtt{pl}}^{\omega} p : [\delta'; \eta] \to \delta}{\Delta; \Gamma \mid y : \varepsilon; e \vdash_{\mathtt{pl}}^{\omega} p : [\delta'; \eta]} \\ \frac{\Delta; \Gamma \mid y : \varepsilon; e \vdash_{\mathtt{pl}}^{\omega} p : [\delta'; \eta]}{\Delta; \Gamma \mid y : \varepsilon; e \vdash_{\mathtt{pl}}^{\omega} p : [\delta; \eta]} \\ \frac{\Delta; \Gamma \mid y : \varepsilon; e \vdash_{\mathtt{pl}}^{\omega} p : [\delta; \eta]}{\Delta; \Gamma \mid y : \varepsilon; e \vdash_{\mathtt{pl}}^{\omega} p : [\delta; \eta]} \\ \frac{\Delta; \Gamma \mid y : \varepsilon; e \vdash_{\mathtt{pl}}^{\omega} p : [\delta; \eta]}{\Delta; \Gamma \mid y : \varepsilon; e \vdash_{\mathtt{pl}}^{\omega} p : [\delta; \eta]} \\ \frac{\Delta; \Gamma \mid y : \varepsilon; e \vdash_{\mathtt{pl}}^{\omega} p : [\delta; \eta]}{\Delta; \Gamma \mid y : \varepsilon; e \vdash_{\mathtt{pl}}^{\omega} p : [\delta; \eta]} \\ \frac{\Delta; \Gamma \mid y : \varepsilon; e \vdash_{\mathtt{pl}}^{\omega} p : [\delta; \eta]}{\Delta; \Gamma \mid y : \varepsilon; e \vdash_{\mathtt{pl}}^{\omega} p : [\delta; \eta]}$$

Figure 7: Place expression typing rules

$$\frac{\text{RR-Refl}}{\Delta; \Gamma \vdash^{\nu} \delta_{1} \leadsto \delta_{2} \dashv \Gamma'} \qquad \frac{\text{RR-Array}}{\Delta; \Gamma \vdash^{\nu} \delta_{1} \leadsto \delta_{1} \dashv \Gamma} \qquad \frac{\text{RR-Array}}{\Delta; \Gamma \vdash^{\nu} \delta_{1} \leadsto \delta_{2} \dashv \Gamma'} \qquad \frac{\text{RR-ArrayView}}{\Delta; \Gamma \vdash^{\nu} \delta_{1} \leadsto \delta_{2} \dashv \Gamma'} \\
\frac{\Delta; \Gamma \vdash^{\nu} \delta_{1} \leadsto \delta_{1} \dashv \Gamma}{\Delta; \Gamma \vdash^{\nu} \delta_{1} \leadsto \delta_{2} \dashv \Gamma'} \qquad \frac{\Delta; \Gamma \vdash^{\nu} \delta_{1} \leadsto \delta_{2} \dashv \Gamma'}{\Delta; \Gamma \vdash^{\nu} \delta_{1} \bowtie \delta_{2} \dashv \Gamma'} \\
\frac{RR-Ar}{\Delta; \Gamma \vdash^{\nu} \delta_{1} \bowtie \rho_{2} \dashv \Gamma'} \qquad \frac{RR-Tuple}{\Delta; \Gamma \vdash^{\nu} \delta_{1} \leadsto \delta_{2} \dashv \Gamma'} \\
\frac{\forall i \in \{1 \dots n\}.\Delta; \Gamma_{i-1} \vdash^{\nu} \delta_{i} \leadsto \delta'_{i} \dashv \Gamma_{i}}{\Delta; \Gamma_{0} \vdash^{\nu} (\delta_{1}, \dots, \delta_{n}) \leadsto (\delta'_{1}, \dots, \delta'_{n}) \dashv \Gamma_{n}} \\
\frac{RR-Reference}{\Delta; \Gamma \vdash^{\nu} \rho_{1} :> \rho_{2} \dashv \Gamma'} \qquad \Delta; \Gamma' \vdash^{\nu} \delta_{1} \leadsto \delta_{2} \dashv \Gamma''} \qquad \frac{RR-Dead}{\Delta; \Gamma \vdash^{\nu} \delta_{1} \leadsto \delta_{2} \dashv \Gamma'} \\
\frac{\Delta; \Gamma \vdash^{\nu} \delta_{1} \leadsto \delta_{2} \dashv \Gamma'}{\Delta; \Gamma \vdash^{\nu} \& \rho_{1} \bowtie \mu \delta_{1} \leadsto \& \rho_{2} \bowtie \mu \delta_{2} \dashv \Gamma''} \qquad \frac{\Delta; \Gamma \vdash^{\nu} \delta_{1} \leadsto \delta_{2} \dashv \Gamma'}{\Delta; \Gamma \vdash^{\nu} \delta_{1} \leadsto \delta_{2} \dashv \Gamma'} \\
\frac{\Delta; \Gamma \vdash^{\nu} \delta_{1} \leadsto \delta_{2} \dashv \Gamma'}{\Delta; \Gamma \vdash^{\nu} \& \rho_{1} \bowtie \mu \delta_{1} \leadsto \& \rho_{2} \bowtie \mu \delta_{2} \dashv \Gamma''} \qquad \frac{\Delta; \Gamma \vdash^{\nu} \delta_{1} \leadsto \delta_{2} \dashv \Gamma'}{\Delta; \Gamma \vdash^{\nu} \delta_{1} \leadsto \delta_{2} \dashv \Gamma'}$$

Figure 8: Region rewriting

4 Auxiliary Definitions

narrowable (Γ, ω, e, p)

The predicate narrowable (Γ, ω, e, p) inidicates whether place expression p narrows parallel accesses such that execution

resource e can borrow or access p if $\omega = \text{uniq}$:

$$\operatorname{narrowable}(\Gamma, \omega, e, p) := (\omega = \operatorname{uniq}) \Rightarrow \operatorname{exec}(\Gamma, p) = e$$

 $\pi = \sigma \cdot \sigma$: Path

A path π is a list of σ , where $\sigma \in \{ .j \mid .x \mid * \mid [i] \mid [e] \mid f_v :: \langle \overline{\tau} \rangle (\overline{v}) \}$.

$$p = x | \pi$$

The equation $p = x | \pi$ describes how a place expression p is decomposed into it's root, the variable x, and it's path:

$$x = x \mid \bullet$$

$$p.j = x \mid (\pi \cdot .j) \quad \text{for } p = x \mid \pi$$

$$p.x' = x \mid (\pi \cdot .x') \quad \text{for } p = x \mid \pi$$

$$*p = x \mid (\pi \cdot *) \quad \text{for } p = x \mid \pi$$

$$p[i] = x \mid (\pi \cdot [i]) \quad \text{for } p = x \mid \pi$$

$$p[e] = x \mid (\pi \cdot [e]) \quad \text{for } p = x \mid \pi$$

$$p.f_v::\langle \overline{\tau} \rangle(\overline{v}) = x \mid (\pi \cdot f_v::\langle \overline{\tau} \rangle(\overline{v})) \quad \text{for } p = x \mid \pi$$

race-free $_O(\pi_1, \pi_2)$

$$\frac{\text{race-free}_{\text{Eq}}(\pi, nil) \quad \sigma \neq \llbracket e \rrbracket}{\text{race-free}_{\text{Eq}}(nil, \pi)} \qquad \frac{\text{race-free}_{\text{Eq}}(\pi, nil) \quad \sigma \neq \llbracket e \rrbracket}{\text{race-free}_{\text{Eq}}(\sigma \cdot \pi, nil)} \qquad \frac{\text{race-free}_{\text{Eq}}(\pi_{\text{prev}}, \pi_{\text{current}})}{\text{race-free}_{\text{Eq}}(* \cdot \pi_{\text{prev}}, * \cdot \pi_{\text{current}})} \\ \frac{.\mathsf{i} \neq .\mathsf{j}}{\text{race-free}_{\text{Eq}}(.\mathsf{i} \cdot \pi_{\text{prev}}, .\mathsf{j} \cdot \pi_{\text{current}})} \qquad \frac{\text{race-free}_{\text{Eq}}(\pi_{\text{prev}}, \pi_{\text{current}})}{\text{race-free}_{\text{Eq}}(.\mathsf{j} \cdot \pi_{\text{prev}}, .\mathsf{j} \cdot \pi_{\text{current}})} \qquad \frac{\text{race-free}_{\text{Eq}}(\pi_{\text{prev}}, \pi_{\text{current}})}{\text{race-free}_{\text{Eq}}(\llbracket e \rrbracket \cdot \pi_{\text{prev}}, \llbracket e \rrbracket \cdot \pi_{\text{current}})}$$

$$\frac{\operatorname{race-free}_{O'}(\pi_{\operatorname{prev}}, \pi_{\operatorname{current}})}{\operatorname{race-free}_{O}([\mathsf{i}] \cdot \pi_{\operatorname{prev}}, [\mathsf{j}] \cdot \pi_{\operatorname{current}})} \qquad \frac{\operatorname{race-free}_{O'}(\pi_{\operatorname{prev}}, \pi_{\operatorname{current}})}{\operatorname{race-free}_{O}([\mathsf{i}] \cdot \pi_{\operatorname{prev}}, [\mathsf{j}] \cdot \pi_{\operatorname{current}})} \qquad \frac{\operatorname{race-free}_{\operatorname{Eq}}(v_1 \cdot \ldots v_m, v_1' \cdot \ldots v_n') = O' \qquad \sigma \not\in v}{\operatorname{race-free}_{\operatorname{Overlap}}(\pi_{\operatorname{prev}}, \pi_{\operatorname{current}}) \qquad \sigma \not\in v}$$

$$\frac{\operatorname{race-free}_{\operatorname{Overlap}}(\pi_{\operatorname{prev}}, \pi_{\operatorname{current}}) \qquad \sigma \not\in v}{\operatorname{race-free}_{\operatorname{Overlap}}(v_1 \cdot \ldots v_m \cdot \sigma \cdot \pi_{\operatorname{prev}}, v_1' \cdot \ldots v_n' \cdot \sigma \cdot \pi_{\operatorname{current}})}$$

 $A \vdash^{\omega} p \mid Access Conflict Check:$

$$\frac{p = x | \pi \qquad \forall \stackrel{\omega'}{p_{\mathrm{A}}} \in \mathrm{A.} \ if \ ((\omega = \mathtt{uniq} \vee \omega_{\mathrm{A}} = \mathtt{uniq}) \wedge p_{\mathrm{A}} = x | \pi_{\mathrm{A}}) \ then \ \mathrm{race\text{-}free}_{\mathrm{Eq}}(\pi_{\mathrm{A}}, \pi)}{\mathrm{A} \vdash^{\omega} p}$$

 $\pi \bowtie \pi'$: Paths π and π' are in a memory conflict,

i.e., they can point to the same memory location if applied to the same variable.

(This substitutes the standard conflict check in Oxide's borrowing rules.)

$$\frac{\pi \bowtie \pi'}{\sigma \cdot \pi \bowtie \sigma \cdot \pi'} \qquad \qquad \frac{\sigma \neq \sigma' \qquad \neg (\sigma, \sigma' \in \{ \text{ .fst, .snd } \})}{\sigma \cdot \pi \bowtie \sigma' \cdot \pi'} \qquad \qquad \frac{\epsilon \bowtie \epsilon}{}$$

 $isCopyable(\delta)$

$$\begin{split} & \text{isCopyable}(\delta) = \text{true} \quad \text{for } \delta \in \{ \text{ bool, int, float, AtomicU32, } \& \varrho \text{ shrd } \mu \ \delta \ \} \\ & \text{isCopyable}((\delta_1, \ldots, \delta_n)) = \forall i. \text{ isCopyable}(\delta_i) \\ & \text{isCopyable}(s\{ \ x_1 : \delta_1, \ldots, x_n : \delta_n \ \}) = \forall i. \text{isCopyable}(\delta_i) \\ & \text{isCopyable}([\delta; \eta]) = \text{isCopyable}(\delta) \\ & \text{isCopyable}(\delta) = \text{false} \quad \text{else} \end{split}$$

isPlace(p)

$$isPlace(p) := (p = x \mid \pi) \Rightarrow \forall \sigma \in \pi. \ \sigma \in \{.j, .x\}$$

release-ownership(e, p)

 $\text{release-ownership}(e, p_1) = \begin{cases} p_2 & \text{if there exist } \pi_1 \text{ and } \pi_2 \text{ such that } p_1 = x \mid \pi_1 \cdot \llbracket e \rrbracket \cdot \pi_2 \text{ and } p_2 = x \mid \pi_1 \cdot \llbracket e \rrbracket \\ p_1 & \text{else} \end{cases}$

remove-anon(\mathcal{F})

$$\begin{split} \operatorname{remove-anon}(\bullet) &= \bullet \\ \operatorname{remove-anon}(\mathcal{F}, \underline{} : e \ \tilde{\delta}) &= \operatorname{remove-anon}(\mathcal{F}) \\ \operatorname{remove-anon}(\mathcal{F}, x : e \ \tilde{\delta}) &= \operatorname{remove-anon}(\mathcal{F}), x : e \ \tilde{\delta} \\ \operatorname{remove-anon}(\mathcal{F}, r \mapsto \left\{ \ \overline{\ell} \ \right\}) &= \operatorname{remove-anon}(\mathcal{F}), r \mapsto \left\{ \ \overline{\ell} \ \right\} \end{split}$$

remove-anon(Γ)

$$\begin{split} \operatorname{remove-anon}(\bullet) &= \bullet \\ \operatorname{remove-anon}(\Gamma, (\mathcal{F})) &= \operatorname{remove-anon}(\Gamma, (\operatorname{remove-anon}(\mathcal{F}))) \end{split}$$

 $A + {}^{\omega}p$

 $A_1, {}^{\omega'}p', A_2 + {}^{\omega}p = A_1, A_2, {}^{\omega}p$ if $\exists^{\omega'}p' \in A$. p' is prefix of p $A + {}^{\omega}p = A, {}^{\omega}p$ else

 $A_1 \uplus A_2$

$$A_1 \uplus (A_2, {}^{\omega}p) = (A_1 + {}^{\omega}p) \uplus A_2$$
$$A \uplus \bullet = A$$